Flexim PIOX R532
Process Refractometer
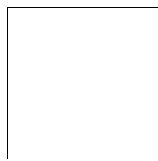
FLEXIM

EMERSON

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Annex

1 Introduction

This operating instruction has been written for users operating the process refractometer PIOX R532. It contains important information about the measuring equipment, how to handle it correctly, and how to avoid damages. Read the safety instructions carefully. Make sure you have read and understood the operating instruction before using the measuring equipment.

Any work on the measuring equipment has to be carried out by authorized and qualified personnel only, able to detect and avoid possible risks and dangers.

Presentation of warnings

This operating instruction contains warnings marked as follows:

Danger!
Type and source of danger   danger with high level of risk, which, if not avoided, can lead to death or serious injuries   → measures of prevention

Warning!
Type and source of danger   danger with medium level of risk, which, if not avoided, can lead to serious or moderate injuries   → measures of prevention

Caution!
Type and source of danger   danger with low level of risk, which, if not avoided, can lead to moderate or minor injuries   → measures of prevention

Important!
This text contains important information which should be observed in order to avoid material damage.

Notice!
This text contains important information about the handling of the measuring equipment.

Storage of the operating instruction

The operating instruction must permanently be available at the place where the measuring equipment is used. It must be available to the user at all times.

User comments

All reasonable effort has been made to ensure the correctness of the content of this operating instruction. If you, however, find some erroneous information or miss information, please inform us.

We will be grateful for any suggestions and comments regarding the concept and your experience when working with the measuring equipment. If you have any suggestions about improving the documentation and particularly this operating instruction, please let us know so that we can consider your comments for future reprints.

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2 Safety instructions

2.1 General safety instructions

Prior to any work, read the operating instruction carefully and in full.

Failure to comply with the instructions, in particular with the safety instructions, poses a risk to health and can lead to material damages. For further information, contact FLEXIM.

During installation and operation of the measuring equipment, observe the ambient and installation conditions specified in the documentation. The measuring equipment comprises the transmitter, the sensors and the accessories.

Explanation of symbols on the transmitter and accessories:

symbol	meaning
===	direct current
⏚	connection for equipotential bonding/grounding
⏚	protective ground terminal
♻	Electric devices and batteries must be disposed of separately. If necessary, additional hazardous substances are indicated for disposal.
⚡	Warning! Electric shock possible.
📖	Observe the operating instruction.
⚠	Warning! Observe the safety instructions in the manufacturer's documentation.

The measuring equipment has to be checked for proper condition and operational safety before each use. If troubles or damages have occurred during installation or operation of the measuring equipment, please inform FLEXIM.

It is not allowed to make unauthorized modifications or alterations to the measuring equipment.

The personnel has to be suitably trained and experienced for the work.

2.2 Intended use

The measuring equipment is intended for the measurement of fluid properties in closed pipes. The refractive index and temperature are measured via the connected sensor.

The transmitter uses the measured values to calculate the sought analysis quantities, e.g., concentration.

Through comparison with the values stored in the transmitter, further physical quantities can be calculated.

The physical quantities are provided via the outputs and the display.

• All instructions of this operating instruction have to be observed to ensure intended use.

• Any use beyond or other than the intended use is not covered by warranty and can present a danger. Any damage arising from not intended use shall be solely the liability of the operator or user.

• The sensor is installed into a standardized flange using the supplied process connection.

• Observe the operating conditions, e.g., environment, voltage ranges. For technical data of the transmitter, sensor and accessories, see technical specification.

2.3 Not intended use

Not intended use in terms of a misuse means:

• any work on the measuring equipment without observing all instructions in this operating instruction

• use of transmitter, sensor and accessories combinations not intended by FLEXIM

• installation of the transmitter, sensor and accessories in explosive atmospheres they are not approved for

• any work on the measuring equipment (e.g., installation, dismounting, connection, start-up, operation, service and maintenance) carried out by unauthorized and untrained personnel

• storage, installation and operation of the measuring equipment outside the specified ambient conditions (see technical specification)

2.4 Safety instructions for the user

Any work on the transmitter has to be carried out by authorized and qualified personnel. Observe the safety instructions in the operating instruction. For the technical data of the transmitter, sensor and accessories, see technical specification.

• Observe the safety and accident prevention regulations applicable on the site of operation.

• Only use the supplied mounting fixtures, the sensor as well as the intended accessories.

• Always wear the required personal protective equipment.

2.5 Safety instructions for the operator

• The operator shall qualify the personnel to perform their assigned tasks. The operator shall provide the required personal protective equipment and oblige the personnel to wear it. It is recommended to risk assess the workplace.

• Besides the safety instructions in this operating instruction, the health, safety and environment regulations applicable for the range of application of the transmitter, sensor and accessories have to be observed.

• With the exceptions stated in chapter 11, the measuring equipment is maintenance-free. Any components and spare parts may only be replaced by FLEXIM. The operator shall carry out periodic checks for changes or damages that can present a danger. For further information, contact FLEXIM.

• Observe the specifications for the installation and connection of the transmitter, sensor and accessories.

2.6 Safety instructions for electrical work

• Prior to any work on the transmitter (e.g., installation, dismounting, connection, service and maintenance), the transmitter has to be disconnected from the power supply. It is not sufficient to remove the internal fuse of the instrument.

• Electrical work may only be carried out if there is enough space.

• Open the transmitter in safe ambient conditions only (e.g., air humidity < 90 %, no conductive pollution, no explosive atmosphere). Otherwise, additional protective measures have to be taken.

• The degree of protection of the transmitter is only ensured if all cables are tightly fitted using cable glands and the housing is firmly screwed.

• The condition and tight fit of the electrical connections have to be checked at regular intervals.

• When connecting the transmitter to the power supply, an appropriate equipment switch according to IEC 60947-1 and IEC 60947-3 has to be installed as disconnecting device. The equipment switch has to disconnect all live wires. The ground conductor connection must not be interrupted. The equipment switch has to be easily accessible and clearly marked as a disconnecting device for the transmitter. It should be located near the transmitter. If the transmitter is used in an explosive atmosphere, the equipment switch has to be installed outside the explosive atmosphere. If this is not possible, it has to be installed in the least hazardous area.

• The connection may only be made to networks up to overvoltage category II. When connecting the inputs and outputs as well as the power supply, observe the installation instructions, in particular the terminal assignment.

Fig. 2.1: Transmitter PIOX R532

front plate
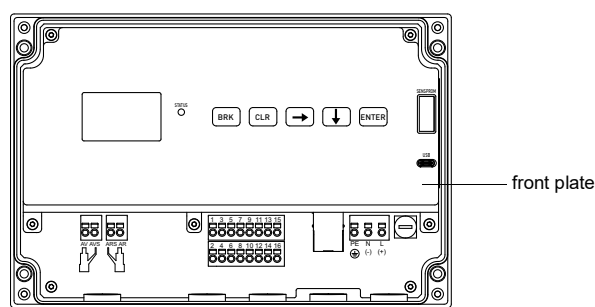
2.7 Safety instructions for transport

Caution!
⚠ **Warning of injuries due to falling objects** Unsecured and falling objects can lead to severe injuries. → Secure all components against falling during transport. → Wear the required personal protective equipment. → Observe the applicable rules.

• If you detect a transport damage when unpacking the delivery, please contact the supplier or FLEXIM immediately.

• The transmitter is a sensitive electronic measuring instrument. Avoid shocks or impacts.

• Handle the sensor cable with care. Avoid excessive bending or buckling. Observe the ambient conditions.

• Select a solid surface to put the transmitter, sensor and accessories on.

• The transmitter, sensor and accessories have to be properly packed for transport:

  – Use, if possible, the original packaging by FLEXIM or an equivalent cardboard box.

  – Position the transmitter, sensor and accessories in the middle of the cardboard box.

  – Fill any voids with appropriate packaging material (e.g., paper, foam, bubble wrap).

  – Protect the cardboard box against humidity.

2.8 Recommended procedure in hazardous situations

Fire fighting measures

• If possible, disconnect the transmitter from the power supply.

• Prior to extinguishing, protect any electrical parts that are not affected by the fire (e.g., using a cover).

• Select a suitable extinguishing agent. Avoid, if possible, conductive extinguishing agents.

• Observe the applicable minimum distances. The minimum distances differ depending on the used extinguishing agent.

3 General principles

3.1 Measurement principle

Terms and abbreviations

term/abbreviation	explanation
analyte	components of a mixture which are to be chemically analyzed
matrix	components of a mixture which are not to be chemically analyzed
fluid data set	data set containing fluid and its properties
• standard fluid data set	data set of a standard fluid (one o the most important watery solutions)
• customized fluid data set	data set of a customized fluid
scale	conversation to a scale value for an arbitrary or unknown material system (e.g., Brix scale)

Determination of the refractive index

The refractive index of a fluid is determined using transmitted light refractometry. A light beam propagates through the fluid and is refracted at the interface of a measuring prism. The angle of refraction is measured and used for the calculation of the refractive index.

The refractive index is calculated using Snell's law of refraction:

$n_i \cdot \sin\theta_i = n_t \cdot \sin\theta_t$

where

n_i	–	refractive index of the fluid
n_t	–	refractive index of the measuring prism
θ_i	–	angle of incidence
θ_t	–	angle of refraction

An LED with a wave length $\lambda = 590$ nm (sodium D-line) is used as the light source. The light passes through a slit, is parallelized by a lens and reversed by a deviating prism.

Then the light enters the fluid through a window and hits a measuring prism. The light beam is split and refracted at the lateral surfaces of the measuring prism.

The resulting light rays are focused in a lens and reproduced on the image sensor creating 2 slit images. The angle of refraction is determined from the distance between the 2 slit images. Influences of pressure and temperature are compensated.

Fig. 3.1: Path of light beam within the sensor
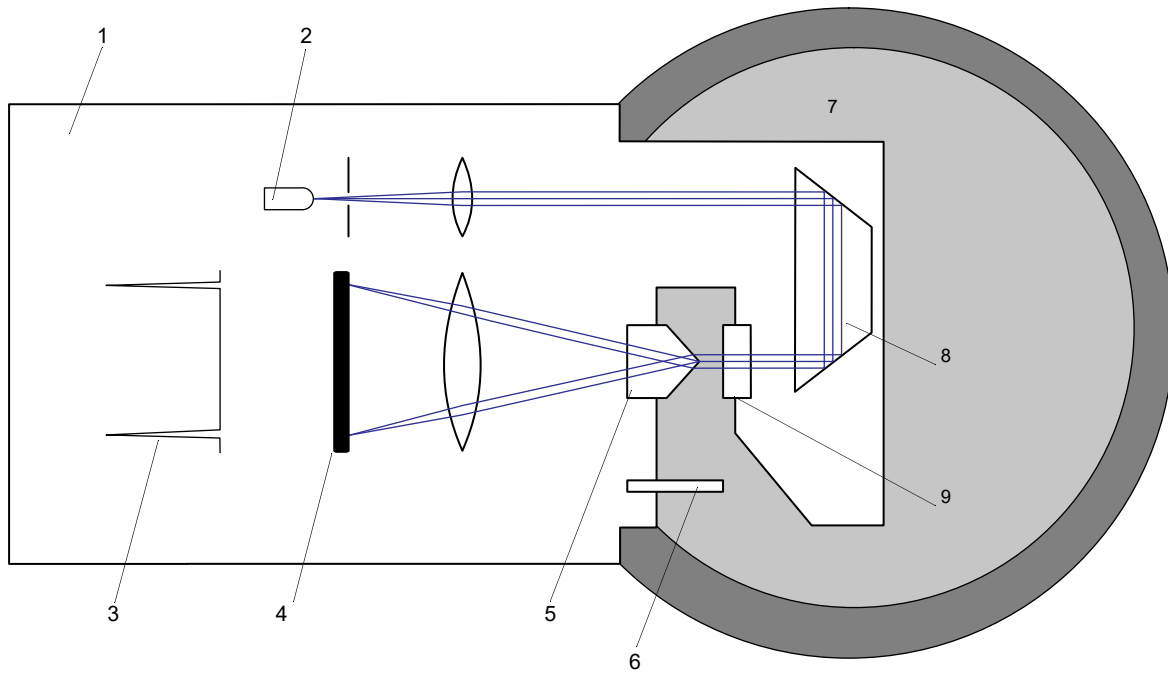
1 – sensor electronics
2 – LED
3 – slit image
4 – image sensor
5 – measuring prism
6 – temperature probe
7 – fluid
8 – deviating prism
9 – window

Determination of the concentration

The concentration is determined with the refractive index.

The refractive index depends on the temperature and concentration of the fluid. This relationship between temperature, refractive index and concentration is depicted with a function. The coefficients and the function are stored in a fluid data set.

Fig. 3.2:   Characteristic curves (saccharose solution)
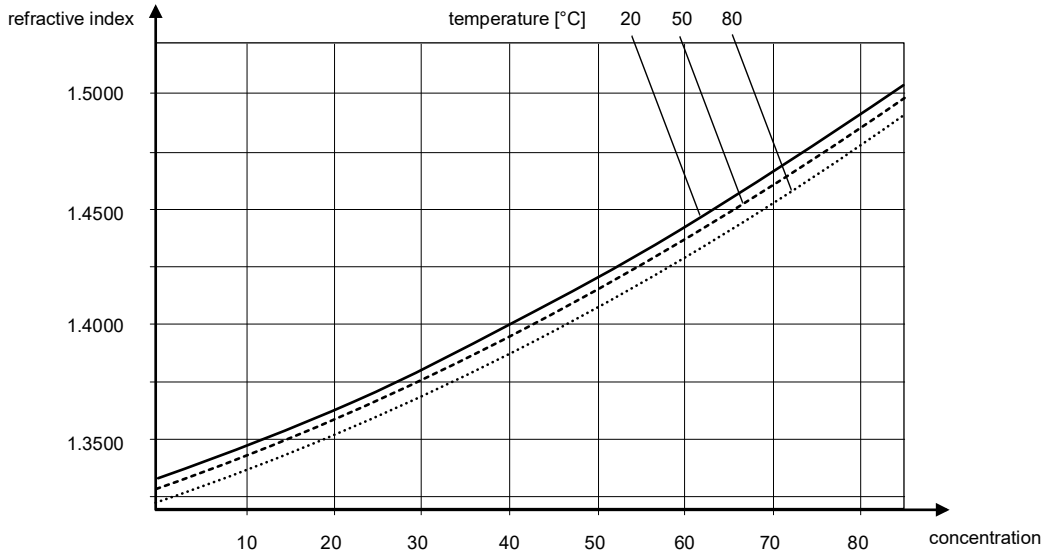
Temperature compensation

For industrial applications, it is often necessary not to determine the refractive index of the measured fluid temperature but rather at a reference temperature. The transmitter converts the refractive index.

In case temperature coefficients for the fluid are stored, they will be used to calculate the refractive index at a reference temperature.

Multi-component system

If the fluid consists of more than 2 components, apart from the refractive index and the temperature, other physical quantities (e.g., sound speed, density, conductivity) are needed to determine the physical quantities for analysis.
These physical quantities can be read via the fieldbuses and are processed with the fluid data set stored in the transmitter.
For the connection of the fieldbuses to the transmitter, see supplement to operating instruction.

3.2 Diagnostic values

Amplitude

The amplitude (unit: %) is the ratio of max. values of the signals to the product of LED lightness and exposure time of the image sensor. At delivery, the amplification with water is normalized to 100 %.

Amplification (gain)

The amplification (unit: dB) is the ratio of max. values of the signals to the product of LED lightness and exposure time of the image sensor. At delivery, the amplification with water is normalized to 20 dB. 0.01 % of the amplification corresponds to a image amplification of 100 dB.

Symmetry

Symmetry is the relation of amplitudes of both slit images. At delivery, they are optically adjusted to the same value.

Quality

The quality (unit: %) is an evaluation of the signal shape in comparison to the ideal one.

SNR

The SNR (unit: dB) is the ratio of useful signal and noise signal. A high SNR is ideal.

Combination of diagnostic values

It is possible to realize a combined evaluation of diagnostic values to determine the cause of error in situations with strong light scattering:

• A contaminated measurement optics and a turbid fluid can lead to a very low amplitude (e.g., < 0.1 %) or to a very high amplification (> 80 dB).

• A contaminated measurement optics and optical maladjustment lead to a symmetry >>1 or <<1.

• A contaminated measurement optics decreases the quality more than a turbid fluid.

• A turbid fluid decreases the SNR more than a strongly absorbing fluid.

3.3 Sensor values

Sensor humidity

The relative humidity within the sensor electronics is measured with an integrated humidity sensor. The humidity sensor only measures water vapor but does not measures other vapors. The sensor humidity must not exceed 80 %.

Sensor temperature

The temperature within the sensor electronics is measured with an integrated temperature sensor.

4   Product description

The transmitter and sensor are the main components of the process refractometer. Both are interconnected with the supplied cable.

Fig. 4.1:   Measuring setup
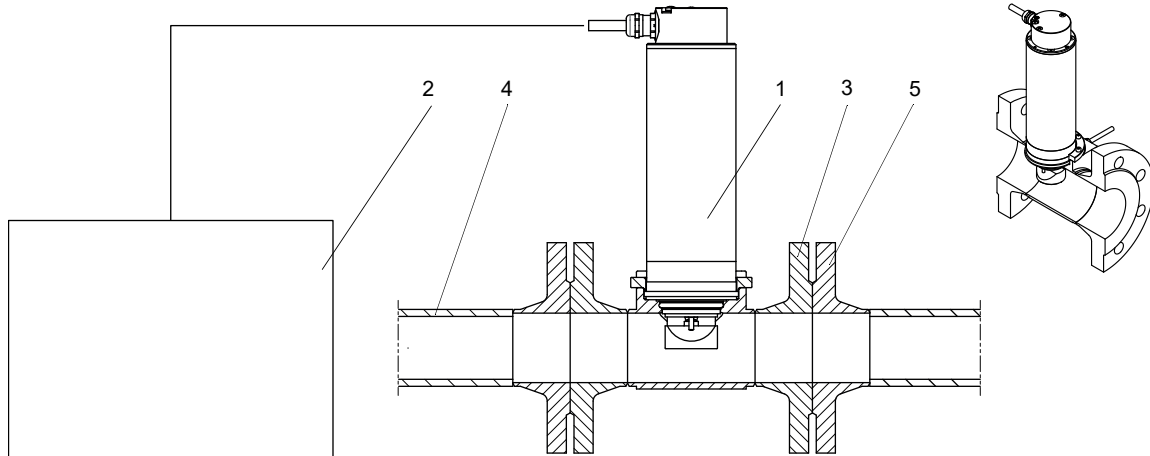
1 – sensor
2 – transmitter
3 – process connection (example)
4 – pipe
5 – connection (customer side)

4.1   Handling concept

The transmitter is operated via the keyboard. By pressing [→] or CLR the menus are displayed consecutively.

Fig. 4.2:   Command panel of the transmitter
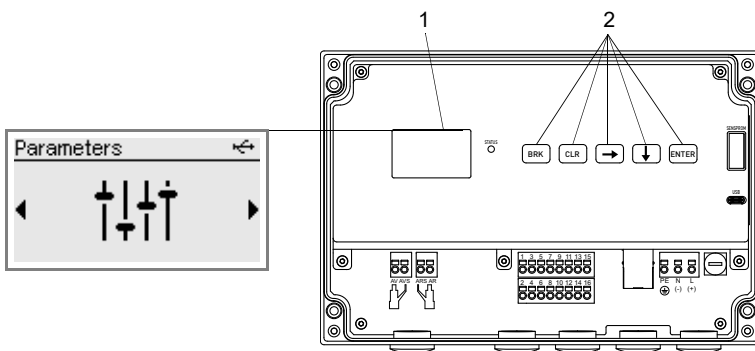
1 – LCD display (backlit)
2 – keyboard

Tab. 4.1:   Description of the menus

menu	description
Parameters	input of sensor and fluid parameters
Start measurement	measurement start [1]
Show measurement	measured value display [2]
Stop measurement	measurement stop [2]
Inputs	input assignment [3]
Outputs	output configuration
Functions	configuration of event triggers R1...R4
Storage	configuration of the data logger, deletion of measured values
Calibration	input of correction values, which are added to the calculated physical quantities or scale values
Communication	configuration of the communication interface (e.g., fieldbuses (optional))
Miscellaneous	change of system, measurement and dialog/menu settings

[1] will only be displayed if no measurement is running

[2] will only be displayed if a measurement is running

[3] will only be displayed if a fieldbus is connected

When starting up the transmitter for the first time, settings relating to the language, time, date and system of units have to be made. Afterwards the menu Parameters will be displayed.

At later start-ups the measured values will be displayed in case the measurement had not been stopped before the transmitter was disconnected from the power supply. If the measurement is stopped, the menu Parameters will be displayed.

After starting the measurement, the parameter settings or the configuration of the transmitter outputs can be displayed at any time without interrupting the measurement. A change of the parameter settings is not possible during the measurement. The measurement has to be stopped in order to change the parameter settings or configuration of the transmitter outputs.

4.2 Display

Structure

Fig. 4.3:   Menu `Parameters` (example)
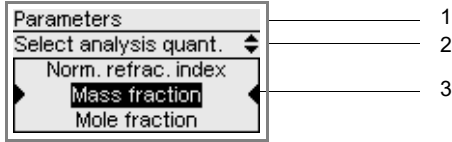
1 – menu
2 – menu item currently edited
3 – area for scroll lists, selection fields or input fields

Tab. 4.2:   Navigation

horizontal scroll list	vertical scroll list	input fields
• scroll horizontally with ➡ or CLR	• scroll vertically with ⬇ or ➡	• input numbers or text with ➡ or ⬇ • delete with CLR

Status indications

Several symbols are used for the status indications.

Fig. 4.4:   Status indications (line 1)

running measurement

error message

data logger full

connection via USB cable

key lock activated
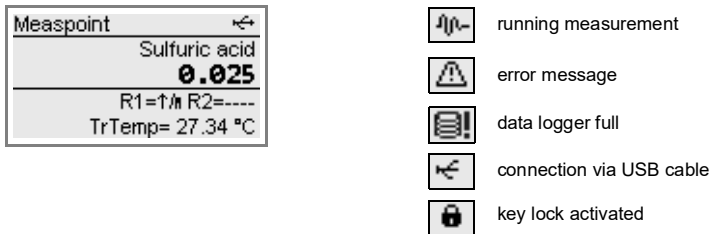
4.3   Keyboard

The keyboard consists of the following keys: ENTER, BRK, CLR, ⟶ and ↓. The keys are operated using a magnetic pen with the housing being closed.

Tab. 4.3:   General functions

ENTER	confirmation of selection or input
BRK	during the parameter input: short press: return to the previous menu item long press (several seconds): return to the beginning of the menu during the measurement: display of scroll list: `Stop measurement`, `Show parameters`, `Show measurement`
BRK + C + ENTER	Reset: press these 3 keys simultaneously to correct a malfunction. The reset has the same effect as a restart of the transmitter. Stored data are not affected.
BRK + C	INIT: when initializing the transmitter, all settings are reset to the factory settings.

Tab. 4.4:   Navigation

⟶	scroll to the right or up through a scroll list
↓	scroll down through a scroll list
CLR	scroll to the left through a scroll list

Tab. 4.5:   Input of numbers

⟶	move the cursor to the right
↓	scroll through the numbers above the cursor
CLR	short press: move the cursor to the left long press (several seconds): reset the value to the previously stored one

Tab. 4.6:   Input of text

⟶	move the cursor to the right
↓	scroll through the characters above the cursor
CLR	short press: move the cursor to the left long press (several seconds): reset the text to the previously stored one

5 Transport and storage

Caution!
⚠ **When packaging, the transmitter can fall down.** There is a danger of crushing body parts or damaging the measuring equipment. → Secure the transmitter against falling during packaging. → Wear the required personal protective equipment. → Observe the applicable rules.

Caution!
⚠ **When lifting, the center of gravity of the transmitter can be displaced within the cardboard box. The transmitter can fall down.** There is a danger of crushing body parts or damaging the measuring equipment. → Secure the transmitter against falling during transport. → Wear the required personal protective equipment. → Observe the applicable rules.

5.1 Transport

The measuring equipment must be packaged properly for transport. For weight indications, see technical specification.

• Use, if possible, the original packaging by FLEXIM or an equivalent cardboard box.

• Position the transmitter, sensor and accessories in the middle of the cardboard box.

• Fill any voids with appropriate packaging material (e.g., paper, foam, bubble wrap).

• Protect the cardboard box against humidity.

5.2 Storage

• Store the measuring equipment within the original package.

• Do not store the measuring equipment outdoors.

• Seal all openings with blind plugs.

• Protect the measuring equipment against sunlight.

• Storage the measuring equipment in a dry place without dust and within the valid temperature range
 (see technical specification).

6   Mounting

Warning!
Installation, connection and start-up by unauthorized and unqualified personnel This may result in personal or material damage or dangerous situations. → Any work on the transmitter has to be carried out by authorized and qualified personnel.

Warning!
Touching live parts Electric shock or arc faults can lead to severe injuries. The measuring equipment can be damaged. → Prior to any work on the transmitter (e.g., installation, dismounting, connection, start-up), the transmitter has to be disconnected from the power supply. It is not sufficient to remove the internal fuse of the instrument.

Caution!
Safety and accident prevention regulations for electrical systems and equipment Failure to observe these regulations may lead to severe injuries. → Observe the safety and accident prevention regulations for electrical systems and equipment.

Caution!
Touching hot or cold surfaces This may result in injuries (e.g., thermal damages). → Observe the ambient conditions at the measuring point during installation. → Wear the required personal protective equipment. → Observe the applicable rules.

Notice!
Protective foils on measuring equipment and sensor mounting fixture can be removed.

6.1   Transmitter

6.1.1   Opening and closing the housings

Opening

Important!
Do not use objects which may damage the housing gasket to open the housing cover.

• Loosen the screws of the transmitter housing.

• Open the housing cover of the transmitter.

• Remove the protection foils on the window of the housing cover (inside and outside) as well as on the transmitter display.

Closing

• Close the housing cover.

• Tighten the screws on the transmitter housing evenly.

Fig. 6.1:   Transmitter
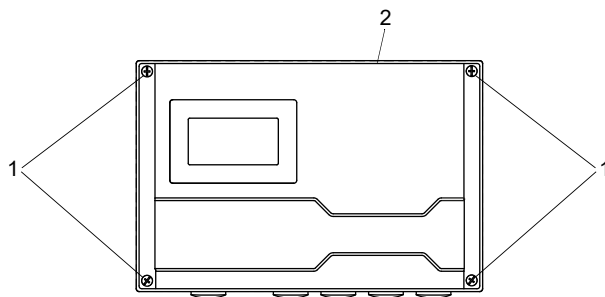
1 – screws
2 – housing cover

6.1.2 Installation of the transmitter

6.1.2.1 Wall mounting

• Loosen the screws of the transmitter housing.

• Open the housing cover of the transmitter.

• Fix the transmitter to the wall using 4 screws.

Fig. 6.2:   Transmitter (dimensions in mm)
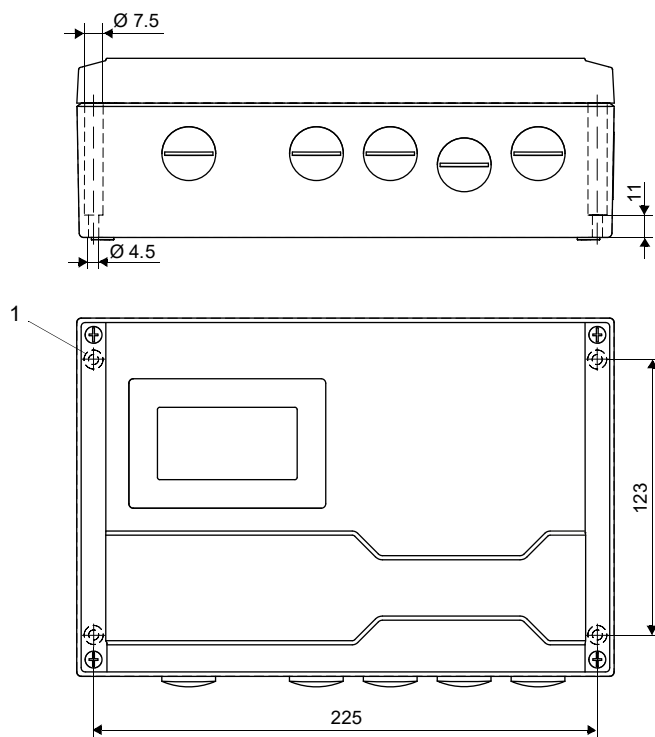
1   – fixing holes for wall mounting

6.1.2.2 Pipe mounting

Important!
The pipe has to be sufficiently stable to withstand the pressure exerted by the transmitter and the shackles.

Mounting on a 2" pipe

The pipe mounting kit is fixed to the pipe using a shackle.

• Fix the pipe mounting plate (2) to the instrument mounting plate (3) using the supplied screws. Make sure the pipe mounting plate is aligned corresponding to the pipe orientation.

• Fix the pipe mounting plate and the instrument mounting plate to the pipe using the nuts (4) and the shackle (1).

• Use the screws to fix the transmitter to the instrument mounting plate.

Fig. 6.3:   Pipe mounting kit
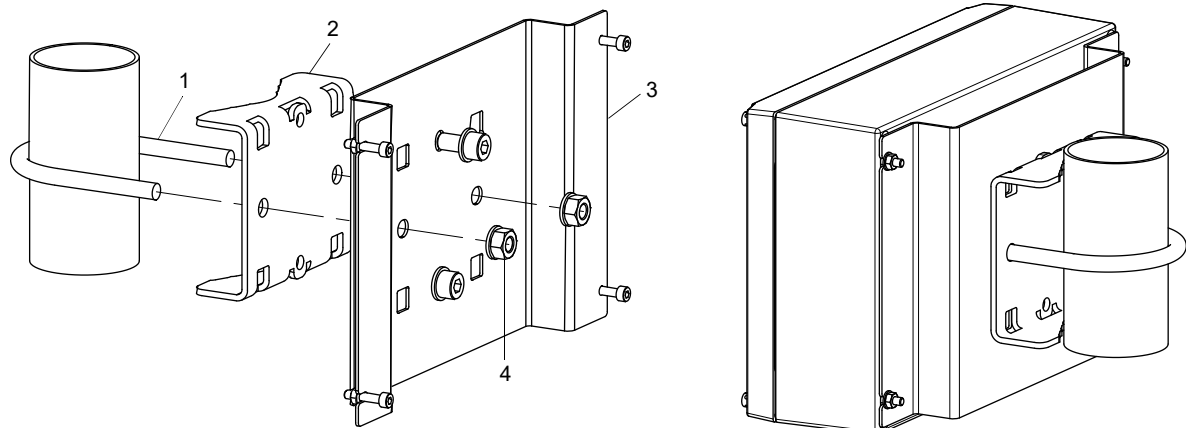
1 – shackle
2 – pipe mounting plate
3 – instrument mounting plate
4 – nut

Mounting on a pipe > 2"

The pipe mounting kit is fixed to the pipe by using tension straps.

Caution!	
⚠️	**The edge of the tension strap is very sharp.** Risk of injury. → Debur sharp edges. → Wear the required personal protective equipment. → Observe the applicable rules.

• Fix the pipe mounting plate (1) to the instrument mounting plate (2) using the supplied screws. Make sure the pipe mounting plate is aligned corresponding to the pipe orientation.

• Insert the tension straps (3) into the holes of the pipe mounting plate and the instrument mounting plate.

• Fix the pipe mounting plate and the instrument mounting plate to the pipe using the tension straps.

• Use the screws to fix the transmitter to the instrument mounting plate.

Fig. 6.4:   Pipe mounting with tension straps
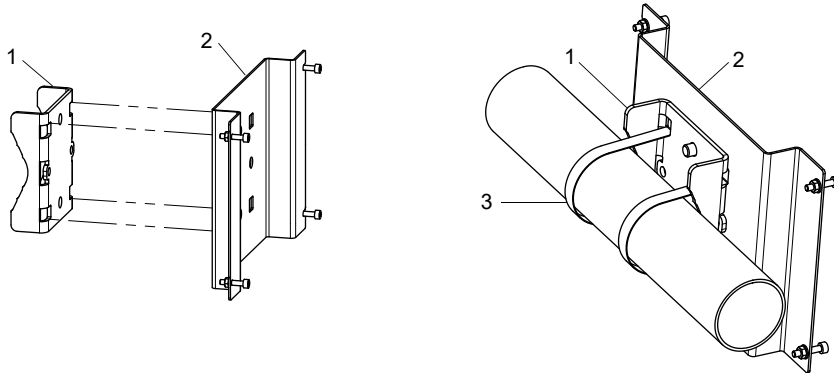
1 – pipe mounting plate
2 – instrument mounting plate
3 – tension strap

6.2 Sensor

6.2.1 Sensor design

The sensor consists of a sensor head with wetted parts (measuring prism, window, temperature probe) and the sensor housing containing the electronic components.

The junction box is situated at the rear part of the sensor housing.

The following 2 sensor designs are available:

• chemistry design

• hygiene design

The designs essentially differ in sealing concept and size and form of the optical components.

Fig. 6.5:   Sensor PIOX R500 (chemistry design)
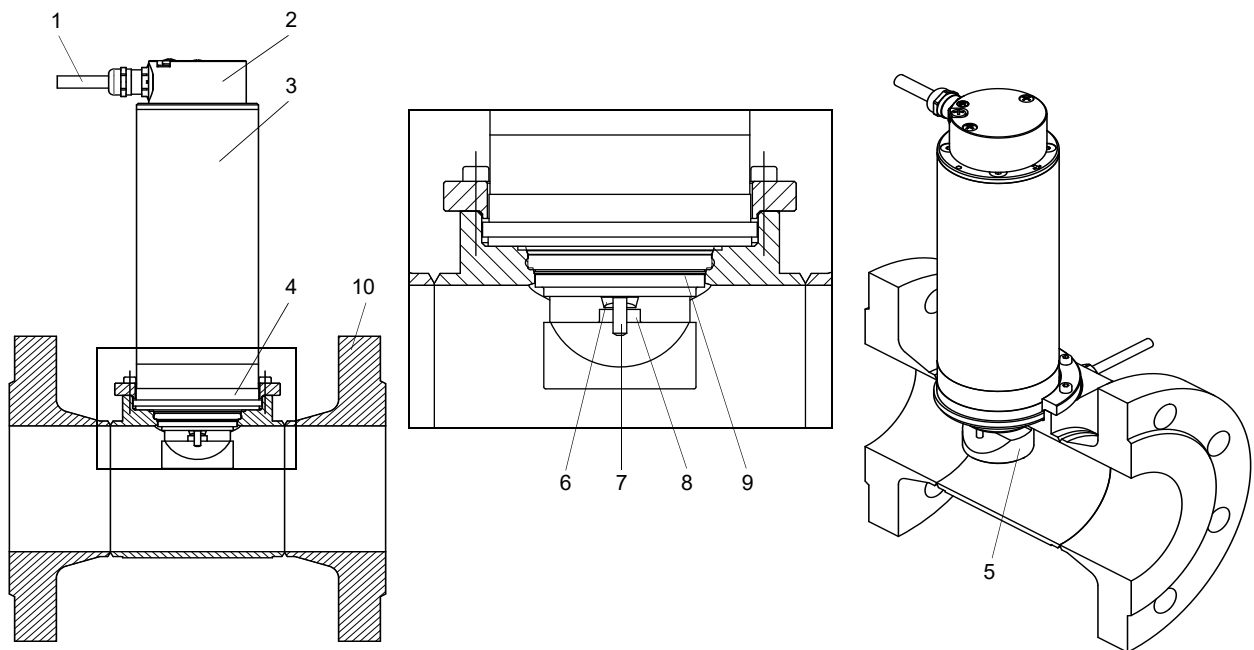
1 – sensor cable
2 – junction box with cover
3 – sensor housing with electronic components
4 – flange
5 – sensor head
6 – measuring prism
7 – temperature probe
8 – window
9 – O-ring
10 – process connection (example)

6.2.2 Mounting of the sensor

6.2.2.1 Selection of the measuring point

Caution!	
⚠	**Warning of severe injuries from hot or cold components** Touching hot or cold components can lead to severe injuries (e.g., thermal damage). → Any mounting, installation or connection work has to be concluded. → Any work on the measuring point during the measurement is prohibited. → Observe the ambient conditions at the measuring point during installation. → Wear the required personal protective equipment. → Observe the applicable rules.

Danger!	
⚠	**Warning of severe injuries caused by leakage of dangerous fluids** Dangerous fluids can escape from insufficiently tightened screw connections. The contact to the fluid may result in personal or material damage or dangerous situations. → The mounting has to be carried out with a reproducible torque procedure and defined screw tightening torque. The screw tightening torque depends on the used gasket and has to be defined by the customer.

- Select a measuring point:
  - which is representative for the process and relevant to the given application
  - where the sensor can quickly respond to changes in the process
  - where the pipe is always filled and no gas bubbles can form in the pipe
  - where the flow can be stopped and the sensor can be installed and removed without problems
- In order to counteract the formation of deposits on the measuring prism and the window, the measuring point should be selected in such a way that:
  - a minimum flow is always present in pipe
  - the sensor is installed in pipe segments with small pipe diameters because smaller pipe diameters cause higher pressures and, therefore a better cleaning effect
  - the fluid temperature is relatively high but always within the operating range of the sensor because higher temperatures increase the solubility and reduce the viscosity
- Select the location of the transmitter within the cable range of the measuring point. The ambient temperature at the measuring point has to be within the operating temperature range of the transmitter and the sensor (see technical specification).
- Protect the sensor against direct sunlight, rain and vibrations. The ambient temperature at the measuring point has to be within the operating temperature range of the sensor (see technical specification).
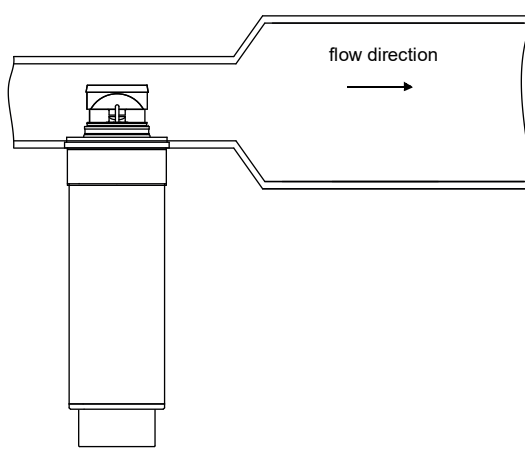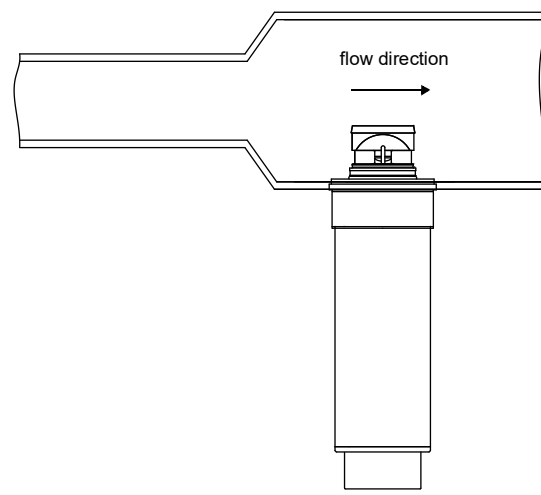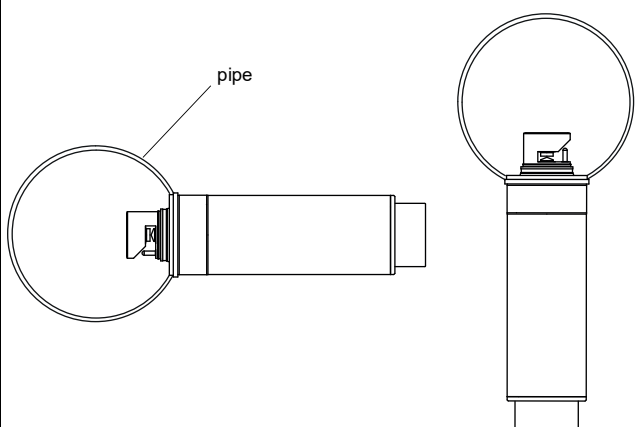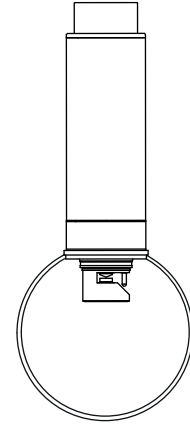
Important!
The sensor cable must never be wrapped around hot pipes.

If the measuring point is within an explosive atmosphere, possibly present danger zones and gases have to be determined. The transmitter and sensor have to be appropriate for these conditions.

Observe the notes in the following table.

Tab. 6.1:   Sensor positioning on a horizontal pipe (basic presentation)

Horizontal pipe
Diffuser If possible, install the sensor in the pipe segment with the smaller pipe diameter (if the flow direction is as indicated). **correct**   **disadvantageous** flow direction   flow direction
Positioning of the sensor If possible, install the sensor on the side or at the bottom of the pipe in such a way that any gas bubbles at the top of the pipe do not influence the measurement. **correct**   **disadvantageous** pipe

Tab. 6.1:   Sensor positioning on a horizontal pipe (basic presentation)

Horizontal pipe
Orientation of the sensor head, in case it is laterally installed

Install the sensor head in such a way that the flow direction of the fluid is parallel to the edge of the measuring prism and the temperature probe points downward. If the sensor is correctly installed, the arrows on the sensor housing are horizontal and the point on the sensor housing points downward.

correct

disadvantageous

Tab. 6.1:   Sensor positioning on a horizontal pipe (basic presentation)

Horizontal pipe
Orientation of the sensor head, in case it is installed at the bottom of the pipe Install the sensor head in such a way that the flow direction of the fluid is parallel to the edge of the measuring prism. If the sensor is correctly installed, the arrows on the sensor housing are aligned along the pipe.   correct   disadvantageous sensor head
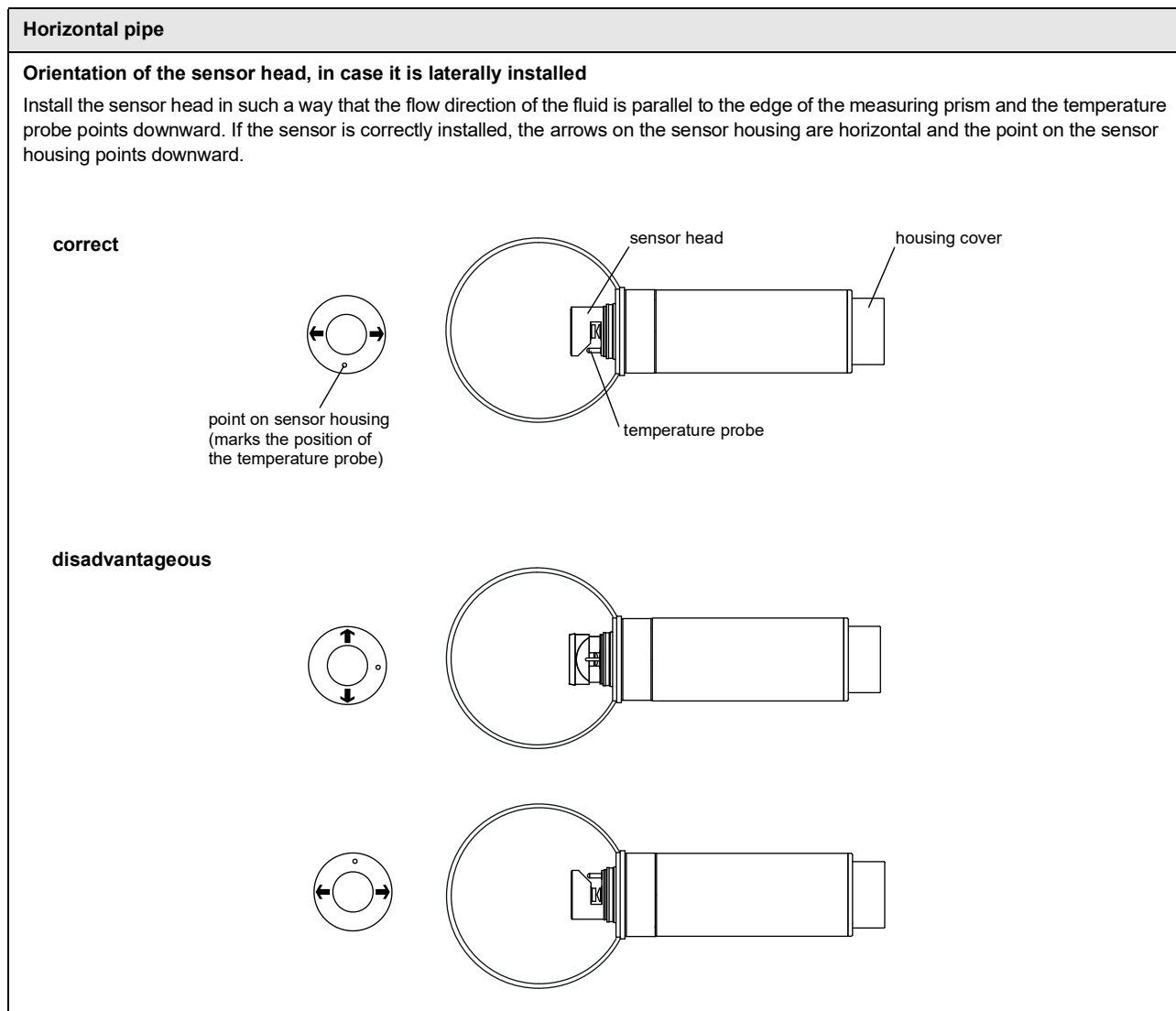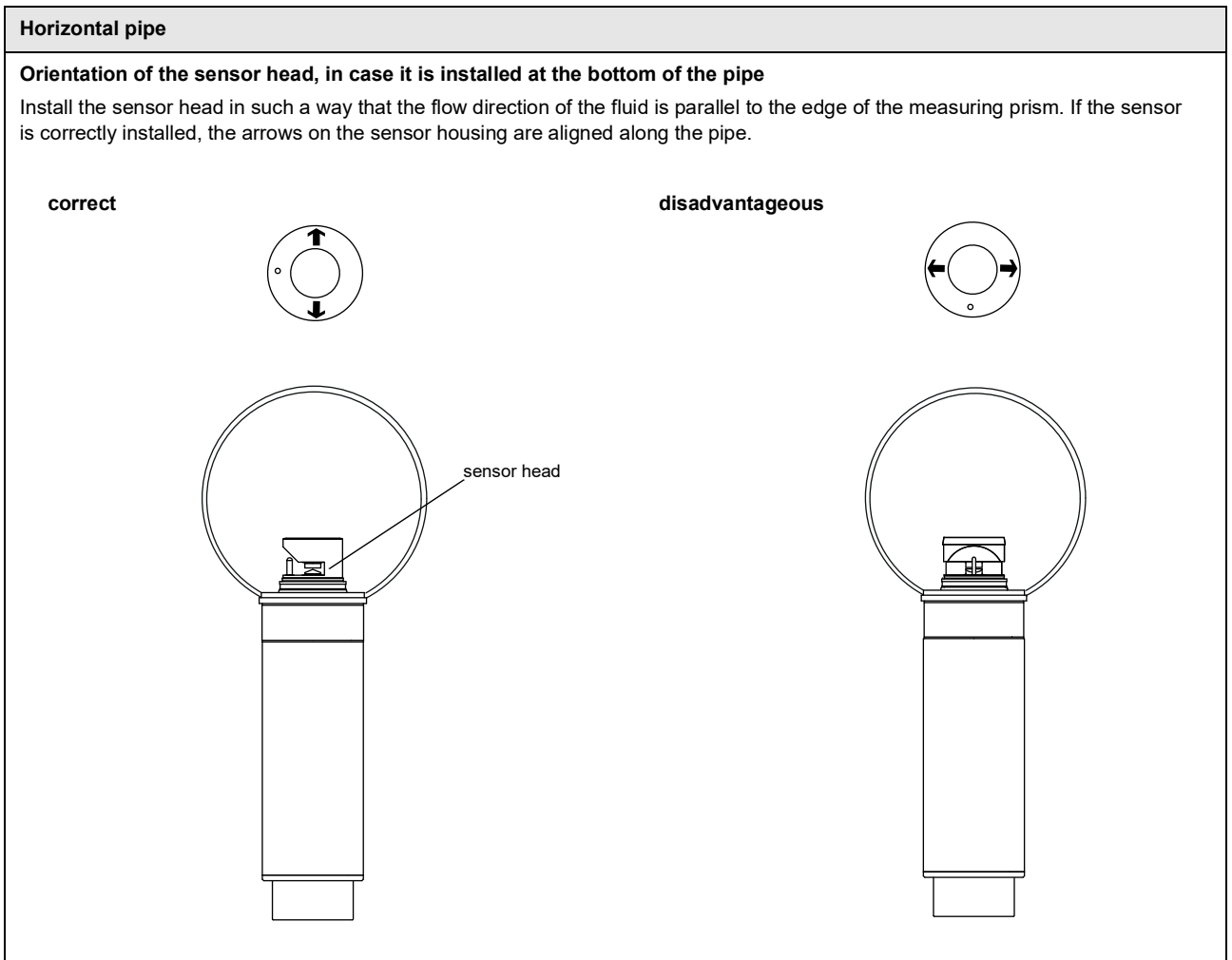
Tab. 6.2:   Sensor positioning on a vertical pipe (basic presentation)

Vertical pipe
Flow direction and orientation of the sensor head The measuring point on a vertically mounted pipe has always to be filled. The fluid should flow upward. The fluid has to wash around the measuring prism and the flow direction of the fluid has to be parallel to the edge of the measuring prism. If the sensor is correctly installed, the arrows on the sensor housing are vertical.   correct   disadvantageous flow direction

6.2.2.3   Installation of the sensor (chemistry design)

The sensor is installed into a standardized flange using the supplied process connection or directly flanged into a T-piece as a long version.

6.2.2.4   Installation of the sensor (hygienic design)

The sensor can be connected to the standardized clamp flange connection Varivent type N or TriClamp 3".

Important!
After installing the sensor, check the tightness of the complete system with a compression test.

7 Connection

Warning!
⚠️ **Installation, connection and start-up by unauthorized and unqualified personnel** This may result in personal or material damage or dangerous situations. → Any work on the transmitter has to be carried out by authorized and qualified personnel.

Warning!
⚠️ **Touching live parts** Electric shock or arc faults can lead to severe injuries. The measuring equipment can be damaged. → Prior to any work on the transmitter (e.g., installation, dismounting, connection, start-up), the transmitter has to be disconnected from the power supply. It is not sufficient to remove the internal fuse of the instrument.

Caution!
⚠️ **Safety and accident prevention regulations for electrical systems and equipment** Failure to observe these regulations may lead to severe injuries. → Observe the safety and accident prevention regulations for electrical systems and equipment.

7.1 Sensor

It is recommended to run the cables from the measuring point to the transmitter before connecting the sensor to avoid load on the connectors.

7.1.1 Connection of the cable to the sensor

Important!
The degree of protection of the transmitter is only ensured if all cables are tightly fitted using cable glands and the housing is firmly screwed.

• Loosen the 2 screws on the junction box of the sensor.
• Remove the housing cover.
• Remove the blind plug on the housing cover to connect the sensor cable.
• Open the cable gland of the sensor cable. The compression part remains in the cap nut.
• Insert the sensor cable through the cap nut, the compression part and the basic part.
• Prepare the sensor cable with the cable gland.
• Insert the sensor cable through the housing cover.
• Tighten the gasket ring side of the basic part firmly into the housing cover.
• Connect the sensor cable to the terminals of the transmitter.

Important!
The external shield of the sensor cable must not have any electrical contact to the sensor housing.

Tab. 7.1:   Terminal assignment

terminal	connection
+	yellow
-	green
A+	brown
B-	white
S	shield

Fig. 7.1.   Sensor PIOX R500
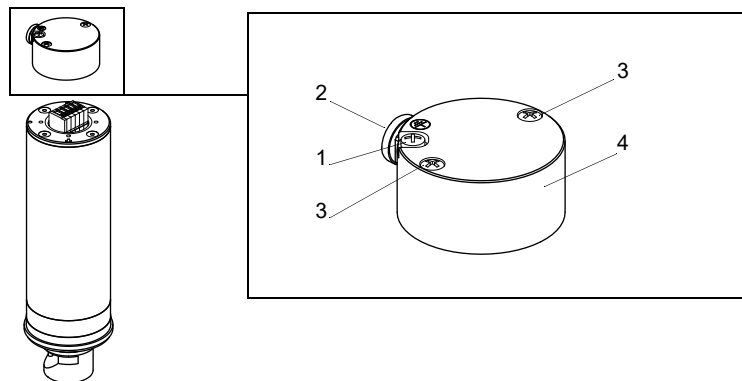
1 – equipotential bonding terminal
2 – blind plug
3 – screws
4 – housing cover

Fig. 7.2:   Preparation of the sensor cable
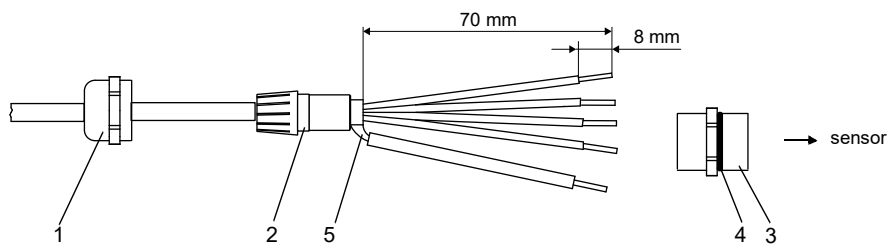
1 – cap nut
2 – compression part
3 – basic part
4 – gasket ring side of the basic part
5 – external shield

• Position the housing cover with the screws on the holes. Observe the orientation of the cable entries on the housing cover.

• Tighten the screws.

• Fix the cable gland by screwing the cap nut onto the basic part.

Fig. 7.3:   Connection of the sensor cable and terminal strip
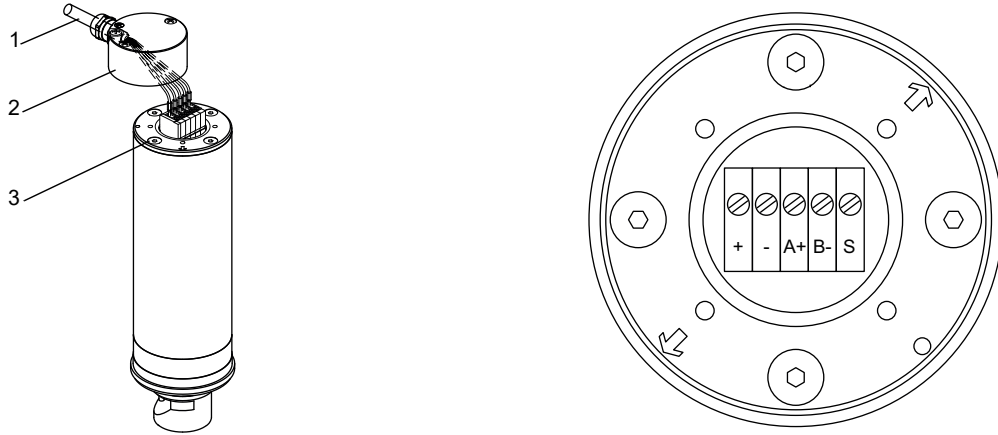
1 – sensor cable
2 – housing cover
3 – hole

7.1.2 Connection of the sensor cable to the transmitter

Important!
The degree of protection of the transmitter is only ensured if all cables are tightly fitted using cable glands and the housing is firmly screwed.

• Remove the blind plug on the left for the connection of the sensor cable.
• Open the cable gland of the sensor cable. The compression part remains in the cap nut.

Notice!
For the connection of the sensor cable to the transmitter, cable glands made from metal have to be used.

• Push the sensor cable through the cap nut and the compression part.
• Prepare the sensor cable.
• Shorten the external shield and brush it back over the compression part.
• Screw the gasket ring side of the basic part tightly into the housing of the transmitter.
• Insert the sensor cable into the housing.
• Fix the cable gland by screwing the cap nut onto the basic part.
• Connect the sensor cable to the terminals of the transmitter.

Tab. 7.2:   Terminal assignment

terminal	connection
1	brown
3	green
2	white
4	yellow

Fig. 7.4:   Connection of the sensor to the transmitter
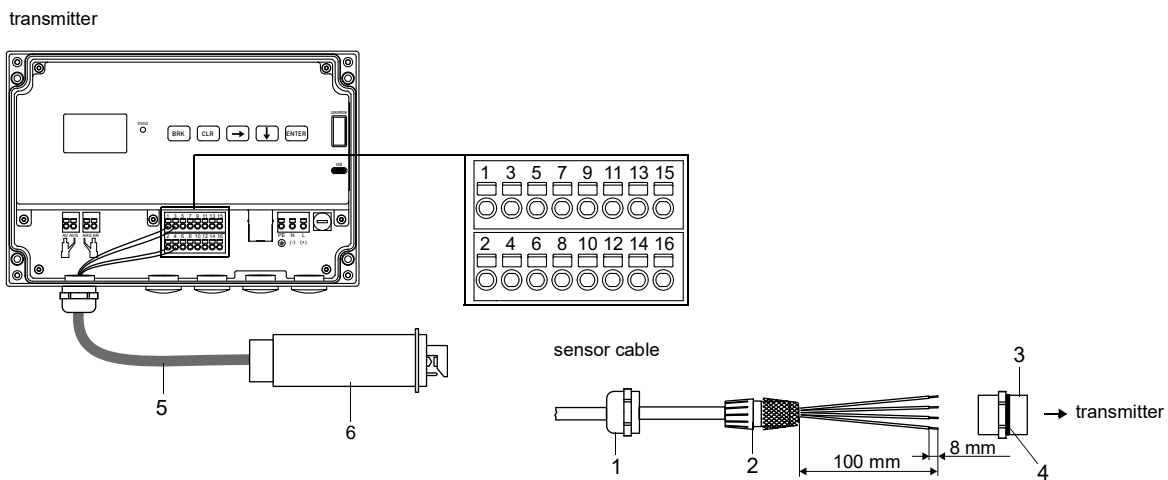
1 – cap nut
2 – compression part
3 – basic part
4 – sealing ring side of the basic part
5 – sensor cable
6 – sensor

7.2 Power supply

The installation of the power supply is carried out by the operator. The operator has to provide an overcurrent protector of max. 16 A (fuse or similar device) disconnecting all energizing wires in case of an inadmissible high current consumption. The impedance of the protective ground has to be low ohmic in order not to allow touch voltage pass the permissible limit.

Important!
The degree of protection of the transmitter will only be guaranteed if the power cable fits firmly and tightly in the cable gland.

• Connect the power cable to the transmitter (see section 7.2.1, Fig. 7.5 and Tab. 7.3).

Fig. 7.5:   Connection of the power supply to the transmitter
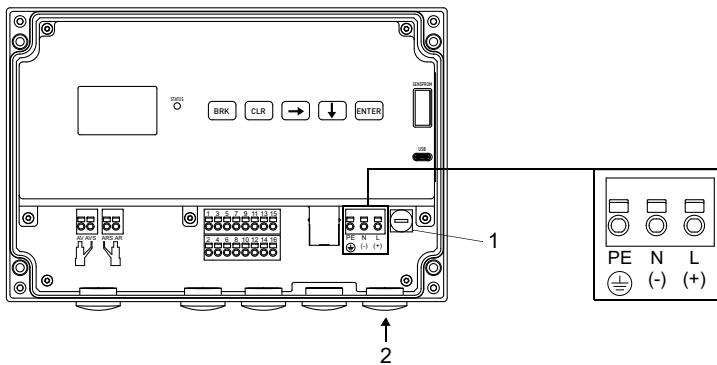
1 – fuse
2 – connection of the power supply

Tab. 7.3:   Terminal assignment

terminal	connection AC	connection DC
L(+)	outer conductor	DC
N(-)	neutral conductor	GND
PE	protective conductor	protective conductor

7.2.1 Cable connection

• Remove the blind plug to connect the cable to the transmitter.

• Prepare the cable with an M20 cable gland. The used cable has to have a wire cross-section of 0.25…2.5 mm^2.

• Push the cable through the cap nut, compression part and basic part of the cable gland.

• Insert the cable into the transmitter housing.

• Screw the sealing ring side of the basic part into the transmitter housing.

• Fix the cable gland by screwing the cap nut onto the basic part.

If the transmitter is connected to a AC power supply, the power cable has to be prepared as shown in Fig. 7.7.

• Connect the cable to the terminals of the transmitter.

Fig. 7.6:   Cable gland
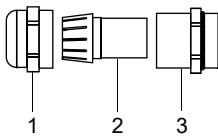
1 – cap nut
2 – compression part
3 – basic part

Fig. 7.7:   Preparation of the power cable
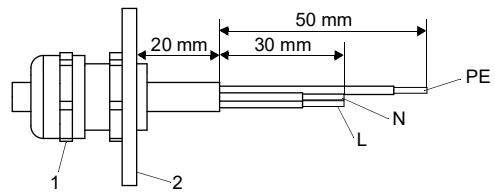
1 – cable gland
2 – transmitter housing

7.3   Outputs

Important!
The max. permissible voltage between the outputs and against PE is 60 V DC (permanent).

Fig. 7.8:   Connection of the outputs to the transmitter
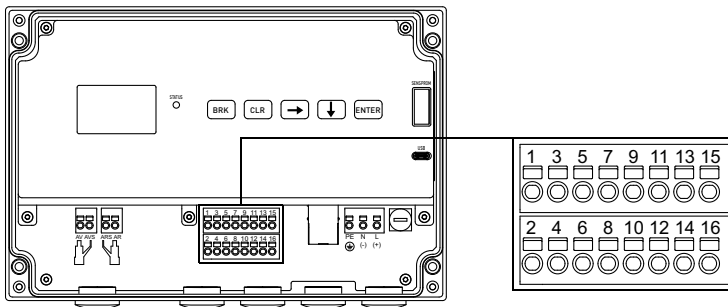
7.3.1   Output circuits
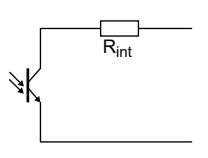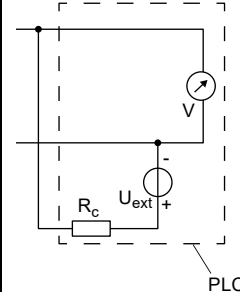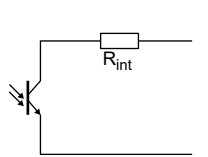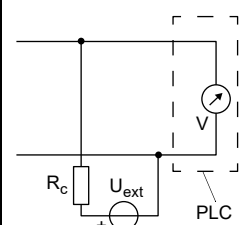
Tab. 7.4:   Switchable current output Ix

transmitter		external circuit	remark
internal circuit	connection		
active			
	x+ x-	mA	R_{ext} = 250...530 Ω $U_{opencircuit}$ = 28 V DC adjustable fault current (no valid measured value, no measurement): 3.2...3.99 mA, 20.01...24 mA hardware fault current: 3.2 mA
passive			
	x+ x-	mA U_{ext} + -	U_{ext} = 9…30 V DC, dependent on R_{ext} (R_{ext} < 458 Ω with 20 V) adjustable fault current (no valid measured value, no measurement): 3.2...3.99 mA, 20.01...24 mA hardware fault current: 3.2 mA

Tab. 7.5:   Switchable current output Ix/HART

transmitter		external circuit	remark
internal circuit	connection		
active			
U_{int}	x+ x-	mA	R_{ext} = 250...530 Ω $U_{opencircuit}$ = 28 V DC adjustable fault current (no valid measured value, no measurement): 3.5...3.99 mA, 20.01...22 mA hardware fault current: 3.2 mA
passive			
	x+ x-	mA U_{ext} + -	U_{ext} = 9…30 V DC, dependent on R_{ext} (R_{ext} = 250...458 Ω with 20 V) adjustable fault current (no valid measured value, no measurement): 3.5...3.99 mA, 20.01...22 mA hardware fault current: 3.2 mA

Tab. 7.6:   Digital output (according to IEC 60947-5-6 (NAMUR))

transmitter		external circuit	remark
internal circuit	connection		
circuit 1			U_{ext} = 8.2 V
	x+ x-		I_{max} = 8 mA with 29 V DC f = 2...10 kHz T_p = 0.05...1000 ms
circuit 2			
	x+ x-		

For all circuits apply:

• R_{ext} is the sum of all ohmic resistances in the circuit (e.g., resistance of the conductors, resistance of the ammeter/voltmeter).

• The number, type and connections of the outputs depend on the order.

• The terminal assignment is displayed on the transmitter during configuration of the outputs.

7.4 Service interfaces

7.4.1 USB interface

The transmitter can be connected directly to the PC via the USB interface.

• Connect the USB cable to the USB interface of the transmitter and to the PC.

Fig. 7.9:   Connection of the USB cable
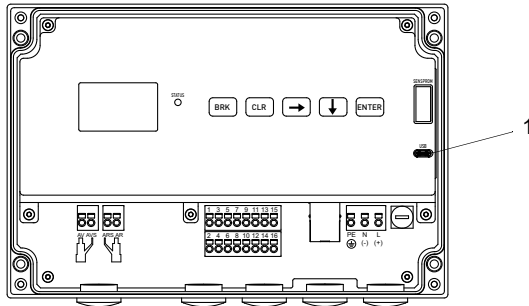
1 – USB interface

7.4.2 LAN interface

The transmitter can be connected to a PC or the local area network via the LAN cable.

Fig. 7.10:   Connection of the LAN cable
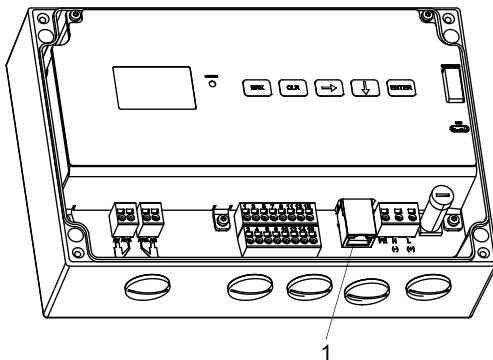
1 – LAN interface

• Remove the blind plug to connect the cable to the transmitter.
• Slide the flat gasket ring onto the LAN cable.
• Insert the cable into the transmitter housing.
• Insert the connector into the LAN interface port.
• Mount the split cable gland on the LAN cable.
• Slide the flat gasket ring onto the cable gland and screw the latter into the transmitter housing.

Fig. 7.11:   Split cable gland
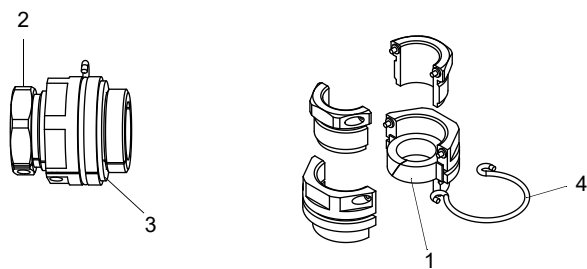
1 – split sealing ring
2 – split fitting
3 – flat gasket ring
4 – annular spring

8 Start-up

Warning!	
⚠️	**Installation, connection and start-up by unauthorized and unqualified personnel** This may result in personal or material damage or dangerous situations. → Any work on the transmitter has to be carried out by authorized and qualified personnel.

Caution!	
⚠️	**Safety and accident prevention regulations for electrical systems and equipment** Failure to observe these regulations may lead to severe injuries. → Observe the safety and accident prevention regulations for electrical systems and equipment.

Caution!	
⚠️	**Warning of severe injuries from hot or cold components** Touching hot or cold components can lead to severe injuries (e.g., thermal damage). → Any mounting, installation or connection work has to be concluded. → Any work on the measuring point during the measurement is prohibited. → Observe the ambient conditions at the measuring point during installation. → Wear the required personal protective equipment. → Observe the applicable rules.

Notice!
The transmitter and the sensor have to be checked for proper condition and operational safety before each use. The housing of the transmitter must always be closed during operation. Observe that maintenance work must be concluded.

8.1 Start-up settings

When starting up the transmitter for the first time, the following settings are required:

• language

• time/date

• system of units

These displays will only be indicated when the transmitter is switched on for the first time or after an initialization.

```
Language
```

The available transmitter languages are displayed.

• Select a language.

• Press ENTER.

The menus are displayed in the selected language.

```
Set time
```

The current time is displayed.

• Press ENTER to confirm the time or set the current time via the numeric field.

• Press ENTER.

```
Set date
```

The current date is displayed.

• Press ENTER to confirm the date or set the current date via the numeric field.

• Press ENTER.

```
Units of measurement
```

• Select `Metric` or `Imperial`.

• Press ENTER.

```
Region of Canada
```

• Select `Yes` if the transmitter is to be used in the region of Canada.

• Press ENTER.

This display will only be indicated if `Imperial` is selected.

8.2 Switching on

As soon as the transmitter is connected to the power supply, the menu is displayed in the adjusted language.
The language can be changed.

Notice!
The parameters cannot be changed during the measurement. The measurement has to be stopped in order to change the parameters.

If the transmitter was switched off during the measurement, the message `Measurement started` will be displayed after connecting the transmitter to the power supply. The measurement continues with the parameters set last.

By pressing BRK in the menu `Measurement` it is possible either to stop the measurement or to display the current parameter settings.

8.3 Language

```
Miscellaneous\System settings\Language
```

The language of the transmitter can be selected:

• Select the menu item `Language`.

• Press ENTER.

• Select the desired language from the scroll list.

• Press ENTER.

Afterwards the menu will be displayed in the selected language. The selected language remains activated when the transmitter is switched off and on again.

The language can also be changed by entering a HotCode.

8.4   Initialization

During an initialization (INIT) of the transmitter, all settings are reset to factory default. The initialization is started with the HotCode **909000**.

During an initialization it is tested whether the key lock is activated. If so, it has to be deactivated.

• Enter the 6-digit key lock code. For the input of numbers, see section 4.3.

• Press ENTER.

If a measurement is running, it will be stopped.

It will be asked whether the initial settings are to be carried out.

```
Initial settings
```

If `Yes` is selected, the following setting dialogs will be displayed:

•`Language`

•`Date/time`

•`Units of measurement`

•`Delete meas. values`

• `Delete user subst`. (all customized fluids which were stored after delivery will be deleted)

The initialization can also be started with the HotCode **909000**.

8.5   Date and time

```
Miscellaneous\System settings\Date/time
```

The transmitter has a battery-powered clock. Measured values are automatically stored with date and time.

• Select the menu item `Date/time`.

The adjusted time is displayed.

• Enter the current time. For the input of numbers, see section 4.3.

• Press ENTER.

The adjusted date is displayed.

• Enter the current date. For the input of numbers, see section 4.3.

• Press ENTER.

8.6   Information regarding the transmitter

```
Miscellaneous\System settings\Transmitter info
```

• Select the menu item `Transmitter info`.

• Press ENTER.

• Press ↓ to scroll through the list.

• Press BRK to return to the menu item `System settings`.

The following information relating to the transmitter is displayed:

display	description
`Serial number`	serial number of the transmitter
`Firmware version`	version number of the installed firmware
`Firmware date`	creation date of the installed firmware
`Verification log`	state of the verification logger

9 Measurement

Caution!
⚠️	**Warning of injuries when operating devices with damaged components** The transmitter and the sensor with damaged components must not be used. → The transmitter and the sensor have to be checked for proper condition and operational safety before each use. → The housing of the transmitter must always be closed during operation. → Observe that connection and maintenance work must be concluded.

Caution!
⚠️	**Warning of severe injuries from hot or cold components** Touching hot or cold components can lead to severe injuries (e.g., thermal damage). → Any mounting, installation or connection work has to be concluded. → Any work on the measuring point during the measurement is prohibited. → Observe the ambient conditions at the measuring point during installation. → Wear the required personal protective equipment. → Observe the applicable rules.

9.1 Parameter input

Notice!
Avoid a simultaneous parameter entry via the keyboard and the USB, LAN or process interface. The parameter records received via these interfaces will overwrite the current transmitter parametrization.
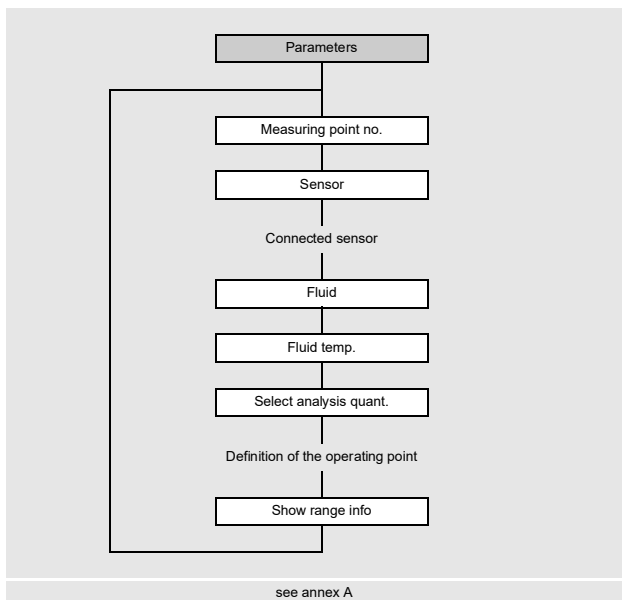
- Select the menu `Parameters`.
- Press ENTER.

9.1.1   Display of the sensor type

`Parameters\Connected sensor`

The sensor type and the terminal assignment are displayed.

• Press ⬇ to scroll through the list.

• Press ENTER.

9.1.2   Input of the measuring point number

`Parameters\Measuring point no.`

• Enter the number of the measuring point.

• Press ENTER.

For the activation of text input see `Miscellaneous\Dialogs/Menus\Measuring point no.`

9.1.3   Input of fluid parameters

The fluid parameters are entered for the selected measuring point.

Notice!
Customized fluids which are not included in the fluid scroll list can be read via the program FluxDiag. These fluids are displayed in the fluid scroll list with an asterisk.

Notice!
The supplied fluid data remain stored even after an initialization of the transmitter.

Fluid

`Parameters\Fluid`

• Select the fluid from the scroll list.

• Press ENTER.

If the fluid is not in the scroll list, select the list item `Other fluid`.

Scale

`Parameters\Fluid\Other fluid\Scale`

• Select the scale (Brix, API) from the scroll list.

• Press ENTER.

This display will only be indicated if `Other fluid` is selected.

Fluid temperature

`Parameters\Fluid temp.`

• Enter the fluid temperature at the operating point.

• Press ENTER.

9.1.4 Selection of the physical quantity for analysis

A fluid data set consisting of analyte and matrix was developed in the FLEXIM laboratory. This allows to calculate the physical quantity for analysis from the measured refractive index and the fluid temperature.

Tab. 9.1: Physical quantities for analysis

physical quantity for analysis	display	description	unit of measurement
mass fraction	`Mass fraction`	mass fraction of the analyte in the mixture (weight proportion)	wt% ppm
mole fraction	`Mole fraction`	proportion of the analyte in the mixture (mole fraction, particle fraction)	mol% ppm
volume fraction	`Volume fraction`	volume fraction of the analyte in the mixture	vol% ppm
analyte concentration	`Analyte concentr.`	mass of the analyte per volume of the mixture at reference temperature	g/l
matrix concentration	`Matrix concentration`	mass of the matrix per volume of the mixture at reference temperature	g/l
density	`Density`	density at current fluid temperature (operating density)	kg/m^3 g/cm^3 pounds per gallon
standardized density	`Norm. density`	density at reference temperature (laboratory density, reference density)	kg/m^3 g/cm^3 pounds per gallon
normalized refractive index	`Norm. refrac. index`	refractive index at reference temperature	-

---

Notice!

The physical quantity for analysis `Matrix concentration` is only displayed in the menu `Parameters\ Select analysis quant.` if a fluid is selected in which analyte and matrix are miscible in any proportion.

Notice!

For the conversion of kg/m³ to g/cm³ and of metric to imperial units, see the menu item `Miscellaneous\ Units of measurement`.

`Parameters\Select analysis quant.`

• Select the physical quantity for analysis.
• Press ENTER.
This display will not be indicated if `Other fluid` is selected.

`Parameters\Select analysis quant.\...\OP analysis quantity`

• Enter the operating point for the physical quantity for analysis.
• Press ENTER.

```
Parameters\Select analysis quant.\...\Show range info
```

The valid range of the physical quantity for analysis and of the temperature, density and refractive index can be displayed.

• Select `Yes` to display the valid range.

• Press ↓ to display the max. and min. values of the valid range.

• Press ENTER.

9.1.5   Input of the damping

```
Parameters\Damping
```

• Enter the damping factor. Values between 0...100 s are accepted.

• Press ENTER.

9.1.6   Input of the error delay

```
Parameters\Error delay
```

The error delay is the time interval after which the error value is transmitted to the output.

This display will only be indicated if the list item `Edit` is selected in the menu item `Miscellaneous\Dialogs/Menus\ Error delay`.

If no error delay is entered, the damping factor will be used.

• Enter a value for the error delay.

• Press ENTER.

9.2   Measurement settings

Swift damping

If `Swift damping` is activated, each displayed measured value is a floating average of the last x seconds, with x being the damping factor. The display thus takes x seconds to fully respond to changes of the measured value.

If `Swift damping` is deactivated, the damping is calculated as first order low-pass filter, i.e. changes of measured values become effective in form of an exponential time course in the measuring result.

```
Miscellaneous\Measurement settings\Swift damping
```

• Select the menu item `Swift damping`.

• Select `On` to activate `Swift damping`. Select `Off` to deactivate `Swift damping`.

• Select `Default` (`Swift damping` = `On`) if no customized inputs are to be made.

• Press ENTER.

Input of the reference temperature

```
Miscellaneous\Measurement settings\Reference temp.
```

• Enter the temperature for the local reference conditions (default value: 20 °C).

• Press ENTER.

Input of the reference pressure

```
Miscellaneous\Measurement settings\Reference pressure
```

• Enter the pressure for the local reference conditions (default value: 1 bar).

• Press ENTER.

9.3   Units of measurement

```
Miscellaneous\Unit of measurement
```

• Select the menu item `Miscellaneous\Unit of measurement`.

The following units of measurement for the physical quantities can be selected:
 – `Temperature`
 – `Pressure`
 – `Sound speed`
 – `Density`
 – `Kinematic viscosity`

• Select the unit of measurement of the physical quantity.

• Press ENTER.

Notice!
If the physical quantity or the unit of measurement is changed, the settings of the outputs will have to be checked.

9.4   Start of measurement

• Select the menu `Start measurement`.

• Press ENTER.

The measurement is started.

9.5   Display during the measurement

9.5.1   Measured value

The measured values are displayed during the measurement as follows:

Fig. 9.1:   Display of measured values
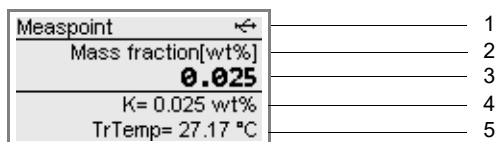
1 – menu, status indications
2 – physical quantity
3 – measured value
4 – further physical quantity
5 – further physical quantity

By pressing ![right] or ![down], additional physical quantities can be displayed during the measurement.

• Press ![down] to display the measured values in line 5. The designation of the physical quantity is displayed in line 4 by pressing ![right] for several seconds.

• Press ![right] to display the measured values in line 4. The designation of the physical quantity is displayed in line 5 by pressing ![down] for several seconds.

9.5.2 Parameters

Parameter settings

The parameter settings can be displayed during the measurement.

• Press BRK during the measurement.

The transmitter returns to the main menu.

Fig. 9.2: Display of the main menu during the measurement
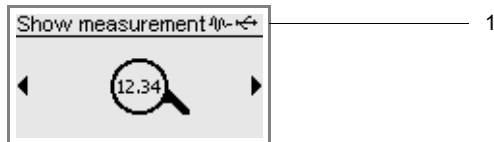
1 – status indication

The measurement is running in the background. The symbol is displayed in the status indication.

• Press → or CLR to select the corresponding menu to display the parameters.

Notice!
The parameters cannot be changed during the measurement. When attempting to change the parameters, the message `Read-only mode` will be displayed.
The measurement has to be stopped in order to change the parameters.

Information regarding the data logger

Information regarding the data logger can be displayed during the measurement.

• Press → until the following is displayed:

Fig. 9.3: Information regarding the data logger
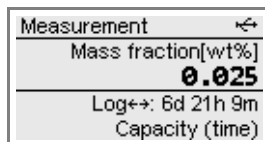
If the ringbuffer is deactivated, line 4 indicates when the data logger will be full in case all settings are kept.

If the ringbuffer is activated, line 4 indicates how long measurement data can still be stored without losing older measurement data.

The information regarding the data logger can also be displayed using the function `Show parameters`.

```
Storage\Data logger\Data logger info
```

• Press BRK during the measurement.
• Select the list item `Data logger\Data logger info` in the menu `Storage`.
• Press ENTER.

The information regarding the data logger is displayed.

9.5.3 Change to the display of measured values

• Press and hold BRK to return to the main menu.
• Select the menu `Show measurement`.
• Press ENTER.

The measured values are displayed.

9.6 Stop of measurement

• Press and hold BRK to return to the main menu.

• Select the menu Stop measurement.
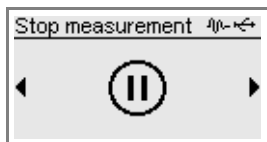
• Press ENTER.

• Select Yes to stop the measurement.

• Press ENTER.

The measurement is stopped. The main menu will be displayed.

10 Troubleshooting

Warning!	
⚠	**Service works by unauthorized and unqualified personnel** This may result in personal or material damage or dangerous situations. → Any work on the transmitter has to be carried out by authorized and qualified personnel.

Caution!	
⚠	**Safety and accident prevention regulations for electrical systems and equipment** Failure to observe these regulations may lead to severe injuries. → Observe the safety and accident prevention regulations for electrical systems and equipment.

Warning!	
⚠	**Touching live parts** Electric shock or arc faults can lead to severe injuries. The measuring equipment can be damaged. → Prior to any work on the transmitter (e.g., installation, dismounting, connection, start-up), the transmitter has to be disconnected from the power supply. It is not sufficient to remove the internal fuse of the instrument.

Caution!	
⚠	**Touching hot or cold surfaces** This may result in injuries (e.g., thermal damages). → Observe the ambient conditions at the measuring point during installation. → Wear the required personal protective equipment. → Observe the applicable rules.

If any problem appears which cannot be solved with the help of this operating instruction, contact our sales office and give a precise description of the problem. Specify the type, the serial number and the firmware version of the transmitter.

The display does not work at all or fails regularly.

• Check the contrast setting of the transmitter or enter the HotCode **555000** to set the display to medium contrast.
• Make sure that the correct voltage is available at the terminals. The destined transmitter voltage is indicated on the nameplate below the outer right terminal strip.
• If the power supply is OK, the sensor or an internal component of the transmitter is defective. The sensor and the transmitter have to be sent to FLEXIM for repair.
• If the transmitter is only connected via the USB interface, the backlight will be switched off.

An error is displayed in the status indication (symbol ⚠).

• Press BRK to return to the main menu.
• Select the menu item `Storage\Event log`.
• Press ENTER.

The error message list will be displayed.

An output does not work.

• Make sure that the outputs are configured correctly. Check the function of the output. If the output is defective, contact FLEXIM.

10.1 Problems with the measurement

A measurement is not possible because no signal is received. An interrogation point is displayed after the physical quantity. The LED lights red after starting the measurement.

• Make sure the sensor is correctly connected to the transmitter. The sensor must be recognized by the transmitter. The serial number of the sensor will be displayed (see menu item `Parameters\Connected transd.`).

The signal is lost during the measurement.

• If there is no measuring signal after the pipe had been run empty and refilled, contact FLEXIM.

• Make sure the pipe is filled with the fluid and the sensor head is completely submerged into the fluid. The sensor can only measure within the fluid, otherwise the measurement becomes invalid. The measurement can be interrupted due to a temporarily higher proportion of gas bubbles and solids in the fluid.

• The sensor functions according to the transmitted light principle. A turbid fluid and contaminated measurement optics can attenuate the light to such an extent that the measuring signal is invalid. Check the measurement optics for contamination.

10.2 Measuring point selection

• Avoid measuring points with deposit formation in the pipe.

• When measuring on a horizontal pipe, the sensor has to be mounted laterally on the pipe.

• A vertical pipe always has to be filled at the measuring point and the fluid should flow upward.

• No gas bubbles should form (even bubble-free fluids can form gas bubbles when the fluid expands, e.g., upstream of pumps and downstream of great cross-section enlargements).

10.3 Application-specific problems

The measuring points of the physical quantities for analysis are outside the valid range

• Check the entered value.

Turbid signals scatter the optical signal

• The measurement of fluids with a turbidity > 10000 FAU (Formazine Attenuation Units) becomes invalid.

Gas bubbles or solids present in high concentration in the fluid scatter and absorb the optical signal and thus attenuate the measuring signal

11 Maintenance and cleaning

Warning!
Service works by unauthorized and unqualified personnel This may result in personal or material damage or dangerous situations. → Any work on the transmitter has to be carried out by authorized and qualified personnel.

Warning!
Touching live parts Electric shock or arc faults can lead to severe injuries. The measuring equipment can be damaged. → Prior to any work on the transmitter (e.g., installation, dismounting, connection, start-up), the transmitter has to be disconnected from the power supply. It is not sufficient to remove the internal fuse of the instrument.

Caution!
Safety and accident prevention regulations for electrical systems and equipment Failure to observe these regulations may lead to severe injuries. → Observe the safety and accident prevention regulations for electrical systems and equipment.

Caution!
Touching hot or cold surfaces This may result in injuries (e.g., thermal damages). → Observe the ambient conditions at the measuring point during installation. → Wear the required personal protective equipment. → Observe the applicable rules.

11.1 Maintenance

The transmitter and the sensor are practically maintenance-free. In order to ensure security, the following maintenance intervals are recommended:

Tab. 11.1: Recommended maintenance intervals

item	maintenance step	interval	measure
transmitter	• visual inspection for corrosion, damages and contamination	annually or more frequently, depending on the ambient conditions	cleaning
	• firmware check for updates	annually	update, if necessary
	• functional test	annually	reading of measured and diagnostic values
sensor	• dismounting and visual inspection of the O-rings and measurement optics for corrosion, damages and contamination	annually or more frequently, depending on the ambient conditions	cleaning, change of O-rings, if necessary
	• functional test	annually	reading of measured and diagnostic values

11.2 Cleaning

Generally, the regular process cleaning and rinsing cycles are sufficient to keep the optical surfaces of the measuring prism and window clean. However, depending on the measured fluid, it can be necessary to clean the measuring prism or window to avoid the formation of deposits.

For manual cleaning the sensor is dismounted and cleaned with a cloth (see Fig. 11.1).

Important!
Do not use aluminous abrasives when cleaning the measuring prism and window.

Notice!
When using aggressive detergents observe the chemical resistance of the corresponding parts.

Fig. 11.1: Cleaning of measuring prism and window

1 – window
2 – measuring prism

12 Dismounting and disposal

Warning!
Installation, connection and start-up by unauthorized and unqualified personnel This may result in personal or material damage or dangerous situations. → Any work on the transmitter has to be carried out by authorized and qualified personnel.

Warning!
Touching live parts Electric shock or arc faults can lead to severe injuries. The measuring equipment can be damaged. → Prior to any work on the transmitter (e.g., installation, dismounting, connection, start-up), the transmitter has to be disconnected from the power supply. It is not sufficient to remove the internal fuse of the instrument.

Caution!
Safety and accident prevention regulations for electrical systems and equipment Failure to observe these regulations may lead to severe injuries. → Observe the safety and accident prevention regulations for electrical systems and equipment.

12.1 Dismounting

Dismounting is carried out in reverse order to the installation.

12.2 Disposal

The measuring equipment has to be disposed of in accordance with the applicable regulations.

Important!
Proper disposal of components of the transmitter and accessories that are no longer required avoids environmental damage and conserves resources. Depending on the material, the corresponding parts have to be disposed of in residual or special waste or recycled in accordance with the applicable regulations. Batteries must be disposed of separately from electrical or electronic equipment. For this purpose, remove the batteries from the device and take them to the designated disposal system. The components are taken back free of charge by FLEXIM in accordance with national regulations. Contact FLEXIM.

13 Outputs

```
                    ┌──────────────┐
                    │   Outputs    │
                    └──────────────┘
                           │
                     Select output
                           │
                           │
                     Enable output
                           │
                    ┌──────────────┐
                    │ Source item  │
                    └──────────────┘
                    ┌──────────────┐
                    │ Output range │
                    └──────────────┘
                           │
                    Measured values
                     Status values
                      Event values

                     see annex A
```
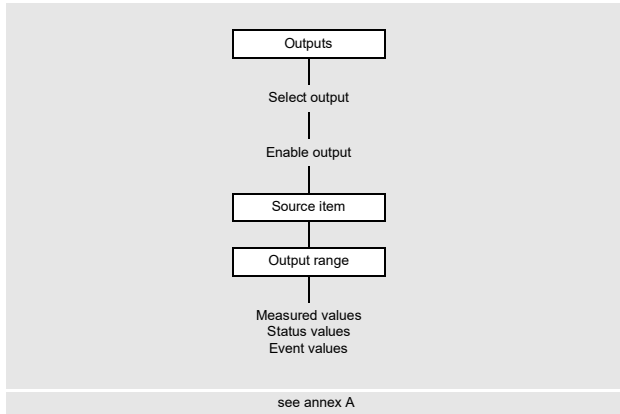
13.1 Analog output

If the transmitter is equipped with outputs, they have to be configured. In principle, the measured value, the status value or an event value can be transmitted via the different outputs.

• Select the menu `Outputs`.

• Press ENTER.

```
Outputs\Current I1(--)
```

• Select the output to be configured.

The scroll list contains all available outputs.

• Press ENTER.

13.1.1 Enabling an output

If the output has to be used, it has to be enabled (here: `Current I1`)

```
Outputs\Current I1(--)
```

• Select the output `Current Ix (--)`.

• Press ENTER.

If the output has already been enabled, it is displayed as follows: `Current I1 (√)`.

```
Outputs\Current I1\I1 Enable
```

• Select `Yes` to enable an output or change the settings for an already enabled output.

• Select `No` to cancel the enabling and to return to the previous menu item.

• Press ENTER.

13.1.2 Assignment of a source item

One source item has to be assigned to each selected output.

```
Outputs\...\Source item
```

• Select a source item whose measured value, status value or event value is to be transmitted to the output.

• Press ENTER.

Tab. 13.1: Configuration of the outputs

source item	list item	output
Refractometer	Symmetry Gain Amplitude Quality SNR	diagnostic values
Sensor	Sensor humidity Transducer temp.	sensor values
Analysis	Mass fraction Brix scale	physical quantity for analysis selected in the menu Parameters
Fluid properties	Fluid temp. Fluid density Norm. density	
Event trigger	R1	limit message (Event trigger R1)
	R2	limit message (Event trigger R2)
	R3	limit message (Event trigger R3)
	R4	limit message (Event trigger R4)
Miscellaneous	Custom. Input 1 Custom. Input 2 Custom. Input 3 Custom. Input 4	If a fieldbus is connected, input quantities (e.g., sound speed, density) which are not used for calculation can be assigned as source item. For the connection of the fieldbuses to the transmitter, see supplement to operating instruction.
Refractive index	Refractive index Norm. refrac. index Refractive index (Δ)	

Depending on the selected source item, it is possible to output measured values, status values or event values.

Tab. 13.2: Output of measured values, status values or event values

	source item	measured value		event value
		value	status	
physical quantities	Refractometer	x	x	-
	Analysis	x	x	-
	Fluid properties	x	x	-
	Miscellaneous	x	x	-
	Refractive index	x	x	-
events	Event trigger	-	-	x

13.1.3   Output of a measured value


```
                    Source item

                      Values

                   Output range

                  Measuring range

                    Output info

                    Test signal

                Test measuring range
```
see annex A
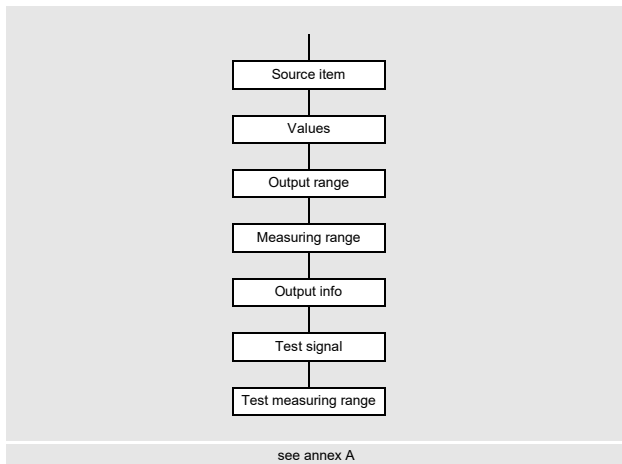
Output range

• Select `Values` in the menu item `Source item`.

• Press ENTER.

```
Outputs\...\Output range
```

• Select a list item.

– `4...20 mA`
– `Other range`

• Press ENTER.

If `Other range` is selected, enter the values `Output MIN` and `Output MAX`.

The output range has to be > 10 % of the max. output value (`Output MAX`).

If the output range is smaller, an error message will be displayed.

The next possible value will be displayed.

• Repeat the input.

Error output

```
Outputs\...\Error value
```

An error value can be defined which is output if the source item cannot be measured.

• Select a list item for the error output.

• Press ENTER.

• If `Other value` is selected, enter an error value. The value has to be outside the output range.

• Press ENTER.
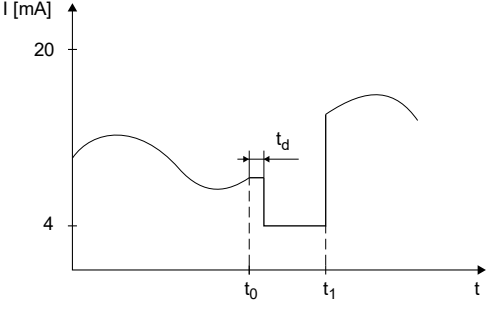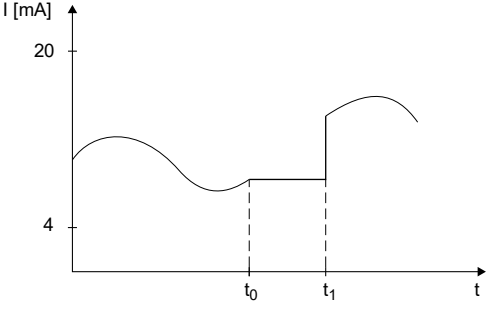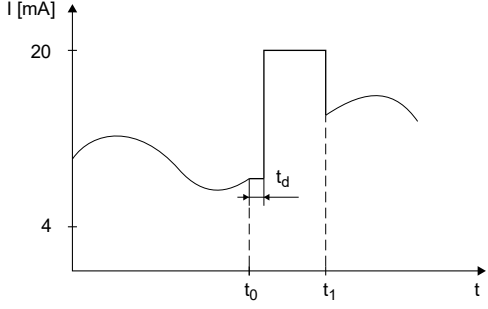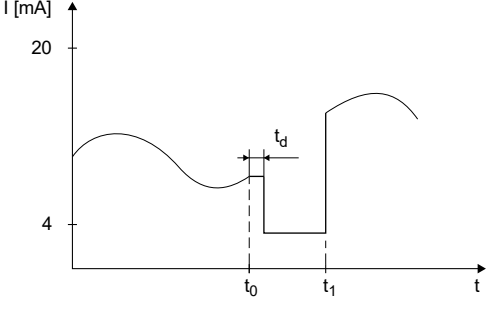
Example

source item:	normalized refractive index n_D
output:	current
output range:	4...20 mA
error delay	$t_d > 0$

The normalized refractive index n_D cannot be measured during the time interval $t_0...t_1$. The error value will be output.
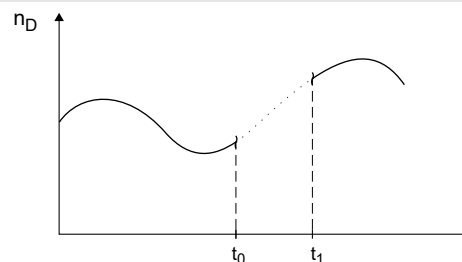
Tab. 13.3:   Examples for the error output (output range: 4...20 mA)

list item	output signal
Minimum (4.0 mA)	
Last value	
Maximum (20.0 mA)	
Other value error value = 3.5 mA	

Measuring range

The measuring range is defined.

```
Outputs\...\Start of meas. range
```

• Enter the lowest expected measured value. The unit of measurement of the source item will be displayed.
`Start of meas. range` is the value assigned to the value `Output MIN` of the output range.

```
Outputs\...\End of meas. range
```

• Enter the highest expected measured value. The unit of measurement of the source item will be displayed.
`End of meas. range` is the value assigned to the value `Output MAX` of the output range.

Terminal assignment

```
Outputs\...\Output info
```

The terminals for the connection of the output are displayed.
By pressing ➡ or ⬇ further information is displayed.
• Press ENTER.

Output function test

The function of the output can now be tested.
• Connect an external measuring instrument to the terminals of the output.

```
Outputs\...\Test signal
```

• Select `Yes` to test the output. Select `No` to display the next menu item.
• Press ENTER.

```
Outputs\...\Enter test value
```

• Enter a test value. It has to be within the output range.
• Press ENTER.
If the external measuring instrument displays the entered value, the output functions correctly.
• Select `Repeat` to repeat the test, `Finish` to display the next menu item.
• Press ENTER.

```
Outputs\...\Test measuring range
```

• Select `Yes` to test the assignment of the measured value to the output signal. Select `No` to display the next menu item.
• Press ENTER.

```
Outputs\...\Enter test value
```

• Enter a test value. It has to be within the expected measuring range.
• Press ENTER.
If the external measuring instrument displays the corresponding current value, the output functions correctly.
• Select `Repeat` to repeat the test or `Finish` to display the next menu item.
• Press ENTER.

13.1.4   Output of a status/event value

```
                        ┌─────────────────┐
                        │   Source item   │
                        └─────────────────┘
                        ┌─────────────────┐
                        │     Status      │
                        └─────────────────┘
                        ┌─────────────────┐
                        │  Output range   │
                        └─────────────────┘
              ┌──────────────┐   ┌──────────────┐
              │  Status OK   │   │  Idle state  │
              └──────────────┘   └──────────────┘
                        ┌─────────────────┐
                        │   Output info   │
                        └─────────────────┘
                        ┌─────────────────┐
                        │   Test signal   │
                        └─────────────────┘
                    ┌─────────────────────────┐
                    │   Test measuring range  │
                    └─────────────────────────┘

                          see annex A
```
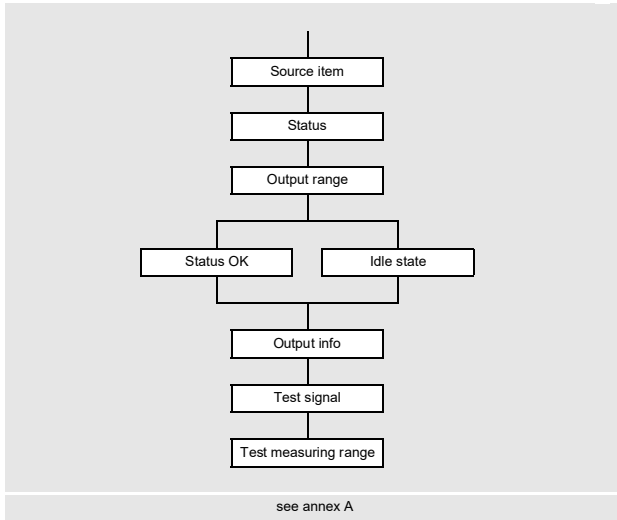
• Select `Status` in the menu item `Source item`.
• Press ENTER.

Output range

> `Outputs\...\Output range`

• Select a list item.

  – `4...20 mA`
  – `Other range`

• Press ENTER.

If `Other range` is selected, enter the values `Output MIN` and `Output MAX`.

The output range has to be > 10 % of the max. output value (`Output MAX`). If the output range is smaller, an error message will be displayed. The next possible value will be displayed.

status value – status OK	event value – idle state
The status of the output signal is defined which is to be output when measuring a measured value.	The status of the output signal is defined which is to be output if no event occurs.
• Select the value for status OK from the scroll list. • Press ENTER.	• Select the value for the idle state. • Press ENTER.

Terminal assignment

> `Outputs\...\Output info`

The terminals for the connection of the output are displayed.

By pressing [→] or [↓] further information is displayed.
• Press ENTER.

Output function test

The function of the output can now be tested.
• Connect an external measuring instrument to the terminals of the output.

> `Outputs\...\Test signal`

• Select `Yes` to test the output. Select `No` to display the next menu item.
• Press ENTER.

> `Outputs\...\Enter test value`

• Enter a test value. It has to be within the output range.
• Press ENTER.

If the external measuring instrument displays the entered value, the output functions correctly.
• Select `Repeat` to repeat the test, `Finish` to display the next menu item.
• Press ENTER.

```
Outputs\...\Test measuring range
```

• Select `Yes` to test the assignment of the measured value to the output signal. Select `No` to display the next menu item.
• Press ENTER.

```
Outputs\...\Enter test value
```

• Select a list item as test value.
• Press ENTER.

status value	event value
`Status OK` or `Status error`.	`Active` or `Passive`.
If the external measuring instrument displays the value (min. output value for `Status error`, max. output value for `Status OK`), the output functions correctly.	If the external measuring instrument displays the value (min. output value for `Passive`, max. output value for `Active`), the output functions correctly.

• Select `Repeat` to repeat the test. Select `Finish` to display the next menu item.
• Press ENTER.

13.2   Digital output

The transmitter can also be equipped with digital outputs. A digital output combines the functions of the following outputs:
• binary output (output of binary switching conditions)
• pulse output (integrating output of quantities)
• frequency output (scaled output of flow quantities)
These functions depend on the selected physical quantity.

Tab. 13.4:   Output via digital outputs

		binary output		pulse output	frequency output
	source item	status value	event value		
physical quantities	`Refractometer`	x			
	`Analysis`	x			
	`Pulse`			x	
	`Fluid properties`	x			x
	`Diagnostic values`				x
	`Miscellaneous`	x			x
	`Refractive index`	x			
events	`Event trigger`		x		

13.2.1   Configuration of a digital output as binary output

A binary output switches if one of the following switching conditions is met:
- – the measured value exceeds or falls below a limit
- – the measured value lays within or outside a defined range
- – a measurement is not possible
- – an event occurs

• Select the menu `Outputs`.

• Press ENTER.

```
Outputs\Binary B1\Enable B1
```

• Select `Yes` to change the settings for an assigned output or to assign a new output.

• Select `No` to cancel the assignment and to return to the previous menu item.

• Press ENTER.

Assignment of a source item

```
Outputs\...\Source item
```

Depending on the selected source item, status or event values can be output.

Tab. 13.5:   Output of status values and event values

	source item	status value	event value
physical quantities	Refractometer	x	
	Analysis	x	
	Fluid properties	x	
	Miscellaneous	x	
	Refractive index	x	
events	Event trigger		x

• Select the source item.

• Press ENTER.

13.2.1.1   Definition of the switching function for the status/event value

• Select the switching function for the output of the status/event value.

• Press ENTER.

Tab. 13.6:   Selection of the switching condition

property	switching function	description
Status OK (status value)	NC	• valid measured value: binary output is closed • invalid measured value: binary output is open
	NO	• valid measured value: binary output is open • invalid measured value: binary output is closed
Idle state (event value)	NO	• event occurs: binary output is closed • event has not occurred yet: binary output is open
	NC	• event occurs: binary output is open • event has not occurred yet: binary output is closed

If no measurement is carried out, all binary outputs are open (de-energized), independent of the set switching condition.

Terminal assignment

```
Outputs\...\Output info
```

The terminals for the connection of the output are displayed.

By pressing ➡ or ⬇ further information is displayed.

• Press ENTER.

Output function test

The function of the output can now be tested.

• Connect a multimeter to the output.

```
Outputs\...\B1 Test signal
```

• Select `Yes` to test the output. Select `No` to display the next menu item.

• Press ENTER.

```
Outputs\...\B1 Enter test value
```

• Select a list item as test value.

• Press ENTER.

Tab. 13.7: Output function test – signal

list item	description
NC	• binary output is energized • measured value has to be low ohmic
NO	• binary output is de-energized • measured value has to be high ohmic

• Select `Repeat` to repeat the test or `Finish` to display the next menu item.

• Press ENTER.

```
Outputs\...\B1 Test measuring range
```

• Select `Yes` to test the status of the output signal. Select `No` to display the next menu item.

• Press ENTER.

```
Outputs\...\B1 Enter test value
```

• Select a list item as test value.

• Press ENTER.

Tab. 13.8: Output function test – measuring range

list item	switching function	test value	description
Status OK (status value)	NC	Status OK	• binary output is energized • measured value has to be low ohmic
		Status error	• binary output is de-energized • measured value has to be high ohmic
	NO	Status OK	• binary output is de-energized • measured value has to be high ohmic
		Status error	• binary output is energized • measured value has to be low ohmic
Idle state (event value)	NC	Passive	• binary output is energized • measured value has to be low ohmic
		Active	• binary output is de-energized • measured value has to be high ohmic
	NO	Passive	• binary output is de-energized • measured value has to be high ohmic
		Active	• binary output is energized • measured value has to be low ohmic

• Select Repeat to repeat the test or Finish to display the next menu item.

• Press ENTER.

13.2.2 Configuration of a digital output as pulse output

A pulse output is an integrating output which emits a pulse when the volume or the mass of the fluid which has passed the measuring point reaches a certain value (pulse value).

The integrated quantity is the selected physical quantity. The integration is restarted as soon as the pulse is emitted. Before the activation, the digital output has to be configured.

```
Outputs\Digital output B1\Source item
```

• Select the menu item Outputs\Digital output B1\Source item.

• Press ENTER.

Assignment of a source item

```
Outputs\Source item\Pulse
```

• Select Pulse as source item.

• Press ENTER.

```
Outputs\Pulse\Pulse +V
```

• Select a list item (here: Pulse +V).

• Press ENTER.

Tab. 13.9: Selection of the physical quantity

source item	list item	output
Pulse	Pulse |V|	pulse without considering the sign of the volumetric flow rate
	Pulse +V	pulse for positive measured values of the volumetric flow rate
	Pulse –V	pulse for negative measured values of the volumetric flow rate
	Pulse |m|	pulse without considering the sign of the mass flow rate
	Pulse +m	pulse for the positive measured values of the mass flow rate
	Pulse –m	pulse for the negative measured values of the mas flow rate

13.2.2.1 Pulse output by defining the pulse value

`Outputs\Pulse output`

• Select the list item `Pulse value`.

• Press ENTER.

The pulse output can be operated in 2 modes:

mode	description
Continuous pulses	• output of a continuous pulse sequence, reproducing the temporal behavior of the corresponding flow quantity (volumetric flow rate, mass flow rate), with simultaneous totalizing • smallest pulse break = pulse width at max. pulse rate (pulse width is constant)
Burst pulses	• output of a discontinuous pulse sequence, reproducing the behavior of the totalizer • several pulses can arise intermittently with equidistant pulse distances (pulse break = pulse width) • serves exclusively for totalizing • max. pulse rate (depends on the pulse width that is constant)

• Select a list item.

• Press ENTER.

`Outputs\Pulse value`

• Enter the pulse value.

The unit of measurement will be displayed according to the actual physical quantity.

When the counted physical quantity reaches the entered pulse value, a pulse will be transmitted.

• Press ENTER.

`Outputs\Pulse width`

• Enter the pulse width.

The range of possible pulse widths depends on the specification of the instrument (e.g., counter, PLC) that is to be connected to the output.

• Press ENTER.

13.2.2.2 Pulse output by defining pulses per unit

```
Outputs\Pulse output
```

• Select the list item `Pulses per unit`.
• Press ENTER.

```
Outputs\Output range
```

• Select a list item:

– `0...1 kHz`
– `0...5 kHz`
– `Other range`

• Press ENTER.

If `Other range` is selected, enter a value for `Output MAX`.

```
Outputs\Pulses per unit
```

• Enter the number of pulses per unit.
• Press ENTER.

The unit of measurement will be displayed according to the actual physical quantity.

13.2.2.3 Output options

```
Outputs\Idle state
```

• Select the setting of the idle state:

setting	description
NO	The pulse output is energized if a pulse is emitted and de-energized if no pulse is emitted (idle state).
NC	The pulse output is de-energized if a pulse is emitted and energized if no pulse is emitted (idle state).

If no measurement is carried out, all pulse outputs are open (de-energized), independent of the set switching condition.

Terminal assignment

```
Outputs\...\Output info
```

The terminals for the connection of the output are displayed.
By pressing ➡ or ⬇ further information is displayed.
• Press ENTER.

Output function test

```
Outputs\...\B1 Test signal
```

• Select `Yes` to test the status of the output signal. Select `No` to display the next menu item.
• Press ENTER.

```
Outputs\...\B1 Enter test value
```

• Select a list item as test value.
• Press ENTER.

Tab. 13.10: Output function test – signal

output mode	test value	description
Pulses per unit	The entered test value has to be within the output range.	If the external measuring instrument displays the entered value, the output functions correctly.
Pulse value	NO	• pulse output is de-energized • measured value has to be high ohmic
	NC	• pulse output is energized • measured value has to be low ohmic

13.2.3   Configuration of a digital output as frequency output

The frequency output emits a square wave signal with a frequency which is proportional to the measured value of the source item sent to the output.

```
Outputs\Digital output B1\Source item
```

• Select the menu item `Outputs\Digital output B1\Source item`.
• Press ENTER.

Assignment of a source item
• Select one of the following source items:
 – `Analysis`
 – `Fluid properties`
 – `Event trigger`
 – `Miscellaneous`
 – `Refractive index`
 – `Refractometer`

```
Outputs\Flow quantities
```

• Select a list item (here: `Fluid properties`).
• Press ENTER.

```
Outputs\Volumetric flow rate
```

• Select a list item (here: `Fluid temp.`).
• Press ENTER.
• Select the list item `Values`.
• Press ENTER.

Output range

```
Outputs\...\Output range
```

• Select a list item.

– `0...1 kHz`
– `0...10 kHz`
– `Other range`

• Press ENTER.

If `Other range` is selected, enter the values `Output MIN` and `Output MAX`.

Error output

```
Outputs\...\Error value
```

An error value can be defined which is output if the source item cannot be measured.

• Select a list item for the error output.

• Press ENTER.

Measuring range

The sign of the measured value and the measuring range are determined.

```
Outputs\...\Measured values\Absolute value
```

• Select `Sign` if the sign of the measured values is to be considered for the output.

• Select `Absolute value` if the sign of the measured values is not to be considered for the output.

```
Outputs\...\Start of meas. range
```

• Enter the lowest expected measured value. The unit of measurement of the source item will be displayed.

`Start of meas. range` is the value assigned to the value `Output MIN` of the output range.

```
Outputs\...\End of meas. range
```

• Enter the highest expected measured value. The unit of measurement of the source item will be displayed.

`End of meas. range` is the value assigned to the value `Output MAX` of the output range.

Idle state

The idle state is the status of the output signal to be output when no measured value is measured.

• Select a list item for the idle state.

• Press ENTER.

Terminal assignment

```
Outputs\...\Output info
```

The terminals for the connection of the output are displayed.

By pressing [→] or [↓] further information is displayed.

• Press ENTER.

Output function test

The function of the output can now be tested.

• Connect an external measuring instrument to the terminals of the installed output.

```
Outputs\...\Test signal
```

• Select `Yes` to test the output. Select `No` to display the next menu item.
• Press ENTER.

```
Outputs\...\Enter test value
```

• Enter a test value. It has to be within the output range.
• Press ENTER.
If the external measuring instrument displays the entered value, the output functions correctly.
• Select `Repeat` to repeat the test or `Finish` to display the next menu item.
• Press ENTER.

```
Outputs\...\Test measuring range
```

• Select `Yes` to test the assignment of the measured value to the output signal. Select `No` to display the next menu item.
• Press ENTER.

```
Outputs\...\Enter test value
```

• Enter a test value. It has to be within the output range.
• Press ENTER.
If the external measuring instrument displays the entered value, the output functions correctly.
• Select `Repeat` to repeat the test and `Finish` to finish it.
• Press ENTER.

14   Data logger

```
                    ┌─────────────────┐
                    │     Storage     │
                    └─────────────────┘
                    ┌─────────────────┐
                    │   Data logger   │
                    └─────────────────┘

                    ┌─────────────────┐
                    │  Configuration  │
                    └─────────────────┘
                    ┌─────────────────┐
                    │  Enable logger  │
                    └─────────────────┘
                    ┌─────────────────┐
                    │  Start storing  │
                    └─────────────────┘
                    ┌─────────────────┐
                    │   Ringbuffer    │
                    └─────────────────┘

          ┌─────────────┐    ┌─────────────┐
          │     On      │    │     Off     │
          └─────────────┘    └─────────────┘

                    ┌─────────────────┐
                    │  Storage mode   │
                    └─────────────────┘

          ┌─────────────┐    ┌─────────────┐
          │   Average   │    │   Sample    │
          └─────────────┘    └─────────────┘

                    ┌──────────────────────┐
                    │ Store diagnost. values│
                    └──────────────────────┘
                    ┌──────────────────────┐
                    │  Store sensor temp.   │
                    └──────────────────────┘

                        see annex A
```
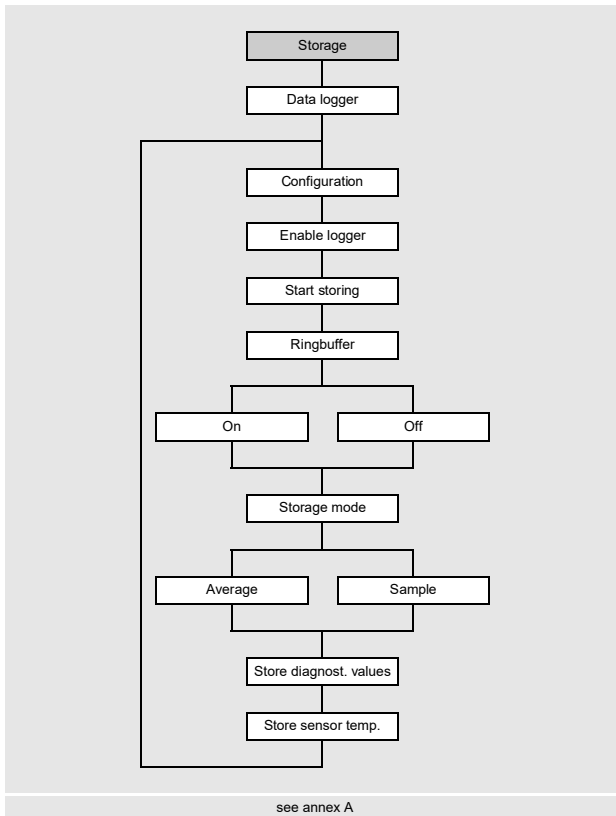
The transmitter has a data logger which stores the measured values during the measurement.

> **Notice!**
>
> In order to store measured data, the data logger has to be configured.

The following data is stored within the data logger:

• date
• time
• measuring point number
• fluid parameters
• sensor data
• physical quantity
• unit of measurement
• measured value

Measured values transmitted via the outputs are also stored in the data logger.

14.1   Configuration of the data logger

Enabling the data logger

```
Storage\Data logger\Configuration\Enable logger
```

• Select the menu item `Data logger\Configuration` in the menu `Storage`.
• Press ENTER.
• Select `Yes` to enable the data logger.
• Press ENTER.

Starting time

```
Storage\Data logger\Configuration\Start storing
```

It is possible to set a starting time if it is necessary to synchronize the storing of measured values for several transmitters.
• Select the menu item `Storage\Data logger\Configuration`.
• Press ENTER until the menu item `Start storing` is displayed.
• Select the moment at which to start the storing.
• Press ENTER.

display	description
`Immediately`	The storing starts immediately.
`Full 5 minutes`	The storing starts in the next full 5 minutes.
`Full 10 minutes`	The storing starts in the next full 10 minutes.
`Full 15 minutes`	The storing starts in the next full 15 minutes.
`Full 30 minutes`	The storing starts in the next full 30 minutes.
`Full hour`	The storing starts in the next full 60 minutes.
`Event-based`	The storing starts when a defined event occurs.

Example

actual time: 09:06 am
setting: `Full 10 minutes`
The storing starts at 09:10 am.

Notice!

Make sure that the time of all transmitters is synchronized.

Event-based starting time
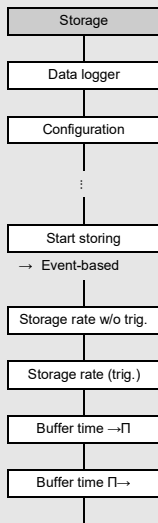
```
Storage
   │
Data logger
   │
Configuration
   ⋮
Start storing
 → Event-based
   │
Storage rate w/o trig.
   │
Storage rate (trig.)
   │
Buffer time →Π
   │
Buffer time Π→
```
see annex A

`Storage\Data logger\Configuration\`
`Start storing\Event-based`

If it is necessary to start the storing of measured values at a particular event, select the list item `Event-based` as starting time.

The event is signalized via an event trigger. All configured event triggers are displayed in the scroll list.

• Select the event trigger through which the event is to be signalized.

• Press ENTER.

`Storage\Data logger\Configuration\Start storing\Event-based\Storage rate w/o trig.`

The storage rate is the frequency to transmit or store measured values.

• Select in the scroll list a storage rate for storing the measured values in case the event does not occur.

• Press ENTER.

• Select `Off` if no measured values are to be stored, as long as the event does not occur.

• Press ENTER.

```
Storage\Data logger\Configuration\Start storing\Event-based\Storage rate (trig.)
```

• Select in the scroll list a storage rate for storing the measured values in case the event occurs.
• Press ENTER.

```
Storage\Data logger\Configuration\Start storing\Event-based\Buffer time ->Π
```

• Enter the time interval for the measured values to be stored before the event occurs.
• Press ENTER.

```
Storage\Data logger\Configuration\Start storing\Event-based\Buffer time Π->
```

• Enter the time interval for the measured values to be stored if the event is no longer activated.
• Press ENTER.

Storage rate

```
Storage\Data logger\Configuration\Storage rate
```

The storage rate is the frequency to transmit or store measured values. If a start time for storing the measured values is defined, a storage rate has to be entered.
• Select the menu item `Storage\Data logger\Configuration`.
• Press ENTER until the menu item `Storage rate` is displayed.
• Select a storage rate from the scroll list.
• Press ENTER.
• If `Customized` is selected, enter the storage rate.
• Press ENTER.

Ringbuffer

```
Storage\Data logger\Configuration\Ringbuffer
```

The data logger can be configured as linear logger or ringbuffer. If the ringbuffer is deactivated and the data logger is full, the storing of measured values will be terminated. It can be continued after clearing the data logger. If the ringbuffer is activated and the data logger is full, the oldest measured values will be overwritten. In ringbuffer mode, the remaining capacity of the data logger is displayed during the measurement, e.g.:

`Log⟷ : 1d 6h 57m` is displayed, if no measured values have been overwritten.

`Log|⟷| : 1d 6h 57m` is displayed, if the old measured values have been overwritten.
• Select the menu item `Storage\Data logger\Configuration`.
• Press ENTER until the menu item `Ringbuffer` is displayed.
• Select `On` to activate the ringbuffer.
• Press ENTER.

If the ringbuffer is deactivated and the data logger is full, the storing of measured values will be terminated.
• Select `Off` to deactivate the ringbuffer.
• Press ENTER.

Storage mode

```
Storage\Data logger\Configuration\Storage mode
```

• Select the menu item `Storage\Data logger\Configuration`.
• Press ENTER until the menu item `Storage mode` is displayed.
• Press ENTER.
• Select `Sample` to store the current measured value.
• Select `Average` if the average of all undamped measured values of a storage interval is to be stored.

Notice!
The storage mode does not affect the outputs.

Notice!
`Storage mode` = `Average`
The average of the physical quantity and of other quantities, e.g., the measured temperature, will be calculated.
If a storage rate < 5 s is selected, `Sample` is used.
If no average could be calculated over the complete storage interval, the value is marked as invalid.

Further parameters for storing

It can be defined whether the following parameters are to be stored together with the measured values.

Tab. 14.1: Parameters for storing

display	description of the parameters
`Store diagnost. values`	diagnostic values
`Store sensor temp.`	sensor temperature

• Select `Yes` to store the value. Select `No` in order not to store the value.

14.2 Deletion of the data logger

```
Storage\Data logger\Delete meas. values
```

• Select the menu item `Storage\Data logger\Delete meas. values`.
• Press ENTER.
• Select `Yes` to delete the measured values.
• Press ENTER.

14.3   Information regarding the data logger

```
Storage\Data logger\Data logger info
```

• Select the menu item `Storage\Data logger\Data logger info`.

• Press ENTER.

The following information regarding the data logger is displayed:

display	description
Activated	data logger is activated/deactivated This display will only be indicated if the measurement has started and the data logger is activated.
Full (date)	date on which the data logger will be full This display will only be indicated if the measurement has started and the ringbuffer is deactivated.
Full (time)	time at which the data logger will be full This display will only be indicated if the measurement has started, the ringbuffer is deactivated and the data logger is not full yet.
Overflow (date)	date from which the oldest measured values will be overwritten This display will only be indicated if the measurement has started, the ringbuffer is activated and the data logger is not full yet.
Capacity (time)	time of remaining data logger capacity This display will only be indicated if the measurement has started and the ringbuffer is activated.
Ringbuffer	ringbuffer is activated/deactivated
Meas. val. Series	number of stored series of measured values

15   Data transmission

15.1   Service interfaces

The service interfaces (USB, LAN) allow data to be transmitted from the transmitter to the PC using the FluxDiagReader program.

The following tasks can be carried out:

• read and store measured values and setup settings

• graphically display measured values

• export data in csv format

For the operation of FluxDiagReader see the help function of this program.

15.1.1   LAN interface

In order to use the LAN interface it is important to adapt the network parameters. The transmitter supports the internet protocol versions 4 and 6.

```
Communication\Network
```

• Select the list item `Network` in the menu item `Communication`.

• Press ENTER.

15.1.1.1   Internet protocol version 6

The transmitter uses the automatic address configuration (SLAAC) to generate 2 individual IPv6 addresses allowing it to be reached in the network.

– link-local address with the prefix "FE80::/64"
  With this address, the transmitter can only be reached within its own network segment.

– global address
  With this address, the transmitter can be reached worldwide.

• Select the list item `IPv6` to display these IPv6 addresses.

• Press ENTER.

The IPv6 addresses are displayed.

15.1.1.2   Internet protocol version 4

• If the network parameters for IPv4 are to be adjusted, select the list item `IPv4`.

• Press ENTER.

Manual input

• Select `Manual` to enter the network parameters (IP address, subnet mask and standard gateway).

Notice!
The entered network parameters have to accord with the LAN parameters.

Default values in the transmitter:

– IP address: 192.168.0.70

– subnet mask: 255.255.255.0

– standard gateway: 192.168.0.1

Automatic addressing with DHCP

• Select `Automatic` to automatically identify the network parameters (IP address, subnet mask and standard gateway) via a DHCP server.

Notice!
The network parameters can only be automatically identified if the LAN supports DCHP.

• Select the menu item `Communication\Network\IPv4\Show auto config.` to display the automatically identified network parameters.

• Press ENTER.

15.2   Process interface

The transmitter can be equipped with a process interface (e.g., Modbus). For the connection of the process interface to the transmitter, see supplement to operating instruction.

16 Event trigger
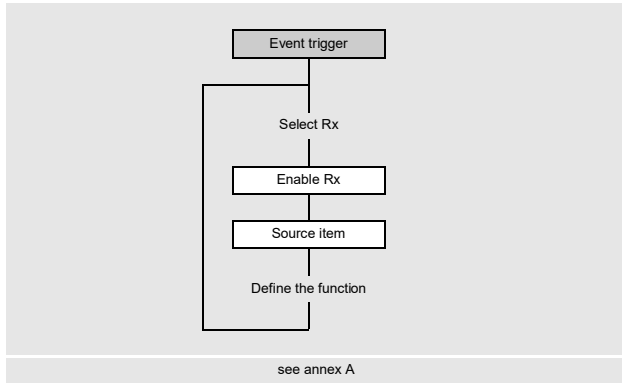
It is possible to activate max. 4 independent event triggers: R1, R2, R3 and R4.

The event triggers can be used, e.g., to output information on the current measurement.

```
Event trigger
```

• Select the menu `Event trigger`.
• Press ENTER.

```
Event trigger\Rx(-)
```

• Select an event trigger.
• Press ENTER.
If the event trigger has already been installed, it is displayed as follows: `Rx(√)`.

```
Event trigger\Enable Rx
```

• Select `Yes` to change the settings for an already assigned event trigger or to assign a new one.
• Select `No` to cancel the assignment and to return to the previous menu item.
• Press ENTER.

```
Event trigger\Enable Rx\Source item
```

• Select the source item (physical quantity) for which a condition has to be defined.

Tab. 16.1: Source items

source item	list item	output
Refractometer	Symmetry	diagnostic values
	Gain	
	Amplitude	
	Quality	
	SNR	
Analysis	Volume fraction	physical quantity for analysis selected in the menu Parameters
	Brix scale	
Fluid properties	Fluid temp.	fluid temperature
	Fluid density	fluid density
	Norm. density	standardized density
Miscellaneous	Custom. Input 1	If a fieldbus is connected, input quantities (e.g., sound speed, density) which are not used for calculation can be assigned as source item.
	Custom. Input 2	
	Custom. Input 3	For the connection of the fieldbuses to the transmitter, see supplement to operating instruction.
	Custom. Input 4	
Refractive index	Refractive index	measured refractive index in the fluid
	Refractive index (Δ)	
	Norm. refrac. index	

Afterwards the properties of the event trigger are defined.

Tab. 16.2: Properties of the event trigger

property	setting	description
Function (switching condition)	MAX (x>limit)	The event trigger switches when the measured value exceeds the upper limit.
	MIN (x<limit)	The event trigger switches when the measured value falls below the lower limit.
	ERR (x=fail)	The event trigger switches when a measurement is not possible.
	Within range	The event trigger switches when the measured value is within the defined range.
	Out of range	The event trigger switches when the measured value is outside the defined range.
Type (holding behavior)	Non-hold	When the switching condition is no longer met, the event trigger returns to the idle state after approx. 1 s.
	Hold	The event trigger remains activated even when the switching condition is no longer met.
	Hold for a while	The event trigger remains activated during a defined time even when the switching condition is no longer met.

Definition of the switching condition

```
Event trigger\Enable Rx\Source item\...\Function
```

• Select the switching condition.
• Press ENTER.

Definition of the holding behavior

```
Event trigger\Enable Rx\Source item\...\Type
```

• Select the type of the holding behavior.
• Press ENTER.

Definition of trigger limits

```
Event trigger\Enable Rx\Source item\...\Trigger value
```

The limits are to be entered at which the event trigger has to switch.
• Enter the upper limit `MAX (x>limit)`.
• Press ENTER.
• Enter the lower limit `MIN (x<limit)`.
• Press ENTER.

```
Event trigger\Enable Rx\Source item\...\Hysteresis
```

It is possible to define a hysteresis to avoid constant switching of the event trigger.
The event trigger is activated when the measured values exceed the upper limit. It is deactivated when the measured values fall below the lower limit.
• Enter the value for the hysteresis.
If zero is entered, no hysteresis is used.
• Press ENTER.

Example

`MAX (x>limit)`: 40 wt%
`Hysteresis`: 1 wt%
The event trigger is activated for measured values > 40.5 wt% and deactivated for measured values < 39.5 wt%.

```
Event trigger\Enable Rx\Source item\...\Range center
```

• Enter the center of the range in which the event trigger has to be switched.
• Press ENTER.

```
Event trigger\Enable Rx\Source item\...\Range width
```

• Enter the width of the range in which the event trigger has to be switched.
• Press ENTER.

Example

`Function`: Out of range
`Range center`: 40 wt%
`Range width`: 10 wt%
The event trigger will switch if the measured value is below 35 wt% or above 45 wt%.

Definition of the switching delay

```
Event trigger\Enable Rx\Source item\...\Glitch interval
```

• Enter a time interval after which the event trigger has to switch in case the event occurred.

• Press ENTER.

```
Event trigger\Enable Rx\Source item\...\Failure delay
```

• Enter a time interval after which the event trigger has to be deactivated in case of a measurement failure.

• Press ENTER.

16.1   Apparent switching delay

The measured values and totalizer values will be displayed rounded according to the set number of decimal places.
The limits, however, will be compared to the non-rounded measured values. This might cause an apparent switching delay when the measured value changes marginally (less than the visualized decimal places). In this case, the switching accuracy of the event trigger is higher than the accuracy of the display.

16.2   Reset and initialization of the event trigger

After an initialization of the transmitter all event triggers are deactivated.

Event triggers whose switching condition is still met will be activated again after 1 s. This function is used to reset event triggers of the type `HOLD` if the switching condition is no longer met.

If a measurement is stopped, all event triggers will be deactivated and the corresponding process outputs will be de-energized, independently of the programmed idle state.

16.3   Event trigger during the measurement

An event trigger with the switching condition `MAX (x>limit)`, `MIN (x<limit)`, `Within range` or `Out of range` is updated max. once per second to avoid a constant switching of the event trigger (in case the measured values fluctuate around the value of the switching condition).

An event trigger with switching condition `ERR (x=fail)` is activated during a measurement failure.

An event trigger of the type `Non-hold` is activated when the switching condition is met. It is deactivated when the switching condition is no longer met. But it remains activated for at least 1 s even when the switching condition is met for a shorter period of time.

An event trigger of the type `Hold` is activated when the switching condition is met. It remains activated even when the switching condition is no longer met.

An event trigger of the type `Hold for a while` is activated when the switching condition is met. The time after which the deactivation takes place is defined in the menu item `Hold interval`.

16.4   Status display of the event trigger

Notice!
There is no visual or acoustic indication of event trigger switching.

The state of the event triggers is displayed during the measurement.

• Press ⟶ to scroll through the second line from below until the event trigger status is displayed.

The status display of the event triggers is structured as follows.

Rx = ☐ ☐ ☐   with X being the number of the event trigger and ☐ a pictogram according to Tab. 16.3.

Tab. 16.3:   Pictograms for the status display of the event triggers

	no.		Function (switching condition)		Type (holding behavior)		current state	
R	☐	=	☐		☐		☐	
	1			MAX (x>limit)		Non-hold		deactivated (false state)
	2			MIN (x<limit)		Hold		activated (true state)
	3			Within range		Hold for a while		
	4			Out of range				
				ERR (x=fail)				

Example
R1 =

16.5   Event log

If an error occurs, an error message will be displayed in the first line indicating the symbol . The error message can be displayed.

```
Storage\Event log
```

• Select the menu item Event log in the menu Storage.

• Press ENTER.

A list is displayed containing all error messages since the last time the transmitter was switched on.

• Press ↓ to select an error message.

• Press ENTER.

The display indicates the cause of the error.

Notice!
After reading out the event protocol the error message symbol will be deleted on the display, even if the error has not been eliminated yet.
The event protocol will be deleted after a restart of the transmitter.

17   Calibration

Correction values can be entered:

• for the values calculated by the transmitter (e.g., percentage by mass)

• for scale values (z.B. Brix scale).

Correction values for the values calculated by the transmitter

The correction value is added to the value calculated by the transmitter.

```
Calibration\Result offset
```

• Select the menu item `Calibration\Result offset`.

• Press ENTER.

• Select `On` to define an offset for the displayed physical quantity.

• Press ENTER.

Correction values for the scale values

The correction value is added to the scale value.

```
Calibration\Scale offset
```

• Select the menu item `Calibration\Scale offset`.

• Press ENTER.

• Select `On` to define an offset for the scale value.

• Press ENTER.

18   Settings

18.1   Dialogs and menus

```
Miscellaneous\Dialogs/Menus
```

• Select the menu item `Dialogs/Menus` in the menu `Miscellaneous`.

• Press ENTER.

Measuring point number

```
Miscellaneous\Dialogs/Menus\Measuring point no.
```

• Press ENTER until the menu item `Measuring point no.` is displayed.

• Select `Number` if the measuring point number should only consist of numeric characters. Select `Text` if the measuring point number should only consist of alphabetic characters.

• Press ENTER.

Error delay

The error delay is the time after which an error value will be sent to an output if no valid measured values are available.

```
Miscellaneous\Dialogs/Menus\Error delay
```

• Press ENTER until the menu item `Error delay` is displayed.

• Select `Edit` to enter an error delay. Select `Damping` if the damping factor is to be used as the error delay.

• Press ENTER.

Display of the last value

```
Miscellaneous\Dialogs/Menus\Display last value
```

• Press ENTER until the menu item `Display last value` is displayed.

• Select `Yes` to display the last valid value.

• Press ENTER.

If `Yes` is selected and no valid measured value can be displayed during the measurement, the last valid value will be displayed. Behind this value an interrogation point will be displayed.

Switching off the display backlight

```
Miscellaneous\Dialogs/Menus\Light autom. off
```

• Press ENTER until the menu item `Light autom. off` is displayed.

• Select `Yes` to activate the automatic switch-off.

• Press ENTER.

If the automatic switch-off of the display backlight is activated, the backlight is switched off after about 30 s.
When pressing a key or connecting a USB cable, the backlight is switched on again.

18.2   Working with parameter sets

18.2.1   Introduction

Working with parameter sets will make repeated measurement tasks easier and faster. The parameter records contain setup settings of the transmitter. Depending on which measuring task has to be carried out, it is possible to load the corresponding parameter record and use it for the measurement. The transmitter can store up to 20 parameter records.

A parameter record contains among others the following parameters:

• sensor parameters

• fluid parameters

• output quantities

• output parameters

Notice!
No parameter records are stored in the delivery state. Parameter records have to be entered manually.

The parameters have first to be entered in the following menus `Parameters` and `Miscellaneous`. Afterwards, they can be stored as parameter record.

```
Miscellaneous\Param. record memo.
```

• Select the menu item `Param. record memo.` in the menu `Miscellaneous`.

• Press ENTER.

• Select the menu item `Save current record`.

• Press ENTER.

```
Miscellaneous\Param. record name
```

• Enter the name the parameter record has to be stored with.

• Press ENTER.

18.2.2   Load of a parameter record

Stored parameter records can be loaded and used for measurement.

```
Miscellaneous\Param. record memo.\Load param. record
```

• Select the menu item `Load param. record`.

• Press ENTER.

• Select the parameter record to be loaded.

• Press ENTER.

18.2.3   Deletion of parameter records

```
Miscellaneous\Param. record memo.\Delete param. record
```

• Select the menu item `Delete param. record`.

• Press ENTER.

• Select the parameter record to be deleted.

• Press ENTER.

18.3   Contrast settings

The display contrast can be adjusted with the following keys:

→   increase contrast

CLR   reduce contrast

• Press ENTER.

Notice!
After an initialization of the transmitter, the display is reset to medium contrast.

18.4   HotCodes

`Miscellaneous\System settings\HotCode`

• Select the menu item `Miscellaneous` in the menu `System settings`.
• Press ENTER.
• Select the menu item `HotCode`.
• Press ENTER.
• Enter the HotCode via the keyboard. For the input of numbers, see section 4.3.
• Press ENTER.

function	HotCode
setting to medium display contrast	555000
language selection	9090xx
initialization	909000

Language selection

The language selection can either be carried out via the menu `Miscellaneous\System settings\Language` or a HotCode:

language	HotCode
English	909044
German	909049
French	909033
Spanish	909034
Dutch	909031
Russian	909007
Polish	909048
Turkish	909090
Italian	909039
Chinese	909086

After the last digit has been entered, the main menu is displayed in the selected language. The selected language remains activated when the transmitter is switched off and on again.

18.5   Key lock

An ongoing measurement can be protected from an inadvertent intervention by means of a key lock.

Definition of a key lock code

• Select the menu item `System settings` in the menu `Miscellaneous`.

• Press ENTER.

```
Miscellaneous\System settings\Key lock
```

• Select the menu item `Key lock`.

• Press ENTER.

• Enter a 6-digit key lock code. For the input of numbers, see section 4.3.

• Press ENTER.

Notice!
Do not forget the key lock code!

• Enter a 6-digit key lock code. For the input of numbers, see section 4.3.

• Press ENTER.

Intervention in the measurement

If the key lock is activated, the message `Key lock activated` will be displayed for a few seconds when pressing a key.

In order to interrupt a measurement, the key lock has to be deactivated.

• Press BRK.

• Select `Show parameters`.

• Press ENTER.

• Deactivate the key lock.

Disabled functions with activated key lock

The following table gives an overview of the transmitter functions that are not available when the key lock is activated.

measurement not started	measurement started
• parameter input • modification of settings (e.g., measuring modes) • deletion of the data logger • setting of time/date • start of measurement (start-up)	• modification of settings that are available in an ongoing measurement (e.g., language selection) • measurement stop

Annex

A   Menu structure

Main menu

Parameters
Measuring point no.
Sensor
Fluid
Scale
Fluid temp.
Select analysis quant.
Volume fraction
OP analysis quantity
Show range info
Damping
Error delay

Start measurement
Measurement

Inputs	[1]

→ Assign inputs

Outputs
Enable
Source item

→ Refractometer
→ Analysis
→ Fluid properties
→ Event trigger
→ Miscellaneous
→ Refractive index

Output info
Test signal
Test measuring range

Event trigger
Enable
Source item

→ Refractometer
→ Analysis
→ Fluid properties
→ Miscellaneous
→ Refractive index

Function
Type
Trigger value
Hysteresis
Glitch interval
Failure delay

Storage

→ Data logger
→ Event log

Calibration

→ Result offset
→ Scale offset

Communication

→ Network
→ Fieldbuses

Miscellaneous

→ System settings
→ Measurement settings
→ Units of measurement
→ Dialogs/Menus
→ Param. record memo.

Legend
[1]   only if a fieldbus is connected

Parameter input

Parameters

Connected sensor

Measuring point no.

Fluid

Scale

→   Brix
→   API

Fluid temp.

Select analysis quant.

→   Mass fraction
→   Volume fraction
→   Analyte concentr.
→   Matrix concentration
→   Density
→   Norm. density
→   Norm. refrac. index

Unit of   [1]
measurement

OP analysis quantity

Show range info

Damping

Error delay   [2]

Legend
[1]   only if `Mass fraction` or `Volume fraction` has been selected as physical
      quantity for analysis
[2]   only if `Edit` is selected in the menu item `Miscellaneous\Dialogs/Menus\`
      `Error delay`

Measurement start

Main menu

Start measurement

Measurement started

↺

Stop measurement

Show measurement

Display parameters

Read-only mode

Yes

No

Outputs

1 Outputs

→ Current
→ Voltage
→ Binary

... Enable

No | Yes

Source item

| Refractive index | Refractometer | Analysis | Fluid properties | Miscellaneous | Event trigger |

Refractive index:
→ Refractive index
→ Norm. refrac. index
→ Refractive index (Δ)

Refractometer:
→ Amplitude
→ Quality
→ SNR
→ Symmetry
→ Sensor temp.
→ Sensor humidity
→ Gain

Analysis:
→ Brix scale
→ Mass fraction

Fluid properties:
→ Fluid temp.
→ Fluid density
→ Norm. density

Miscellaneous:
→ Custom. Input 1
→ Custom. Input 2
→ Custom. Input 3
→ Custom. Input 4

Event trigger:
→ R1
→ R2
→ R3
→ R4

| Status | Values |

Status:
Output range
Status OK
Output info
Test signal
Test measuring range

Values:
Output range
Error value
Measured values [1]

| Absolute value | Sign |

Start of meas. range
End of meas. range
Output info
Test signal
Test measuring range

Event trigger:
Start of meas. range
Idle state
Output info
Test signal
Test measuring range

2 Miscellaneous [2]

Current output

| Active | Passive |

Legend
[1] requested only if the physical quantity can adopt a negative value
[2] only if switchable current outputs are available

Event triggers

① Event trigger

Select Rx

Enable Rx

No | Yes

Source item

| Refractive index | Refractometer | Analysis | Fluid properties | Miscellaneous |

Function

→ MAX (x>limit)
→ MIN (x<limit)
→ Within range
→ Out of range
→ ERR (x=fail)

Type

Non-hold | Hold for a while | Hold

Hold interval

[1] | [2]

Range center | Trigger value

Range width | Hysteresis

Glitch interval

Failure delay

② Outputs

Select an output

Enable ...

Yes

Source item

→ Event trigger

Output range

Idle state

Output info

Test signal

Legend
[1] if `Within range` or `Out of range` has been selected as function
[2] if `MAX (x>limit)`, `MIN (x<limit)` or `ERR (x=fail)` has been selected as function

Data logger

Data logger

Configuration

Delete meas. values

Data logger info

Enable logger

Start storing

→ Activated
→ Ringbuffer
→ Logger full
→ Meas. val. series
→ Occup. logger

Event-based   [1]

→ Immediately
→ Full 5 minutes
→ Full 10 minutes
→ Full 15 minutes
→ Full 30 minutes
→ Full hour

Storage rate w/o trig.

Storage rate (trig.)

Buffer time →Π

Storage rate

Buffer time Π→

Ringbuffer

On

Off

Storage mode

Average

Sample

Store diagnost. values

Store sensor temp.

Beep on storage

Legend
[1]   list of parameterized event triggers

Calibration

```
                          ┌──────────────┐
                          │ Calibration  │
                          └──────┬───────┘
         ┌───────────────────────┼────────────────────┐
         │          ┌────────────┴──────┐    ┌─────────┴────────┐
         │          │  Scale offset     │    │  Result offset   │
         │          └────────┬──────────┘    └────────┬─────────┘
         │          ┌────────┴───┐          ┌──────────┴───┐
         │      ┌───┴──┐   ┌────┴──┐     ┌───┴──┐   ┌─────┴──┐
         │      │ Yes  │   │  No   │     │ Yes  │   │   No   │
         │      └───┬──┘   └───┬───┘     └───┬──┘   └────┬───┘
         │          │          │            │           │
         │        value        │          value         │
         │          └──────┬───┘            └────────┬──┘
         └─────────────────┴─────────────────────────┘
```
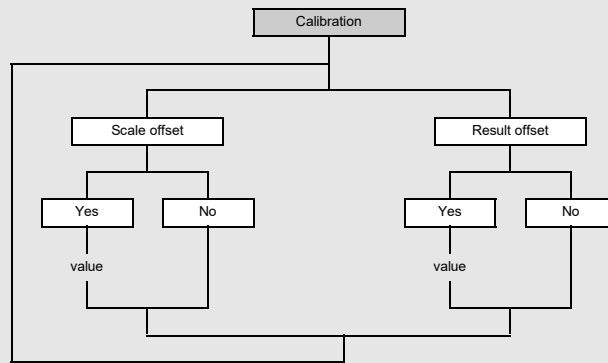
Event-based storing of measured values
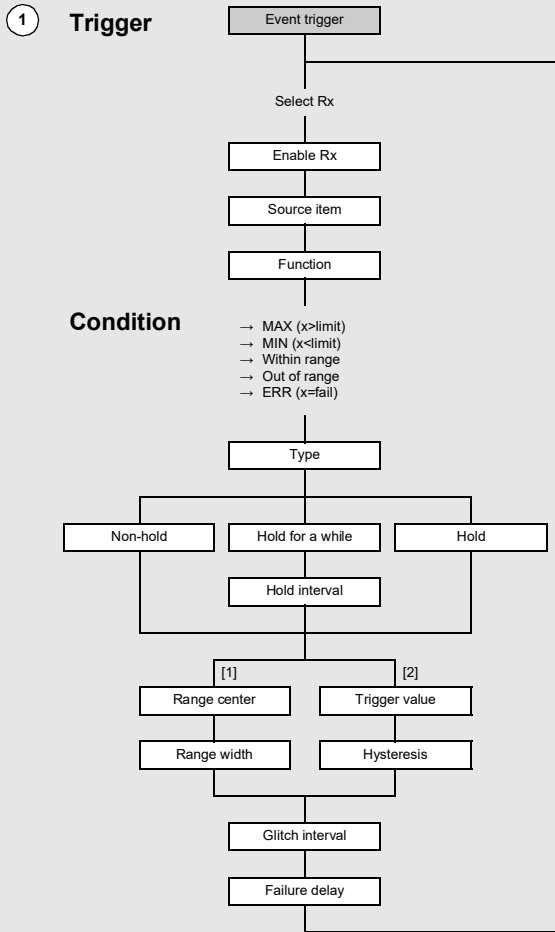
① Trigger

Event trigger

Select Rx

Enable Rx

Source item

Function

Condition

→ MAX (x>limit)
→ MIN (x<limit)
→ Within range
→ Out of range
→ ERR (x=fail)

Type

| Non-hold | Hold for a while | Hold |

Hold interval

[1] Range center
[2] Trigger value

Range width
Hysteresis

Glitch interval

Failure delay

② Action

Data logger

Configuration

Enable logger

Event-based

Rx

Storage rate

Storage rate (trig.)

Ringbuffer

Storage mode

Legend
[1] if `Within range` or `Out of range` has been selected as function
[2] if `MAX (x>limit)`, `MIN (x<limit)` or `ERR (x=fail)` has been selected as function

B   Start-up protocol

Start-up

device			
sensor	PIOX R500	ser. no.:	
transmitter	PIOX R532	ser. no.:	

Measuring point (designation):

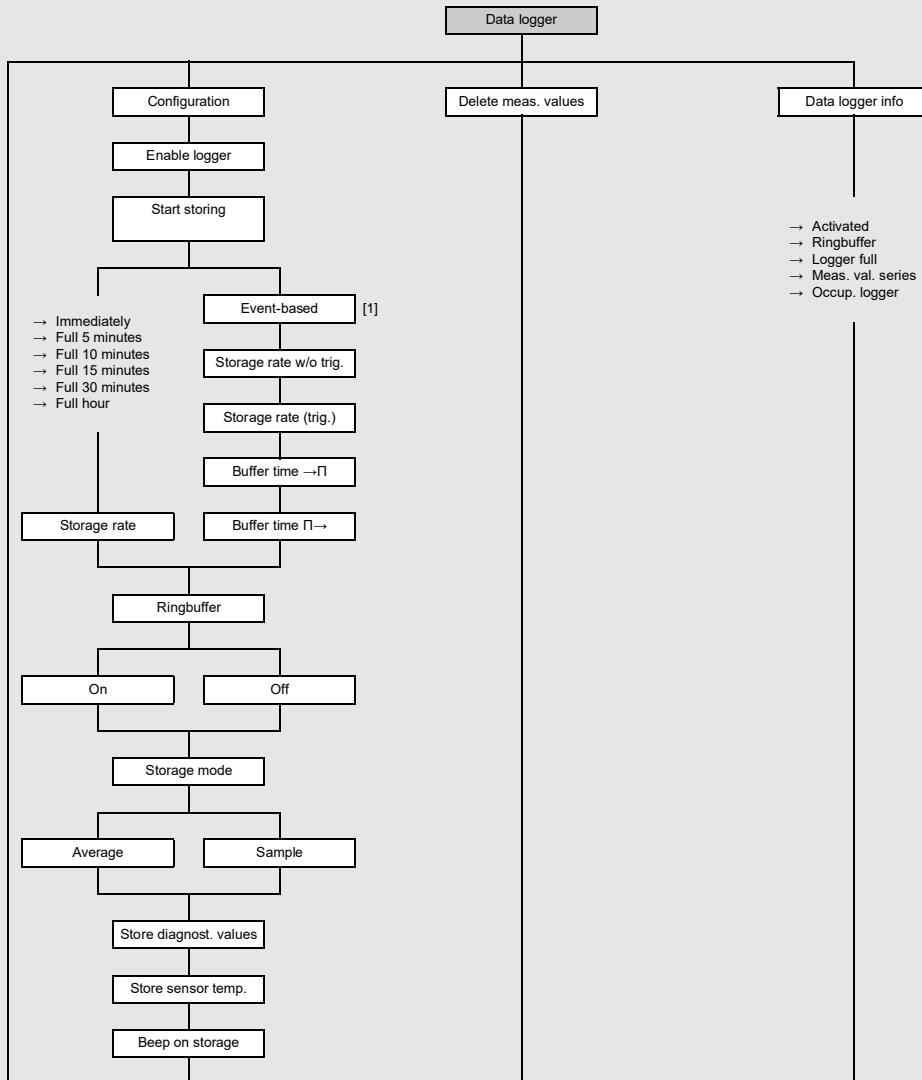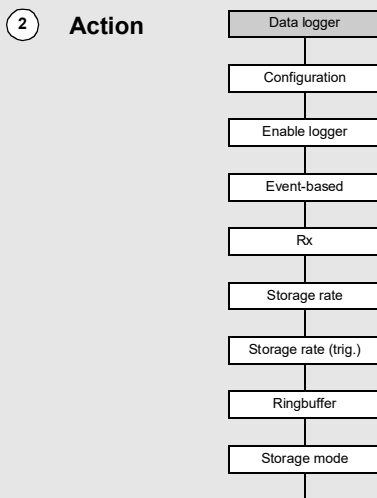| **process fluid**	
solvent	
physical quantity	
concentration	operating point:
	range:
other components	
fluid temperature	
ambient temperature	
pressure	

Settings and measured values in the transmitter:

selected fluid in the transmitter	

Characteristic curve of the fluid created by:

☐   FLEXIM   ☐   customer   ☐   _____

Measured values: one representative measured value for each typical process state at the measuring point
(e.g., operating point, CIP)

process state	physical quantity	reference value [1]	T_{fluid}	n_D	humidity [%]	T_{dev}	amplitude	gain	symmetry

[1] determined with (e.g., lab refractometer, type):   accuracy:

Offset input:

☐   no offset

☐   result offset   _____

☐   scale offset   _____

Outputs

	type	source item	min. value	max. value	output range [mA]	abs./sign	error [mA]	terminal
I1								
I2								

	type	source item	trigger condition	trigger value	trigger hysteresis	switching delay	holding behavior	0/1	terminal
B1									
B2									

Notes

Start-up completed on: Signature:

C Maintenance protocol

Maintenance

Date: _____

device			
sensor	PIOX R500	ser. no.:	
transmitter	PIOX R532	ser. no.:	

C.1 Visual inspection

• Clean the sensor. Remove any deposits or dirt on the window and measuring prism.
• Check the sensor head (the part in contact with the fluid). If there are any signs of corrosion, deep scratches or damages, especially on the gaskets, please contact FLEXIM and give a precise description of the problem.

The sensor head is intact: ☐ yes ☐ no: contact FLEXIM

• Check all gaskets. If the gaskets are swollen or brittle and cracked, send the sensor to FLEXIM to replace the gaskets.

The gaskets are intact: ☐ yes ☐ no: send the sensor to FLEXIM for repair

C.2 Functional test

Measuring point (designation):

☐ the composition of the fluid has not changed since the last start-up/maintenance
date: _____

☐ a changed/new fluid is measured since: _____

Type of change:

process fluid		
solvent		
physical quantity		
concentration	operating point:	
	range:	
other components		
fluid temperature		
ambient temperature		
pressure		

Settings and measured values in the transmitter:

selected fluid in the transmitter	

Characteristic curve of the fluid created by:

☐ FLEXIM   ☐ customer   ☐ _____

Measured values: one representative measured value for each typical process state at the measuring point
(e.g., operating point, CIP)

process state	physical quantity	reference value [1]	T_{fluid}	n_D	humidity [%]	T_{dev}	amplitude	gain	symmetry

[1] determined with (e.g., lab refractometer, type):   accuracy:

Comparison of the amplitude values

If the amplitude value measured during maintenance is far below the value measured at the start-up, for example,
if the fluid is slightly cloudy, a cleaning of the sapphire optics is recommended.

amplitude value $_{(maintenance)}$ ≤ 1/20 amplitude value $_{(start-up)}$

Notice!
Make sure that the sensor material (stainless steel 1.4571) and the gaskets (for material, see confirmation of order) are resistant against the cleaning agent. The cleaning agent also has to be suitable for the fluid.

☐ cleaned with: _____

Check of the zero point (optional)

After the cleaning, we recommend to check the zero point. PIOX R500 is checked using deionized water.

• Select `Brix` in the menu item `Parameters\Fluid\Other fluid\Scale`.

default: Brix value = 0

operating temperature	Brix value	deviation

Offset input:

☐ no offset

☐ result offset   _____

☐ scale offset   _____

Maintenance completed on: Signature:

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https://github.com/weston-embedded/uC-TCP-IP/tree/v3.06.01

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E   Conformity declarations

FLEXIM

EU declaration of conformity according to low voltage directive

FLEXIM Flexible Industriemesstechnik GmbH

Boxberger Straße 4

12681 Berlin

Germany

declares as manufacturer under its sole responsibility that the transmitter **PIOX R532*aa*-NNN** and the sensor **R500**

a = any

comply with the relevant EU regulations and directives, including any amendments valid at the time this declaration was signed. This declaration of conformity is based on the following harmonized standards:

EU directive 2014/35/EU (low voltage directive) relating to the making available on the market of electrical equipment designed for use within certain voltage limits

EN 61010-1:2010 + A1:2019 + A1:2019/AC:2019	Safety requirements for electrical equipment for measurement, control, and laboratory use Part 1: General requirements

EU directive 2014/30/EU (EMC directive) relating to electromagnetic compatibility

EN IEC 61326-1:2021	Electrical equipment for measurement, control, and laboratory use – EMC requirements Part 1: General requirements

EU directive 2011/65/EU (RoHS directive) on the restriction of the use of certain hazardous substances in electrical and electronic equipment

EN IEC 63000:2018	Technical documentation for the assessment of electrical and electronic products with respect to the restriction of hazardous substances

FLEXIM GmbH	Berlin, 2024-02-07	Jens Hilpert
Signed for and on behalf of	Place and date	Managing Director

FLEXIM Flexible Industriemesstechnik GmbH · Boxberger Straße 4 · 12681 Berlin · Tel.: +49 (30) 936 67 660 · Fax: +49 (30) 936 67 680

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FLEXIM

UK declaration of conformity according to UK statutory instruments

FLEXIM Flexible Industriemesstechnik GmbH

Boxberger Straße 4

12681 Berlin

Germany

declares as manufacturer under its sole responsibility that the transmitter **PIOX R532*aa*-NNN** and the sensor **R500**

***a* = any**

comply with the relevant UK regulations and legislations, including any amendments valid at the time this declaration was signed. This declaration of conformity is based on the following designated standards:

UK statutory instruments 2016 No. 1101 (electrical equipment (safety) regulations) relating to the safety of electrical equipment designed for use within certain voltage limits

EN 61010-1:2010 + A1:2019 + A1:2019/AC:2019	Safety requirements for electrical equipment for measurement, control, and laboratory use Part 1: General requirements

UK statutory instruments 2016 No. 1091 (EMC regulations) relating to electromagnetic compatibility

EN IEC 61326-1:2021	Electrical equipment for measurement, control, and laboratory use – EMC requirements Part 1: General requirements

UK statutory instruments 2012 No. 3032 (RoHS regulations) on the restriction of the use of certain hazardous substances in electrical and electronic equipment

EN IEC 63000:2018	Technical documentation for the assessment of electrical and electronic products with respect to the restriction of hazardous substances

FLEXIM GmbH	Berlin, 2024-02-07	Jens Hilpert
Signed for and on behalf of	Place and date	Managing Director

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