



DCX F-DP Power Supply

Operating Manual

Branson Ultrasonics Corp.

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Manual Change Information

At Branson, we strive to maintain our position as the leader in ultrasonics plastics joining, metal welding, cleaning and related technologies by continually improving our circuits and components in our equipment. These improvements are incorporated as soon as they are developed and thoroughly tested.

Information concerning any improvements will be added to the appropriate technical documentation at its next revision and printing. Therefore, when requesting service assistance for specific units, note the Revision information found on this document, and refer to the printing date which appears on this page.

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Foreword

Congratulations on your choice of a Branson Ultrasonics Corporation system!

The Branson DCX F-DP Power Supply system is process equipment for the joining of plastic parts using ultrasonic energy. It is the newest generation of product using this sophisticated technology for a variety of customer applications. This Operating Manual is part of the documentation set for this system, and should be kept with the equipment.

Thank you for choosing Branson!

Introduction

This manual is arranged into several structured chapters which will help you find the information you may need to know to safely handle, install, set up, program, operate, and/or maintain this product. Please refer to the <u>Table Of Contents</u> and/or the <u>Index</u> of this manual to find the information you may be looking for. In the event you require additional assistance or information, please contact our Product Support department (see <u>1.3 How to Contact Branson</u> for information on how to contact them) or your local Branson representative.

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Chapter 1: Safety and Support

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1.1 Safety Requirements and Warnings

This chapter contains an explanation of the different Safety Notice symbols and icons found both in this manual and on the product itself and provides additional safety information for ultrasonic welding. This chapter also describes how to contact Branson for assistance.

1.1.1 Symbols Found in this Manual

These symbols used throughout this manual warrant special attention:

WARNING	Indicates a possible danger
<u> </u>	If these risks are not avoided, death or severe injury might result.

WARNING	High Voltage Hazard
4	High voltage. Turn power off before servicing.

WARNING	Corrosive Material Hazard
	Corrosive material. Avoid contact with eyes and skin. Wear proper protection.

CAUTION	Indicates a possible danger
	If these risks are not avoided, slight or minor injury might result.

CAUTION	Loud Noise Hazard
	Loud noise hazard. Ear protection must be worn.

CAUTION	Heavy Object
	Heavy object. To avoid muscle strain or back injury, use lifting aids and proper lifting techniques.

NOTICE	Indicates a possible damaging situation			
1	If this situation is not avoided, the system or something in its vicinity might get damaged. Application types and other important or useful information are emphasized.			

1.1.2 Symbols Found on the Product

The DCX F-DP Power Supply has several safety-related labels on it to indicate the presence of hazardous voltages inside the unit.

Figure 1.1 Safety-related Labels found on the DCX F-DP Power Supply



WARNING

To prevent electrical shock wait 5 minutes after disconnecting before servicing.



Figure 1.2 Safety-related Labels found on the DCX F-DP Power Supply (cont.)



MADE IN MEXICO





GROUND UNIT BEFORE OPER ATING

1.2 General Precautions

Take the following precautions before servicing the power supply:

- Be sure the power is disconnected before making any electrical connections
- To prevent the possibility of an electrical shock, always plug the power supply into a grounded power source
- To prevent the possibility of an electrical shock, ground the power supply by securing an 8 gauge grounded conductor to the ground screw located next to the air outlet
- Power supplies produce high voltage. Before working on the power supply assembly, do the following:

Turn off the power supply

Unplug main power

Allow at least 5 minutes for capacitors to discharge

- High voltage is present in the power supply. Do not operate with the cover removed
- High line voltages exist in the ultrasonic power supply assembly. Common points are tied to circuit reference, not chassis ground. Therefore, use only non-grounded, battery-powered multimeters when testing the power supply assembly. Using other types of test equipment can present a shock hazard
- Keep hands from under the horn. Down force (pressure) and ultrasonic vibrations can cause injury
- · Do not cycle the welding system if either the RF cable or converter is disconnected
- When using larger horns, avoid situations where fingers could be pinched between the horn and the fixture
- Ensure power supply installation is performed by qualified personnel and in accordance with local standards and regulations

CAUTION	Loud Noise Hazard
	Sound level and frequency of the noise emitted during the ultrasonic assembly process may depend upon a. type of application, b. size, shape and composition of the material being assembled, c. shape and material of the holding fixture, d. welder setup parameters and e. tool design.
	Some parts vibrate at an audible frequency during the process. Some or all of these factors may result in an uncomfortable noise being emitted during the process.
	In such cases operators may need to be provided with personal protective equipment. See 29 CFR (Code of Federal Regulations) 1910.95 Occupational Noise Exposure.

NOTICE	
1	When the battery is worn out, dispose it under the ordinance of each local government.

WARNING	Corrosive Material Hazard
	First aid measures (in case of electrolyte leakage from the battery):
	Eye Contact: Flush the eyes with plenty of clean water for at least 15 minutes immediately, without rubbing. Get immediate medical treatment.
	If appropriate procedures are not taken, this may cause eye injury.
	Skin Contact: Wash the affected area under tepid running water using a mild soap. If appropriates procedures are not taken, this may cause sores on the skin. Get medical attention if irritation develops or persists.
	Inhalation: Remove to fresh air immediately. Get medical treatment immediately.

1.2.1 Intended Use of the System

The DCX F-DP Power Supply and components are designed to be used as part of an ultrasonic welding system. These are designed for a wide variety of welding or processing applications.

If the equipment is used in a manner not specified by Branson, the protection provided by the equipment may be impaired.

Branson Ultrasonics Corporation designs and manufactures machines giving the first priority to safety precautions, to allow customers to use the machines safely and effectively. Only trained operators should run and service the equipment. Untrained operators can misuse the equipment or ignore safety instructions that can result in personal injury or equipment damage. It is most essential that all operators and service personnel pay attention to safety instructions when operating and servicing the equipment.

1.2.2 Emissions

Because of the various types of toxic or injurious gases that may be liberated during the welding based on the material being processed, sufficient ventilation should be provided to prevent a concentration of these gases in excess of 0.1 ppm. Check with your materials suppliers for recommended protection when processing their materials.

CAUTION	Corrosive Material Hazard
	Processing of many materials, such as PVC, can be hazardous to an operator's health and could cause corrosion/damage to the equipment. Use proper ventilation and take protective measures.

1.2.3 Setting up the Workplace

Measures for setting up a workplace for safe operation of the ultrasonic welder are outlined in <u>Chapter 5: Installation and Setup</u>.

1.2.4 Regulatory Compliance

This product meets electrical safety requirements and EMC (Electromagnetic Compliance) requirements for North America, Great Britain, and the European Union.



1.3 How to Contact Branson

Branson is here to help you. We appreciate your business and are interested in helping you successfully use our products. To contact Branson for help, use the following telephone numbers, or contact the field office nearest you (business hours from 8 a.m. to 4 p.m. Central and Eastern Time Zones):

- North American Headquarters (all Departments): (203) 796-0400
- Parts Store (direct number): (877) 330-0406
- Repair department: (877)-330-0405
- For emergency after-hours service (5 p.m. 8 a.m. EST): (203) 796-0500 (US phone numbers only)

Tell the operator which product you have and which person or department you need (<u>Table 1.1 Branson Contacts</u>). If after hours, please leave a voice message with your name and return telephone number.

1.3.1 Before Calling Branson for Assistance

This manual provides information for troubleshooting and resolving problems that could occur with the equipment (see <u>Chapter 9: Maintenance</u>). If you still require assistance, Branson Product Support is here to help you. To help identify the problem, use the following questionnaire which lists the common questions you will be asked when you contact the Product Support department.

Before calling, determine the following information:

- 1. Your company name and location.
- 2. Your return telephone number.
- 3. Have your manual with you. If troubleshooting a problem, refer to Chapter 9: Maintenance.
- 4. Know your equipment model and serial numbers (found on a gray data label on the units). Information about the horn (part number, gain, etc.) or other tooling may be etched into the tooling. Software- or firmware-based systems may provide a BOS or software version number, which may be required.
- 5. What tooling (horn) and booster are being used?
- 6. What are the setup parameters and mode?
- 7. Is your equipment in an automated system? If so, what is supplying the "start" signal?
- 8. Describe the problem; provide as much detail as possible. For example, is the problem intermittent? How often does it occur? How long before it occurs if you are just powering up? If an error is occurring, which error (give error number or name)?
- 9. List the steps you have already taken.
- 10. What is your application, including the materials being processed?
- 11. Have a list of service or spare parts you have on hand (tips, horns, etc.)

Notes:							
1	. Notes:	Notes:	Notes:	Notes:	Notes:	Notes:	Notes:

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1.4 Returning Equipment for Repair

Before sending equipment for repair, provide as much information with the equipment to help determine the problem with the system. Use the following page to record necessary information.

NOTICE	
1	To return equipment to Branson, you must first obtain an RGA number from a Branson representative, or the shipment may be delayed or refused.

If you are returning equipment to Branson for repair, you must first call the Repair department to obtain a **Returned Goods Authorization** (RGA) number. (If you request it, the repair department will fax a Returned Goods Authorization form to fill out and return with your equipment).

Branson Repair Department, C/O Zuniga Logistics, LTD

12013 Sara Road, Killam Industrial Park

Laredo, Texas 78045 U.S.A.

Direct telephone number: (877) 330-0405

Fax number: (877) 330-0404

- Provide as much information as possible that will help identify the need for repair
- Carefully pack the equipment in original packing cartons
- Clearly label all shipping cartons with the RGA number on the outside of cartons as well as on your packing slip, along with the reason for return
- Return general repairs by any convenient method. Send priority repairs by air freight
- You must prepay the transportation charges FOB Laredo, Texas, U.S.A.

will fax an RGA form to fill out and return with the equipment).

1.4.1 Get an RGA Number

RGA#

If you are returning equipment to Branson, please call the Repair Department to obtain a Returned Goods Authorization (RGA) number. (At your request, the Repair Department



1.4.2 Record Information About the Problem

Before sending equipment for repair, record the following information and send a copy of it with the equipment. This will greatly increase Branson's ability to address the problem.

1.	Describe the problem; provide as much detail as possible. For example, is the problem intermittent? How often does it occur? How long before it occurs after powering up?
2.	Is your equipment in an automated system?
3.	If the problem is with an external signal, which signal?
4.	If known, include plug/pin # (e.g., P29, pin #3) for that signal:
5.	What are the Weld Parameters?
6.	What is your application? (Type of weld, plastic material, etc.):
7.	Name and phone number of the person most familiar with the problem:

Contact the Branson office prior to shipping the equipment.

For equipment not covered by warranty, to avoid delay, include a Purchase Order.

Send a copy of this page with the equipment being returned for repair.

1.4.3 Departments to Contact

Call your local Branson Representative, or contact Branson by calling and asking for the appropriate department, as indicated in <u>Table 1.1 Branson Contacts</u> below.

Table 1.1 Branson Contacts

What you need help with or information about	Whom to Call	At this Phone Number
Information about new welding systems or components	Your local Branson Rep or Branson Customer Service	203-796-0400 Ext 384
Application and setup questions on the welding system	Welding Applications Lab	203-796-0400 Ext 368
Application assistance on the horns and tooling	ATG Lab	203-796-0400 Ext 495
Technical questions about the welding system	Welding Product Support	203-796-0400 Ext 355, 551
Technical questions about horns and tooling	ATG Lab	203-796-0400 Ext 495
Ordering new parts	Parts Store	877-330-0406
RGA's, request for repair, status of a repair	Welding Repair Department	877-330-0405
System automation/hookup information	Product Support	203-796-0400 Ext 355, 551

Му	Local	Branson	Represen	tative	's name	is:
----	-------	---------	----------	--------	---------	-----

		representative	

1.4.4 Pack and Ship the Equipment

- 1. Carefully pack the system in original packing material to avoid shipping damage. Plainly show the RGA number on the outside of cartons as well as inside the carton along with the reason for return. Make a list of all components packed in the box. KEEP YOUR MANUAL.
- 2. Return general repairs by any convenient method. Send priority repairs by air freight. Prepay the transportation charges FOB the repair site.

NOTICE	
1	Items that are sent Freight Collect will be refused.



1.5 Obtaining Replacement Parts

You can reach Branson Parts Store at the following telephone numbers:

Branson Part Store

Direct telephone number: 877-330-0406

Fax number: 877-330-0404

Many parts can be shipped the same day if ordered before 2:30 p.m., Eastern time.

A parts list is found in <u>Chapter 9: Maintenance</u> of this manual, listing descriptions and EDP part numbers. If you need replacement parts, coordinate the following with your purchasing agent:

- · Purchase order number
- Ship to information
- Bill to information
- Shipping instructions (air freight, truck, etc.)
- Any special instructions (for example, "Hold at the airport and call"). Be sure to give a name and phone number
- · Contact name information

Chapter 2: Introduction

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2.1 Models Covered

This manual covers all models of the DCX F-DP Power Supply.

Table 2.1 Models Covered in this Manual

Frequency	Power	EDP
	1250 W	101-132-2067
20 kHz	2500 W	101-132-2068
	4000 W	101-132-2069
30 kHz	1500 W	101-132-2066
40 kHz	800 W	101-132-2065

2.1.1 Overview of these Models

Figure 2.1 The DCX F-DP Power Supply



The DCX F-DP Power Supply generates ultrasonic energy through an ultrasonic converter for welding plastics. Several models are available, depending on the desired frequency (for example, 20 kHz) and the desired power range (for example, 4.0 kW). The power supply also contains a microprocessor-based controller module that provides for control and monitoring of welding operations.

The power supply provides the following features:

End of Weld Store: Allows the power supply to track and store the frequency of the last weld.

Timed Seek: Tracks and starts the stack on the correct frequency. It does this by running the horn at a low-level amplitude (10%) to find and lock on to the stack operating frequency. Seeks are timed from the moment sonics was last activated.

Line Regulation: Maintains converter amplitude by regulating for variances in the line voltages.

Load Regulation: Maintains converter amplitude over the full range of rated power.

System Protection: Protects the power supply by providing six levels of protection.

Voltage

Current

Phase

Temperature

Power

Frequency

Web Page Interface: Provides access, via Ethernet connection, to power supply information, diagnostics, and configuration web pages.



2.2 Compatibility with other Branson Products

Table 2.2 Power Supply Compatibility with Branson Converters

DCX F-DP Models	Converter
	CR-20S
	CR-20C
20 kHz	CH-20S (932 AH SPL)
ZU KIIZ	CH-20C
	CS-20S
	CS-20C
	CR-30S
	CR-30C
30 kHz	CH-30S
JO KIIZ	CH-30C
	CS-30S
	CS-30C
	CR-40S (4TH)
40 kHz	CR-40C
	4TP

2.3 Features

2.3.1 The Welding System

The welding system consists of a DCX F-DP Power Supply and a converter-booster-horn stack. The system can perform ultrasonic welding, inserting, staking, spot welding, swaging, degating, and continuous ultrasonic operations. It is designed for automated, semi-automated and/or manual production operations.

2.3.2 The Power Supply

The DCX F-DP Power Supply consists of an ultrasonic power supply assembly with a system controller and user interfaces. The ultrasonic power supply assembly converts conventional 50/60 Hz line current to 20 kHz, 30 kHz or 40 kHz electrical energy. The system controller controls the welding system.

Listed below are the control features of the Branson DCX F-DP Power Supply ultrasonic welding system:

Table 2.3 Control Features

Name	Description
Autotuning	Branson power supply tuning ensures that the system is running at peak efficiency.
Digital Amplitude Setting	This feature allows you to set the exact amplitude necessary for your application, allowing increased range and setting repeatability over analog systems.
Frequency Offset	This process feature allows a user to set an offset relative to the starting frequency, for certain specific applications, where the force imparted on the fixture or anvil causes a frequency shift in the stack's operation. You should only use this feature when advised to do so by Branson.
Horn Signature	Using the DCX F-DP Power Supply Web Page Interface, you may scan your ultrasonic stack to view its operating frequency on your computer, using digital readouts to give you the best picture of the stack's operation.
LCD (Liquid Crystal Display)	Provides a clear visual interface to monitor and configure the system.
Line Regulation	Maintains converter amplitude by regulating for variances in the line voltages.
Load Regulation	Maintains converter amplitude over the full range of rated power.
Membrane Keys	Front panel controls are designed for high reliability and immunity from factory dust and oils.
PROFIBUS DP	Via a single bus cable, PROFIBUS links controller or control systems with decentralized field devices (sensors and actuators) on the field level and also enables consistent data exchange with higher ranking communication systems.
Ramp Starting	The starting of the DCX F-DP Power Supply and horn is done at a rate that helps reduce electrical and mechanical stress on the system. The horn start rate may be adjusted for some tough-to-start applications.

Table 2.3 Control Features

Name	Description
Seek	Ensures operation at resonance; minimizes tuning errors; and operates the stack at low amplitude (10%), then provides a means of sensing and storing the resonant operating frequency value.
Start-up Diagnostics	At start-up, the controls test the major internal components.
System Protection	Protects the power supply by providing six levels of protection: voltage, current, phase, temperature, power, and frequency.
Timed Seek	When enabled, will do a Seek once every minute to update horn resonant frequency to memory. This is especially useful when the welding process affects the actual temperature of the horn, causing a resonant frequency shift.
True Watt-meter	The controls on the power supply include a true watt-meter for accurate measurement of power and energy.
User ID and Passcodes	Allows for keeping track of user access to the DCX F-DP Power Supply Web Page Interface.
Web Page Interface	Provides access, via Ethernet connection, to power supply information, diagnostics, and configuration web pages.

2.3.3 The Actuator

The DCX F-DP Power Supply can interface with actuator signals, only when operating in manual mode.

2.3.4 Converter/Booster/Horn Assembly

The Converter

The ultrasonic electrical energy from the power supply is applied to the converter (sometimes called the transducer). This transforms the high frequency electrical oscillations into mechanical vibrations at the same frequency as the electrical oscillations. The heart of the converter is piezoelectric ceramic elements. When subjected to an alternating voltage, these elements alternately expand and contract, resulting in better than 90% conversion of electrical to mechanical energy.

The Booster

Success in ultrasonic assembly depends on the right amplitude of movement at the horn face. Amplitude is a function of horn shape, which is largely determined by the size and form of the parts to be assembled. The booster can be used as a mechanical transformer to increase or decrease the amplitude of vibrations applied to the parts through the horn.

The booster is a resonant half-wave section of aluminum or titanium. It is mounted between the converter and the horn, as part of the ultrasonic stack. It also provides a clamping point for rigid stack mounting.

Boosters are designed to resonate at the same frequency as the converter with which they are used. Boosters are usually mounted at a nodal (minimum vibration) point of axial motion. This minimizes the loss of energy and prevents vibration from being transmitted to the stack supporting structure.

The Horn

The horn is selected or designed for a specific application. Each horn is tuned typically as a half-wave section that applies the necessary force and vibration uniformly to the parts to be assembled. It transfers ultrasonic vibrations from the converter to the workpiece. The horn is mounted to the booster as part of the ultrasonic stack.

Depending on their profile, horns are referred to as stepped, conical, exponential, bar, or catenoidal. The shape of the horn determines the amplitude at the face of the horn. Depending on the application, horns can be made from titanium alloys, aluminum, or steel. Titanium alloys are the best materials for horn fabrication due to their high level of strength and low loss. Aluminum horns are usually chrome- or nickel-plated or hard-coated to reduce wear. Steel horns are for low amplitude requiring hardness, such as ultrasonic insertion applications.

2.4 Controls and Indicators

2.4.1 DCX F-DP Power Supply Front Panel

Figure 2.2 DCX F-DP Power Supply Front Panel Controls and Indicators



 Table 2.4
 DCX F-DP Power Supply Front Panel Controls and Indicators

Reference	Description
	LCD For detailed information refer to Figure 2.3 LCD Description and Table 2.5 LCD Description.
	Up/Down Keys Use to adjust the amplitude of ultrasonic vibrations (10% to 100%). Also used to adjust weld mode parameters, select registers and edit register values.
	Alarm Reset Key
	Use the Reset key to reset alarms.
	When changing system registers, use the Reset key to set a register back to its default value after entering the register and before editing the value.

 Table 2.4
 DCX F-DP Power Supply Front Panel Controls and Indicators

Reference	Description
	Configuration Key Use the Configuration key to change system registers. For information on using the Configuration key to set system registers see 7.5 Configuring the Power Supply Registers.
	Ultrasonics Test Key Use the Test key to perform an ultrasonic test. Test performs a seek and then ramps the amplitude to the current setting.
	PROFIBUS DP Connector Use the PROFIBUS DP Connector to connect the DCX F-DP Power Supply to a master/slave PROFIBUS DP network. For more information, refer to Chapter 5 : Installation and Setup and Chapter 7 : Operation.
	Ethernet Port Use the Ethernet Port to connect to the DCX F-DP Power Supply Web Page Interface.
	Power-On Indicator Lights when the power supply is connected to main power and the power is on.
24V	24 V Indicator Lights when 24 V DC are supplied to the DCX F-DP Power Supply.
SYS COM	PROFIBUS DP Status Indicator Indicate the status of the PROFIBUS DP module. For more information see Chapter 7: Operation.

Figure 2.3 LCD Description

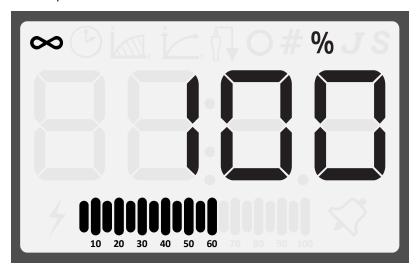


Table 2.5LCD Description

Reference	Description
	Numeric Display
8.8:8.8	Displays the Power Supply amplitude settings, weld time settings, weld energy settings, peak power settings, scrub time settings, register numbers, register values or alarm numbers.
	Continuous Mode Icon
∞	Indicates the power supply is running in Continuous mode. When in Continuous mode, the amplitude setting is shown on the numeric display in conjunction with the % icon. The amplitude setting may range from 10% to 100%. For more information see Chapter 7: Operation .
	Time Mode Icon
(t)	Indicates the power supply is running in Time mode. When in Time mode, the weld time setting is shown on the numeric display in conjunction with the S icon. The weld time setting can range from 10 ms to 30 seconds. For more information see Chapter 7: Operation .
	Energy Mode Icon
P T	Indicates the power supply is running in Energy mode. When in Energy mode, the weld energy setting is shown on the numeric display in conjunction with the J icon. The energy setting may range from 1 Joule to 9999 Joules. For more information see Chapter 7: Operation .

Table 2.5LCD Description

Table 2.5 LCD Description	
Reference	Description
	Peak Power Icon
P _T	Indicates the power supply is running in Peak Power mode. When in Peak Power mode, the peak power percentage is shown on the numeric display in conjunction with the % icon. The peak power setting may range from 1% to 100% of the maximum power supply output power. For more information see Chapter 7: Operation .
	Ground Detect Icon
	Indicates the power supply is running in Ground Detect mode. When in Ground Detect mode, the scrub time setting will be shown on the numeric display in conjunction with the S icon. Scrub time setting may range from 1 millisecond to 500 milliseconds. For more information see Chapter 7: Operation .
	Sonics Active Indicator
4	Indicates ultrasonics is running.
	Time Icon
S	Indicates that the value shown on the numeric display represents time in seconds.
_	Joule Icon
J	Indicates that the value shown on the numeric display represents energy.
	Percentage Icon
%	Indicates that the value shown on the numeric display represents a percentage. When in Peak Power mode, the value shown on the numeric display represents a percentage of the power supply rated power. If not in Peak Power mode, the value shown on the numeric represents the amplitude setting.
	Number Sign Icon
#	Indicates that the value shown on the numeric display is a register number. Use up and down keys to select a register. For more information see <u>7.5 Configuring the Power Supply Registers</u> .

Table 2.5LCD Description

Reference	Description
	Circle Icon Indicates that the value shown on the numeric display is a register value. Use up and down keys to modify the register value. For more information see 7.5 Configuring the Power Supply Registers.
	Alarm Icon A flashing icon which indicates and alarm condition.
	Power/Frequency Bar-Graph
10 20 30 40 50 60 70 80 90 100	Shows the true percentage of ultrasonic power during a weld cycle. The bar-graph can be configured to show the peak power or the memory frequency at the end of each weld or test cycle. For instructions on how to modify this setting see 7.5 Configuring the Power Supply Registers.
	For detailed bar-graph description and bar-graph reading examples, see <u>7.7.1 Power Bar-Graph Interpretation</u> and <u>7.7.2 Frequency Bar-Graph Interpretation</u> .

2.4.2 DCX F-DP Power Supply Connections

Figure 2.4 DCX F-DP Power Supply Back Panel

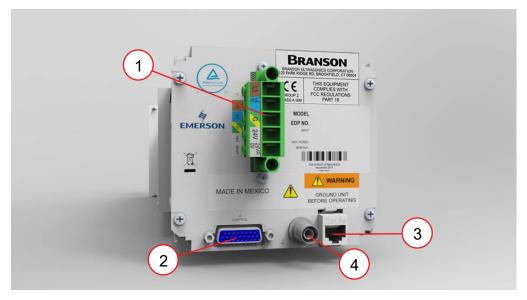


 Table 2.6
 Connections to the DCX F-DP Power Supply

Item	Name	Function
1	Line Input Connector	Detachable connector block for connecting the input power. For wiring details refer to Chapter 5: Installation and Setup .
2	User I/O Connector	Provides the necessary input/output signals to interface with actuators, user automation or control interfaces. For detailed information on interfacing with the DCX F-DP Power Supply refer to Chapter 5 : Installation and Setup .
3	Ethernet Port	Use the Ethernet Port to connect to the DCX F-DP Power Supply Web Page Interface.
4	RF Connector	SHV connector for RF cable, which provides ultrasonic energy to the converter.

2.5 Welding Systems

2.5.1 Principle of Operation

Thermoplastic parts are welded ultrasonically by applying high frequency vibrations to the parts being assembled. The vibrations, through surface and intermolecular friction, produce a sharp rise in temperature at the welding interface.

When the temperature is high enough to melt the plastic, there is a flow of material between the parts. When the vibrations stop, the material solidifies under pressure and a weld results.

2.5.2 Weld System Applications

DCX F-DP Power Supply weld systems can be used for the following applications:

- Ultrasonic welding
- · Cutting and sealing thermoplastic fabric and film
- Staking, spot welding, swaging, and degating thermoplastic parts
- Other ultrasonic processing applications



2.6 Glossary

The following terminology may be encountered when using or operating a DCX F-DP Power Supply ultrasonic welding system:

Table 2.7 Glossary

Name	Description
Actuator	The unit which houses the converter/booster/horn stack assembly in a rigid mounting, allowing the stack to move up and down, either mechanically or pneumatically, applying force to the part at a user-adjustable force and velocity.
Alarm	Visual indication of error.
Amplitude	The peak-to-peak movement at the horn face. Always expressed as a percentage of the maximum.
Amplitude Control	The ability to set amplitude digitally or by an external control.
Booster	A one-half-wavelength-long resonant metal section mounted between the converter and horn, sometimes having a change in cross-sectional area between the input and output surfaces. The booster mechanically alters the amplitude of vibrations received from the converter, and imparts the new amplitude to the horn.
Clamping Force	The pounds or kilograms exerted by the horn onto the workpiece.
Cold Start	Restores the settings of the power supply back to its original condition.
Converter	The device that converts electrical energy into mechanical vibrations at a high frequency (an ultrasonic rate).
Counters	A record of the number of preset cycles recorded in the power supply.
Degating	Removing a molded part from its runner system
Energy Director	A triangular-shaped projection of plastic material which concentrates the ultrasonic energy at the joint interface of a plastic part.
External Amplitude Control	Enables you to access real-time amplitude control directly via the user I/O connector.
External Frequency Control	Enables you to access real-time frequency offset control directly via the user I/O connector.
Fieldbus	Computer network protocols for industrial two way communications used for real-time distributed control.
Fixture	A device for holding a part in position for assembly.
Flash	Material displaced from the joint area.
Forming	Reshaping a section of thermoplastic.
Frequency	The operating frequency of the ultrasonic stack. The frequency stored is measured at the end of the ultrasonic portion of the cycle (when ultrasonics are terminated).

Table 2.7Glossary

Name	Description
Frequency Offset	An offset factor applied to the ultrasonic frequency stored in the power supply.
Fretting Corrosion	A black surface condition, that results from friction between metal parts, that appears on the converter-booster-horn stack mating surfaces.
Gain	The ratio of output to input amplitude of a horn or booster.
Horn	A bar or metal section, usually one half-wavelength-long which transfers vibratory energy to the workpiece.
Horn Amplitude	The peak-to-peak displacement of a horn at its work face.
Horn Signature	A scan to enhance selection of operating frequency and control parameters.
Insertion	The process of embedding a metal component in plastic.
Interface	 The contact surface of two mating parts. The connection between two pieces of equipment.
Joint	The weld surfaces.
Parameter	A unique factor or element which affects the welding operation in a particular mode.
Parameter Range	Valid range of parameters accepted for a particular setup.
Power Supply	The electronic instrument in an ultrasonic assembly system which changes conventional 50/60 Hz electrical power into high frequency electrical power at 20 kHz, 30 kHz or 40 kHz.
Seek	The activation of ultrasonics at a low-level (10%) amplitude, for the purpose of finding the resonant frequency of the stack.
Staking	The process of melting and reforming a plastic stud to mechanically lock a dissimilar material in place.
Swaging	The process of capturing another component of an assembly by melting and reforming a ridge of plastic.
Thermoplastic	A polymer which undergoes a reversible change of state when subjected to heat.
Thermoset	A polymer which undergoes an irreversible change when subjected to heat.
Token	Token is a concept that applies to who can make a change to the preset. If the fieldbus has gotten the token, then only the fieldbus can perform a change. However, if fieldbus has not gotten the token (or has released the token), then the preset can be changed by any other means, for example, via Web Page or front panel controls.
Ultrasonic Power	Presence of ultrasonic power at the horn face.

Table 2.7 Glossary

Name	Description
Ultrasonic Welding	The use of ultrasonic vibrations to generate heat and subsequently melt the mating surfaces of two thermoplastic parts. When ultrasonic vibrations stop, the molten material resolidifies, and a weld occurs.
User ID	A unique 12 character long alphanumeric ID used to keep track of user access to the web page interface.
Weld System	A combination of components required to perform an ultrasonic operation. Usually consists of a power supply, converter, booster, and horn, with either an actuator or a handheld device, or in a fixed, mounted location.

Chapter 3: Delivery and Handling

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3.1 Shipping and Handling

CAUTION	Heavy Object
	The power supply may be heavy. Handling, unpacking, and installation may require the assistance of a colleague or the use of lifting platforms or hoists.

3.1.1 Environmental Specifications

The DCX F-DP Power Supply is an electronic unit that converts line voltage to ultrasonic energy and responds to user input for regulating the weld process. Its internal components are sensitive to static discharge, and many of its components can be harmed if the unit is dropped, shipped under improper conditions, or otherwise mishandled.

The following environmental guidelines should be respected in the shipping of the power supply.

Table 3.1 Shipping Specifications

Environmental Condition	Acceptable Range
Storage / Shipping Temperature	-25° C / -13° F to +55° C / +131° F (+70° C / +158° F for 24 hours)
Shock / Vibration (transit)	45 g shock / 0.5 g and (3 to 100 Hz) vibration per ASTM 3332-88 and 3580-90
Drop Test	ISTA Procedure 1 & 2A (while packaged)
Humidity	Maximum 95%, non-condensing

3.2 Receiving

The DCX F-DP Power Supply is a sensitive electronic device. Many of its components can be harmed if the unit is dropped or otherwise mishandled.

Scope of Delivery

Branson equipment is carefully checked and packed before dispatch. It is recommended, however, that you follow the procedure below upon receiving your DCX F-DP Power Supply.

Inspect the Power Supply when it is delivered, take the following steps

Table 3.2 Inspect the Power Supply

Step	Action
1	Verify that all parts are complete according to the packing slip.
2	Check the packing and the unit for damage (visual inspection).
3	Report any damage claims to your carrier immediately.
4	Determine if any component has become loose during shipping and, if necessary, tighten screws.

NOTICE	
1	If the goods delivered have been damaged during shipping, please contact the forwarding agent immediately. Retain packing material (for possible inspection or for sending back the unit).

3.3 Unpacking the Power Supply

NOTICE	
1	If there are any visible signs of damage to the shipping containers or the product, or you later discover hidden damage, NOTIFY YOUR CARRIER IMMEDIATELY. Save the packing material.

The power supply is fully assembled. It is shipped in a sturdy cardboard box. Some additional items are shipped in the box with the power supply. Note orientation of packaging material in case return/repack is necessary. When unpacking the power supply, take the following steps:

Table 3.3 Unpacking the Power Supply

Step	Action		
1	Unpack the power supply as soon as it arrives. Save the packing material		
2	Verify you have all of the equipment ordered. Some components are packed inside other boxes.		
3	Inspect the controls, indicators, and surface for signs of damage.		
4	Remove the cover of the power supply to check if any components became loose during shipping.		

3.4 Take Inventory of Small Parts

Table 3.4 Small Parts included with the Power Supply Assemblies

Part or Kit	20 kHz	30 kHz	40 kHz
Mylar®* plastic film Washer Kit	X	X	
Silicone Grease			Х
Spanners (2)	Х	X	Х

^{*} Mylar is a registered trademark of DuPont Teijin Films.

3.4.1 Cables

The RF cable connects the power supply to the converter. For automated systems you will also need a user I/O cable to monitor and control the power supply. Check your invoice for cable types and cable lengths.

Table 3.5 DCX F-DP Power Supply System

P/N	Description
100-240-383	Cable, RF 8 ft (2.5 m)
100-240-384	Cable, RF 15 ft (4.5 m)
100-240-385	Cable, RF 25 ft (7.5 m)
100-240-387	Cable, RF right angle 8 ft (2.5 m)
100-240-388	Cable, RF right angle 15 ft (4.5 m)
100-240-389	Cable, RF right angle 25 ft (7.5 m)
100-240-392	Cable, User I/O 25 ft (7.5 m)
100-240-393	Cable, User I/O 50 ft (15 m)
200-240-396	Cable Ethernet Cat 5e 7 ft (2.1 m)

3.5 Returning Equipment

If you are returning equipment to Branson Ultrasonic Corporation, please call your Customer Service Representative to receive approval to return the goods. Refer to $\underline{1.3}$ How to Contact Branson.

Chapter 4: Technical Specifications

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4.3	EU Declaration of Conformity4	3
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4.1 Technical Specifications

NOTICE	
1	All specifications are subject to change without notice.

4.1.1 Environmental Specifications

The DCX F-DP Power Supply has the following environmental specifications:

Table 4.1 Environmental Specifications

Environmental Condition	Acceptable Range
Ambient Operating Temperature	+41° F to +104° F (+5° C to +40° C)
Storage / Shipping Temperature	-13° F to +131° F (-25° C to +55° C)
Operating Altitude	Up to 6560 ft (2000 m)
Humidity	Maximum 95%, non-condensing
IP Rating	2X
Altitude	Up to 3280ft (1000m)
Pollution degree	2
Overvoltage category	II

4.1.2 Electrical Specifications

The following tables list input voltage and current requirements for the DCX F-DP Power Supply.

Electrical Input Operating Voltages

 Table 4.2
 Electrical Input Operating Voltages

Power Supply Rating	Input Operating Voltage
All Models	200 V to 240 V Nominal (180 V Min.* to 253 V Max.), 50 Hz or 60 Hz, Single Phase
	24 VDC, 2.5 A

^{* 200} V Min. for 4 kW units.

Input Current and Fuse Specifications

Table 4.3 Input Current and Fuse Specifications

Model	Power	Current Rating
20 kHz	1250 W	7 A Max. @ 200 - 240 V / 15 A Fuse
	2500 W	14 A Max. @ 200 - 240 V / 15 A Fuse
	4000 W	25 A Max. @ 200 - 240 V / 25 A Fuse
30 kHz	1500 W	10 A Max. @ 200 - 240 V / 15 A Fuse
40 kHz	800 W	5 A Max. @ 200 - 240 V / 15 A Fuse

Continuous Duty Maximum Power

Table 4.4 Continuous Duty Maximum Power

Model	Power	Continuous Duty Max. Power
	1250 W	375 W
20 kHz	2500 W	750 W
	4000 W	1200 W
30 kHz	1500 W	450 W
40 kHz	800 W	240 W

NOTICE	
f	High duty cycles require additional cooling for the converter. For information on converter cooling refer to <u>5.7 Converter Cooling</u> in <u>Chapter 5: Installation and Setup</u> .

NOTICE	
(i)	System average power must be limited to the specified continuous maximum. Duty cycle for each power and frequency is 1 second on and 2.4 seconds off.

Cycle Rate – up to 200 cpm. Cycle rate including off time is application and stack dependent.

4.2 Physical Description

This section describes the physical dimensions of the DCX F-DP Power Supply.

NOTICE	
1	Dimensions are nominal.

Table 4.5 Dimensions and Weight of the DCX F-DP Power Supply

Size	Width	Height	Depth	Weight
Small	4.2" 106 mm	5.07″ 128 mm	22" 560mm	8 lb 3.6 kg
Medium	5.6" 142 mm			12 lb 5.4 kg
Large	8.4" 213 mm			15 lb 6.8 kg

For detailed dimensional information refer to Chapter 5: Installation and Setup.

4.3 EU Declaration of Conformity

Figure 4.1 EU Declaration of Conformity

EU DECLARATION OF CONFORMITY



We, the manufacturer

BRANSON ULTRASONICS CORPORATION

120 Park Ridge Rd. Brookfield, CT 06804 USA

represented in the community by

BRANSON ULTRASONICS, a.s. Piestanska 1202 91501 Nove Mesto nad Vahom Slovak Republic

expressly declare under our sole responsibility that the following electrical equipment product:

Ultrasonic Assembly System consisting of an Ultrasonic Power Supply, model:

```
0.80 DCX(S, A, f-EIP, or f-DP) 40 RACKMT
                                               0.40DCX(s, v, a, f-dp or f-eip)40(VRT, V, H or HOR)
                                               0.80DCX(s, v, a, f-dp or f-eip)40(VRT, V, H or HOR)
1.50 DCX(S, A, f-EIP, or f-DP) 30 RACKMT
                                               0.75DCX(s, v, a, f-dp or f-eip)30(VRT, V, H or HOR)
1.25 DCX(S, A, f-EIP, or f-DP) 20 RACKMT
2.50 DCX(S, A, f-EIP, or f-DP) 20 RACKMT
                                               1.50DCX(s, v, a, f-dp or f-eip)30(VRT, V, H or HOR)
                                               1.25DCX(s, v, a, f-dp or f-eip)20(VRT, V, H or HOR)
4.00 DCX(S, A, f-EIP, or f-DP) 20 RACKMT
DCX RM 222 STD
                                               2.50DCX(S+, s, v, a, f-dp or f-eip)20(VRT, V, H or HOR)
DCX RM 240 STD
                                               4.00DCX(S+, s, v, a, f-dp or f-eip)20(VRT, V, H or HOR)
                                               4.00DCXs20HD -V
DCX RM 222 B
DCX RM 240 B
                                               P/S 0.8 DCX S HD 40 VRT
DCX RM 480 STD
                                              1.50 DCX-S HD 30 HOR
DCX RM 315 STD
                                               1.50 DCX-S HD 30 VRT
DCX RM 211 STD
                                               4.00DCXs20HD -H
DCX RM 480 B
                                               P/S 0.8 DCX S HD 40 HOR
DCX RM 315 B
                                               P/S 4.0KW 20KHZ DCX S LIM RES
DCX RM 211 B
                                              1.6DCX(a, f-dp or f-eip)40(B2H or B2V)
P/S 2.20 DCX STD 20 SIG
```

used with converter model: CR-20S, CR-20C, CH-20C, CS-20S, CS-20C, CR-30, CR-30C, CH-30, CH-30C, CS-30S, CS-30C, CR-40C, 4TH, 4TP or 932, and associated cables.

in the state in which it was placed on the market, fulfills all the relevant provisions and their amendments of:

Low Voltage Directive 2014/35/EU EMC Directive 2014/30/EU RoHS Directive 2011/65/EU

The object of this declaration is in conformity with relevant Union harmonization legislation. The electrical equipment product, to which this declaration relates, is in conformity with the following standards:

EN 61010-1:2010+A1:2019 EN 55011:2016/A11:2020 EN 61000-6-2:2005/AC:2005

Luis Benavides
Luis Benavides (Sep 23, 2024 10:10 CDT)

Brookfield, CT, USA Sr. Engineering Manager / Product Safety Officer

4.4 UK Declaration of Conformity

Figure 4.2 UK Declaration of Conformity



UK DECLARATION OF CONFORMITY

We, the manufacturer

BRANSON ULTRASONICS CORPORATION

120 Park Ridge Rd. Brookfield, CT 06804 USA

expressly declare under our sole responsibility that the following electrical equipment product:

Ultrasonic Assembly System consisting of an Ultrasonic Power Supply, model:

used with converter model: CR-20S, CR-20C, CH-20C, CS-20S, CS-20C, CR-30, CR-30C, CH-30, CH-30C, CS-30S, CS-30C, CR-40C, 4TH, 4TP or 932, and associated cables.

in the state in which it was placed on the market, fulfills all the relevant provisions and their amendments of:

Electrical Equipment (Safety) Regulations 2016
Electromagnetic Compatibility Regulations 2016
Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations 2012.

The electrical equipment product, to which this declaration relates, is in conformity with the following designated standards:

EN 61010-1:2010+A1:2019 EN 55011:2016/A11:2020 EN 61000-6-2:2005/AC:2005

Sr. Engineering Manager / Product Safety Officer

Luis Benavides

Brookfield, CT, USA

4.5 PROFIBUS Certificate

Figure 4.3 PROFIBUS Certificate



Certificate

PROFIBUS Nutzerorganisation e.V. grants to

Branson Ultrasonics Corp. 41 Eagle Road, 06813 Danbury, CT, USA

the Certificate No: **Z02072** for the PROFIBUS Device:

Model Name:

DCX RM AF

Revision:

1; SW/FW: 7; HW: 102-242-105R REV0

GSD:

BRAN0E05.GSD, File Version: 1

This certificate confirms that the product has successfully passed the certification tests with the following scope:

DP-V0 MS0

☐ Physical Layer RS485

Test Report Number:

PB 185-1

Authorized Test Laboratory:

PROFI Interface Center, Johnson City USA

The tests were executed in accordance with the following documents: "Test Specifications for PROFIBUS DP Slaves, Version 3.0, November 2005".

This certificate is granted according to the document:

"Framework for testing and certification of PROFIBUS and PROFINET products".

For all products that are placed in circulation by March 04, 2019 the certificate is valid for life.

(Official in Charge)

Board of PROFIBUS Nutzerorganisation e. V.

(Karsten Schneider)

(K.-P. Lindner)

4.5.1 Terms of use for Trademarks of PROFIBUS & PROFINET International PI

Figure 4.4 Association Trademark



Figure 4.5 Technology Trademarks









Figure 4.6 Certification Trademark



Figure 4.7 Certified by PI Trademark



The Association Trademark, the Technology Trademarks, the Certification Trademark and the Certified by PI Trademark are protected trademarks.

General Terms

The Association Trademark, the Technology Trademarks, the Certification Trademark and the Certified by PI Trademark may only be used in the registered form in the course of business by holders of the right of use.

The Association Trademark, Technology Trademarks, Certification Trademark or the Certified by PI Trademark may not be modified with respect to the registered form or combined with other characteristics than the additions approved by PI.

The granted rights to the Association Trademark, the Technology Trademarks, the Certification Trademark and the Certified by PI Trademark terminate as soon as the necessary conditions for the grant of the rights are no longer satisfied.

Terms of use for Association Trademark (PI Logo)

The right to use the Association Trademark is acquired through membership in one of the Regional PI Associations. Non-members are not granted any rights to use the Association Trademark.

Terms of use for Technology Trademarks (PROFIBUS, PROFINET, PROFIsafe, and PROFIenergy Logo)

The right to use the Technology Trademarks is acquired through membership in one of the Regional PI Associations. Upon request, rights to use the Technology Trademarks may be granted by Regional PI Associations.

Terms of use for Certification Trademark

The Certification Trademark*) serves:

- To identify products that satisfy the test criteria established by PI and for which PI is issuing product certificates
- To identify experts who have passed successfully an official PROFIBUS and/or PROFINET Installer, PROFIBUS and/or PROFINET Engineer or a PROFIsafe Designer course and for which PI is issuing expert certificates in accordance with the "Quality of Services Agreement for PITCs"

The right to use the Certification Trademark related to a product may be issued when the following requirements are met:

- The applicant has the right to use the associated Technology Trademarks
- The applicant possesses a valid certificate from PI for the product

The right to use the Certification Trademark terminates automatically in the event that the product is so modified in any way that it no longer satisfies the established test criteria.

The right to use the Certification Trademark related to an expert may be issued when the following requirements are met:

 The applicant possesses a valid expert certificate from PI for one of the above mentioned official courses

The right to use the Certification Trademark terminates automatically in the event that the applicant has given negative statements to the public about PI and/or its technologies without prior consultation or clarification with PI.

Terms of use for Certified by PI Trademark

The Certified by PI Trademark*) serves to identify PI Competence Centers (PICC), PI Training Centers (PITC) and PI Test Laboratories (PITL) that fulfill the criteria defined by PI ("Quality of Services Agreement for PICCs", "Quality of Services Agreement for PITCs", "Framework for Testing and Certification of PROFIBUS/PROFINET Products" and "How to become and run an accredited PROFIBUS/PROFINET Test Lab").

The right to use the Certified by PI Trademark may be issued only when the applicant is accredited as PICC, PITC or PITL.

The right to use the Certified by PI Trademark terminates automatically in the event that the applicant has given negative statements to the public about PI and/or its technologies without prior consultation or clarification with PI, and when the accreditation as PICC, PITC or PITL has ended.

* The Certification Trademark and the Certified by PI Trademark are not available for free member download. It will be handed out by PI Business Office directly to qualified companies and/or persons.

Chapter 5: Installation and Setup

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5.1 About Installation

This chapter is intended to help the installer with the basic installation and setup of your new DCX F-DP Power Supply.

CAUTION	Heavy Object
	The power supply, and related components are heavy. Handling, unpacking, and installation may require the assistance of a colleague or the use of lifting platforms or hoists.

International safety-related labels are found on the power supply. Those that are of importance during installation of the system are identified in <u>Figure 1.1 Safety-related Labels found on the DCX F-DP Power Supply</u>.

5.2 Installation Requirements

This section covers the location requirements, mounting options, power supply dimensions, environmental requirements, and electrical requirements, to help you plan and execute your installation successfully.

5.2.1 Installing the DCX F-DP Power Supply Drawers in a Customer Rack

The power supply units can be installed in any rack complying with the 19" industrial standard.

For successful installation in a rack, the respective demands on the electric and cooling system have to be met.

- If multiple drawers are to be installed in a rack we recommend to provide three phase power to the rack in order to provide each drawer with a dedicated supply and one phase to each drawer
- Particular care has to be taken that the heat generated during operation is dissipated. The heat generated depends on the power output by the module and the ambient conditions
- The heat sink of the module is mounted on the right. Make sure that the cooling device is mounted in a way allowing the cooling air to pass freely on this side
- For each group of four power supply modules installed one cooling drawer is required. The cooling drawers must be installed directly under the power supplies in order to ensure sufficient cooling
- In case a filter element is used to clean the intake air, regular inspection and cleaning of the filter depending on the ambient conditions is required to maintain the airflow volume
- To prevent thermal overload, the system is protected by thermoswitches which are reset automatically after cooling down

NOTICE	
1	Three 105 CFM fans must be placed directly underneath each unit for cooling.

5.2.2 Location

The power supply should be accessible for parameter changes and settings. The power supply should be located in an area away from radiators or heating vents.

The DCX F-DP Power Supply must not be positioned so that is difficult to plug in or unplug the main power plug.

5.2.3 Dimensions

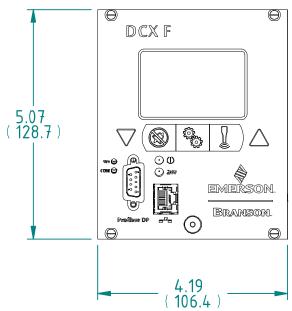
Refer to the illustrations on the pages that follow for dimensional drawings. All dimensions are approximate and may vary slightly:

Figure 5.1 DCX F-DP Power Supply Dimensional Drawing (Small)

Figure 5.2 DCX F-DP Power Supply Dimensional Drawing (Medium)

Figure 5.3 DCX F-DP Power Supply Dimensional Drawing (Large)

Figure 5.1 DCX F-DP Power Supply Dimensional Drawing (Small)



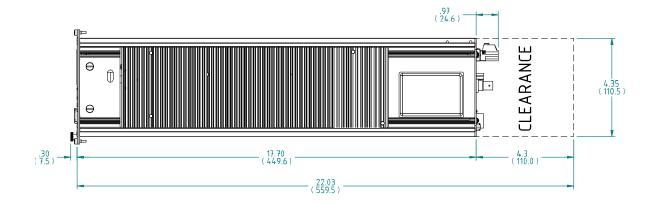
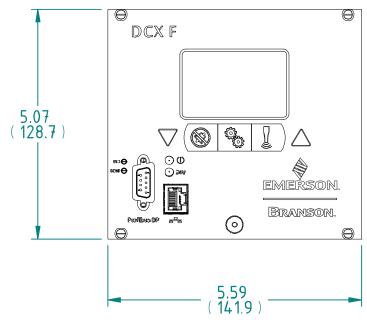


Figure 5.2 DCX F-DP Power Supply Dimensional Drawing (Medium)



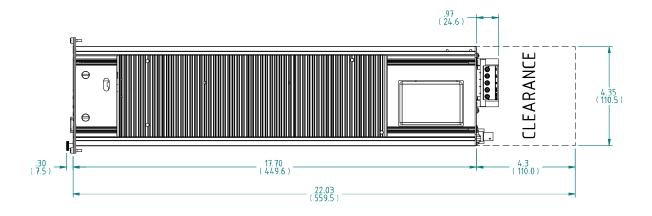
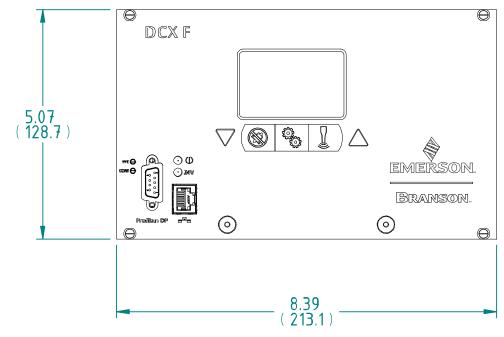
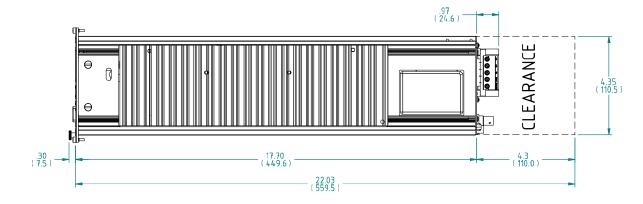


Figure 5.3 DCX F-DP Power Supply Dimensional Drawing (Large)





5.2.4 Environmental Requirements

Verify the DCX F-DP Power Supply is operated in an environment that meets the temperature and humidity requirements indicated in <u>Table 5.1 Environmental Requirements</u>.

Table 5.1 Environmental Requirements

Environmental Condition	Acceptable Range
Ambient Operating Temperature	+41° F to +104° F (+5° C to +40° C)
Storage / Shipping Temperature	-13° F to +131° F (-25° C to +55° C)
Operating Altitude	Up to 6560 ft (2000 m)
Humidity	Maximum 95%, non-condensing
IP Rating	2X
Altitude	Up to 3280ft (1000m)
Pollution degree	2
Overvoltage category	II

5.2.5 Electrical Input Power Ratings

Connect the power supply to a single-phase, grounded, 3-wire, 50 Hz or 60 Hz 200 V to 240 V power source. <u>Table 5.2 Input Current and Circuit Breaker Specifications</u> lists the current and breaker ratings for the various models.

 Table 5.2
 Input Current and Circuit Breaker Specifications

Model	Power	Current Rating
	1250 W	7 A Max. @ 200 - 240 V / 15 A Breaker
20 kHz	2500 W	14 A Max. @ 200 - 240 V / 15 A Breaker
	4000 W	25 A Max. @ 200 - 240 V / 25 A Breaker
30 kHz	1500 W	10 A Max. @ 200 - 240 V / 15 A Breaker
40 kHz	800 W	5 A Max. @ 200 - 240 V / 10 A Breaker

5.2.6 Pneumatic Requirements

Your welding system may require a cooling air stream for the converters. In continuous operations, or applications with longer duty cycles, it may be necessary to cool the horn as well as the converter.

Typically 80 cubic feet (2.26 m³) per hour of clean, dry, compressed air are required to cool most welding operations.

To verify the 80 cubic feet (2.26 m³) per hour cooling air stream required for your welding system, refer to 5.7 Converter Cooling.

5.3 Installation Steps

WARNING	High Voltage Hazard		
	To prevent the possibility of an electrical shock:		
4	Ensure the power source is disconnected before beginning work on line connections		
	Always plug the power supply into a grounded power source		
	To prevent the possibility of an electrical shock, ground the power supply by securing an 8 gauge grounded conductor to the ground screw located next to the air outlet		
	Ensure power supply installation is performed by qualified personnel and in accordance with local standards and regulations		

All persons who are involved with installation, commissioning, operation and maintenance must have the required qualification, strictly follow this operating manual.

Basic installation notes:

- To avoid problems associated with EMI, you should route high power lines (AC and Ultrasonic RF) away from low power lines (controls signals)
- You should consider future troubleshooting and repair when installing all wiring. All wiring should be either color coded or tagged with industrial wire tags
- The minimum cable bend radius is 5 times the cable outer diameter for RF cables
- The minimum cable bend radius is 10 times the cable outer diameter for user I/O & Ethernet cables
- Ground wires should not be shared with other equipment
- All inductive coils must be suppressed with appropriate devices, such as diodes or RC networks

5.3.1 Mount the Power Supply

The cable lengths are limited based on the operating frequency of the welding system. Performance and results can suffer if the RF cable is crushed, pinched, damaged or modified. Contact your Branson Representative if you have special cable requirements.

Do not place the power supply on the floor or in other locations that will allow dust, dirt or contaminants to be drawn into the power supply.

NOTICE	
1	Do not block exhaust and intake air circulation, which is needed to maintain a safe operating temperature.

5.3.2 Mounting Considerations

In addition to the considerations mentioned above, the LCD's viewing angle should be taken into account when selecting a location for your DCX F-DP Power Supply. The LCD is designed to be viewed from the top. Please refer to Figure 5.4 LCD Viewing Angle below when selecting a location for your DCX F-DP Power Supply.

Figure 5.4 LCD Viewing Angle



NOTICE	
1	Optimal viewing angle is 25° above the normal to the display (indicated by 0°).

5.3.3 Electrical Connections

Figure 5.5 DCX F-DP Power Supply Connections

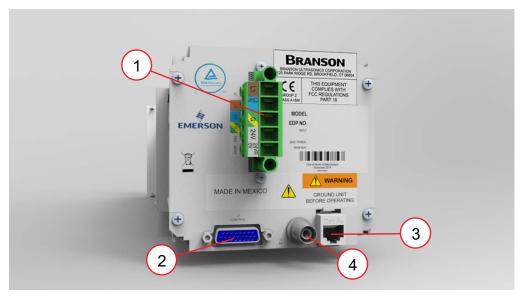


 Table 5.3
 DCX F-DP Power Supply Connections

Item	Name
1	Line Input Connector
2	User I/O Connector
3	Ethernet Port
4	RF Connector

5.4 User I/O

5.4.1 User I/O Connections

NOTICE	
1	User I/O interface is only available in manual mode.

The user I/O is a standard interface for automation, provided on the power supply. It provides the ability to make your own interface for your automation, actuator interface, special control, or reporting needs. The interface cable has a 26-pin HD male D-Sub connector on one end, and wires on the other end. Pins are wired to ICEA standard color code (see Figure 5.6 User I/O Cable Identification and Wire Color Diagram and Table 5.5 User I/O Cable Pin Assignments).

NOTICE	
f	Ensure all unused wires are properly isolated. Failure to do so may result in a power supply malfunction.

Digital I/O functions can be configured to either active-high or active-low using the DCX F-DP Power Supply Web Page Interface. <u>Table 5.7 Digital Input Functions</u> to <u>Table 5.10 Analog Output Functions</u> list the input and output functions available on the DCX F-DP Power Supply. See <u>Table 5.6 Default Branson User I/O Connector Pin Assignments</u> for the default user I/O pin assignments.

<u>Figure 5.7 Typical Digital I/O Wiring Examples</u> and <u>Figure 5.8 Typical Analog I/O Wiring Examples</u> show typical wiring examples.

Figure 5.6 User I/O Cable Identification and Wire Color Diagram

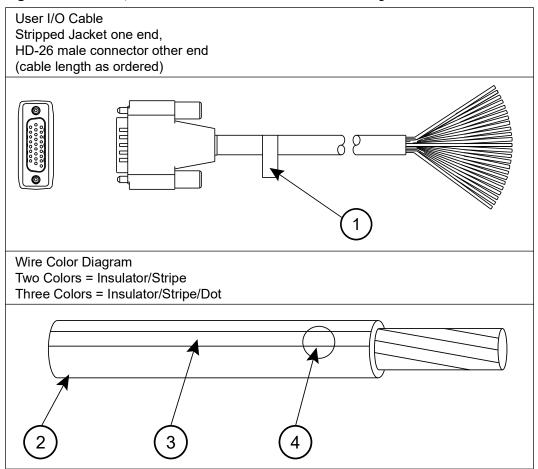


Table 5.4 User I/O Cable Identification and Wire Color Diagram

Item	Description		
1	Part number		
2	Insulation		
3	Stripe		
4	Dot		



5.4.2 User I/O Cable Pin Assignments

Table 5.5 User I/O Cable Pin Assignments

Pin	Input/ Output	Available Function	Signal Type	Signal Range	Color
1	Digital in 1		Digital Input		Blk
2	Digital in 2	See <u>Table 5.7 Digital</u>		0V to 24V	Wht
3	Digital in 3	Input Functions		±10%, 12mA	Red
4	Digital in 4				Grn
5	+24V	N/A	24V	24V ±10%,	Orn
6	+240	IN/A	Source	250mA Max	Blu
7	Digital out 1				Wht/Blk
8	Digital out 2	See <u>Table 5.8 Digital</u>	Digital	0V to 24V, ±10%,	Red/Blk
9	Digital out 3	Output Functions	Output	25mA Max	Grn/Blk
10	Digital out 4				Orn/Blk
11	Digital in 5			0V to 24V	Blu/Blk
12	Digital in 6		Digital Input	±10%, 12mA	Blk/Wht
13	Digital in 7				Red/Wht
14	14 15 Ground	N/A	24V Ground	0V	Grn/Wht
15					Blu/Wht
16	Digital in 8	See <u>Table 5.7 Digital</u> <u>Input Functions</u>	Digital Input	0V to 24V ±10%, 12mA	Blk/Red
17	Analog in 1	See <u>Table 5.9 Analog</u>	Analog 0V to +10	0V to +10V,	Wht/Red
18	Analog in 2	Input Functions	Input	2mA	Orn/Red
19	Digital out 5				Blu/Red
20	Digital out 6	See <u>Table 5.8 Digital</u>	Digital	0V to 24V ±10%, 12mA Max	Red/Grn
21	Digital out 7	Output Functions	Output		Orn/Grn
22	Digital out 8				Blk/Wht/Red
23	Digital in 9	See <u>Table 5.7 Digital</u> <u>Input Functions</u>	Digital Input	0V to 24V ±10%, 12mA	Wht/Blk/Red
24	Analog out 1	See Table 5.10	Analog	0V to 10V	Red/Blk/Wht
25	Analog out 2	Analog Output Functions	Output	±5%, 1mA Max	Grn/Blk/Wht
26	Analog Ground	N/A	Analog Ground	0V	Orn/Blk/Wht



5.4.3 Default Branson User I/O Connector Pin Assignments

Table 5.6Default Branson User I/O Connector Pin Assignments

Pin	Input/Output	Signal Type	Signal Description		
			Apply +24VDC to run cycle		
1	STD-External Start		Power supply must be in ready mode before External Start		
		Digital Input	NOTICE Signal must be held for 10ms minimum		
2	STD-External Seek		Apply +24VDC to perform a seek		
3	STD-External Reset		Apply +24VDC to reset alarm		
4	STD-Memory Clear		Apply +24VDC to clear memory		
5	+24VDC Source	I/O Signal	124V 250mA May		
6	+24VDC Source	Source	+24V, 250mA Max		
7	STD-Ready		+24V indicates the system is ready		
8	STD-Sonics Active		+24V indicates ultrasonics are active		
9	STD-General Alarm	Digital Output	+24V indicates an alarm occurred		
10	STD-Seek/Scan Out		+24V indicates either Seek or a Scan is in progress		
11	STD-Recall Preset 1		Bit 0 for preset recall binary code		
12	STD-Recall Preset 2	Digital Input	Bit 1 for preset recall binary code		
13	ACT-Ground Detect		Apply +24 VDC to activate ground detect		
14	+24VDC Return and	I/O Signal	Return for all pins except pins 17, 18,		
15	I/O Return	Return	24, and 25		
16	ACT-Cycle Abort	Digital Input	Apply +24 VDC to abort cycle		
17	Amplitude In	A la - Tarant	+1V to +10V (10% to 100%)*		
18	Frequency Offset	Analog Input	+1V to +9V (5V is zero offset)		
19	STD-Confirm Preset Change		+24V indicates a load new preset request has occurred and the preset was successfully recalled		
20	STD-Overload Alarm	Digital Output	+24V indicates an overload alarm occurred		
21	STD-Plus Peak Power Limit Alarm		+24 V indicates a +peak power limit alarm occurred		
22	STD-Minus Peak Power Limit Alarm		+24V indicates a -peak power limit alarm occurred		

 Table 5.6
 Default Branson User I/O Connector Pin Assignments

Pin	Input/Output	Signal Type	Signal Description	
23	STD-Display Lock	Digital Input	Apply +24 VDC to lock the display	
24	Power Out	Analog	0V to +10V (0% to 100%)	
25	Amplitude Out	Output	0V to +10V (0% to 100%)	
26	Analog Signal Return	Analog Signal Return	Return for pins 17, 18, 24, and 25	

^{*}If the input signals are not within their valid range, or if left unconnected, the power supply will use 50% amplitude and zero frequency offset, respectively.



5.4.4 Digital Input Functions

Table 5.7Digital Input Functions

Function	Description		
ACT-Actuator Present	Must be active at power up to activate TRS, ULS, Interlock, Part in Place.		
ACT-Cycle Abort	Will immediately terminate the current weld cycle and not accept another External Start until removed. Reset required is user settable.		
ACT-Ground Detect	Will start scrub time. When scrub time expires, ultrasonics will be turned off.		
ACT-Interlock In Place	Prevents a cycle from starting until the signal becomes active.		
ACT-Part In Place	When enabled, signal must be active before weld cycle is started.		
ACT-Trigger Switch (TRS)	Indicates the power supply to start ultrasonics.		
ACT-Upperlimit Switch (ULS)	Tells the power supply that the actuator is at home position.		
RF-Feedback A, B, C, D	Indicates which relay the RF switch has changed to. Bit 0 to bit 3 are binary coded values indicating the selected RF switch. It can also be uncoded. This function is user settable.		
RF-Status Feedback	Indicates the RF switch has changed to the proper relay. NOTICE Single value. Not coded/uncoded like RF-Feedback A, B, C, D.		
STD-Cable Detect	When enabled 24 volts must be present on pin at all times. If 24 volts is removed, suggesting that the cable has been removed, ultrasonics will not be allowed to run and will stop if already running.		
STD-Display Lock	Locks the front panel display controls. Registers are read only when signal is active.		
STD-External Amp Step Trigger	When set to +24 V sets amplitude to Amplitude 2. If set again to 0 during a weld cycle will set amplitude back to Amplitude 1. Used onl if amplitude stepping is turned on and set to external input.		
STD-External Horn Scan	Starts horn scan. Signal must be maintained during the scan.		
STD-External Reset	Resets alarm conditions.		
STD-External Seek	Activates ultrasonic energy at 10% amplitude for the purpose of finding the ultrasonic stack resonant frequency.		

Table 5.7 Digital Input Functions

Function	Description			
STD-External Sonics Delay	Delays the start of ultrasonics even if a trigger occurs. This can be used to enable an external operation to be complete before continuing the cycle (e. g. test device or part marking operation). If the delay is maintained for 1 minute, the cycle is aborted and all inputs must be cycled again.			
	Activates ultrasonic energy at the currently set amplitude.			
STD-External	DCX F-DP Power Supply must be in ready mode before External Start.			
Start	WARNING When using 0 V to activate ultrasonics (External Start signal), it is recommended to assign one input as Cable Detect to prevent sonics from activating if 24 V is lost by accident.			
STD-External Test	Performs a test cycle. Signal must be maintained.			
STD-Load New Preset	Loads a weld preset as defined by Recall Preset Bits 1-32.			
STD-Memory Clear	Centers the power supply start frequency.			
STD-Recall Preset 1, 2, 4, 8, 16, 32	Bit 0 to bit 5 for preset recall binary code. This code will be used recall a preset when Load Preset input is activated.			
Prevents ultrasonics from coming on. If active throughout a cycle, the cycle will be performed but without ultrasonics. She weld mode be time indeterminate (energy, power, etc) then time will extend to the cutoff time.				
STD-Start Cycle	Starts a cycle.			



5.4.5 Digital Output Functions

Table 5.8Digital Output Functions

Function	Description	
ACT-Actuator Home	Indicates that a ULS input has been received.	
ACT-Afterburst Delay	Indicates if the weld cycle is in the Afterburst Delay state.	
ACT-Afterburst Time	Indicates if the weld cycle is in the Afterburst state.	
ACT-End of Hold Time	Indicates the system has reached the end of Hold since the cycle started.	
ACT-Holdtime	Indicates if the weld cycle is in the Hold Time state.	
RF-Select A-D	Output to select stacks 1 to 4 or a binary coded value (bit 0-3) to select RF relay.	
STD-Amp1 Amp2	If output is 0 V, indicates the amplitude setting is Amplitude 1. If output is 24 V, indicates the amplitude setting is Amplitude 2.	
STD-Confirm Preset Change	Output will go active when a preset has been recalled.	
STD-Custom Alarm	Indicates a Custom Alarm has occurred. This function is user defined.	
STD-Cycle Okay	Output will go inactive with cycle start input, and will go high at the end of the cycle if no alarms occurred.	
STD-Cycle Start Out	Indicates start signal is active. It will stay active through weld time and hold time.	
STD-General Alarm	Indicates an alarm occurred. This function is user configurable.	
STD-Minus Energy Limit Alarm	Indicates the weld did not reach the minimum energy set.	
STD-Minus Time Limit Alarm	Indicates the weld time has not reached the minimum time set.	
STD-Minus Peakpower Limit Alarm	Indicates the weld has not reached the minimum peak power set.	
STD-Overload Alarm	Indicates an overload alarm has occurred.	
STD-Plus Energy Limit Alarm	Indicates the weld has exceeded the maximum energy set.	

Table 5.8Digital Output Functions

Function	Description			
STD-Plus Time Limit Alarm	Indicates the weld time did exceed the maximum time set.			
STD-Plus Peakpower Limit Alarm	Indicates the weld has exceeded the maximum peak power set.			
STD-Ready	If active, indicates the system is ready to start a weld cycle, enter test mode, or start a horn scan. If inactive, it indicates the system is already cycling, in test mode, performing a horn scan, or has a reset-required alarm.			
STD-Seek/Scan Out	Indicates either a seek or a horn scan is in progress.			
STD-Sonics Active	Indicates sonics are active.			
STD-Start Signal Release	If output is active, it indicates the start signal can be removed. If output is inactive, it indicates start signal is either inactive or that it cannot yet be removed.			
STD-Status	To be used to drive an external beeper. Single 0.5 second beeps will occur when trigger is received. Three Beeps indicate an alarm occurred (e.g. overload alarm). Beeps 0.5 seconds on, 0.5 seconds off long are in between each beep.			
STD-Weldcycle Complete	Indicates if a weld cycle is no longer in process.			



5.4.6 Analog Input Functions

Table 5.9 Analog Input Functions

Function	Desci	Valid Range		
Amplitude In	Controls the amplitude energy that will be de	1 V to 10 V*		
7 WT PREGGE 111	supply.	(10% to 100%)		
Custom Input 1 2	Define an analog volt to create a cutoff.	0 V to 10 V		
Custom Input 1, 2	Voltage must be excelled cutoff.			
	Controls the frequency offset to the power supply operating frequency. Actual offset depends on the power supply operating frequency:			
Frequency Offset	Frequency	Offset Range	1 V to 9 V* (5 V is zero offset)	
	20 kHz	+/- 400 Hz	(3 1 13 2010 011300)	
	30 kHz	+/- 600 Hz		
	40 kHz +/- 800 Hz			

 $^{^{\}ast}$ If the input signals are not within their valid range, or if left unconnected, the power supply will use 50% amplitude and zero frequency offset, respectively.

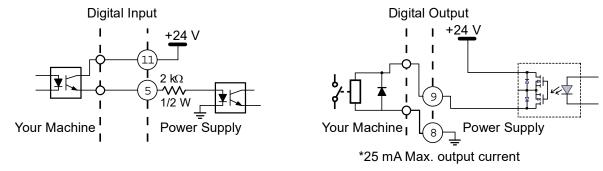
5.4.7 Analog Output Functions

 Table 5.10
 Analog Output Functions

Function		Valid Range		
Amplitude Out	Provides a 0 V to amplitude (0	0 V to 10 V (0% to 100%)		
Power Out	Provides a 0 V to ultrasonic po	0 V to 10 V (0% to 100%)		
Frequency Out	Provides a 0 V memory plus o the power supp			
	Frequency	Lower Limit (0 V)	Upper Limit (10 V)	0 V to 10 V (5 V is zero offset)
	20 kHz	19,450 Hz	20,450 Hz	
	30 kHz	29,250 Hz	30,750 Hz	
	40 kHz	38,900 Hz	40,900 Hz	

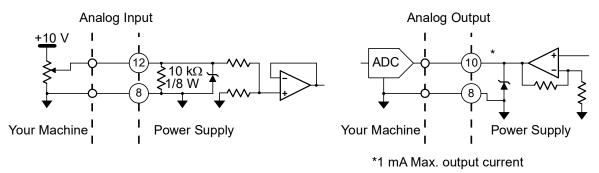
5.4.8 Typical Digital I/O Wiring Examples

Figure 5.7 Typical Digital I/O Wiring Examples



5.4.9 Typical Analog I/O Wiring Examples

Figure 5.8 Typical Analog I/O Wiring Examples



5.4.10 Output Power (RF Cable) Connection

Ultrasonic energy is delivered to the SHV connector on the power supply, which is then transmitted to the converter via the RF cable. The RF connector position depends on the power supply configuration. For Horizontal models it is located on the rear panel of the power supply. For Vertical models it is located on the bottom panel of the power supply.

To reduce electromagnetic interference (EMI), RF cables are equipped with a ferrite core (plastic case) on one end. This end is meant to be connected to the power supply.

WARNING	High Voltage Hazard
4	Operating the System with the RF Cable disconnected or damaged can present an electrical shock hazard.

WARNING	High Voltage Hazard
4	To avoid the possibility of electrical shock, converters need to be properly grounded.

NOTICE	
1	To avoid the possibility of EMI, ensure the RF connection to the power supply is made with the cable end that has the ferrite core box attached (see Figure 5.9 RF Cable Connection).

Figure 5.9 RF Cable Connection

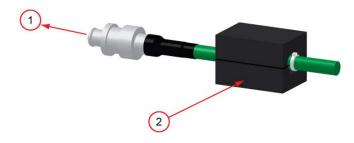


Table 5.11 RF Cable Connection

Item	Description
1	To Power Supply
2	Ferrite Core Box

5.4.11 Input Power Connection

WARNING	High Voltage Hazard
4	Ensure all electrical power is off when wiring input power to your DCX F-DP Power Supply connector block. To prevent the possibility of an electrical shock, ground the power supply by securing an 8 gauge grounded conductor to the ground
	screw located next to the air outlet.

WARNING	High Voltage Hazard
4	If miss-wired, the power supply can present an electrical shock hazard.

NOTICE	
1	The power supply can be permanently damaged if it is connected to the incorrect line voltage, or if the connection is mis-wired.

Use the following procedure to connect the power supply to a 24 VDC 2.5A external power supply and to a single-phase, grounded 3-wire, 50 Hz or 60 Hz 200 V to 230 V power source. The 24 VDC power supply must be safety certified and agency approved.

Table 5.12 Input Power Connection

Step	Action
1	Detach the connector block on the back of the power supply.
2	Use two properly sized wires (according to local standards) to connect a 24 VDC 2.5A power supply as shown on Figure 5.5 DCX F-DP Power Supply Connections.
3	Use three properly sized wires (AWG #12, 2.5 mm or according to local standards) to connect the line 1, line 2, and ground to the connector block as shown on Figure 5.5 DCX F-DP Power Supply Connections. Choose wires according to the current rating as specified in Table 5.2 Input Current and Circuit Breaker Specifications and on the label located on the back of the unit. Be sure to use agency approved wiring and use sleeving or tubing on each wire for double insulation.
4	Secure an AWG #12 grounded conductor to the ground screw located next to the air outlet.



 Table 5.12
 Input Power Connection

Step	Action
5	Connect the converter-booster-horn stack to the power supply using the RF cable. See <u>5.4.10 Output Power (RF Cable) Connection</u> .
6	Ensure the power of the unit is disconnected. Plug the connector block back into the power supply. Tighten the two securing screws.
7	Connect the power supply to a single-phase, grounded, 3-wire, 50 Hz or 60 Hz 200 V to 230 V power source.

5.5 Power Supply Setup

Certain power supply configurations can be modified from the factory setting if needed. Although not usually requiring modifications from the factory setting, the following features are selectable:

Table 5.13 Power Supply Features

Name	Description
Afterburst	Allows for a short activation of ultrasonics at the end of the weld cycle to reliably release parts from the horn.
Cutoffs	Allows for setting parameter values for immediately terminating a weld cycle: Time (S); Energy (J); Peak Power (%); Frequency Low (Hz); Frequency High (Hz); Custom Input1 (V); and Custom Input2 (v).
End of Weld Store	Provides an option for selecting if the stack frequency is stored at the end of each weld cycle.
Energy Brake	Allows the user to set the power supply to reduce the amplitude before the sonics are shut off.
Frequency Offset	Allows for varying the start frequency by way of external controls (analog signal applied though the user I/O analog input) or setting a fixed value using the web page interface. This is useful for certain applications, where the force applied on the fixture or anvil causes a frequency shift in the stack's operation.
Limits	Allows for setting up limits within a weld mode: +/- Continuous; +/- Time (s); +/- Energy (J); or +/- Peak Power (%).
Mode	Allows for selecting the weld mode from the different available options: Continuous; Time (s); Energy (J); Peak Power (%); and Ground detect.
Power Up	Allows an option to configure the power supply to perform a seek on power up; a horn scan on power up; or to perform no action at power up.
Seek Ramp	Provides a selection for different power supply seek ramp times.
Seek Time	Provides an option for selecting seek duration.
Start Ramp	Provides a selection for different start ramp times. This controls how fast the amplitude of the horn rises from 0 to 100. Long ramp times may be useful when using large horns or high gain stacks.
Timed Seek	Provides an option for monitoring, and storing the operating frequency at timed intervals (60 seconds). Periodic frequency seeks may be helpful when welder is not used for long periods of time. Seeks are timed from the moment sonics was last activated.
Weld Amplitude	Allows for varying the amplitude (10% to 100%) using the front panel LCD, the web page interface, or by way of external controls (analog signal applied though the user I/O analog input). Via the web page interface scrub amplitude, afterburst amplitude, and amplitude stepping options may also be configured.

For instruction on how to change the power supply settings refer to <u>7.5 Configuring the Power Supply Registers</u> in <u>Chapter 7</u>: <u>Operation</u>.

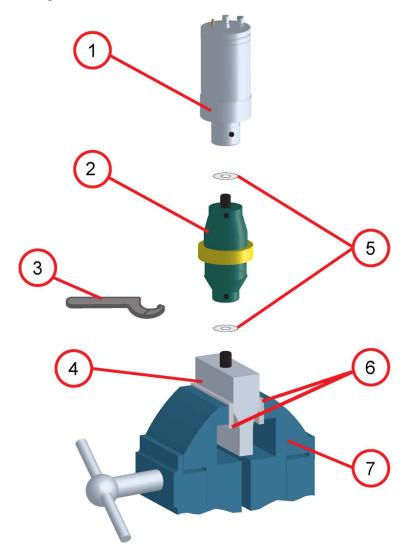
5.6 Assembling the Acoustic Stack

CAUTION	General Warning
<u> </u>	The following procedure must be performed by a trained operator. If necessary, secure the largest portion of a square or rectangular horn in a soft jawed vise. NEVER attempt to assemble or remove a horn by holding the converter housing or the booster clamp ring in a vise.

CAUTION	General Warning
<u>^</u>	Do not use silicone grease with Mylar plastic film washers. Use only 1 (one) Mylar plastic film washer of the correct inside and outside diameters at each interface.

NOTICE	
6	The use of a Branson torque wrench or the equivalent is recommended. P/N 101-063-787 for 20 kHz, and 30 kHz systems and 101-063-618 for 40 kHz systems.

Figure 5.10 Assembling the Acoustic Stack



Acoustic Stack Description

Table 5.14 Acoustic Stack Description

Item	Description	
1	Converter	
2	Booster	
3	Spanner (provided)	
4	Horn	
5	See stack assembly procedure	
6	Vise Jaw protectors (aluminum or soft metal)	
7	Vise	

Stack Torque Values

Table 5.15 Stack Torque Values

Frequency	Torque
20 kHz	220 in·lb (24.85 N·m)
30 kHz	185 in·lb (21 N·m)
40 kHz	95 in·lb (10.73 N·m)

Tools

Table 5.16 Tools

Tool	EDP Number
20 kHz, and 30 kHz Torque Wrench Kit	101-063-787
40 kHz Torque Wrench	101-063-618
20 kHz Spanner Wrench	101-118-039
30 kHz Spanner Wrench	201-118-033
40 kHz Spanner Wrench	201-118-024
Silicone Grease	101-053-002
Mylar Plastic Film Washers (20 kHz)	100-063-357
Mylar Plastic Film Washers (30 kHz)	100-063-632

5.6.1 For a 20 kHz System

Table 5.17 20 kHz System

Step	Action
1	Ensure that the mating surfaces of the converter, booster, and horn are clean, and that the threaded holes are free of foreign material.
2	Install a single Mylar plastic film washer (matching the size of the washer to the stud) to each interface.
3	Assemble the converter to the booster and the booster to the horn.
4	Torque to 220 in·lb (24.85 N·m) at each interface.

5.6.2 For a 30 kHz System

Table 5.18 30 kHz System

Step	Action
1	Ensure that the mating surfaces of the converter, booster, and horn are clean, and that the threaded holes are free of foreign material.
2	Install a single Mylar plastic film washer (matching the size of the washer to the stud) to each interface.
3	Assemble the converter to the booster and the booster to the horn.
4	Torque to 185 in·lb (21 N·m) at each interface.

5.6.3 For a 40 kHz System

Table 5.19 40 kHz System

Step	Action
1	Ensure that the mating surfaces of the converter, booster, and horn are clean, and that the threaded holes are free of foreign material.
2	Coat each interface surface with a thin film of silicon grease - but do not apply silicon grease to a threaded stud or tip.
3	Assemble the converter to the booster and the booster to the horn.
4	Torque to 95 in·lb (10.73 N·m) at each interface.

5.6.4 Connecting Tip to Horn

- 1. Ensure that the mating surfaces of the tip and horn are clean. Remove any foreign matter from the threaded stud and hole.
- 2. Hand assemble the tip to the horn. Assemble dry. Do not use any silicone grease.
- 3. Use the spanner wrench and an open-end wrench (refer to <u>Figure 5.11 Connecting Tip to Horn</u>) and tighten to the following torque tip specifications:

Figure 5.11 Connecting Tip to Horn

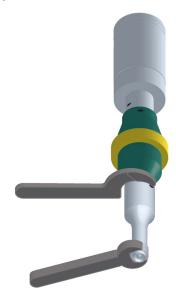


Table 5.20 Tip to horn torque values

Tip Thread	Torque
1/4 - 28	110 in·lbs (12.42 N·m)
3/8 - 24	180 in·lbs (20.33 N·m)

5.7 Converter Cooling

Converter performance and reliability can be adversely affected if the converter ceramics are subjected to temperatures above 140° F (60° C). The converter front driver temperature should not exceed 122° F (50° C).

To prolong converter life and maintain a high degree of system reliability, the converter should be cooled with clean, dry, compressed air, particularly if your application calls for continuous ultrasonic operation. Converter cooling is especially critical in 40 kHz applications.

Use one of the following procedures to determine if a converter is operating close to the maximum allowable temperature. Check converter temperature immediately after substantial machine operation and without power applied to the horn.

- Press a pyrometer probe (or similar temperature measuring device) against the front driver of the converter assembly. Wait for the probe to reach the temperature of the shell. If the temperature is 120° F (49° C) or higher, the converter requires a cooling air stream
- If a temperature measuring device is unavailable, use your hand to feel the shell of the converter. If the converter is hot to touch, the converter requires a cooling air stream

High duty cycles require additional cooling for the converter. System average power must be limited to the specified continuous maximum. Higher peak power, up to the maximum acceptable power limit, with an on time of up to 10 seconds may be obtained, if appropriate off time ensures that, on average, the continuous duty maximum power is not exceeded.

Table 5.21 Continuous Duty Max. Power & Full Power Duty Cycle

Configuration	Continuous Duty Max. Power	Full Power Duty Cycle
20 kHz / 1250 W	375 W	1 s on 2.4 s off (30% Duty Cycle)
20 kHz / 2500 W	750 W	1 s on 2.4 s off (30% Duty Cycle)
20 kHz / 4000 W	1200 W	1 s on 2.4 s off (30% Duty Cycle)
30 kHz / 1500 W	450 W	1 s on 2.4 s off (30% Duty Cycle)
40 kHz / 800 W	240 W	1 s on 2.4 s off (30% Duty Cycle)



If converter cooling is required, use the following steps:

Table 5.22 Converter Cooling Procedure

Step	Action	
1	Start with a 50 psi (345 kPa) air source or higher from a 0.06 in (1.5 mm) I.D. orifice	
2	Perform a run of welding operations.	
3	Immediately after completing the welding run, check the converter temperature.	
4	If the converter is still too hot, increase the diameter of the orifice in small increments until the temperature falls within the ranges in the chart.	

A 0.06 in (1.5 mm) orifice at 50 psi (345 kPa) will result in a reading of 80 $\rm ft^3$ (2.26 $\rm m^3$) per hour. This should be sufficient to cool most operations requiring a cooling air stream. In continuous welding operations, or applications with longer duty cycles, it may be necessary to cool the horn as well as the converter. Horns may require cooling because of the heat transfer from contacting the work piece.

5.8 Testing the Installation

To test the power supply follow the procedure described in $\underline{7.8~\text{Ultrasonics Test Procedure}}$ in $\underline{\text{Chapter 7: Operation}}$.



5.9 Still Need Help?

Branson is pleased that you chose our product and we are here for you! If you need parts or technical assistance with your DCX F-DP Power Supply system, call your local Branson representative. Please refer to <u>1.3 How to Contact Branson</u> for a list of Branson key contacts.

Chapter 6: Converters and Boosters

6.1 Converters and Boosters	. 8	8	ſ	ĺ
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6.1 Converters and Boosters

A variety of converters and boosters available for use with the DCX F-DP Power Supply are illustrated in the following pages.

WARNING	High Voltage Hazard
4	To avoid the possibility of electrical shock, converters need to be properly grounded.

Figure 6.1 20 kHz typical Converter Dimensions

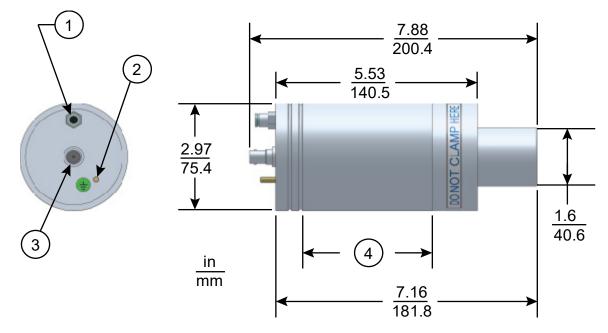


Table 6.1 20 kHz Converter

Item	Description
1	Air inlet
2	Ground stud
3	SHV connector
4	Grip area

Figure 6.2 20 kHz Booster Dimensions

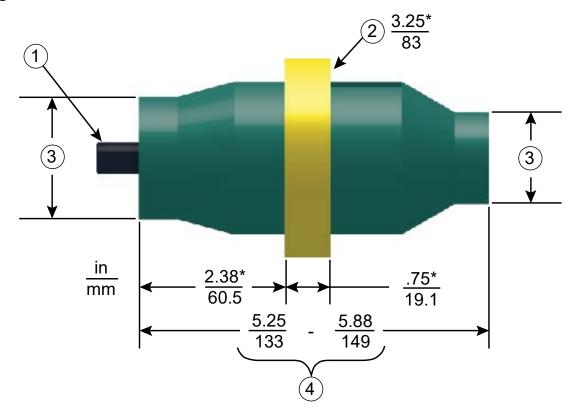


Table 6.2 20 kHz Booster

Item	Description
1	1/2 - 20 x 1 - 1/4 stud (Ti boosters)
	1/2 - 20 x 1 - 1/2 stud (Al boosters)
2	Grip Ring Diameter
3	Variable
4	Varies with tuning and gain

* These dimensions do not vary.

Figure 6.3 20 kHz Converter/Booster/Horn, Typical Dimensions

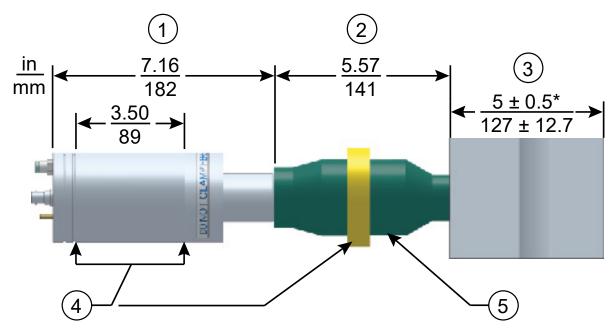


Table 6.3 20 kHz Converter/Booster/Horn

Item	Description
1	Converter
2	Booster
3	One-half wavelength horn
4	Recommended clamping area
5	Booster front end diameter will vary with amplitude

^{*} Overall horn length can vary beyond these typical dimensions depending on the application.

Figure 6.4 30 kHz Converter Dimensions

Table 6.4 30 kHz Converter

CH-30S

Item	Description
1	Air inlet
2	SHV connector
3	Ground stud
4	Grip area

CR-30S and CH-30S are dimensionally identical, and differ only in their respective cooling feature.

CR-30S has flow through cooling, and CH-30S has closed loop cooling (air circulates in the converter and returns to its source).

Figure 6.5 30 kHz Booster Dimensions

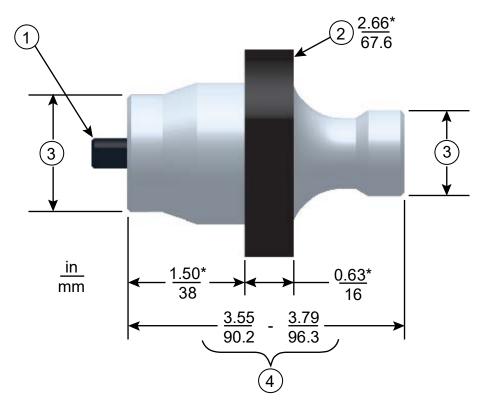


Table 6.5 30 kHz Booster

Item	Description
1	3/8 - 24 x 1 - 1/4 stud
2	Grip Ring Diameter
3	Variable
4	Varies with tuning and gain

^{*} These dimensions do not vary.

Figure 6.6 30 kHz Converter/Booster/Horn, Typical Dimensions

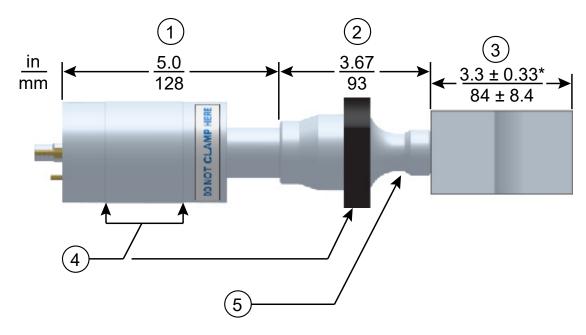


Table 6.6 30 kHz Converter/Booster/Horn

Item	Description
1	Converter
2	Booster
3	One-half wavelength horn
4	Recommended clamping area
5	Booster front end diameter will vary with amplitude

st Overall horn length can vary beyond these typical dimensions depending on the application.

Figure 6.7 40 kHz Booster Dimensions

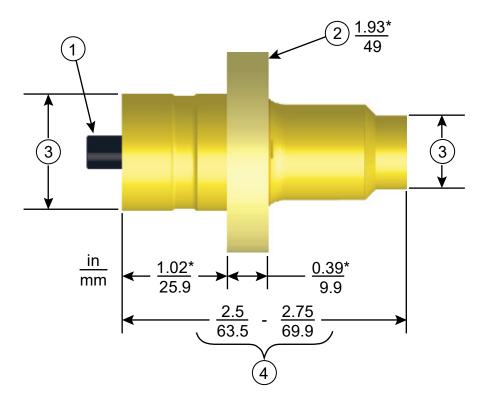


Table 6.7 40 kHz Booster

Item	Description
1	M8 x 1 - 1/4 stud (Ti boosters) M8 x 1 - 1/2 stud (Al boosters)
2	Grip ring diameter
3	Variable
4	Varies with tuning and gain

Figure 6.8 40 kHz Converter/Booster/Horn, Typical Dimensions

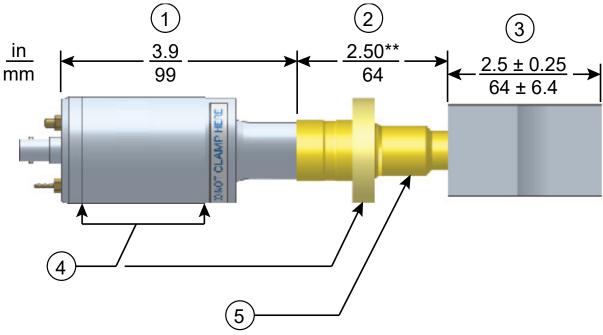


Table 6.8 40 kHz Converter/Booster/Horn

Item	Description
1	Converter
2	Booster
3	One-half wavelength horn
4	Recommended clamping area
5	Booster front end diameter will vary with amplitude

st Overall horn length can vary beyond these typical dimensions depending on the application.

^{**} Dimension varies with tuning and gain.

6.1.1 Component Functional Description

Ultrasonic Stack

Converter

The converter is mounted in the customer's automation as part of the ultrasonic stack. The ultrasonic electrical energy from the power supply is applied to the converter (sometimes called the transducer). This transforms the high frequency electrical oscillations into mechanical vibrations at the same frequency as the electrical oscillations. The heart of the converter are piezoelectric ceramic elements. When subjected to an alternating voltage, these elements alternately expand and contract, resulting in better than 90% conversion of electrical to mechanical energy.

Booster

It is important to be able to modify the horn face amplitude for successful ultrasonic assembly. The booster provides a means to modify the amplitude. It is designed to couple different ratios of ultrasonic energy to the horn, which will in turn increase or decrease the amplitude at the face of the horn. This is accomplished by varying the ratios of the masses of the input and output half sections of the booster.

The booster is a resonant half-wave section of aluminum or titanium. It is mounted between the converter and the horn, as part of the ultrasonic stack. It also provides a clamping point for rigid stack mounting.

Horn

The horn is selected or designed for a specific application. Each horn is tuned typically as a half-wave section that applies the necessary force and vibration uniformly to the parts to be assembled. It transfers ultrasonic vibrations from the converter to the workpiece. The horn is mounted to the booster as part of the ultrasonic stack.

Depending on their profile, horns are referred to as stepped, conical, exponential, bar, or catenoidal. The shape of the horn determines the amplitude at the face of the horn. Depending on the application, horns can be made from titanium alloys, aluminum, or steel. Titanium alloys are the best materials for horn fabrication due to their high level of strength and low loss. Aluminum horns are usually chrome- or nickel-plated or hard-coated to reduce wear. Steel horns are for low amplitude requiring hardness, such as ultrasonic insertion applications.



Solid Mount Boosters

The solid mount booster is a one-half wave-length resonant section made exclusively of titanium. It is mounted between the converter and the horn, modifying the amplitude of vibration applied to the horn and providing a clamping point.

The solid mount booster is superior to prior versions in that deflection is minimized. This is the result of a redesigned clamp-ring which employs a metal-to-metal press fit rather than an O-ring assembly.

The advantage this booster offers is its improved rigidity. For continuous applications, this means more energy delivered to the product, while in plunge applications, improved alignment is possible. The solid mount provides improved positional alignment and will benefit continuous applications where high force, high side load, or high cycle rates are necessary. In plunge welding applications, overall deflection is reduced by an average of 0.0025 in. (0.064 mm) over a wide variety of materials, joint designs, and operating conditions. The results of this testing in combination with information drawn from field testing indicate that the solid mount will benefit plunge applications where precision alignment is necessary (such as staking, swaging, or insertion) or where concentricity/parallelism is critical.

Chapter 7: Operation

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7.1 Setting Primary Parameters

After analyzing your specific application, you can determine the Weld Mode to use to weld your parts. A Weld Mode is a set of parameters that governs the weld. (Contact the Branson Ultrasonics Applications Laboratory for more information on determining the best mode for welding your application. See $\underline{1.3 \text{ How to Contact Branson}}$.

There are five Weld Modes to choose from Continuous, Time, Energy, Peak Power, and Ground Detect Modes. The following table describes each mode:

Table 7.1 Summary of Weld Modes

Weld Mode	Description		
Continuous	On this mode, ultrasonic energy will be delivered continuously while the start signal is present.		
Time You select the length of time (in seconds) that ultrasonic energy be transmitted to your parts.			
Energy You select the amount of energy (in Joules) that will be transmotory to your parts. (A Joule is one Watt-Second).			
Peak Power	You select the peak power level (as a percentage of full power) at which the weld is terminated.		
Ground Detect	The DCX F-DP Power Supply provides ultrasonic energy until the horn comes in contact with your electrically isolated fixture or with the anvil, providing that you made an electrical connection between the actuator and your fixture or anvil. NOTICE Ground detect signal is required to terminate the weld and enter		
Ground Detect	horn comes in contact with your electrically isolated fixture or we the anvil, providing that you made an electrical connection between the actuator and your fixture or anvil.		

NOTICE	
1	In these modes, cutoffs can be used as secondary controls.

7.1.1 Continuous Mode

In this mode, ultrasonic energy will be delivered continuously while the start signal is present. Within Continuous Mode, you can also select several other parameters, ranging from afterburst to limits and cutoffs. For more information on setting the optional parameters within Continuous Mode, or any other welding mode, refer to the DCX A/F Series Web Page Instruction Manual.

Table 7.2 Continuous Mode Operational Sequence

Step	Action	Reference
1	Press the Configuration key until the number icon (#) appears on the LCD. The power supply will display register 101 at every power up.	
2	Press and release the Up/Down arrow keys to select register 138. For a detailed description of available registers refer to Table 7.26 Power Supply Registers.	
3	Once you have reached register 138, press the Configuration key. The register value will be displayed; this is indicated by the circle icon.	

 Table 7.2
 Continuous Mode Operational Sequence

Step	Action	Reference
4	Use the Up/Down arrow keys to select value 0 (Continuous mode), then press the Configuration key to confirm the selection.	
5	Continuous mode icon and amplitude value will be displayed.	

7.1.2 Time Mode

You can use Time Mode to select the length of time that ultrasonic energy is applied to your parts. Within Time Mode, you can also select several other parameters, ranging from afterburst to limits and cutoffs. For more information on setting the optional parameters within Time Mode, or any other welding mode, refer to the DCX A/F Series Web Page Instruction Manual.

Table 7.3 Time Mode Parameters

Parameter	Default	Max. Value	Min. Value
Time	0.010 seconds	30 seconds	0.010 seconds

Table 7.4 Time Mode Operational Sequence

Step	Action	Reference
1	Press the Configuration key until the number icon (#) appears on the LCD. The power supply will display register 101 at every power up.	
2	Press and release the Up/Down arrow keys to select register 138. For a detailed description of available registers refer to Table 7.26 Power Supply Registers.	

Table 7.4 Time Mode Operational Sequence

Step	Action	Reference
3	Once you have reached register 138, press the Configuration key. The register value will be displayed; this is indicated by the circle icon.	
4	Use the Up/Down arrow keys to select value 1 (Time mode), then press the Configuration key to confirm the selection.	
5	Time mode icon and parameter value will be displayed. Use the Up/Down keys to enter the desired parameter value, then press the Configuration key to confirm the selected value.	

7.1.3 Energy Mode

You can use Energy Mode to select the amount of ultrasonic energy that is applied to your parts. Within Energy Mode, you can also select several other parameters, ranging from afterburst to limits and cutoffs. For more information on setting the optional parameters within Energy Mode, or any other welding mode, refer to the DCX A/F Series Web Page Instruction Manual.

Table 7.5 Energy Mode Parameters

Parameter	Default	Max. Value	Min. Value
Energy	500 Joules	9999 Joules	0.1 Joules

Table 7.6 Energy Mode Operational Sequence

Step	Action	Reference
1	Press the Configuration key until the number icon (#) appears on the LCD. The power supply will display register 101 at every power up.	
2	Press and release the Up/Down arrow keys to select register 138. For a detailed description of available registers refer to Table 7.26 Power Supply Registers.	

Table 7.6 Energy Mode Operational Sequence

Step	Action	Reference
3	Once you have reached register 138, press the Configuration key. The register value will be displayed; this is indicated by the circle icon.	
4	Use the Up/Down arrow keys to select value 2 (Energy mode), then press the Configuration key to confirm the selection.	
5	Energy mode icon and parameter value will be displayed. Use the Up/Down keys to enter the desired parameter value, then press the Configuration key to confirm the selected value.	

7.1.4 Peak Power Mode

You can use Peak Power Mode to select the maximum percentage of the total available power that will be used to process your welds. When the power level you set is reached, ultrasonics will be terminated. From within Peak Power Mode, you can also select several other parameters, ranging from afterburst to limits and cutoffs. For more information on setting the optional parameters within Peak Power Mode, or any other welding mode, refer to the DCX A/F Series Web Page Instruction Manual.

Table 7.7 Peak Power Mode Parameters

Parameter	Default	Max. Value	Min. Value
Peak Power	1%	100%	1%

Table 7.8 Peak Power Mode Operational Sequence

Step	Action	Reference
1	Press the Configuration key until the number icon (#) appears on the LCD. The power supply will display register 101 at every power up.	
2	Press and release the Up/Down arrow keys to select register 138. For a detailed description of available registers refer to Table 7.26 Power Supply Registers.	

Table 7.8 Peak Power Mode Operational Sequence

Step	Action	Reference
3	Once you have reached register 138, press the Configuration key. The register value will be displayed; this is indicated by the circle icon.	
4	Use the Up/Down arrow keys to select value 3 (Peak Power mode), then press the Configuration key to confirm the selection.	
5	Peak Power mode icon and parameter value will be displayed. Use the Up/ Down keys to enter the desired parameter value, then press the Configuration key to confirm the selected value.	

7.1.5 Ground Detect Mode

You can use Ground Detect Weld Mode to have ultrasonic energy turn off when the horn comes in contact with your electrically isolated fixture or anvil.

From within Ground Detect Mode, you can also select several other parameters, ranging from Hold Time (in seconds) to Suspect and Reject Limits. For more information on setting the optional parameters within Ground Detect Mode, or any other welding mode, refer to the DCX A/F Series Web Page Instruction Manual.

Table 7.9 Ground Detect Mode Parameters

Parameter	Default	Max. Value	Min. Value
Ground Detect	0.001 seconds	0.500 seconds	0.001 seconds

Table 7.10 Ground Detect Mode Operational Sequence

Step	Action	Reference
1	Press the Configuration key until the number icon (#) appears on the LCD. The power supply will display register 101 at every power up.	
2	Press and release the Up/Down arrow keys to select register 138. For a detailed description of available registers refer to Table 7.26 Power Supply Registers.	

Table 7.10 Ground Detect Mode Operational Sequence

Step	Action	Reference
3	Once you have reached register 138, press the Configuration key. The register value will be displayed; this is indicated by the circle icon.	
4	Use the Up/Down arrow keys to select value 4 (Ground Detect mode), then press the Configuration key to confirm the selection.	
5	Ground Detect mode icon and parameter value will be displayed. Use the Up/Down keys to enter the desired parameter value, then press the Configuration key to confirm the selected value.	

7.2 Setting Limits

NOTICE	
6	Register 114 (Limits) must be set to On before proceeding. See <u>7.5</u> Configuring the Power Supply Registers for more information.

7.2.1 Time Window Limit High

 Table 7.11
 Time Window Limit High Parameters

Parameter	Default	Max. Value	Min. Value
Time Window Limit High	30.00s	30.00s	0.010s

NOTICE	
6	Minimum value should be higher than the window limit low value.

NOTICE	
1	Set value to 0 to set the window limit high to off.

NOTICE	
1	Time window limits must be set in multiples of 1.

Table 7.12 Time Window Limit High Operational Sequence

Step	Action	Reference
1	Press the Configuration key until the number icon (#) appears on the LCD. The power supply will display register 101 at every power up.	
2	Press and release the Up/Down arrow keys to select register 158. For a detailed description of available registers refer to Table 7.26 Power Supply Registers.	
3	Once you have reached register 158, press the Configuration key. The register value will be displayed; this is indicated by the circle icon. Use the Up/Down arrow keys to select the desired time window limit high value, then press the Configuration key to confirm the selection. NOTICE Register 114 (Limits) must be set to On before proceeding. Otherwise, the value of the limits cannot be changed.	

7.2.2 Time Window Limit Low

Table 7.13 Time Window Limit Low Parameters

Parameter	Default	Max. Value	Min. Value
Time Window Limit Low	0s	30.00s	0.010s

NOTICE	
1	Maximum value should be lower than the window limit high value.

NOTICE	
(1)	Set value to 0 to set the window limit high to off.

NOTICE	
1	Time window limits must be set in multiples of 1.

Table 7.14 Time Window Limit Low Operational Sequence

Step	Action	Reference
1	Press the Configuration key until the number icon (#) appears on the LCD. The power supply will display register 101 at every power up.	
2	Press and release the Up/Down arrow keys to select register 159. For a detailed description of available registers refer to Table 7.26 Power Supply Registers.	
3	Once you have reached register 159, press the Configuration key. The register value will be displayed; this is indicated by the circle icon. Use the Up/Down arrow keys to select the desired time window limit low value, then press the Configuration key to confirm the selection. NOTICE Register 114 (Limits) must be set to On before proceeding. Otherwise, the value of the limits cannot be changed.	

7.2.3 Energy Window Limit High

Table 7.15 Energy Window Limit High Parameters

Parameter	Default	Max. Value	Min. Value
Energy Window Limit High	0J	9999]	0.1J

NOTICE	
1	Minimum value should be higher than the window limit low value.

NOTICE	
(1)	Set value to 0 to set the window limit high to off.

NOTICE	
1	Energy window limits must be set in multiples of 1.

 Table 7.16
 Energy Window Limit High Operational Sequence

Step	Action	Reference
1	Press the Configuration key until the number icon (#) appears on the LCD. The power supply will display register 101 at every power up.	
2	Press and release the Up/Down arrow keys to select register 160. For a detailed description of available registers refer to <u>Table 7.26 Power Supply Registers</u> .	
3	Once you have reached register 160, press the Configuration key. The register value will be displayed; this is indicated by the circle icon. Use the Up/Down arrow keys to select the desired energy window limit high value, then press the Configuration key to confirm the selection. NOTICE Register 114 (Limits) must be set to On before proceeding. Otherwise, the value of the limits cannot be changed.	

7.2.4 Energy Window Limit Low

Table 7.17 Energy Window Limit Low Parameters

Parameter	Default	Max. Value	Min. Value
Energy Window Limit Low	03	9999]	0.1J

NOTICE	
1	Maximum value should be lower than the window limit high value.

NOTICE	
f	Set value to 0 to set the window limit high to off.

NOTICE	
1	Energy window limits must be set in multiples of 1.

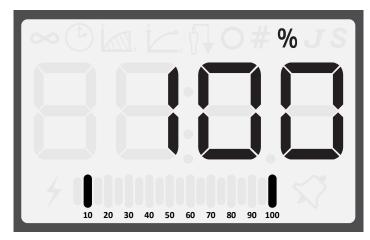
 Table 7.18
 Energy Window Limit Low Operational Sequence

Step	Action	Reference
1	Press the Configuration key until the number icon (#) appears on the LCD. The power supply will display register 101 at every power up.	
2	Press and release the Up/Down arrow keys to select register 161. For a detailed description of available registers refer to Table 7.26 Power Supply Registers.	
3	Once you have reached register 161, press the Configuration key. The register value will be displayed; this is indicated by the circle icon. Use the Up/Down arrow keys to select the desired energy window limit low value, then press the Configuration key to confirm the selection. NOTICE Register 114 (Limits) must be set to On before proceeding. Otherwise, the value of the limits cannot be changed.	

7.2.5 Setting Power Window Limits

If power window high or power window low limits are enabled, it will display a single slowly blinking segment for the high limit and a single slowly blinking segment for the low limit in the bar-graph. In case of a window limit alarm, the respective segment will blink faster.

Figure 7.1 Power Window Limits



7.2.6 Power Window Limit High

Table 7.19 Power Window Limit High Parameters

Parameter	Default	Max. Value	Min. Value
Power Window Limit High	0%	100%	1%

NOTICE	
1	Minimum value should be higher than the window limit low value.

NOTICE	
1	Set value to 0 to set the window limit high to off.

NOTICE	
1	Power window limits must be set in multiples of 1.

 Table 7.20
 Power Window Limit High Operational Sequence

Step	Action	Reference
1	Press the Configuration key until the number icon (#) appears on the LCD. The power supply will display register 101 at every power up.	# # 10 20 30 40 50 60 70 80 90 100
2	Press and release the Up/Down arrow keys to select register 162. For a detailed description of available registers refer to Table 7.26 Power Supply Registers.	# # 10 20 30 40 50 60 70 80 90 100
3	Once you have reached register 162, press the Configuration key. The register value will be displayed; this is indicated by the circle icon. Use the Up/Down arrow keys to select the desired power window limit high value, then press the Configuration key to confirm the selection. NOTICE Register 114 (Limits) must be set to On before proceeding. Otherwise, the value of the limits cannot be changed.	10 20 30 40 50 60 70 80 90 100

7.2.7 Power Window Limit Low

Table 7.21 Power Window Limit Low Parameters

Parameter	Default	Max. Value	Min. Value
Power Window Limit Low	0%	100%	1%

NOTICE	
1	Maximum value should be lower than the window limit high value.

NOTICE	
1	Set value to 0 to set the window limit high to off.

NOTICE	
1	Power window limits must be set in multiples of 1.

 Table 7.22
 Power Window Limit Low Operational Sequence

Step	Action	Reference
1	Press the Configuration key until the number icon (#) appears on the LCD. The power supply will display register 101 at every power up.	# 10 20 30 40 50 60 70 80 90 100
2	Press and release the Up/Down arrow keys to select register 163. For a detailed description of available registers refer to Table 7.26 Power Supply Registers.	# /
3	Once you have reached register 163, press the Configuration key. The register value will be displayed; this is indicated by the circle icon. Use the Up/Down arrow keys to select the desired power window limit low value, then press the Configuration key to confirm the selection. NOTICE Register 114 (Limits) must be set to On before proceeding. Otherwise, the value of the limits cannot be changed.	10 20 30 40 50 60 70 80 90 100

7.2.8 Using the Web Page Interface

Window limits can be set to a user specified value using the web page interface. For more information, refer to the DCX A/F Rack Mount Series Web Page Interface Instruction Manual.

7.3 Setting the Amplitude

7.3.1 Using the Front Panel Controls

At power up the DCX F-DP Power Supply will display the last amplitude setting on the LCD. It can also be set to show weld mode.

Figure 7.2 LCD at Power Up



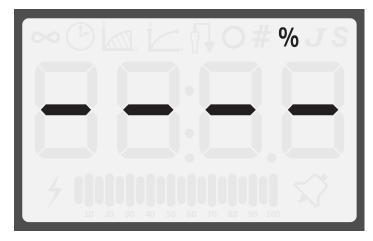
Table 7.23 Setting the Amplitude Using the Front Panel Controls

Step	Action	Reference
1	Press the Configuration key until the percentage icon (%) and no mode icons are displaying on the LCD.	
2	Press and release the Up or Down arrow keys to select the desired amplitude at 1% increments. Press and hold down the Up or Down arrow keys and the Amplitude will auto increment at 1% increments every quarter of a second. After holding down an arrow key for four straight seconds, the amplitude will auto increment at 5% increments every quarter of a second.	

7.3.2 Using External Amplitude Control

When External Amplitude Control is enabled, the front panel amplitude control is disabled and the LCD displays four dashes (see <u>Figure 7.3 LCD when in External Amplitude Control Mode</u> below).

Figure 7.3 LCD when in External Amplitude Control Mode



The ultrasonic amplitude can be controlled using one of the two analog input pins on the user I/O connector (pins 17 and 18) or through the Profibus interface.

7.3.3 Using the Web Page Interface

The ultrasonic amplitude can be set to a user specified value using the web page interface. For more information, refer to the DCX A/F Series Web Page Instruction Manual.

7.4 Resetting the Power Supply Alarms

You need to reset the weld system when you get an overload. When there is an overload, the alarm icon appears on the front panel LCD and the General Alarm output on the user I/O connector becomes active. The procedure for resetting the power supply depends on the power supply alarm settings. Refer to <u>Table 7.24 Resetting the DCX F-DP Power Supply</u> for reset procedures.

Table 7.24 Resetting the DCX F-DP Power Supply

Alarm Setting	Reset Procedure
Reset Required	Press the front panel Reset key. You can also send an External Reset signal.
No Reset Required	Remove and re-apply the start signal.

For more information on interfacing the DCX F-DP Power Supply using the user I/O connections refer to 5.4.1 User I/O Connections in Chapter 5: Installation and Setup.

7.5 Configuring the Power Supply Registers

At power up the DCX F-DP Power Supply will display the last amplitude setting, this is indicated by the percentage icon (%) on the LCD. Refer to Figure 7.2 LCD at Power Up.

Table 7.25 Steps to Configure the Power Supply Registers

Step	Action	Reference
1	Press the Configuration key until the number icon (#) appears on the LCD. The power supply will display register 101 at every power up.	
2	Press and release the Up or Down arrow keys to select the desired register. For a detailed description of available registers refer to Table 7.26 Power Supply Registers.	
3	Once you have reached the desired register, press the Configuration key. The register value will be displayed, this is indicated by the circle icon.	

 Table 7.25
 Steps to Configure the Power Supply Registers

Step	Action	Reference
4	Press and release the Up or Down arrow keys to enter the desired value at 1 increments.	
	Press and hold down the Up and Down arrow keys and the value will auto increment at 1 increments every quarter of a second.	
	After holding down an arrow key for four straight seconds, the value will auto increment at 5 increments every quarter of a second.	7 (M) (M) (M) (M) (M) (M)
	Or press the Reset key to enter the default value. For detailed default values of available registers refer to <u>Table 7.26</u> <u>Power Supply Registers</u> .	
5	Press the Configuration key to save the value. The current amplitude setting will be displayed only for continuous mode. For all the other modes, it will display the primary parameter of that mode.	

7.5.1 Power Supply Registers

 Table 7.26
 Power Supply Registers

Register	Description	Default Value	Max. Value	Min. Value
101	Software version	N/A	N/A	N/A
102	Bar graph identification after weld complete 0: Power 1: Frequency	0	1	0
104	External amplitude control - user analog input or fieldbus 0: Off 1: On	0	1	0
105	Start ramp time (ms)	80	1000	10
106	Store frequency at end of weld 0: Off 1: On	1	1	0
107	Power up seek/scan 0: Off 1: Seek, 2: Scan	1	2	0
108	Seek ramp time (ms)	80	1000	10
109	Timed seek (every 60 seconds) 0: Off 1: On	0	1	0
110	Seek time (ms)	500	1000	10
111	External Frequency Offset 0: Off 1: On	0	1	0
112	Frequency Offset Value	0		
113	Cutoffs 0: Off 1: On	0	1	0
114	Limits 0: Off 1: On	0	1	0

Table 7.26 Power Supply Registers

Register	Description	Default Value	Max. Value	Min. Value
115	Restore Defaults 0=Off 1=Just weld preset 2=System defaults	0	2	0
116	IP Address - 1	192	255	0
117	IP Address - 2	168	255	0
118	IP Address - 3	10	255	0
119	IP Address - 4	100	255	0
120	Gateway for IP Address - 1	192	255	0
121	Gateway for IP Address - 2	168	255	0
122	Gateway for IP Address - 3	10	255	0
123	Gateway for IP Address - 4	1	255	0
124	Subnet Mask for IP Address - 1	255	255	0
125	Subnet Mask for IP Address - 2	255	255	0
126	Subnet Mask for IP Address - 3	255	255	0
127	Subnet Mask for IP Address - 4	0	255	0
128	DHCP Settings 0: Server 1: Client 2: Static 3: Restore Registers 116-128 to default	2	3	0
129	Profibus Address 1	125	126	0
134	Backlight Timeout (s) 0: Always on	600	9999	0
135	Auto scroll step size	5	50	1
136	Power on display 0: Weld Mode 1: Amplitude	1	1	0
138	Weld Mode 0: Continuous 1: Time 2: Energy 3: Peak Power 4: Ground Detect	0	4	0

 Table 7.26
 Power Supply Registers

Register	Description	Default Value	Max. Value	Min. Value
139	MAC Address 1	N/A	FFFF	0
140	MAC Address 2	N/A	FFFF	0
141	MAC Address 3	N/A	FFFF	0
154	Restore registers 142–154 to default.	0	1	0
158	+Time Limit 0: Off 0.010s-30.00s: Set +Time Limit	30.00s	30.00s	0.010s
159	-Time Limit 0: Off 0.010s-30.00s: Set -Time Limit	0.010s	30.00s	0.010s
160	+Energy Limit 0: Off 0.1-9999J: Set +Energy Limit	99993	99991	0.1J
161	-Energy Limit 0: Off 0.1-9999J: Set -Energy Limit	1.0J	99993	0.13
162	+Power Limit 0: Off 1-100%: Set +Power Limit	100%	100%	1%
163	-Power Limit 0: Off 1-100%: Set -Power Limit	1%	100%	1%

7.6 Save/Recall Presets

If you wish to save your current weld cycle settings for later use, you can save it into a preset location. 32 preset locations are available. Preset settings are saved until they are over-written, and are maintained in memory even if the system is turned off or unplugged.

7.6.1 Save Preset

Table 7.27 Save Preset

Step	Action	Reference
1	Set the desired weld mode and parameters. See 7.1 Setting Primary Parameters for more information.	
2	Press the Configuration key until the preset location screen (Pr:XX) appears on the LCD.	
3	Press the Up or Down arrow keys to select the desired preset location to use. Once you have reached the desired preset location, press the Configuration key to select it. You will be returned to the main screen.	

Table 7.27 Save Preset

Step	Action	Reference
4	While on the main screen, press and hold the Reset key. While holding down the Reset key, press the Configuration to save your current control mode and parameters into the selected preset location (Pr:XX). The LCD will blink twice to confirm that the preset was saved correctly.	

7.6.2 Recall Preset

Table 7.28 Recall Preset

Step	Action	Reference
1	Press the Configuration key until the preset location screen (Pr:XX) appears on the LCD.	
2	Press the Up or Down arrow keys to select the desired preset location to recall. Once you have reached the desired preset location, press and hold the Reset key. While holding down the Reset key, press the Configuration for 3 seconds to recall the selected preset location (Pr:XX). The LCD will blink twice to confirm that the preset was recalled correctly.	

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Table 7.28 Recall Preset

Step	Action	Reference
3	You will be returned to the main screen with the recalled preset location settings.	

7.7 LCD Bar-Graph

While ultrasonic power is active the LCD will always display the power value on the 20-segment LCD bar-graph as a percentage of the maximum output power.

At the end of a weld or test cycle, the bar-graph is factory set to represent the cycle's peak power as a percentage of the maximum output power.

The power supply can also be configured to show a single bar on the LCD bar-graph to represent the stack operating frequency stored at the end of each weld or test cycle. This option can be used to troubleshoot operating frequency changes as a result of heating effects, coupling, tooling wear, etc.

For information on how to set the power supply registers see <u>7.5 Configuring the Power Supply Registers</u>.

7.7.1 Power Bar-Graph Interpretation

The lightning bolt left of the bar-graph indicates ultrasonic power is running. Each of the segments represent 5% increments of the maximum output power. The segments will only appear if the output power has exceeded the value represented. For example if the power is 4% only the lightning bolt will be on. When it reaches 5% the first bar-graph segment will appear.

 Table 7.29
 Power Bar-Graph Interpretation Examples

Description	Reference
In this example only the lightning bolt appears left of the bar-graph. This means power is between 0% and 5%. If the power supply is 800W the actual output power is between 0W and 40W.	7 10 20 20 20 20 20 20 20 20 20 20 20 20 20
In this example the first six segments appear on the bar-graph. This means power is between 30% and 35%. If the power supply is 800W, the actual output power is between 240W and 280W.	## White

7.7.2 Frequency Bar-Graph Interpretation

The actual frequency depends on the power supply's operating frequency. Use <u>Table 7.30</u> <u>Frequency Bar-Graph Interpretation - 20 kHz (50 Hz Segment)</u> to <u>Table 7.32 Frequency Bar-Graph Interpretation - 40 kHz (100 Hz/Segment)</u> below to interpret frequency bargraph readings.

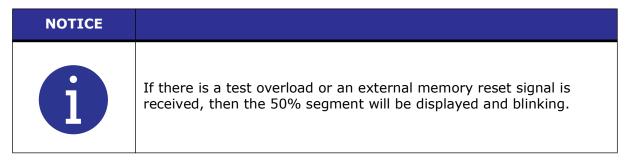


Table 7.30 Frequency Bar-Graph Interpretation - 20 kHz (50 Hz Segment)

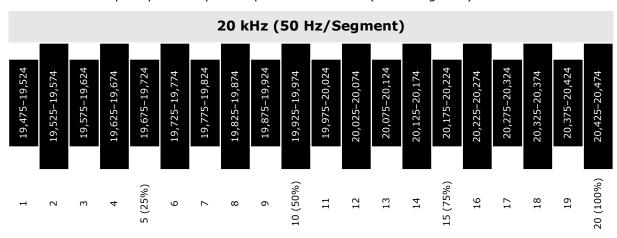


Table 7.31 Frequency Bar-Graph Interpretation - 30 kHz (76 Hz Segment)

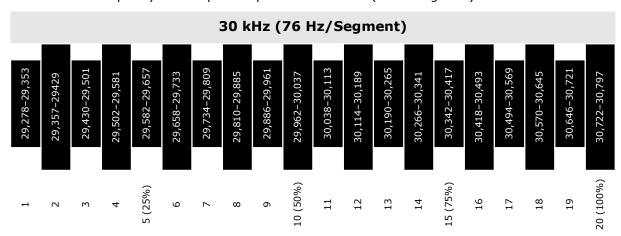


Table 7.32 Frequency Bar-Graph Interpretation - 40 kHz (100 Hz/Segment)

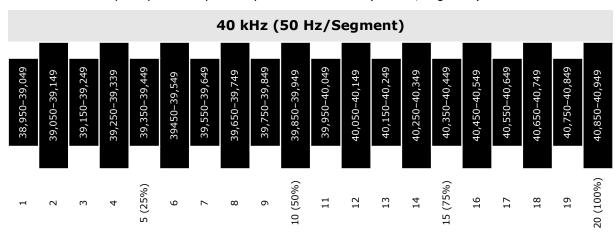


Table 7.33 Frequency Bar-Graph Interpretation Examples

Description	Reference
In this example the bar is located in the 11 th segment. If the power supply is a 20 kHz unit, the stack is running in the frequency range of 19,975 Hz to 20,024 Hz.	
In this example the bar is located in the 7 th segment. If the power supply is a 20 kHz unit, the stack is running in the frequency range of 19,775 Hz to 19,824 Hz.	

7.8 Ultrasonics Test Procedure

The Ultrasonics Test function measures ultrasonic power dissipated by the ultrasonic stack with no load. The ultrasonics test procedure involves an automatic matching of the frequency of the power supply to the frequency of the converter-booster-horn stack.

WARNING	High Voltage Hazard
4	Ensure that no one is in contact with the horn when testing the power supply. Do not cycle the welding system if either the RF cable or converter is disconnected.

WARNING	High Voltage Hazard
4	Ensure the power supply is properly connected, as indicated in <u>5.3</u> <u>Installation Steps</u> .

7.8.1 Using the Front Panel Controls

NOTICE	
1	To use the front panel controls, the DCX F-DP Power Supply unit must be in manual mode.

 Table 7.34
 Power Supply Ultrasonic Test Procedure (Front Panel)

Step	Action	Reference
1	Press the test key for 1-2 seconds, then release. The Sonics Active indicator appears while the test key is pressed. If the power supply alarm indicator does not appear, the test procedure is finished.	→ → → → → → → → → →

 Table 7.34
 Power Supply Ultrasonic Test Procedure (Front Panel)

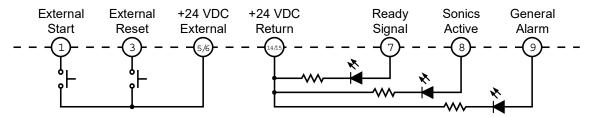
Step	Action	Reference
2	If the alarm indicator appears, press the alarm reset key and repeat step 2 one time only. If the alarm persists, refer to 9.5 Troubleshooting. See Appendix A: Communication Channel Alarms for additional information.	

7.9 Using the I/O Connections

 Table 7.35
 Power Supply Ultrasonic Test Procedure (User I/O)

Step	Action	Reference
1	Wire the necessary I/O signals as shown on <u>Figure 7.4 Test Connections</u> , or using a similar setup.	Refer to Figure 7.4 Test Connections below.
2	Send an External Test signal for 1-2 seconds. The Sonics Active output will become active and the Sonics Active indicator appears while the External Start Signal is present. If the General Alarm output/ alarm indicator does not become active, the test procedure is finished. NOTICE Power supply must be in manual mode.	9 10 10 10 10 10 10 10 10 10 10 10 10 10
3	If the General Alarm output/alarm indicator becomes active, send an External Reset signal and repeat step 2 one time only. If the alarm persists, refer to 9.5 Troubleshooting.	

Figure 7.4 Test Connections



Chapter 8: PROFIBUS DP Operation

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8.1 PROFIBUS DP

PROFIBUS is an open, vendor independent fieldbus standard for a wide range of applications in industrial automation.

8.1.1 LED Status Indicator

To get a fast overview about the status of the DCX F-DP Power Supply, two LEDs are placed on the front of the unit. The subsequent table describes the meaning of the LEDs.

Figure 8.1 LED Status Indicator



Table 8.1 DCX F-DP Power Supply LED Status Indicator

LED	Color	State	Description		
	Green	On	Operating System running.		
SYS	Green/ Yellow	Blinking green/yellow	Bootloader is waiting for firmware.		
313	Yellow	Static	Bootloader is waiting for software.		
	-	Off	Power supply for the device is missing or hardware defect.		
	Green	Flashing (acyclic)	No configuration or stack error.		
	Green	Flashing (cyclic)	PROFIBUS is configured, but bus communication is not yet released from the application.		
COM	Green	On	Communication to all Slaves is established.		
	Red Flashing (cyclic)		Communication to at least one Slave is disconnected.		
	Red	On	Communication to one/all Slaves is disconnected.		

8.1.2 Bus Communication

The PROFIBUS specification defines the technical characteristics of a serial field bus system that links distributed digital controllers on the network, from field level to cell level. PROFIBUS is a multi-master system that allows the joint operation of several automation, engineering or visualization systems with their distributed peripherals on one bus. PROFIBUS distinguishes between the following types of devices:

- Master devices determine the data communication on the bus. A master can send messages without an external request when it holds the bus access rights (the token). Masters are also called active stations
- Slave devices include motion controllers, drives, I/O devices, valves, and transducers. Slaves do not have bus access rights and can only acknowledge received messages or send messages to the master when requested to do so. Slave devices are passive stations and require only small portions of the bus protocol

The majority of PROFIBUS-DP applications are located at field level. The field level typically includes slave devices such as the S2K motion controller station and host devices like PLC or PC control systems for the PROFIBUS-DP master station. Operator interfaces and DCS type systems usually operate at the cell level.

Table 8.2	Data Bandwidth	Demands or	n PROFIBUS	Communications Systems
-----------	----------------	------------	------------	------------------------

Level	Amount of Data	Transmission Duration	Transmission Frequency
Management level	Megabytes	Hours/Minutes	Day/Shift
Cell level	Kilobytes	Seconds	Hours/Minutes
Field Level	Bytes	Several 100 microseconds to 100 milliseconds	10 to 100 milliseconds
Actuator sensor level	Bits	Microseconds to	Milliseconds

8.1.3 Network Topology

A PROFIBUS-DP network may have up to 127 stations (address 0-126), however address 126 is reserved for commissioning purposes. The bus system must be sub-divided into individual segments to handle this many participants. These segments are linked by repeaters. The function of a repeater is to condition the serial signal to allow connection of segments. In practice, both regenerating and non-regenerating repeaters may be used. Regenerating repeaters actually condition the signal to allow increased range of the bus. Up to 32 stations are allowed per segment and the repeater counts as a station address.

The user assigns a unique PROFIBUS station address to identify each master, slave, or repeater in the entire network. Each participant on the bus must have a unique station address.

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8.1.4 Network Connectors

PROFIBUS connections are created with a 9 pin sub-D connector. A minimum connection consists of a shielded twisted-pair cable (shield to pin 1 and twisted-pair wires to pins 3 and 8) with terminating connections in the appropriate bus plugs. The pin to signal conventions are described below:

 Table 8.3
 Pin-out Listing for the PROFIBUS Bus Plug Connector

Pin	Signal	Designation
1	Shield	Shield I Protective Ground
2	M24	Ground I Common of the 24V output voltage
3	RxDfTxD-P	Receive data / transmission data plus
4	CNTR-P	Control signal for repeaters (direction control)
5	DGND	Data transmission potential (ground to 5V)
6	VP	Supply voltage of the terminating resistance (+ 5V)
7	P24	Output voltage (+ 24V)
8	RxDfTxD-N	Receive data I transmission data negative
9	CNTR-N	Control signal for repeaters (direction control)

8.1.5 Network Segment Length

A PROFIBUS network uses either fiber optic or RS-485 copper media. The copper bus line, Line Type A is the recommended cable type. A more economical copper cable, Line Type B, is commonly used for smaller installations. It is extremely important to use cable rated to PROFIBUS specifications. The higher the baud rate selected and the longer the distances involved, the more critical cable selection becomes. (PROFIBUS cable has a distinctive purple color.)

The data rates for network communication with maximum segment trunk length per cable type are provided below. Multiple segments may be connected via repeater stations to extend the total bus length.

Table 8.4 Line Types

Baud Rate	Line A Distance (Max)	Line B Distance (Max)	Glass Fiber
9.6KBps, 19.2KBps and 93.75KBps	1200m	1200m	6Km
187.5KBps	1000m	600m	6Km
500KBps	400m	200m	6Km
1.5MBps	200m	N/A	6Km
3, 6 and 12MBps	100m	N/A	6Km

NOTICE	
1	The two physical ends of the PROFIBUS network should be terminated. There should be two, and only two, terminators on a network.

8.2 Configuration

Due to the many different makes of PLCs available, the information in this section may not be relevant to all types of PLCs. These configuration procedures are intended for users with at least a basic knowledge of the profibus PLC programming. For help with using the profibus PLC software, please refer to PLC vendor's help guide.

8.2.1 Communication

After the PROFIBUS Master has recognized the DCX F-DP Power Supply, the parameters of the DCX F-DP Power Supply can be set by means of "User Parameters". This parameter assignment should not be confused with parameters that are transmitted via the communication channel in the I/O image. The "User Parameters" are transmitted prior to the subsequent DATA_ EXCHANGE services. The following "User Parameters" have been implemented:

Table 8.5 User Parameters

Byte	Description				
1	PROFIBUS Standard				
2	PROFIBUS Standard				
3	PROFIBUS Standard				
4	PROFIBUS Standard				
5	PROFIBUS Standard				
6	PROFIBUS Standard				
7	PROFIBUS Standard				
8	PROFIBUS Standard				
9	PROFIBUS Standard				
	BRANSON-specific data format				
10	Default: $0x00$ (Bit0 = Bit1 = 0)				
10	Bit $0 = 1$, Bit $1 = 0$: BIG-ENDIAN (MOTOROLA)				
	Bit 0 = 0, Bit 1 = 1 : LITTLE-ENDIAN				
11	BRANSON-specific: Reserved				

The respective parameters are selected via the PROFIBUS network configuration function, by means of the PROFIBUS configuration file (*.gsd) located in the manual CD. To ensure that the DCX F-DP can be coupled as flexibly as possible, it is possible to choose the format of the I/O image by means of the "User Parameters". As shown above, you can select between BIG ENDIAN (MOTOROLA) or LITTLE ENDIAN (INTEL).

NOTICE	
1	As "Default", neither has been specified. This causes a "User Parameter Error" during startup of the PROFIBUS network. This is intentional. Thus you are forced to enter the desired format. The data formats shown in this document use the BIG-ENDIAN (MOTOROLA) format.

8.2.2 I/O Image

If the master has recognized, parameterized and configured the DCX F-DP Power Supply on the bus, a cyclic data exchange with the PROFIBUS DATA_EXCHANGE service occurs. This involves exchanging the I/O image between the master and slave in one cycle. The I/O image is divided into two fundamentally different areas:

Process data channel: Only binary signals are read and written via this channel. This channel is processed in each DATA_EXCHANGE cycle. It is used for controlling the DCX F-DP Power Supply, for example for selecting the parameter set and triggering weld or horn functions. This channel has real-time capability.

Communication channel: This channel can be used to exchange welding parameters, status values of completed welding jobs and graphics to the PROFIBUS DP master. The communication follows a defined "handshake process" and stretches across several DATA EXCHANGE cycles. This channel therefore has no real-time capability.

The I/O image has been divided as follows:

Table 8.6 Communication Channel (PKW)

Communication channel (PKW)			Process da (Pz	Remarks		
PKE	IND	PWE	PWE	STW1	STW2	Ma>Sl. (Out)
				ZSW1	ZSW2	Sl>Ma. (In)
8 Byte			4 Byte		Consistency	

STW1, STW2 Control word 1, 2 ZSW1, ZSW2 Status word 1, 2

The I/O image thus consists of 12 bytes. The consistency specification defines for which parts the content has to be consistent. These conditions are also contained in the PROFIBUS configuration file (*.gsd). They affect the access mechanisms that are possible for the DP master.

8.2.3 Communication Channel (PKW)

The subsequent text describes the communication channel (PKW) for transmitting parameters and status values (data). The following functions are offered:

- Reading/writing test values; to test the implementation of the communication protocol in the super ordinate control system
- Reading version information; to read various hardware/software version numbers
- Reading system information
 - Power supply type, frequency
 - Power supply type, power
- RTC (real-time clock) reading/writing
- Error category 1, 2, 5 and "Fieldbus-reading": Reading error categories 1, 2, 5 and "Fieldbus". Errors in this category can occur constantly. Therefore they can also be read independent of the cycle. The "Fieldbus" error category can only be read via another, error-free interface
- External control, visualization (analog values), reading/writing: For visualization, or to structure external control circuits, certain "analog values" (for example frequency, power) can be read continuously, independent of the status sets. Similarly, it is possible to continuously write certain "analog values" (for example the set amplitude value) as external set value specifications, independent of the parameter sets
- Reading/writing a parameter set
- Reading/writing a horn-specific parameter set
- Reading/writing a status set
- Reading/writing a horn-specific status set

The communication channel (PKW) is further divided into the following:

Table 8.7 Subdivisions of the communication channel (PKW)

	Communication Channel (PKW)								
	PKE		IND		PWE-HIGH		PWE-LOW		
Contents	Identifi	er	Index		Param., high word		Param., low word		
	High byte	Low byte	High byte (extend. access)	Low byte	High byte	Low byte	High byte	Low byte	
Byte no.	0	1	2	3	4	5	6	7	

The identifier (PKE) is further divided into two sections:

Table 8.8 Identifier (PKE) of the communication channel (PKW)

	PKE, high byte						ı	PKE,	low	byte					
Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
Contents	AK PNU														

AK: Instruction/answer code (0...15) PNU: Parameter number (1...3999)



The respective instruction code (data type, read/write) can be found in the following table, the master writes it in the AK field.

Table 8.9 Answer code - Master > Slave

AK, instruction code Master > Slave	Data type	Function
0		No instruction
1	INT / UINT 8	Read
2	IN / UINT16	Read
3	INT / UINT 32	Read
4	AINT / AUINT 8	Read array
5	AINT / AUINT 16	Read array
6	AINT / AUINT 32	Read array
7	INT / UINT 8	Write
8	INT / UINT 16	Write
9	INT / UINT 32	Write
10	AINT / AUINT 8	Write array
11	AINT / AUINT 16	Write array
12	AINT / AUINT 32	Write array
13		Not def.
14		Not def.
15		Not def.
(A)INT = (Array) Integer (A)UINT = (Array) Unsigned Integer		

Furthermore the master assigns the parameter number of the parameter to be read or written to the PNU field. If the data type is an array object, the relevant index additionally has to be entered in the IND field, otherwise IND has to be set to 0. However, for certain parameter numbers, it is possible to select extended access options by means of the IND index field. The High Byte in the IND field serves this purpose. In this case, the actual array index is only transferred in the Low Byte of the IND field, and is thus limited to 255. Even if the data type is not an Array (IND (Low-Byte) = 0), extended access options may be available for certain data numbers. The following table defines the interpretation of IND (High Byte) in these cases:

Table 8.10 IND (High Byte)

IND (High Byte)	Function	Extended access
0x00	(Array) Read	Std. access
0x01 (Bit0)	(Array) Read	"Default Value": Read
0x02 (Bit1)	(Array) Read	"Limit Low": Read

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Table 8.10 IND (High Byte)

IND (High Byte)	Function	Extended access
0x04 (Bit2)	(Array) Read	"Limit High" Read
0x00	(Array) Write	Std. access
0x01 (Bit0)	(Array) Write	"Non-volatile (RAM)" Write

If "extended access options" are applied to data numbers that do not support or permit these functions, the corresponding error, "Index erroneous" (see below) is generated. The parameter to be written is written to the "PWE" field. If a parameter has to be read, these fields can be ignored. However, after the instruction has been carried out, they contained the parameters that were read accordingly. To confirm an instruction, the master receives one of the following answer codes in the "AK" field. If this answer code matches the instruction code, the instruction has been carried out successfully.

Table 8.11 Answer Code: Slave > Master

AK, answer code Slave- >Master	Data type	Function			
0		No instruction			
1	INT / UINT 8	Read			
2	IN / UINT16	Read			
3	INT / UINT 32	Read			
4	AINT / AUINT 8	Read array			
5	AINT / AUINT 16	Read array			
6	AINT / AUINT 32	Read array			
7	INT / UINT 8	Write			
8	INT / UINT 16	Write			
9	INT / UINT 32	Write			
10	AINT / AUINT 8	Write array			
11	AINT / AUINT 16	Write array			
12	AINT / AUINT 32	Write array			
13		Not def.			
14		Not def.			
15		Error			
(A)INT = (Array) Integer	(A)INT = (Array) Integer				
(A)UINT = (Array) Unsigned Integer					

However, it is possible that the slave can also generate errors while an instruction is being carried out. An error is signaled by the respective answer code (= 15). A corresponding error message (error number) is then additionally contained in PKE, low byte (byte 1).

Table 8.12 Error Number PKE, Low Byte

Error number PKE, low byte	Description
1	Undefined instruction code
2	Undefined parameter number
3	Data type erroneous
4	Index erroneous
5	Parameter, value cannot be written
6	Parameter, currently no access right, "Access Token (AT)"
7	Parameter, currently no access right, "Security Level"
8	Parameter, lower limit value not reached
9	Parameter, upper limit value exceeded
10	NV write error -> Category 1 error present
11	No access -> Category 1 error present
12	
13	
14	
15	
16	
17	
18	
49	
50	Other errors
51 255	

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8.2.4 Special Functions Within the Communication Channel

To establish the best possible coupling of DCX F-DP Power Supply and PROFIBUS Master, certain mechanisms have to be kept in mind for certain values when the communication channel is being implemented. This includes, amongst others:

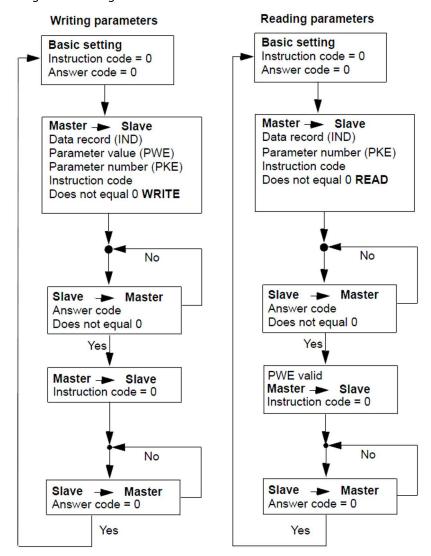
- "Get Access Token" and "Put Access Token"
- Reading and writing the real-time clock (RTC)
- Buffering the entire welding parameter set, in order to move or copy it within the DCX F-DP Power Supply
- Setting default values within a welding parameter set
- Buffering the entire status set (welding function)
- Buffering the entire horn parameter set, in order to move or copy it within the DCX F-DP Power Supply
- Buffering the entire status set (horn function)

These special functions, with the necessary commands, are explained in more detail in the appendix.

8.2.5 Writing and reading parameters

The communication process (handshake between master and slave) is as follows: An instruction from the master is always confirmed by an answer from the slave. Therefore there is a fixed handshake process, which has to be observed! This handshake process uses several DATA_EXCHANGE cycles. Originally the instruction code and answer code have to be 0. The master now sets "PWE" (write parameter), "IND" and subsequently "PKE" including "AK". This is recognized by the slave, and the instruction is carried out. The master waits for this to happen, until the slave sets answer code # 0. The "PKE" fields, including the error messages (and the "PWE" (read parameter) fields) have been set by the slave in accordance with the instruction, and can now be evaluated and processed by the master. Subsequently the master sets "AK (instruction code)" = 0 and waits until the slave confirms with "AK (answer code)" = 0. Thus the original status has been restored and a new communication cycle can start. The slave only answers new instructions when it has confirmed the instruction code = 0 with answer code = 0.

Figure 8.2 Writing and reading Parameters



Prior to writing certain parameters, it is necessary to "get" the "Access Token" with the respective command. The "Access Token" is kept until it is "put back" again or until the DCX F-DP Power Supply is separated from the voltage supply. The PKW communication channel is used independent of the process data channel (PZD).

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8.2.6 Process Data Channel (PZD Area)

The 8-byte process data area is used to cyclically update the process data. In the direction "master to slave", control words STW1 and STW2 are used for the transfer. The master can query the slave status by means of status words ZSW1 and ZSW2.

- The process data channel supports the following functions:
- · Selection: manual mode or auto mode
- Parameter set including horn selection
- Controlling the cycle
- · Ground detect function
- Amplitude profiling function
- "Error lines" for analyzing the errors of the last cycle

8.2.7 Signal/Control Processes Run Via Process Data Channel

The Test and Reset buttons can be used in manual mode but are disabled in auto mode. In auto mode, everything is controlled via the process data channel.

The following are prerequisites for a cycle in automatic mode:

MA = AUTO Automatic mode selected

PSN0..PSN4 = XX Parameter set number selected

If the prerequisites above have been met, the DCX F-DP Power Supply is OFF. Setting the "ON / STW2" bit switches it to the ON state (ultrasonic output). The appropriate parameters within the selected parameter set for the respective function is also adopted at this point in time. The complete "STW2 / Low-Byte" is evaluated simultaneously. Within "STW2 / Low-Byte", either the "STW2 / FCT" or the "STW2 / SFCT" bit has to be set, in accordance with the desired cycle for the welding and horn function. This determines the actual function of the cycle.

Welding and horn-specific functions have to be stopped - as per the respective parameter assignment - either by the PLC (continuous welding) or the power supply, depending on the operating mode (for example: welding time expired, energy -> energy reached).



8.3 Process Data Channel (PZD)

8.3.1 DCX Inputs/PLC Outputs (4 Words)

 Table 8.13
 DCX Inputs/PLC Outputs (4 Words)

Data	Description	Data Type	Access	Unit	Notes
0	STW1 (STW Word 1)			-	See <u>Table 8.14</u>
1	SWT2 (STW Word 2)	UINT16	w	-	and <u>Table 8.17</u>
2	External Amplitude	OINTIO	VV	%	
3	Frequency Offset			Hz	

8.3.1.1 Control Word (STW1)

Table 8.14 Control Word (STW1)

Bit	Name	Description	Notes
0	RES	Reserved	Not used
1	ES	Emergency Stop	1=Emergency Stop
2	RES	Reserved	Not used
3	RES	Reserved	Not used
4	HFS0	Stack Preset Number 0	
5	HFS1	Stack Preset Number 1	See <u>Table 8.15 HFS Bit (Control</u>
6	HFS2	Stack Preset Number 2	Word).
7	HFS3	Stack Preset Number 3	

NOTICE

HFS stack presets numbers are feedback inputs to indicate RF relay switching state. This is used only in stack sequencing applications. Set HFS to 0 if not using stack sequencing.

STW1

8	PSN0	Weld Preset Number 0	
9	PSN1	Weld Preset Number 1	
10	PSN2	Weld Preset Number 2	See <u>Table 8.16 PSN Bit (Control</u> Word).
11	PSN3	Weld Preset Number 3	
12	PSN4	Weld Preset Number 4	

NOTICE

Preset 0 is reserved for the running preset. When a preset number is recalled, it is copied to Preset 0 and becomes the running preset.

13	RES	Reserved	Not used
14	MA	Manual/Auto	Set and leave to 1 for implicit messaging control Set to 0 for discrete I/O control
			Set to 0 for discrete 1/0 control
15	RES	Reserved	Not used

HFS Bit (Control Word)

Table 8.15 HFS Bit (Control Word)

		•	,	
HFS3	HFS2	HFS1	HFS0	Stack Selected
0	0	0	0	No stack change
0	0	0	1	1 (factory default)
0	0	1	0	2
0	0	1	1	3
0	1	0	0	4
0	1	0	1	5
0	1	1	0	6
0	1	1	1	7
1	0	0	0	8
1	0	0	1	9
1	0	1	0	10
1	0	1	1	11
1	1	0	0	12
1	1	0	1	13
1	1	1	0	14
1	1	1	1	15

PSN Bit (Control Word)

Table 8.16 PSN Bit (Control Word)

PSN4	PSN3	PSN2	PSN1	PSN0	Preset Selected
0	0	0	0	0	Previous preset
0	0	0	0	1	1
0	0	0	1	0	2
0	0	0	1	1	3
0	0	1	0	0	4
0	0	1	0	1	5
0	0	1	1	0	6
0	0	1	1	1	7
0	1	0	0	0	8
0	1	0	0	1	9

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Table 8.16 PSN Bit (Control Word)

PSN4	PSN3	PSN2	PSN1	PSN0	Preset Selected
0	1	0	1	0	10
0	1	0	1	1	11
0	1	1	0	0	12
0	1	1	0	1	13
0	1	1	1	0	14
0	1	1	1	1	15
1	0	0	0	0	16
1	0	0	0	1	17
1	0	0	1	0	18
1	0	0	1	1	19
1	0	1	0	0	20
1	0	1	0	1	21
1	0	1	1	0	22
1	0	1	1	1	23
1	1	0	0	0	24
1	1	0	0	1	25
1	1	0	1	0	26
1	1	0	1	1	27
1	1	1	0	0	28
1	1	1	0	1	29
1	1	1	1	0	30
1	1	1	1	1	31

8.3.1.2 Control Word (STW2)

Table 8.17 Control Word (STW2)

	Bit	Name	Description	Notes	
	0	FCT	Weld Function	1 = To run ultrasonics in normal mode	
	1	SFCT	Stack Function		
	2	SFCT0	Stack Function 0	See Table 8.23	
	3	SFCT1	Stack Function 1	See lable 6.25	
	4	SFCT2	Stack Function 2		
	5	RES	Reserved	Not used	
	6	MCLR	Memory Clear	1 = Memory offset will be set to 0	
	7 RES Reserved	Reserved	Not used		
STW2	8	RST	Reset	1 = Reset	
	9	ON	Run Ultrasonics	1 = Will turn on ultrasonics based on combination of SFCT or FCT bits. See table below.	
	10	RES	Reserved	Not used	
	11	RES	Reserved	Not used	
	12	GNDDT	Ground Detect	1 = Ground has been detected	
	13	APROF	Amplitude Profile	1 = Switch from amplitude 1 to amplitude 2	
	14	RES	Reserved	Not used	
	15 RES Reserved		Reserved	Not used	



8.3.2 DCX Outputs/PLC Inputs (12 Words)

Table 8.18 DCX Outputs/PLC Inputs (12 Words)

Data	Description	Data Type	Access	Unit	Notes
0	Reserved				
1	Reserved				
2	ZSW1 (ZSW Word 1)			-	See <u>Table 8.19</u>
3	ZSW2 (ZSW Word 2)	UINT16		-	and <u>Table 8.22</u>
4	Nominal Amplitude Set	Olivilo		%	
5	Amplitude Output		R	%	
6	Current		K	%	
7	Power			%	
8	Phase	INT16		0	
9	PWM			%	
10	Frequency	UINT16		Hz	
11	Temperature			С	

8.3.2.1 Status Word (ZSW1)

Table 8.19 Status Word (ZSW1)

	Bit	Name	Description	Notes					
	0	NO-B	Non Cycle Overload Group B	1 = Non cycle overload has occurred					
	1 ES	ES	Emergency Stop Active	1 = Emergency stop active					
	2	TEE	Future Use	Not used					
	3	HFSE	Tuture ose	Not used					
	4	HFS0	Stack Preset Number 0 Status						
	5	HFS1	Stack Preset Number 1 Status	See <u>Table 8.20 HFS Bit (Status</u>					
	6	HFS2	Stack Preset Number 2 Status	Word).					
ZSW1	7	HFS3	Stack Preset Number 3 Status						
23001	8	PSN0	Weld Preset Number 0 Active						
	9	PSN1	Weld Preset Number 1 Active						
	10	PSN2	Weld Preset Number 2 Active	See <u>Table 8.21 PSN Bit (Status Word)</u> .					
	11	PSN3	Weld Preset Number 3 Active						
	12	PSN4	Weld Preset Number 4 Active						
	13	PSCA	Preset Change Complete	1 = Preset change complete					
	14	MA	Manual/Auto Mode Active	1 = Auto Mode					
	15	OL-0	Overload Group 0	1 = Overload has occurred					

HSF Bit (Status Word)

Table 8.20 HFS Bit (Status Word)

HFS3	HFS2	HFS1	HFS0	Stack Active
0	0	0	0	Not valid
0	0	0	1	1
0	0	1	0	2
0	0	1	1	3
0	1	0	0	4
0	1	0	1	5
0	1	1	0	6
0	1	1	1	7
1	0	0	0	8
1	0	0	1	9
1	0	1	0	10
1	0	1	1	11
1	1	0	0	12
1	1	0	1	13
1	1	1	0	14
1	1	1	1	15

PSN Bit (Status Word)

Table 8.21 PSN Bit (Status Word)

PSN4	PSN3	PSN2	PSN1	PSN0	Preset Active
0	0	0	0	0	No preset active
0	0	0	0	1	1
0	0	0	1	0	2
0	0	0	1	1	3
0	0	1	0	0	4
0	0	1	0	1	5
0	0	1	1	0	6
0	0	1	1	1	7
0	1	0	0	0	8
0	1	0	0	1	9

Table 8.21 PSN Bit (Status Word)

PSN4	PSN3	PSN2	PSN1	PSN0	Preset Active
0	1	0	1	0	10
0	1	0	1	1	11
0	1	1	0	0	12
0	1	1	0	1	13
0	1	1	1	0	14
0	1	1	1	1	15
1	0	0	0	0	16
1	0	0	0	1	17
1	0	0	1	0	18
1	0	0	1	1	19
1	0	1	0	0	20
1	0	1	0	1	21
1	0	1	1	0	22
1	0	1	1	1	23
1	1	0	0	0	24
1	1	0	0	1	25
1	1	0	1	0	26
1	1	0	1	1	27
1	1	1	0	0	28
1	1	1	0	1	29
1	1	1	1	0	30
1	1	1	1	1	31

8.3.2.2 Status Word (ZSW2)

Table 8.22 Status Word (ZSW2)

	Bit	Name	Description	Notes			
	0	SE-2	Setup Group 2	1 = Setup alarm has occurred			
	1	CM-3	Cycle Modified Group 3	1 = Cycle modified alarm has occurred			
	2	WA-4	Warning Group 4	1 = Warning alarm has occurred			
	3	EQ-6	Equipment Failure Group 6	1 = Equipment failure alarm has occurred			
	4	NC-7	No Cycle Group 7	1 = No cycle alarm has occurred			
	5	CF-8	Communication Failure Group 8	1 = Communication alarm has occurred			
70,412	6	HW-A	Hardware Group A	1 = Hardware alarm has occurred			
ZSW2	7	CU-1	Cutoff Group 1	1 = Cutoff alarm has occurred			
	8	TP-9	Future Use	Not used			
	9	SM	Future Use	Not used			
	10	OFF	Ultrasonics Off and DCX Ready	1 = Ultrasonics off and DCX ready			
	11	ON	Ultrasonics Active	1 = Ultrasonics active			
	12	ок	End of Weld Cycle Without Error	1 = End cycle without error			
	13	LM-5	Limit Group 5	1 = Limit alarm has occurred			
	14	MCLR	Memory Clear	1 = Memory offset will be set to 0			
	15	RES	Reserved	Not used			

8.3.2.3 Stack Function

Table 8.23 Stack Function

Bit	Name	Test	Scan	Seek
STW2/1	SFCT	1	1	1
STW2/2	SFCT0	1	0	0
STW2/3	SFCT1	0	1	0
STW2/4	SFCT2	0	0	0

8.3.3 Process Data Channel Information for Run

 Table 8.24
 Process Data Channel Information for Run

Value		STW1 Bit														
16384d	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
103040	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Value								STW	2 Bit	t						
513d	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
513u	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	1

8.3.4 Process Data Channel Information for Seek

Table 8.25 Process Data Channel Information for Seek

Value		STW1 Bit														
16384d	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
103040	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0
		STW2 Bit														
Value								STW	2 Bit	•						
Value 514d	15	14	13	12	11	10	9	STW	2 Bit	6	5	4	3	2	1	0

8.3.5 Process Data Channel Information for Scan

Table 8.26 Process Data Channel Information for Scan

Value		STW1 Bit														
16384d	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
103040	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Value								STW	2 Bit	t						
522d	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
J22u	0	0	0	0	0	0	1	0	0	0	0	0	1	0	1	0

8.3.6 Process Data Channel Information for Reset

 Table 8.27
 Process Data Channel Information for Reset

Value		STW1 Bit														
16384d	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
103640	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0
		STW2 Bit														
Value								STW	2 Bit							
Value 256d	15	14	13	12	11	10	9	STW 8	2 Bit	6	5	4	3	2	1	0

Chapter 9: Maintenance

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9.1 General Maintenance Considerations

WARNING	High Voltage Hazard
4	Power supplies produce high voltage. To avoid the possibility of an electrical shock, you should always power down your system prior to repairing any portion of it.

CAUTION	General Warning
<u>₹</u>	When performing maintenance on the welder, make sure that no other automated systems are active.

NOTICE	
1	There are no customer replaceable components inside the power supply. Have all servicing done by a qualified Branson technician.

NOTICE	
6	When returning printed circuit boards, make sure to enclose them in an anti-static package.

NOTICE	
1	Connectors may not be keyed and wires may not be color-coded. Therefore, when disconnecting cables and wires, label them so you can reconnect them properly.



NOTICE	
1	To prevent circuit damage from electrostatic discharge, always service the power supply on a static-dissipative surface, while wearing a properly grounded wrist strap.

NOTICE	
1	When the battery is worn out, dispose it under the ordinance of each local government.

9.2 DCX F-DP Power Supply Preventive Maintenance

The following preventive measures help assure long term operation of your Branson DCX F-DP Power Supply equipment.

9.2.1 Periodically Clean the Equipment

NOTICE	
1	Use only anti-static vacuum cleaners to prevent damage from electrostatic discharge to your power supply.

Air is continuously drawn into the power supply. Periodically disconnect the unit from power, remove the cover and vacuum out any accumulated dust and debris. Remove material adhering to:

- Power supply heat sink cooling fins
- Transformers
- · Circuit boards
- Cooling intake vents
- Exhaust ports

External covers may be cleaned with a damp sponge or cloth using a solution of mild soap and water. Do not allow cleaning solution to enter the unit.

To prevent rust in areas of high humidity, exposed steel surfaces, may require a very light film of rust preventing oil, such as WD-40 \mathbb{R}^* .

* WD-40 is a registered trademark of WD-40 Manufacturing Company.

9.2.2 Recondition the Stack (Converter, Booster, and Horn)

NOTICE	
1	Never clean the converter-booster-horn stack mating surfaces by using a buffing wheel or by filing.

Welding system components work most efficiently when the converter-booster-horn stack mating surfaces are flat, in solid contact, and free from fretting corrosion. Poor contact between mating surfaces wastes power output, makes tuning difficult, increases noise and heat, and may cause damage to the converter.

For standard 20 kHz and 30 kHz products, a Branson Mylar polyester film washer should be installed between the horn and booster, and horn and converter. Replace the washer if torn or perforated. Stacks using Mylar plastic film washers should be inspected every three months.

Stacks used with silicone grease, as with certain 20 kHz, 30 kHz and all 40 kHz products, should be periodically reconditioned to eliminate fretting corrosion. A stack using silicone grease should be inspected every two weeks for corrosion. When experience is gained for specific stacks, the inspection interval can be adjusted to a longer or shorter period as required.

Stack Reconditioning Procedure

To recondition stack mating surfaces, take the following steps:

Table 9.1 Stack Reconditioning Procedure

Step	Action		
1	Disassemble the converter-booster-horn stack and wipe the mating surfaces with a clean cloth or paper towel.		
2	Examine all mating surfaces. If any mating surface shows corrosion or a hard, dark deposit, recondition it.		
3	If necessary, remove the threaded stud from the part.		
4	Tape a clean sheet of #400 (or finer) grit emery cloth to a clean, smooth, flat surface (such as a sheet of plate glass), as in Figure 9.1 Reconditioning Stack Mating Surfaces.		
5	Place the interface surface on the emery cloth. Grasp the part at the lower end, with your thumb over the spanner-wrench hole, and lap the part in a straight line across the emery cloth. Do not apply downward pressure — the weight of the part alone provides sufficient pressure.		
6	Lap the part, two or three times, in the same direction against the emery cloth. (See <u>Figure 9.1 Reconditioning Stack Mating Surfaces</u>).		
7	Rotate the part 120 degrees, placing your thumb over the spanner-wrench hole, and repeat the lapping procedure in step 6.		

Table 9.1 Stack Reconditioning Procedure

Step	Action		
8	Rotate the part another 120 degrees to the next spanner-wrench hole, and repeat the lapping procedure in step 6.		
9	Re-examine the mating surface. If necessary, repeat steps 2-5 until you remove most of the contaminant. Remember, this should not require more than two to three complete rotations for an aluminum horn or booster; a titanium component may require more rotations.		
	Before re-inserting a threaded stud in an aluminum booster or horn:		
	Using a file card or wire brush, clean any aluminum bits from the knurled end of the stud.		
	Using a clean cloth or towel, clean the threaded hole.		
10	Examine the knurled end of the stud. If worn, replace the stud. Also, examine the stud and threaded hole for stripped threads.		
	Threaded studs cannot be reused in titanium horns or boosters. Replace all studs in these components.		
11	Assemble and install the stack.		

Figure 9.1 Reconditioning Stack Mating Surfaces

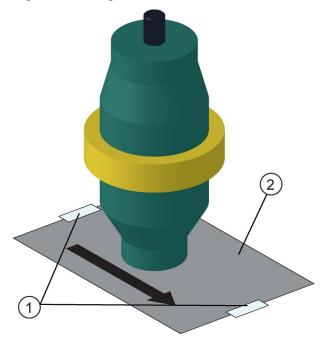


 Table 9.2
 Reconditioning Stack Mating Surfaces

Item	Description
1	Таре
2	#400 Emery Cloth

9.2.3 Stack Torque Values

Table 9.3 Stack Torque Values

Frequency	Torque
20 kHz	220 in·lb (25 N·m)
30 kHz	185 in·lb (21 N·m)
40 kHz	95 in·lb (11 N·m)

For a 20 kHz System

Table 9.4 Stack Reassembly for a 20 kHz System

Step	Action
1	Clean the mating surfaces of the converter, booster, and horn. Remove any foreign material from the threaded holes.
2	Install the threaded stud into the top of the booster. Torque to 450 in·lb (50.84 N·m). If the stud is dry, apply 1 or 2 drops of a light lubricating oil before installing.
3	Install the threaded stud into the top of the horn. Torque to 450 in·lb (50.84 N·m). If the stud is dry, apply 1 or 2 drops of a light lubricating oil before installing.
4	Install a single Mylar plastic film washer (matching the size of the washer to the stud) to each interface.
5	Assemble the converter to the booster and the booster to the horn.
6	Torque to 220 in·lb (24.85 N·m) at each interface.



For a 30 kHz System

Table 9.5 Stack Reassembly for a 30 kHz System

Step	Action
1	Clean the mating surfaces of the converter, booster, and horn. Remove any foreign material from the threaded holes.
2	Install the threaded stud into the top of the booster. Torque to 290 in·lb (32.76 N·m). If the stud is dry, apply 1 or 2 drops of a light lubricating oil before installing.
3	Install the threaded stud into the top of the horn. Torque to 290 in·lb (32.76 N·m). If the stud is dry, apply 1 or 2 drops of a light lubricating oil before installing.
4	Install a single Mylar plastic film washer (matching the size of the washer to the stud) to each interface.
5	Assemble the converter to the booster and the booster to the horn.
6	Torque to 185 in·lb (21 N·m) at each interface.

For a 40 kHz System

Table 9.6 Stack Reassembly for a 40 kHz System

Step	Action
1	Clean the mating surfaces of the converter, booster, and horn. Remove any foreign material from the threaded holes.
2	Apply a drop of Loctite®* 290 threadlocker (or equivalent) to the studs for the booster and horn.
3	Install the threaded stud into the top of the booster. Torque to 70 in·lb (7.91 N·m). Remove excess Loctite 290 threadlocker from the booster face and let cure for 30 minutes.
4	Install the threaded stud into the top of the horn. Torque to 70 in·lb (7.91 N·m). Remove excess Loctite 290 threadlocker from the horn face and let cure for 30 minutes.
5	Coat each interface surface with a thin film of silicon grease - but do not apply silicon grease to a threaded stud or tip.
6	Torque to 95 in·lb (10.73 N·m) at each interface.

^{*} Loctite is a registered trademark of Henkel Corporation, U.S.A.

9.2.4 Stud Torque Values

Table 9.7 Stud Torque Values

Used on	Stud Size	Torque	EDP#
20 kHz	1/2 in x 20 x 1-1/4 in	450 in·lb, 50.84 N·m	100-098-370
	1/2 in x 20 x 1-1/2 in		100-098-123
30 kHz	3/8 in x 24 x 1 in	290 in·lb, 32.76 N·m	100-298-170R
40 kHz*	M8X1.25 X 20 (40 kHz horns and boosters)	70 in·lb, 7.91 N·m	100-098-790

st Add a drop of Loctite 290 threadlocker to the stud. Torque and let cure for 30 minutes before using.

9.3 Recommended Spare Stock

This section provides lists of replacement parts, system cables, and suggested spares.

9.3.1 System Cables

You can order the following cables:

Table 9.8DCX F-DP Power Supply System Cables

P/N	Description
100-240-383	Cable, RF 8 ft (2.5 m)
100-240-384	Cable, RF 15 ft (4.5 m)
100-240-385	Cable, RF 25 ft (7.5 m)
100-240-387	Cable, RF right angle 8 ft (2.5 m)
100-240-388	Cable, RF right angle 15 ft (4.5 m)
100-240-389	Cable, RF right angle 25 ft (7.5 m)
100-240-392	Cable, User I/O 25 ft (7.5 m)
100-240-393	Cable, User I/O 50 ft (15 m)
200-240-396	Cable Ethernet Cat 5e 7 ft (2.1 m)

9.3.2 Suggested Spares

Table 9.9 Suggested Spares

Description	EDP#	1-4 Units	6-12 Units	14+ Units
Converter	Refer to Table 9.10 Converters Compatible with the DCX F-DP Power Supply.	0	1	2
Booster	Refer to Table 9.11 DCX F-DP Power Supply Compatible Boosters.	0	1	2
Horn	As Ordered	1	1	2
Studs	Refer to Table 9.12 Other Items used with the DCX F-DP Power Supply.	4	6	8
Mylar Plastic Film Washer Kit	Refer to Table 9.12 Other Items used with the DCX F-DP Power Supply.	1	1	1



9.3.3 Converters Compatible with the DCX F-DP Power Supply

 Table 9.10
 Converters Compatible with the DCX F-DP Power Supply

Where used	Model	Connector	Part Number
	CR-20S	SHV connector	125-135-115R
	CR-20C	SHV connector with 3 ft (0.9 m) cable	159-135-210R
20 kHz / 1250 W 20 kHz / 2500 W	CH-20S (932 AH SPL)	SHV connector	159-135-075R
20 kHz / 4000 W	CH-20C	SHV connector with 3 ft (0.9 m) cable	159-135-211R
	CS-20S	SHV connector	159-135-138R
	CS-20C	SHV connector with 3 ft (0.9 m) cable	159-135-209R
	CR-30S	SHV connectors	101-135-081R
	CR-30C	SHV connector with 3 ft (0.9 m) cable	159-135-213R
	CH-30S	SHV connector	101-135-071R
30 kHz / 1500 W	CH-30C	SHV connector with 3 ft (0.9 m) cable	159-135-214R
	CS-30S	SHV connector	159-135-110R
	CS-30C	SHV connector with 3 ft (0.9 m) cable	159-135-212R
40 kHz / 800 W	4TP	SHV connector (platen mount)	101-135-068R
	CR-40S (4TH)	SHV connector	101-135-067R
	CR-40C	SHV connector with 3 ft (0.9 m) cable	159-135-215R



9.3.4 DCX F-DP Power Supply Compatible Boosters

Table 9.11 DCX F-DP Power Supply Compatible Boosters

Type of Booster	Description	Part Number
	Titanium, 1:0.6 (Purple)	101-149-095
Solid Mount	Titanium, 1:1 (Green)	101-149-096
(1/2-20 horn stud)	Titanium, 1:1.5 (Gold)	101-149-097
20 kHz	Titanium, 1:2 (Silver)	101-149-098
	Titanium, 1:2.5 (Black)	101-149-099
	Titanium, 1:0.6 (Purple)	109-041-178
Solid Mount	Titanium, 1:1 (Green)	109-041-177
(M8 x 1.25 horn stud)	Titanium, 1:1.5 (Gold)	109-041-176
40 kHz	Titanium, 1:2 (Silver)	109-041-175
	Titanium, 1:2.5 (Black)	109-041-174
	Aluminum, 1:0.6 (Purple)	101-149-055
	Aluminum, 1:1 (Green)	101-149-051
	Aluminum, 1:1.5 (Gold)	101-149-052
Standard Series	Aluminum, 1:2 (Silver)	101-149-053
(1/2-20 horn stud)	Titanium, 1:0.6 (Purple)	101-149-060
20 kHz	Titanium, 1:1 (Green)	101-149-056
	Titanium, 1:1.5 (Gold)	101-149-057
	Titanium, 1:2 (Silver)	101-149-058
	Titanium, 1:2.5 (Black)	101-149-059
Standard Series	Titanium, 1:2.5 (Black)	101-149-103
	Titanium, 1:2 (Silver)	101-149-104
(3/8-24 horn stud) 30 kHz	Titanium, 1:1.5 (Gold)	101-149-105
30 KHZ	Titanium, 1:1 (Green)	101-149-106

 Table 9.11
 DCX F-DP Power Supply Compatible Boosters

Type of Booster	Description	Part Number
	Aluminum, 1:0.6 (Purple)	101-149-087
	Aluminum, 1:1 (Green)	101-149-079
	Aluminum, 1:1.5 (Gold)	101-149-080
Standard Series (M8 x 1.25 horn stud)	Aluminum, 1:2 (Silver)	101-149-081R
	Aluminum, 1:2.5 (Black)	101-149-082
40 kHz	Titanium, 1:1 (Green)	101-149-085
	Titanium, 1:1.5 (Gold)	101-149-086
	Titanium, 1:2 (Silver)	101-149-083
	Titanium, 1:2.5 (Black)	101-149-084



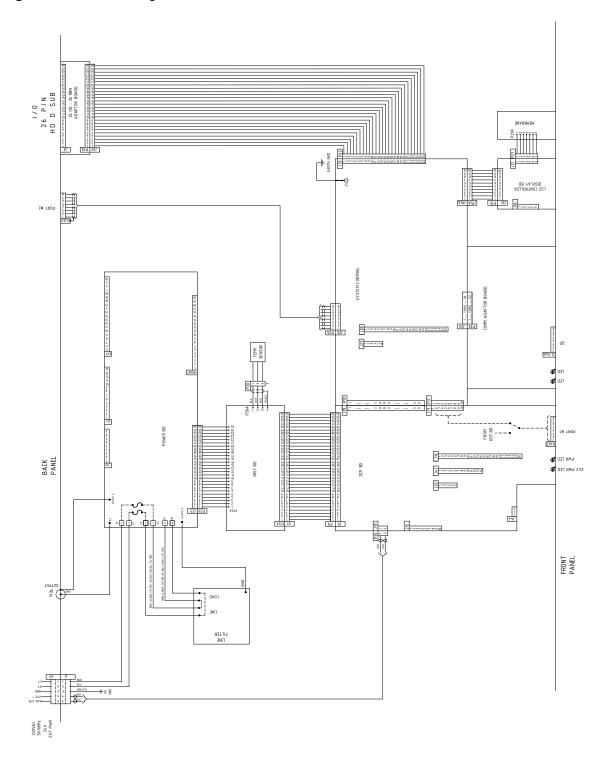
9.3.5 Other Items used with the DCX F-DP Power Supply

Table 9.12 Other Items used with the DCX F-DP Power Supply

Product	Description	Part No.
Silicone grease	For use with 40 kHz systems	101-053-002
Mular Plactic Film Washers	Kit, 10 each (1/2 in. and 3/8 in.)	100-063-357
Mylar Plastic Film Washers (for 20 kHz systems)	Kit, 150 each (1/2 in.)	100-063-471
(101 20 KH2 Systems)	Kit, 150 each (3/8 in.)	100-063-472
Mylar Plastic Film Washers	Kit, 10 each (3/8 in.)	100-063-632
(for 30 kHz systems)	Kit, 150 each (3/8 in)	100-063-712
	20 kHz (spanner wrench and 10 pc washer kit)	101-063-208R
Tool Kit	30 kHz (spanner wrench and 10 pc washer kit)	101-063-636R
	40 kHz (spanner wrench and silicone grease)	101-063-176R
	20 kHz	101-118-039
Spanner wrench	30 kHz	201-118-033
	40 kHz	201-118-024
	1/2-20 x 1-1/4 (titanium horns)	100-098-370
Studs	1/2-20 x 1-1/2 (aluminum horns, 20 kHz boosters)	100-098-123
	3/8-24 x 1 (30 kHz titanium horns and boosters)	100-298-170R
	M8X1.25 X 20 (40 kHz horns and boosters)	100-098-790

9.4 Circuit Diagram

Figure 9.2 Circuit Diagram





9.5 Troubleshooting

If you have a problem operating the DCX F-DP Power Supply, take the following steps:

Table 9.13 Troubleshooting

Step	Action
1	Make sure the converter-booster-horn stack is properly assembled and installed.
2	For instructions on reconditioning stack component surfaces, refer to 9.2.2 Recondition the Stack (Converter, Booster, and Horn).
3	If you need additional help, call your local Branson representative, refer to 1.3 How to Contact Branson.

NOTICE	
1	DCX F-DP Power Supply should be serviced only by qualified technicians using Branson-approved test and repair equipment, repair procedures, and replacement parts. Unauthorized attempts at repair or modification of the power supply will void the warranty.



9.5.1 Common Electrical Problems

Table 9.14 Troubleshooting Common Electrical Problems

Problem	Check	Solution
When touching a component of the weld system, you get a	Ensure the Ground cable is connected properly.	N/A
slight electrical shock.	Inspect the line cables.	If failed, repair or replace.



9.5.2 Ultrasonic Power Problems

Table 9.15 Troubleshooting Ultrasonic Power Problems

Problem	Check	Solution
Ultrasonic power delivered to horn; no	Check connector cables, replace if failed.	Replace defective cables.
indication on bar graph.	Test power supply.	See <u>7.8 Ultrasonics Test</u> <u>Procedure</u> .
	Failed or missing stack.	Replace.
No ultrasonic power generated when Test key pressed; no Alarm indicator.	RF cable unplugged or failed; replace if failed.	Plug in or replace.
	Test power supply (<u>7.8</u> <u>Ultrasonics Test Procedure</u>).	If defective, send unit for repair.
Unable to adjust amplitude using the front panel keypad.	Register setting configured to "External Amplitude Control"	Reset if required, See 7.5 Configuring the Power Supply Registers.
Unable to remote control.	User fieldbus or I/O cabling	Repair or replace.
	Customer's switching device	Test/inspect/repair/ replace.



9.5.3 Weld Cycle Problems

Table 9.16 Troubleshooting Weld Cycle Problems

Problem	Check	Solution	
	Unsuitable horn or booster selection.		
	Plastic part material varies.		
Full ultrasonic power not delivered.	Mold release lubricant in weld area.	Contact Branson Applications Lab	
not delivered.	Unsuitable joint design.		
	Unsuitable or misaligned part fixture.		
	Amplitude setting	Adjust if required.	
No ultrasonic power passed to horn.	Power supply overheating.	If defective, send unit for repair.	
	Check converter-booster-horn stack interface for fretting corrosion.	See 9.2.2 Recondition the Stack (Converter, Booster, and Horn).	
Alarm indicator illuminates when you press the Test key or	Check for loose or failed horn converter or booster.	Tighten or replace as peeded	
during the weld cycle.	Check for loose or failed horn or booster stud.	Tighten or replace as needed.	
	Failed RF cable.	Replace if failed.	
Excessively warm horn, booster, and converter; occasional overloads.	Check converter-booster-horn stack mating surfaces for fretting corrosion.	See 9.2.2 Recondition the Stack (Converter, Booster, and Horn).	
	Be certain proper cooling has been provided.	If defective, send unit for repair.	

9.6 Cold Start Procedure

The power supply internal memory stores the system default settings and the registers that you set. It also provides temporary storage to support the power supply internal functions. A cold start clears and restores all the power supply settings back to the original factory defaults. It is not necessary to perform a cold start during normal operation and servicing, but you might find a cold start helpful when:

- You suspect the system is not operating properly
- · You want to make a new setup
- Some system memory registers, such as Software version, will not be cleared by this Cold Start procedure

9.6.1 Performing a Cold Start

NOTICE	
1	Using the Cold Start procedure will erase the current Amplitude Setting, the IP address and some of the Registers that you set. Be sure you have a record of your setup if you want to retain it or use the system backup feature from the DCX F-DP Power Supply Web Page Interface.

 Table 9.17
 Steps to Perform a Cold Start

Step	Action
1	Turn off the power supply.
2	Connect together pins 4 and 10 on the 26-pin User I/O Connector.
3	Turn on the power supply.
4	After the power up sequence ends, turn off the power supply.
5	Disconnect pins 4 and 10 of the 26-pin on User I/O Connector.

Appendix A: Communication Channel Alarms

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A.1 Overload Alarms (Group 0)

This group includes all overload alarms that can occur during a weld cycle. This overload group will abort the weld cycle after stopping the sonics.

Table A.1 Overload Alarms (Group 0)

LCD Alarm Code	Fieldbus Bit Assignment	Alarm	Description
E0:01	Bit01	Weld Overload - Phase	This alarm is generated in case of weld phase is out of weld phase limit for weld phase limit time period.
E0:02	Bit02	Weld Overload - Current	This alarm is generated in case of weld current reaches to peak RF current limit of the system.
E0:03	Bit03	Weld Overload - Frequency	This alarm is generated in case of weld frequency is out of weld frequency low and high limit window.
E0:04	Bit04	Weld Overload - Power	This alarm is generated in case of weld power reaches to peak RF power limit of the system.
E0:05	Bit05	Weld Overload - Voltage	This alarm is generated in case of voltage during weld reaches to peak RF voltage limit of the system.
E0:06	Bit06	Weld Overload - Temperature	This alarm is generated in case of temperature inside the system (at the heat sink) reaches to 85° C (±5° C). NOTICE Alarm cannot be cleared until the temperature returns below threshold.
E0:11	Bit17	Energy Brake Overload - Phase	This alarm is generated in case of phase is out of weld phase limit for weld phase limit time period during energy breaking.
E0:12	Bit18	Energy Brake Overload - Current	This alarm is generated in case of weld current reaches to peak RF current limit of the system during energy breaking.
E0:13	Bit19	Energy Brake Overload - Frequency	This alarm is generated in case of weld frequency is out of weld frequency low and high limit window during energy breaking.



Table A.1 Overload Alarms (Group 0)

LCD Alarm Code	Fieldbus Bit Assignment	Alarm	Description
E0:14	Bit20	Energy Brake Overload - Power	This alarm is generated in case of weld power reaches to peak RF power limit of the system during energy breaking.
E0:15	Bit21	Energy Brake Overload - Voltage	This alarm is generated in case of voltage during weld reaches to peak RF voltage limit of the system during energy breaking.
E0:16	Bit22	Energy Brake Overload - Temperature	This alarm is generated in case of temperature inside the system (at the heat sink) reaches to 85° C (±5° C) during energy breaking. NOTICE Alarm cannot be cleared until the temperature returns below threshold.

A.2 Cutoff Alarms (Group 1)

This groups includes all cutoff alarms. Cutoff alarms are defined as a limit on a parameter, that when exceeded, will stop ultrasonics. The remaining portion of a weld cycle will continue.

Table A.2 Cutoff Alarms (Group 1)

LCD Alarm Code	Fieldbus Bit Assignment	Alarm	Description
E1:02	Bit02	Energy Cutoff	Energy cutoff alarm is generated if the energy value during sonics on exceeded to the set cutoff value during a weld.
E1:03	Bit03	Power Cutoff	Power cutoff alarm is generated if the peak power value during sonics on exceeded to the set cutoff value.
E1:04	Bit04	Custom Input1 Cutoff	User can configure one of the user analog input as a Custom Input1 and also set a cutoff value from that input. System will generate custom Input1 Cutoff alarm if the user input voltage exceeds from the cutoff value set by user.
E1:05	Bit05	Time Cutoff (Maximum Time-out)	User can set a time cutoff for weld and the alarm will be generated if the sonic on time during weld exceeds to the set value.
E1:06	Bit06	Frequency Low Cutoff	User can set frequency low cutoff (negative offset to be applied from weld start frequency) for weld and the alarm will be generated if the frequency during weld goes below to the weld start frequency minus set value.
E1:07	Bit07	Frequency High Cutoff	User can set frequency high cutoff (positive offset to be applied from weld start frequency) for weld and the alarm will be generated if the frequency during weld goes above to the weld start frequency plus set value.
E1:08	Bit08	Custom Input2 Cutoff	User can configure one of the user analog input as a Custom Input2 and also set a cutoff value from that input. System will generate Custom Input2 cutoff alarm if the user input voltage exceeds from the cutoff value set by user.



A.3 Setup Alarms (Group 2)

This group includes all alarms that can occur during setup.

Table A.3 Setup Alarms (Group 2)

LCD Alarm Code	Fieldbus Bit Assignment	Alarm	Description
E2:03	Bit02	Invalid Preset	Recalling invalid preset. Preset > 32.

A.4 Cycle Modified Alarms (Group 3)

Cycle modified alarms cause the cycle to be modified from the intended parameters. This can be caused by the user or equipment conditions changing. This group of alarms will always abort the cycle.

Table A.4 Cycle Modified Alarms (Group 3)

LCD Alarm Code	Fieldbus Bit Assignment	Alarm	Description
E3:01	Bit01	Trigger Lost During Weld Or Hold	This alarm is generated during a weld cycle in case actuator is present and trigger input is lost before completing the weld (in case of time, energy, peak power and ground detect mode).
E3:02	Bit02	Cycle Aborted Via User I/O	This alarm is generated if user aborts the cycle using cycle abort user input.



A.5 Warning Alarms (Group 4)

Warnings occur when a condition is happening that may have been unexpected. This group of alarms does not abort the cycle. This group includes overloads during afterburst because they do not abort the cycle.

Table A.5 Warning Alarms (Group 4)

LCD Alarm Code	Fieldbus Bit Assignment	Alarm	Description
E4:04	Bit04	Amplitude Step Not Reached	This alarm is generated if Amplitude Stepping is ON but weld cycle finishes before stepping take places.
E4:05	Bit05	Sonics Disabled Via User I/O	This alarm indicates the user has enabled an input pin as "Sonics Disable" and has run a cycle with this input active.
E4:11	Bit17	Afterburst Overload - Phase	This alarm is generated in case of afterburst phase is out of Weld Phase limit for Weld Phase limit time period.
E4:12	Bit18	Afterburst Overload - Current	This Alarm is generated in case of weld current reaches to peak RF current limit of the system during afterburst.
E4:13	Bit19	Afterburst Overload - Frequency	This alarm is generated in case of Weld Frequency is out of Weld Frequency Low and High limit window during afterburst.
E4:14	Bit20	Afterburst Overload - Power	This alarm is generated in case of weld power reaches to peak RF power limit of the system during afterburst.
E4:15	Bit21	Afterburst Overload - Voltage	This alarm is generated in case of weld voltage reaches to peak RF voltage limit of the system during afterburst.
E4:16	Bit22	Afterburst Overload - Temperature	The internal heat sink temperature is greater than allowed. NOTICE Alarm cannot be cleared until
			the temperature returns below threshold.

A.6 Limit Alarms (Group 5)

Limits will be reported at the end of the weld, but, unlike cutoffs, will not stop the sonics or abort the cycle.

Table A.6 Limit Alarms (Group 5)

LCD Alarm Code	Fieldbus Bit Assignment	Alarm	Description
E5:03	Bit03	Power - Minus Limit	This alarm is generated at the end of the cycle in case of Weld peak power is lower than the Power Minus limit.
E5:04	Bit04	Power - Plus Limit	This alarm is generated at the end of the cycle in case of Weld peak power is bigger than the Power Plus limit.
E5:05	Bit05	Time - Minus Limit	This alarm is generated at the end of the cycle in case of Weld time is lower than the Time Minus limit.
E5:06	Bit06	Time - Plus Limit	This alarm is generated at the end of the cycle in case of Weld time is bigger than the time Plus limit.
E5:07	Bit07	Energy - Minus Limit	This alarm is generated at the end of the cycle in case of Weld energy is lower than the energy Minus limit.
E5:08	Bit08	Energy - Plus Limit	This alarm is generated at the end of the cycle in case of Weld energy is bigger than the energy Plus limit.



A.7 Equipment Failure Alarms (Group 6)

Equipment alarms are caused by user equipment malfunction. These alarms occur before a cycle starts and therefore, will prevent a cycle from starting until the malfunction is corrected.

NOTICE	
1	Alarm message will not reset until the malfunction is corrected.

Table A.7 Equipment Failure Alarms (Group 6)

LCD Alarm Code	Fieldbus Bit Assignment	Alarm	Description
E6:01	Bit01	Start Input Still Active	This alarm is generated if External Start/Cycle Start/Trigger signal is active for more than 4 seconds after finishing the weld or while system is waiting to come into ready state.
E6:02	Bit02	Trigger Active While ULS Active	This alarm is generated any time if Trigger and ULS both becomes active.
E6:03	Bit03	Trigger Active In Ready	This alarm is generated if Trigger signal becomes active while system is in ready state and actuator is present.
E6:04	Bit04	ULS Not Active In Ready	This alarm is generated if actuator is present and ULS is not active while system is already in ready state.
E6:05	Bit05	Ground Detect Active In Ready	This alarm is generated if ground detect signal becomes active while system is in ready state.
E6:07	Bit07	Cable Failure - User I/O	The cable detect user I/O feature has been enabled and detected that the assigned pin does not have the voltage applied.
E6:08	Bit08	Field Bus Removed	Communication between the internal field bus card and the internal weld controller has failed.
E6:09	Bit09	Start Input Lost	This alarm is generated when source of cycle start is removed before Trigger comes.

Table A.7 Equipment Failure Alarms (Group 6)

LCD Alarm Code	Fieldbus Bit Assignment	Alarm	Description
E6:10	Bit16	Cycle Abort In Ready	This alarm is generated if Cycle Abort signal becomes active while system is in ready state.
E6:11	Bit17	ULS Time Out	This alarm is generated if Actuator is present and ULS does not become active with a time-out at the end of the cycle.
E6:12	Bit18	ULS Active During Weld	This alarm is generated if System is waiting for TRS and ULS becomes active. After TRS is active and system jumps to next state of cycle this alarm is generated when ULS becomes active during cycle along with "TRS active while ULS Active" alarm.



A.8 No Cycle Alarms (Group 7)

No cycle alarms are caused by possible mechanical setup errors or user errors. These are usually time out errors because an expected input did not occur in time. They will prevent a cycle from continuing. So although a cycle may have started, the cycle will be aborted.

Table A.8 No Cycle Alarms (Group 7)

LCD Alarm Code	Fieldbus Bit Assignment	Alarm	Description
E7:01	Bit01	ULS Time-Out (Start Of Cycle)	A cycle start has been received but the upper limit switch has not gone inactive within the time-out specified by the system.
E7:02	Bit02	Trigger Time-Out	A cycle has been started, but the trigger input has not gone active within the time-out specified by the system.
E7:03	Bit03	External Sonics Delay Time-Out (User I/O)	The system is waiting for an external user defined input (if configured), but has not received the input within the time-out specified by the system.
E7:04	Bit04	Interlock Not In Place (User I/O)	The system is waiting for a valid status from a user defined Interlock input (if configured), but the input is not active at the time of Cycle start.
E7:05	Bit05	RF Switch Feedback Failure	A feedback signal from the RF switch not was not received within the time specified by the user.
E7:06	Bit06	Part Not In Place (User I/O)	The system is waiting for an external user defined input, but the input is not active at the Cycle Start.
E7:07	Bit07	Stack Number Not Valid For RF Switching	An invalid horn number is being requested from the preset. Any values outside the range of 16 horn numbers will cause an alarm.



A.9 Communication Failure Alarms (Group 8)

This group handles any communication issue that occur between processors. This is generally the result of noisy environments or other conditions that interrupt communications. Physical cable failures will be included in the Hardware Failure group. Because data cannot be transmitted between internal hardware, the cycle will be aborted.

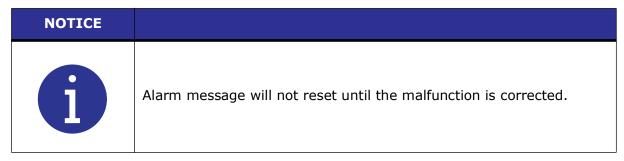


Table A.9 Communication Failure Alarms (Group 8)

LCD Alarm Code	Fieldbus Bit Assignment	Alarm	Description
E8:01	Bit01	Modbus Communication Failure	Internal communication failure.
E8:02	Bit02	LCD Communication Failure	Communication between the LCD user interface and the internal weld controller has failed.
E8:03	Bit03	Fieldbus Communication Failure	The field bus was detected at power on, but is no longer responding. Either the cable has been removed or the field bus master has stop working. If the system is powered down and field bus is not detected at power up, then the system can still be used without the field bus.



A.10 Hardware Alarms (Group A)

This group of alarms will deal with internal equipment failures. This will generally be equipment that is supplied by Branson as part in the internal workings of the power supply. Cycles cannot be started if there is a Hardware alarm. If a cycle is in process when the alarm is detected then the cycle is aborted.

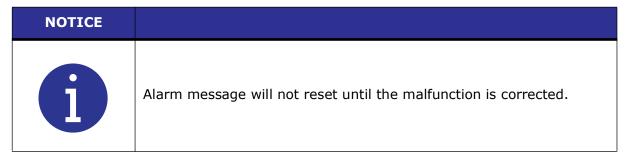


Table A.10 Hardware Alarms (Group A)

LCD Alarm Code	Fieldbus Bit Assignment	Alarm	Description
EA:01	Bit01	LCD NOVRAM Failure	LCD NOVRAM is not working.
EA:02	Bit02	FRAM or NOVRAM Failure	FRAM or NOVRAM is not working.
EA:03	Bit03	SD RAM Failure	SD RAM is now working.
EA:04	Bit04	Connection Failure - WC to LCD	The physical connection between the WC board and LCD board is missing or broken.
EA:05	Bit05	Connection Failure - WC to DCP	The physical connection between the WC board and DCP board is missing or broken.
EA:06	Bit06	AC Line Voltage Lost	The AC line voltage to the system is lost but the 24 V supply is still present.
			ES bit activated, check ZSW1 Low Byte.



A.11 Non-Cycle Overload Alarms (Group B)

This group deals with overloads that occur outside of a weld cycle. By definition a weld is not in process so the weld cycle counter is not affected and the weld is not aborted.

Table A.11 Non-Cycle Overload Alarms (Group B)

LCD Alarm Code	Fieldbus Bit Assignment	Alarm	Description
Eb:01	Bit01	Seek Overload - Phase	This alarm is generated in case of phase during Seek reaches to peak RF phase limit of the system.
Eb:02	Bit02	Seek Overload - Current	This alarm is generated in case of current during Seek reaches to peak RF current limit of the system.
Eb:03	Bit03	Seek Overload - Frequency	This alarm is generated in case of Frequency during seek is out of Seek Frequency Low and High limit window.
Eb:04	Bit04	Seek Overload - Power	This alarm is generated in case of Power during seek reaches to peak RF Power limit of the system.
Eb:05	Bit05	Seek Overload - Voltage	This alarm is generated in case of Voltage during seek reaches to peak RF voltage limit of the system.
Eb:06	Bit06	Seek Overload - Temperature	This alarm is generated in case of temperature inside the system (at the heat sink) reaches to 85° C (±5° C) during Seek. NOTICE Alarm cannot be cleared until the temperature returns below threshold.
Eb:11	Bit17	Test Overload - Phase	This alarm is generated in case of phase during Test reaches to peak RF phase limit of the system.
Eb:12	Bit18	Test Overload - Current	This alarm is generated in case of current during Test reaches to peak RF current limit of the system.
Eb:13	Bit19	Test Overload - Frequency	This alarm is generated in case of Frequency during seek is out of Test Frequency Low and High limit window.



Table A.11 Non-Cycle Overload Alarms (Group B)

LCD Alarm Code	Fieldbus Bit Assignment	Alarm	Description
Eb:14	Bit20	Test Overload - Power	This alarm is generated in case of Power during Test reaches to peak RF Power limit of the system.
Eb:15	Bit21	Test Overload - Voltage	This Alarm is generated in case of Voltage during Test reaches to peak RF voltage limit of the system.
Eb:16	Bit22	Test Overload - Temperature	This alarm is generated in case of temperature inside the system (at the heat sink) reaches to 85° C (±5° C) during Test. NOTICE Alarm cannot be cleared until the temperature returns below threshold.

Appendix B: Communication Channel Commands

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B.16	Version, System, & RTC Information
B.17	System Configuration Parameters

B.1 Weld Parameters

Table B.1 Weld Parameters

DALL	Description	Data	AK	TNID		PWE		- Format	Unit
PNU	Description	Туре	AK	IND	Default	Min.	Max.	Format	Unit
1010	Preset Name (Character 1)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1011	Preset Name (Character 2)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1012	Preset Name (Character 3)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1013	Preset Name (Character 4)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1014	Preset Name (Character 5)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1015	Preset Name (Character 6)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1016	Preset Name (Character 7)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1017	Preset Name (Character 8)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1018	Preset Name (Character 9)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1019	Preset Name (Character 10)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1020	Preset Name (Character 11)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1021	Preset Name (Character 12)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1022	Preset Name (Character 13)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1023	Preset Name (Character 14)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1024	Preset Name (Character 15)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1025	Preset Name (Character 16)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1026	Preset Name (Character 17)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1027	Preset Name (Character 18)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1028	Preset Name (Character 19)	AINT8	R: 4 W:10	031/32	64	32	128	-	-
1029	Preset Name (Character 20)	AINT8	R: 4 W:10	031/32	64	32	128	-	-

Table B.1 Weld Parameters

		Data				PWE		_	
PNU	Description	Туре	AK	IND	Default	Min.	Max.	Format	Unit
1040	Horn Number assigned to a preset	AUINT8	R: 1 W: 7	031/32	0	0	15	-	-
1060	Weld Mode (Function Mode) (0=Continous, 1=Time, 2=Energy, 3=Peak Power, 4=Ground Detect)	AINT32	R: 6 W: 12	031/32	0	0	4		
1061	Time	AINT32	R: 6 W: 12	031/32	10	10	30000		ms
1062	Energy (Value should be entered 10 times higher)	AINT32	R: 6 W: 12	031/32	10	1	99990		0.1xJ
1063	Peak Power	AINT32	R: 6 W: 12	031/32	1	1	100		%
1064	Ground Detect Time	AINT32	R: 6 W: 12	031/32	1	0	500		ms
1065	Amplitude 1	AINT32	R: 6 W: 12	031/32	100	10	100		%
1066	Amplitude 2	AINT32	R: 6 W: 12	031/32	100	10	100		%
1067	Amplitude Profile Criterion (0=Fix, 1=External analog in, 2=Step@Time, 3=Step@Energy, 4=Step@Power, 5=Step@External)	AINT32	R: 6 W: 12	031/32	0	0	5	Selection	-
1068	Amplitude Profile Time	AINT32	R: 6 W: 12	031/32	10	1	30000		ms
1069	Amplitude Profile Energy (Value should be entered 10 times higher)	AINT32	R: 6 W: 12	031/32	10	1	99990		0.1xJ
1070	Amplitude Profile Peak Power	AINT32	R: 6 W: 12	031/32	1	1	100		%
1071	Amplitude Start Ramp Time	AINT32	R: 6 W: 12	031/32	80	10	1000		ms
1072	Amplitude Profile Ramp Time	AINT32	R: 6 W: 12	031/32	80	10	1000		ms
1073	Frequency Resonance Store At End	AINT32	R: 6 W: 12	031/32	1	0	1	Selection	
1074	Frequency Offset (Relative)	AINT32	R: 6 W: 12	031/32	0	-500	500		Hz
1075	Hold Time	AINT32	R: 6 W: 12	031/32	10	10	30000	0=OFF	ms
1076	Energy Breaking	AINT32	R: 6 W: 12	031/32	1	0	1	Selection	
1077	EB Target Amplitude	AINT32	R: 6 W: 12	031/32	3	1	100		%
1078	EB Time	AINT32	R: 6 W: 12	031/32	20	10	1000		ms

Table B.1 Weld Parameters

B. S. C.		Data		****		PWE		Format	
PNU	Description	Туре	AK	IND	Default	Min.	Max.	Format	Unit
1079	After Burst	AINT32	R: 6 W: 12	031/32	1	0	1	Selection	
1080	AB Amplitude	AINT32	R: 6 W: 12	031/32	100	10	100		%
1081	AB Time	AINT32	R: 6 W: 12	031/32	100	100	2000		ms
1082	AB Delay	AINT32	R: 6 W: 12	031/32	100	100	2000		ms
1083	Reserved	'	'	•	•	!	1	1	
1084	Scrub Amplitude	AINT32	R: 6 W: 12	031/32	100	10	100		%
1085	Reserved								
1086	Time Error High (Cutoff)	AINT32	R: 6 W: 12	031/32	6000	10	30000	0=OFF	ms
1087	Energy Error High (Cutoff) (Value should be entered 10 times higher)	AINT32	R: 6 W: 12	031/32	1	1	99990	0=OFF	0.1xJ
1088	Peak Power Error High (Cutoff)	AINT32	R: 6 W: 12	031/32	10	1	100	0=OFF	%
1089	- Time Limit	AINT32	R: 6 W: 12	031/32	10	10	30000	0=OFF	ms
1090	+ Time Limit	AINT32	R: 6 W: 12	031/32	30000	10	30000	0=OFF	ms
1091	- Energy Limit (Value should be entered 10 times higher)	AINT32	R: 6 W: 12	031/32	1	1	99990	0=OFF	0.1xJ
1092	+ Energy Limit (Value should be entered 10 times higher)	AINT32	R: 6 W: 12	031/32	99990	1	99990	0=OFF	0.1xJ
1093	- Peak Power Limit	AINT32	R: 6 W: 12	031/32	1	1	100	0=OFF	%
1094	+ Peak Power Limit	AINT32	R: 6 W: 12	031/32	100	1	100	0=OFF	%
	- Frequency Cutoff (Relative) (It depends on the				20 kHz: 500	20 kHz: 1	20 kHz: 500		
1095	power supply operating frequency.	AINT32	R: 6 W: 12	031/32	30 kHz: 750	30 kHz: 1	30 kHz: 750	0=OFF	Hz
	Frequency ranges will be added)				40 kHz: 1000	40 kHz: 1	40 kHz: 1000		
	+ Frequency Cutoff (Relative)				20 kHz: 500	20 kHz: 1	20 kHz: 500		
1096	(It depends on the power supply operating frequency.	AINT32	R: 6 W: 12	031/32	30 kHz: 750	30 kHz: 1	30 kHz: 750	0=OFF	Hz
	Frequency ranges will be added)				40 kHz: 1000	40 kHz: 1	40 kHz: 1000		
1097	Ground Detect Error	AINT32	R: 6 W: 12	031/32	0	0	1	Selection	
	.1	1	1	-				ļ	L

B.2 Seek Stack Parameters

Table B.2Seek Stack Parameters

PNU	Description	Data Type	AK	IND -		PWE	Format	Unit	
					Default	Min.	Max.	Tomac	
1460	Time	AINT32	R: 6 W: 12	015 / 16	500	10	1000		ms
1462	Amplitude Start Ramp Time	AINT32	R: 6 W: 12	015 / 16	80	10	1000		ms
1465	Frequency Offset (Relative)	AINT32	R: 6 W: 12	015 / 16	0	-500	500		Hz

B.3 Test Stack Parameters

Table B.3 Test Stack Parameters

PNU	Description	Data	AK	IND		PWE	Format	Unit	
PNU		Туре			Default	Min.	Max.	romat	
1475	Amplitude Set A	AINT32	R: 6 W: 12	015 / 16	100	10	100	-	%



B.4 Scan Stack Parameters

Table B.4 Scan Stack Parameters

PNU	Description	Data Type	AK	IND -		PWE	Format	Unit	
PNU					Default	Min.	Max.	Tormac	Oiiit
	Digital Tune	AINT32	R: 6 W: 12		20 kHz: 19,950	20 kHz: 19,450	20 kHz: 20,450	-	Hz
1505				015 / 16	30 kHz: 30,000	30 kHz: 29,250	30 kHz: 30,750	-	Hz
					40 kHz: 39,900	40 kHz: 38,900	40 kHz: 40,900	-	Hz

B.5 Alarm Commands

Table B.5 Alarm Commands

PNU	Description	Data Type	AK	IND	Format
200	OL - Overload Group 0 (bit 0-31)	UINT32	R: 6	0	ОЕРВ
204	CU - Cutoffs Group 1 (bit 0-31)	UINT32	R: 6	0	ОЕРВ
208	SE - Setup Group 2 (bit 0-31)	UINT32	R: 6	0	ОЕРВ
212	CM - Cycle Modified Group 3 (bit 0-31)	UINT32	R: 6	0	ОЕРВ
216	WA - Warnings Group 4 (bit 0-31)	UINT32	R: 6	0	ОЕРВ
220	LM - Limits Group 5 (bit 0-31)	UINT32	R: 6	0	ОЕРВ
224	EQ - Equip.Failure Group 6 (bit 0-31)	UINT32	R: 6	0	ОЕРВ
228	NC - No Cycle Group 7 (bit 0-31)	UINT32	R: 6	0	ОЕРВ
232	CF - Comm. Failure Group 8 (bit 0-31)	UINT32	R: 6	0	ОЕРВ
236	TP - Temperature Group 9 (bit 0-31)	UINT32	R: 6	0	ОЕРВ
240	HW - Hardware Group A (bit 0-31)	UINT32	R: 6	0	ОЕРВ
244	NO - No Cycle Overload Group B (bit 0-31)	UINT32	R: 6	0	ОЕРВ

B.6 Weld Parameter Status

 Table B.6
 Weld Parameter Status

PNU	Description	Data Type	AK	IND	Format
1210	Preset Name (Character 1)	AINT8	R: 4	031/32	ОЕРВ
1211	Preset Name (Character 2)	AINT8	R: 4	031/32	ОЕРВ
1212	Preset Name (Character 3)	AINT8	R: 4	031/32	ОЕРВ
1213	Preset Name (Character 4)	AINT8	R: 4	031/32	ОЕРВ
1214	Preset Name (Character 5)	AINT8	R: 4	031/32	ОЕРВ
1215	Preset Name (Character 6)	AINT8	R: 4	031/32	ОЕРВ
1216	Preset Name (Character 7)	AINT8	R: 4	031/32	ОЕРВ
1217	Preset Name (Character 8)	AINT8	R: 4	031/32	ОЕРВ
1218	Preset Name (Character 9)	AINT8	R: 4	031/32	ОЕРВ
1219	Preset Name (Character 10)	AINT8	R: 4	031/32	ОЕРВ
1220	Preset Name (Character 11)	AINT8	R: 4	031/32	ОЕРВ
1221	Preset Name (Character 12)	AINT8	R: 4	031/32	ОЕРВ
1222	Preset Name (Character 13)	AINT8	R: 4	031/32	ОЕРВ
1223	Preset Name (Character 14)	AINT8	R: 4	031/32	ОЕРВ
1224	Preset Name (Character 15)	AINT8	R: 4	031/32	ОЕРВ
1225	Preset Name (Character 16)	AINT8	R: 4	031/32	ОЕРВ
1226	Preset Name (Character 17)	AINT8	R: 4	031/32	ОЕРВ
1227	Preset Name (Character 18)	AINT8	R: 4	031/32	ОЕРВ
1228	Preset Name (Character 19)	AINT8	R: 4	031/32	ОЕРВ
1229	Preset Name (Character 20)	AINT8	R: 4	031/32	ОЕРВ
1306*	RTC, Date (DD/MM/YY)	AUINT32	R: 6	031/32	ОЕРВ
1307**	RTC, Time (SS:MM:HH)	AUINT32	R: 6	031/32	ОЕРВ
1308***	Ctm. Fct. Cycle Counter	AUINT32	R: 6	031/32	ОЕРВ
1309	OL - Overload Group 0 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1313	CU - Cutoffs Group 1 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1317	SE - Setup Group 2 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1321	CM - Cycle Modified Group 3 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1325	WA - Warnings Group 4 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1329	LM - Limits Group 5 (bit 0-31)	AUINT32	R: 6	031/32	OEFB
1333	EQ - Equipment Failure Group 6 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1337	NC - No Cycle Group 7 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1341	CF - Comm. Failure Group 8 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1345	TP - Temperature Group 9 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ

Table B.6 Weld Parameter Status

PNU	Description	Data Type	AK	IND	Format
1349	HW - Hardware Group A (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1353	NO - No Cycle Overload Group B (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1357	Error Reason	AUINT32	R: 6	031/32	ОЕРВ

*(Date) It's given in the order: day, month, year - for example 180810

18 Hex = 24 decimal = day

08 Hex = 08 decimal = month

10 Hex = 16 decimal = year

Date = 24/08/16

**(Time) It's given in the order: seconds, minutes, hours - for example 371E0F

37 Hex = 55 decimal = seconds

1E Hex = 30 decimal = minutes

0F Hex = 15 decimal = hours

Time = 15:30:55

***ID 1308 is a 32-bit long command

B.7 Weld Status Commands

Table B.7 Weld Status Commands

PNU	Description	Data Type	AK	IND	Format	Unit	Other
1360	Weld Time	AINT32	R: 6	031 / 32		ms	1), 2)
1361	Hold Time	AINT32	R: 6	031 / 32		ms	1), 2)
1362	Energy	AINT32	R: 6	031 / 32		0.1xJ	1), 2)
1363	Peak Power	AINT32	R: 6	031 / 32		%	1), 2)
1364	Average Power	AINT32	R: 6	031 / 32		%	1), 2)
1365	Average Amplitude A	AINT32	R: 6	031 / 32		%	1), 2)
1366	Average Amplitude B	AINT32	R: 6	031 / 32		%	1), 2)
1367	Recalled ResFrequency (Abs.)	AINT32	R: 6	031 / 32		Hz	1), 2)
1368	Start Frequency (Abs.)	AINT32	R: 6	031 / 32		Hz	1), 2)
1369	End Frequency (Abs.)	AINT32	R: 6	031 / 32		Hz	1), 2)
1370	Stored Frequency (Abs.)	AINT32	R: 6	031 / 32		Hz	1), 2)
1371	ResFrequency OK	AINT32	R: 6	031 / 32	Selection		1), 2)
1372	End Amplitude Set	AINT32	R: 6	031 / 32		%	1), 2)
1373	End Amplitude	AINT32	R: 6	031 / 32		%	1), 2)
1374	End Psv	AINT32	R: 6	031 / 32		%	1), 2)
1375	End Power	AINT32	R: 6	031 / 32		%	1), 2)
1376	End Current	AINT32	R: 6	031 / 32		%	1), 2)
1377	End Phase	AINT32	R: 6	031 / 32		deg. (°)	1), 2)
1378	End Temperature	AINT32	R: 6	031 / 32		°C	1), 2)

B.8 Seek Parameter Status

Table B.8 Seek Parameter Status

PNU	Description	Data Type	AK	IND	Format
1625*	RTC, Date (DD/MM/YY)	AUINT32	R: 6	015/16	ОЕРВ
1626**	RTC, Time (SS:MM:HH)	AUINT32	R: 6	031/32	ОЕРВ
1630	OL - Overload Group 0 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1634	CU - Cutoffs Group 1 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1638	SE - Setup Group 2 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1642	CM - Cycle Modified Group 3 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1646	WA - Warnings Group 4 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1650	LM - Limits Group 5 (bit 0-31)	AUINT32	R: 6	031/32	OEFB
1654	EQ - Equipment Failure Group 6 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1658	NC - No Cycle Group 7 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1662	CF - Comm. Failure Group 8 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1666	TP - Temperature Group 9 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1670	HW - Hardware Group A (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1674	NO - No Cycle Overload Group B (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1678	Error Reason	AUINT32	R: 6	031/32	-

*(Date) It's given in the order: day, month, year - for example 180810

18 Hex = 24 decimal = day

08 Hex = 08 decimal = month

10 Hex = 16 decimal = year

Date = 24/08/16

**(Time) It's given in the order: seconds, minutes, hours - for example 371E0F

37 Hex = 55 decimal = seconds

1E Hex = 30 decimal = minutes

0F Hex = 15 decimal = hours

Time = 15:30:55

B.9 Seek Stack Commands

Table B.9 Seek Stack Commands

PNU	Description	Data Type	AK	IND	Format	Unit	Other
1680	Time	AINT32	R: 6	015 / 16	-	ms	1)
1681	Average Amplitude	AINT32	R: 6	015 / 16	-	%	1)
1682	Recalled ResFrequency (Abs.)	AINT32	R: 6	015 / 16	-	Hz	1)
1683	Start Frequency (Abs.)	AINT32	R: 6	015 / 16	-	Hz	1)
1684	End Frequency (Abs.)	AINT32	R: 6	015 / 16	-	Hz	1)
1685	Stored Frequency (Abs.)	AINT32	R: 6	015 / 16	-	Hz	1)
1686	ResFrequency OK	AINT32	R: 6	015 / 16	Selection		1)
1687	End Amplitude Set	AINT32	R: 6	015 / 16	-	%	1)
1688	End Amplitude	AINT32	R: 6	015 / 16	-	%	1)
1689	End Psv	AINT32	R: 6	015 / 16	-	%	1)
1690	End Power	AINT32	R: 6	015 / 16	-	%	1)
1691	End Current	AINT32	R: 6	015 / 16	-	%	1)
1692	End Phase	AINT32	R: 6	015 / 16	-	deg. (°)	1)
1693	End Temperature	AINT32	R: 6	015 / 16	-	°C	1)

B.10 Test Parameter Status

Table B.10 Test Parameter Status

PNU	Description	Data Type	AK	IND	Format
1725*	RTC, Date	AUINT32	R: 6	015/16	ОЕРВ
1726**	RTC, Time	AUINT32	R: 6	031/32	ОЕРВ
1730	OL - Overload Group 0 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1734	CU - Cutoffs Group 1 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1738	SE - Setup Group 2 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1742	CM - Cycle Modified Group 3 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1746	WA - Warnings Group 4 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1750	LM - Limits Group 5 (bit 0-31)	AUINT32	R: 6	031/32	OEFB
1754	EQ - Equipment Failure Group 6 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1758	NC - No Cycle Group 7 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1762	CF - Comm. Failure Group 8 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1766	TP - Temperature Group 9 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1770	HW - Hardware Group A (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1774	NO - No Cycle Overload Group B (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1778	Error Reason	AUINT32	R: 6	031/32	-

*(Date) It's given in the order: day, month, year - for example 180810

18 Hex = 24 decimal = day

08 Hex = 08 decimal = month

10 Hex = 16 decimal = year

Date = 24/08/16

**(Time) It's given in the order: seconds, minutes, hours - for example 371E0F

37 Hex = 55 decimal = seconds

1E Hex = 30 decimal = minutes

0F Hex = 15 decimal = hours

Time = 15:30:55

B.11 Test Stack Commands

Table B.11 Test Stack Commands

PNU	Description	Data Type	AK	IND	Format	Unit	Other
1780	Time	AINT32	R: 6	015 / 16	-	ms	1)
1781	Average Amplitude A	AINT32	R: 6	015 / 16	-	%	1)
1782	Average Amplitude B	AINT32	R: 6	015 / 16	-	%	1)
1783	Recalled ResFrequency (Abs.)	AINT32	R: 6	015 / 16	-	Hz	1)
1784	ResFrequency OK	AINT32	R: 6	015 / 16	Selection	-	-
1785	Start Frequency (Abs.)	AINT32	R: 6	015 / 16	-	Hz	1)
1786	End Frequency (Abs.)	AINT32	R: 6	015 / 16	-	Hz	1)
1787	End Amplitude Set	AINT32	R: 6	015 / 16	-	%	1)
1788	End Amplitude	AINT32	R: 6	015 / 16	-	%	1)
1789	End Psv	AINT32	R: 6	015 / 16	-	%	1)
1790	End Power	AINT32	R: 6	015 / 16	-	%	1)
1791	End Current	AINT32	R: 6	015 / 16	-	%	1)
1792	End Phase	AINT32	R: 6	015 / 16	-	deg. (°)	1)
1793	End Temperature	AINT32	R: 6	015 / 16	-	°C	1)

B.12 Scan Parameter Status

 Table B.12
 Scan Parameter Status

PNU	Description	Data Type	AK	IND	Format
1825	RTC, Date	AUINT32	R: 6	015/16	ОЕРВ
1826	RTC, Time	AUINT32	R: 6	031/32	ОЕРВ
1830	OL - Overload Group 0 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1834	CU - Cutoffs Group 1 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1838	SE - Setup Group 2 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1842	CM - Cycle Modified Group 3 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1846	WA - Warnings Group 4 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1850	LM - Limits Group 5 (bit 0-31)	AUINT32	R: 6	031/32	OEFB
1854	EQ - Equipment Failure Group 6 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1858	NC - No Cycle Group 7 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1862	CF - Comm. Failure Group 8 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1866	TP - Temperature Group 9 (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1870	HW - Hardware Group A (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1874	NO - No Cycle Overload Group B (bit 0-31)	AUINT32	R: 6	031/32	ОЕРВ
1878	Error Reason	AUINT32	R: 6	031/32	-



B.13 Scan Stack Commands

Table B.13 Scan Stack Commands

PNU	Description	Data Type	AK	IND	Format	Unit	Other
1880	Time	AINT32	R: 6	015 / 16	-	ms	1)
1881	Start Frequency (Abs.)	AINT32	R: 6	015 / 16	-	Hz	1)
1882	End Frequency (Abs.)	AINT32	R: 6	015 / 16	-	Hz	1)
1883	End Amplitude	AINT32	R: 6	015 / 16	-	%	1)
1884	End Psv	AINT32	R: 6	015 / 16	-	%	1)
1885	End Power	AINT32	R: 6	015 / 16	-	%	1)
1886	End Current	AINT32	R: 6	015 / 16	-	%	1)
1887	End Phase	AINT32	R: 6	015 / 16	-	deg. (°)	1)
1888	End Temperature	AINT32	R: 6	015 / 16	-	°C	1)

B.14 Process Data Channels

Table B.14 Process Data Channels

Selection	Description	Data Type	Format	Unit
-	SELZSVx	-	-	-
1	Amplitude-Set	INT16	-	%
20	Amplitude	INT16	-	%
21	Current	INT16	-	%
22	Power	INT16	-	%
23	Phase	INT16	-	deg. (°)
26	Psv	INT16	-	%
27	Frequency	UINT16	-	Hz
28	Temperature	INT16	-	°C
-	SELSTVx	-	-	-
1	Ext. Amplitude-Set	INT16	-	%
SelAck.	-	-	-	-
-	SELAZSV / SELASTV	-	-	-
0xFF	Error, Undefined Selection	-	-	-

B.15 Token Access

Table B.15 Token Access

PNU	Description	Data Type	AK	IND
50	Get Access Token	UINT8	R: 1	0
51	Put Access Token (Read always 0)	UINT8	R: 1	0
51	Put Access Token	UINT8	W: 7	0

B.16 Version, System, & RTC Information

Table B.16 Version, System, & RTC Information

PNU	Description	Data Type	AK	IND	Format
100	DCP, HW - Version	UINT32	R: 6	0	x.xx
101	DCP, FPGA - Version	UINT32	R: 6	0	x.xx
102	DCP, Bootloader - Version	UINT32	R: 6	0	x.xx
103	DCP, Firmware - Version	UINT32	R: 6	0	x.xx
110	WC, HW - Version	UINT32	R: 6	0	x.xx
112	WC, Bootloader - Version	UINT32	R: 6	0	x.xx
113	WC, Firmware - Version	UINT32	R: 6	0	x.xx
150	PS Frequency	UINT16	R: 5	0	Hz
151	PS Wattage	UINT16	R: 5	0	Watts
154	PS Serial Number	AINT8	R: 1	019	-
170*	RTC, Date (DD/MM/YY)	UINT32	R: 6 W: 12	0	-
171**	RTC, Time (SS:MM:HH)	UINT32	R: 6 W: 12	0	-

*(Date) It's given in the order: day, month, year - for example 180810

18 Hex = 24 decimal = day

08 Hex = 08 decimal = month

10 Hex = 16 decimal = year

Date = 24/08/16

**(Time) It's given in the order: seconds, minutes, hours - for example 371E0F

37 Hex = 55 decimal = seconds

1E Hex = 30 decimal = minutes

0F Hex = 15 decimal = hours

Time = 15:30:55



B.17 System Configuration Parameters

Table B.17 System Configuration Parameters

PNU	Description	Data Type	AK	IND	Format
950	Clear Memory Before Seek	UINT8	R: 1 W: 7	0	-
951	Clear Memory with Reset	UINT8	R: 1 W: 7	0	-
952	Set Digital Tine with Horn Scan	UINT8	R: 1 W: 7	0	-
953	Clear Memory at Power Up	UINT8	R: 1 W: 7	0	-

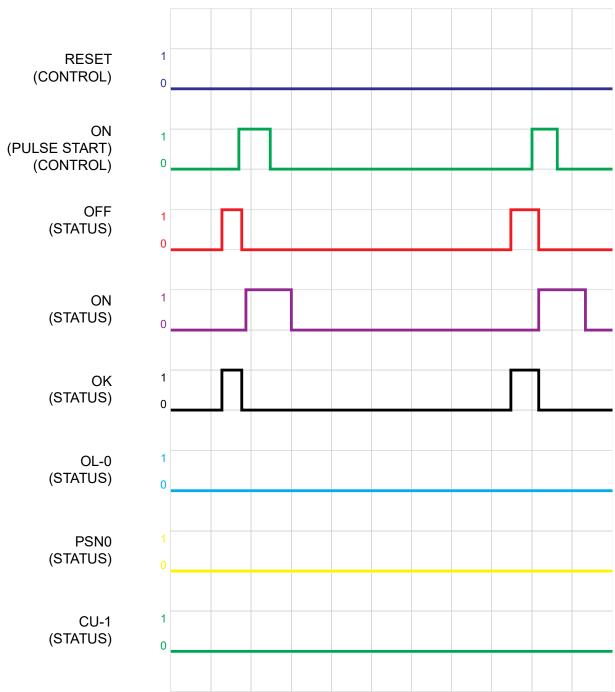
Appendix C: Timing Diagrams

C.1	Timing Diagrams		226
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C.1 Timing Diagrams

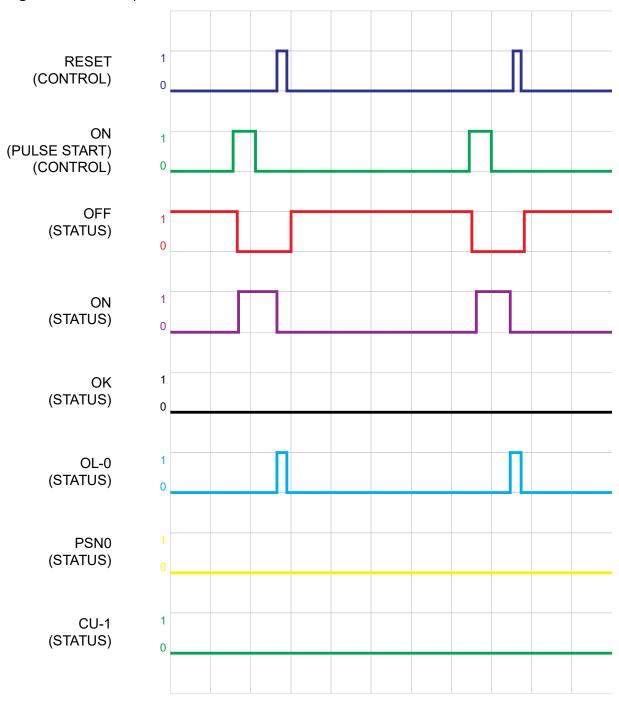
C.1.1 Weld Cycle

Figure C.1 Weld Cycle



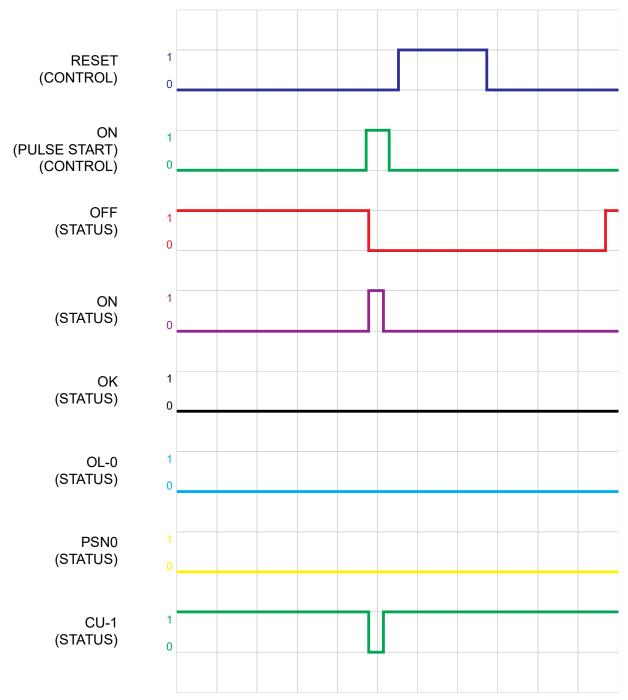
C.1.2 Weld Cycle With Overload Alarm and External Reset

Figure C.2 Weld Cycle With Overload Alarm and External Reset



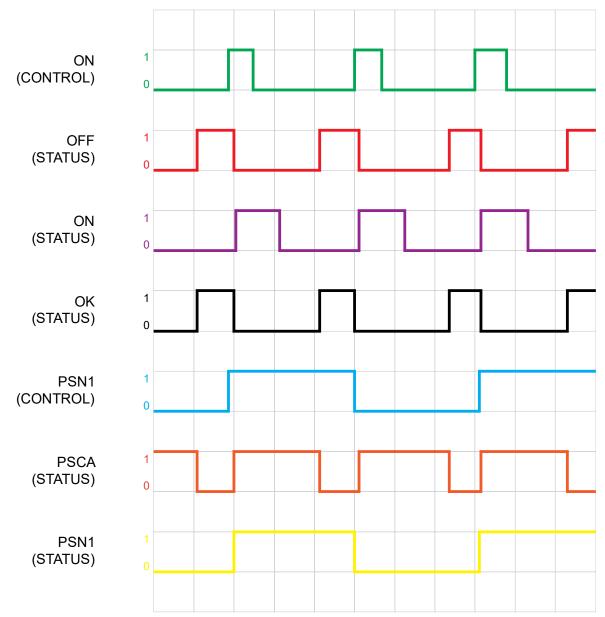
C.1.3 Weld Cycle With Cutoff Alarms and External Reset

Figure C.3 Weld Cycle With Cutoff Alarms and External Reset



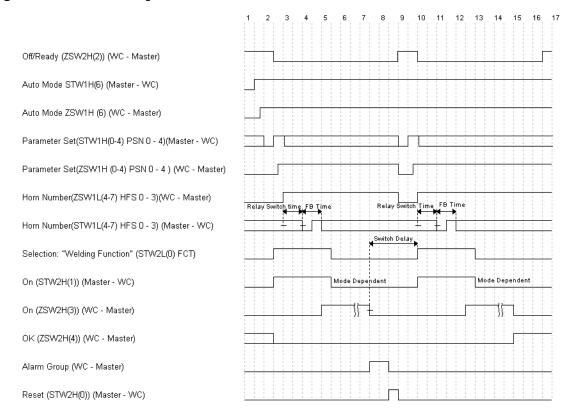
C.1.4 Weld Cycle Using Presets

Figure C.4 Weld Cycle Using Presets



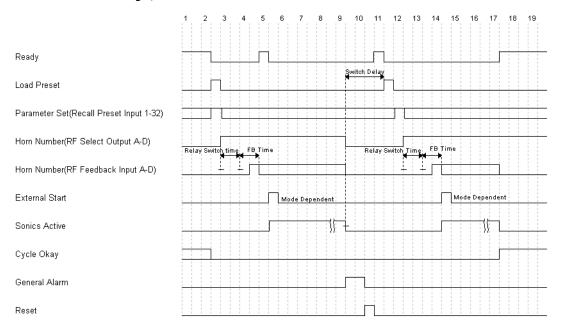
C.1.5 RF Switching Direct With Feedback With And Without Alarm

Figure C.5 RF Switching Direct With Feedback With And Without Alarm



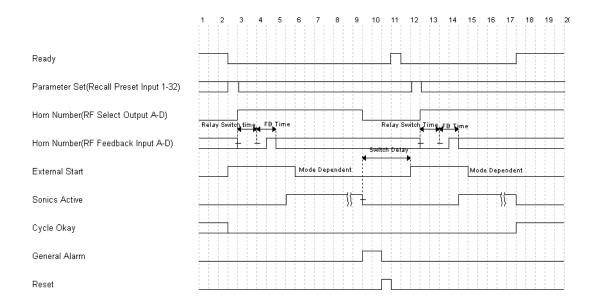
C.1.6 RF Switching I/O Direct With Feedback With And Without Alarm

Figure C.6 RF Switching I/O Direct With Feedback With And Without Alarm



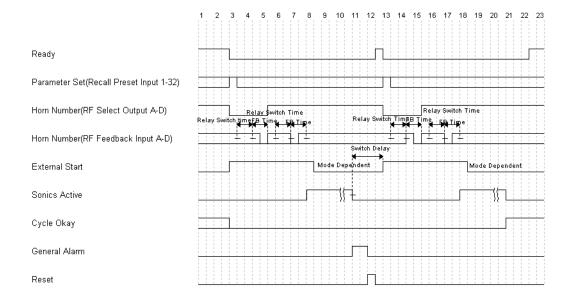
C.1.7 RF Switching I/O Direct With Feedback With And Without Alarm And Load On Start

Figure C.7 RF Switching I/O Direct With Feedback With And Without Alarm And Load On Start



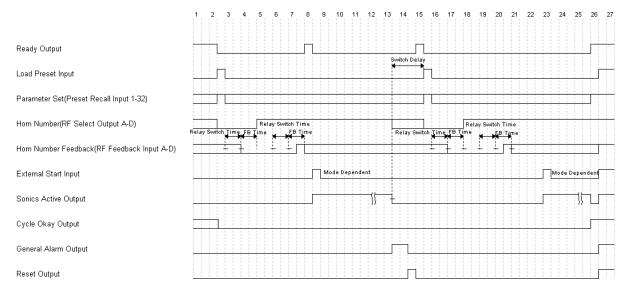
C.1.8 RF Switching I/O With Off With And Without Alarm And Load On Start

Figure C.8 RF Switching I/O With Off With And Without Alarm And Load On Start



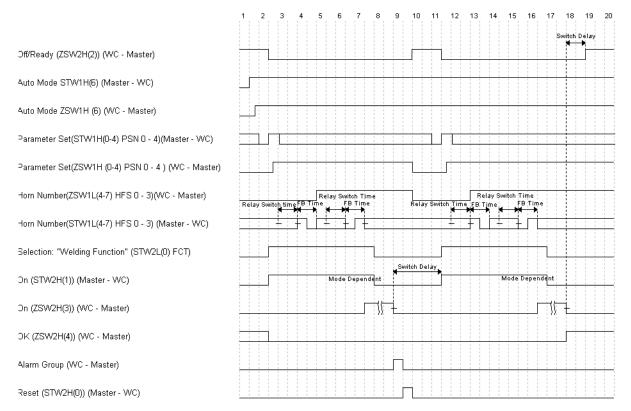
C.1.9 RF Switching I/O With Off With Feedback With And Without Alarm

Figure C.9 RF Switching I/O With Off With Feedback With And Without Alarm



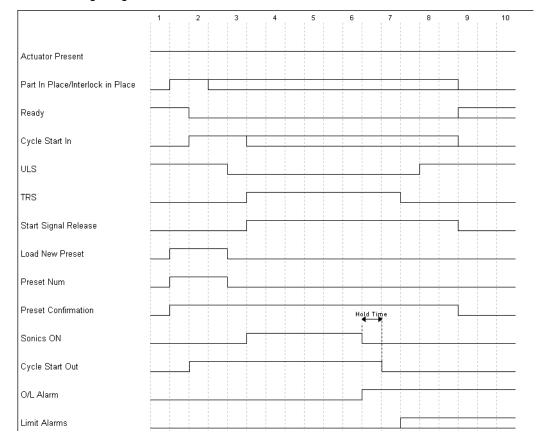
C.1.10 RF Switching With Off With Feedback With And Without Alarm

Figure C.10 RF Switching With Off With Feedback With And Without Alarm



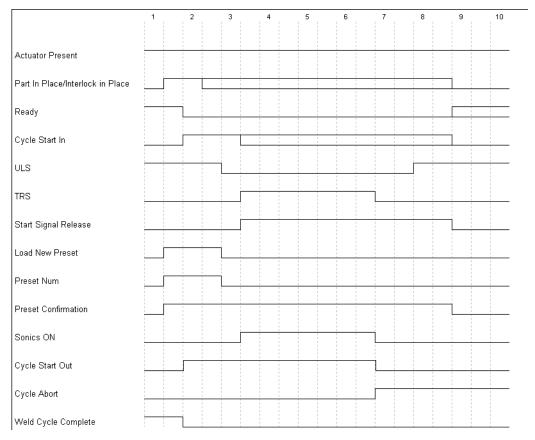
C.1.11 Timing Diagram For All Other Modes With Actuator

Figure C.11 Timing Diagram For All Other Modes With Actuator



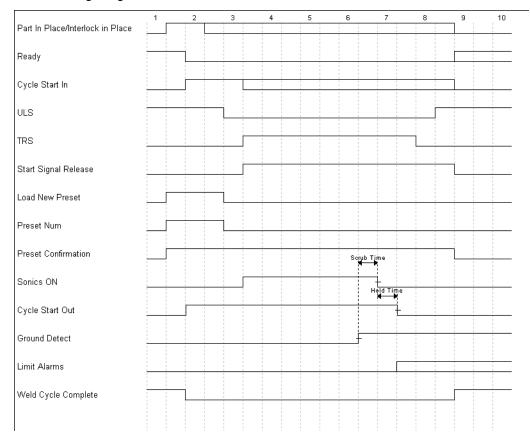
C.1.12 Timing Diagram For Cycle Abort With Actuator

Figure C.12 Timing Diagram For Cycle Abort With Actuator



C.1.13 Timing Diagram For Ground Detect With Actuator

Figure C.13 Timing Diagram For Ground Detect With Actuator

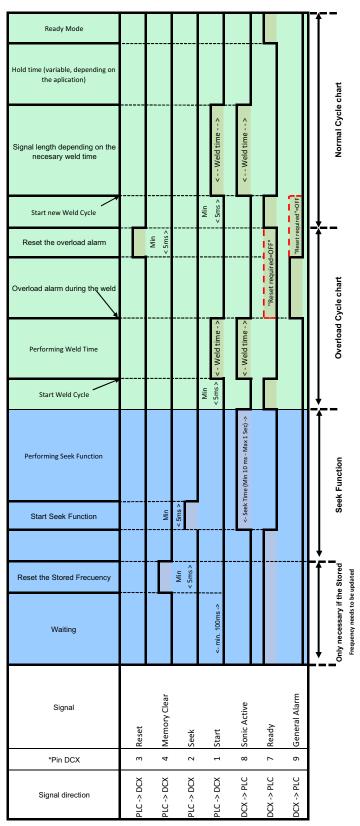


Appendix D: Signal Diagrams

D.1	Signal Diagrams	. 23	3	δ
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D.1 Signal Diagrams

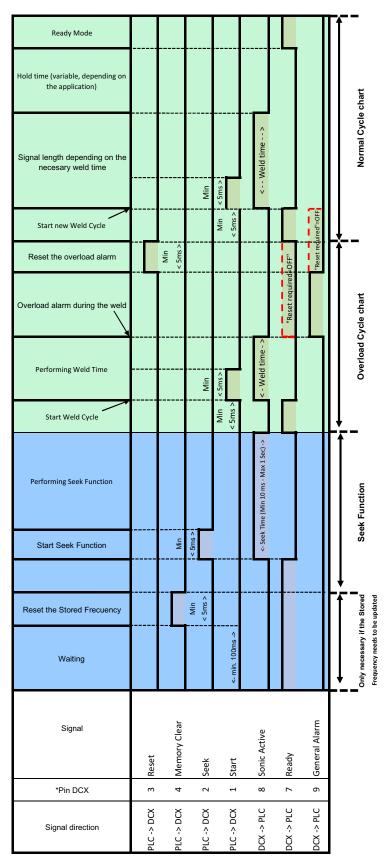
Figure D.1 Continuous Mode



 $^{{\}rm *Inputs/Outputs}$ are configurable on the User I/O Configuration webpage.

⁻⁻⁻ If Reset Required is unchecked for Overload in Alarm Webpage interface, Ready signal will be enabled after Start switch is released.

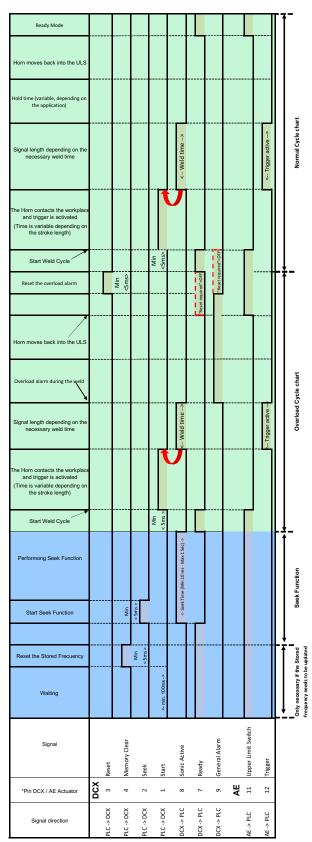
Figure D.2 Time Mode



^{*}Inputs/Outputs are configurable on the User I/O Configuration webpage.

⁻⁻⁻ If Reset Required is unchecked for Overload in Alarm Webpage interface, Ready signal will be enabled when General Alarm becomes active.

Figure D.3 AE Actuator



^{*}Inputs/Outputs are configurable on the User I/O Configuration webpage.

UStart signal should be released by Sonic Active

⁻⁻⁻ If Reset Required is unchecked for Overload in Alarm Webpage interface, Ready signal will be enabled when Upper Limit Switch becomes active.

Appendix E: Manual's Revisions

E.1 Manual's Revisions	242
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E.1 Manual's Revisions

Refer to the table below for the appropriate manual revision depending on your Power Supply's manufacturing date.

Table E.1 Manual's Revisions

Manual's Revisions	Power Supply's Manufacturing Date		
	From	То	
00	May 2022	September 2024	
01	October 2024	To date	

Figure E.1 Manufacturing date on the Information label

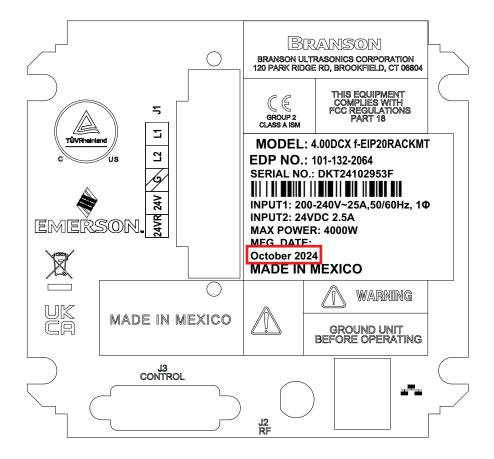
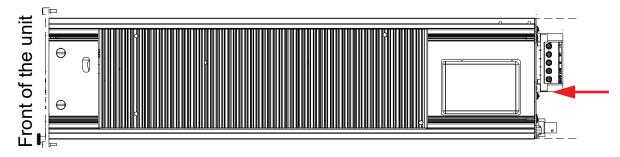
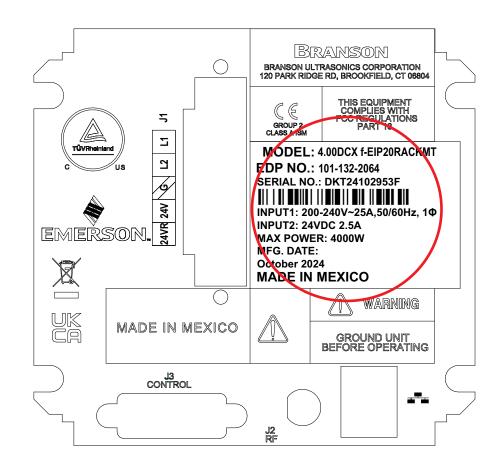


Figure E.2 Location of the Information label on the back of the DCX F-DP Power Supply





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