3810 Modbus Map 00821-0100-3810 Rev AB January 2024

3810 Modbus Map Reference Manual





ROSEMOUNT

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	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Reg Num	Label	Description	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
20	BaudPortA	Communication Port A baud rate The baud rate used for serial port A.	RW	Y	Y		long	bits/sec	Unit bits/sec	uint32	bits/sec	1200 (1200) 2400 (2400) 9600 (9600) 13200 (13200) 38400 (38400) 57600 (57600) 115200 (115200)	19200	1200	115200
22	ModbusIDPortA	Comm Port A Modbus address The Modbus address used by communication Port A. The Modbus address is also used as a basis for the meter's IP address in the form 172:16.17.ModbusID when the meter is running a PPP server on the serial port.	RW	Y	Y		long	-	-	uint8	-		32	1	247
24	CommRspDlyPortA	Comm Port A response delay Communication Port A response delay. The communication port will wait the specified amount of time before sending a response.	RW	Y	Y		long	ms	ms	uint8	ms		0	0	100
26	CommTimeoutPortA	Comm Port A communication timeout value The meter must respond to Modbus request messages within this time limit; if it cannot it will not respond at all.	RW	Y	Y		long	Sec	sec	uint8	Sec		4	0	255
28	IsHWFlowControlEnabledPo rtA	Enables comm port A hardware flow control When TRUE (1), enables communication Port A hardware flow control (RTS/CTS).	RW	Y	Y		long	-	-	boolean	-	Disabled (FALSE) Enabled (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
30	RTSOffDelayPortA	Comm Port A handshaking RTS off delay time Communication Port A handshaking RTS off delay time. The meter will hold RTS active for this amount of time after sending the reply.	RW	Y	Y		long	ms	ms	uint16	ms		0	0	1000
32	RTSOnDelayPortA	Comm Port A handshaking RTS on delay time Communication Port A handshaking RTS on delay time. The meter will activate RTS for this amount of time before sending out the message.	RW	Y	Y		long	ms	ms	uint16	ms		0	0	1000
34	SetPortAToOverride	Comm Port A parameter override indicator Set to TRUE (1) when the CPU Module's switch position 1 is moved from "OFF" to "ON" position. The meter automatically sets Port A to an override configuration (hardware protocol R5-232, baud rate 19200, Modbus address 32). Port A's normal configuration is restored after 2 minutes unless a PPP connection, established while override mode is in progress, in which case Port A's normal configuration is restored after the PPP connection ends.	R	Y			long	-	-	boolean	-	Use normal parameters (FALSE) Use override parameters (TRUE)			
		Inactivity timeout for PPP connections, port A Specifies the inactivity timeout (no TCP/IP packets) before the meter automatically disconnects a PPP connection (direct serial or modern connection) on Port A.			Y		long	SEC	sec	uint8	Sec		15	1	60
		Hardware protocol on Port A Hardware protocol on Port A.	RW		Y		long	-	-	uint8	-	RS-232 (0) RS-485 half-duplex (1) RS-485 full-duplex (2)	0	0	2
40	BaudPortB	Communication Port B baud rate The baud rate used for serial port B.	RW	Y	Y		long	bits/sec	bits/sec	uint32	bits/sec	1200 (1200) 2400 (2400) 9600 (9600) 19200 (19200) 38400 (38400) 57600 (57600) 115220 (115200)	19200	1200	115200
42	ModbusIDPortB	Comm Port B Modbus address The Modbus address used by communication Port B. The Modbus address is also used as a basis for the meter's IP address in the form 172:16.17.ModbusID when the meter is running a PPP server on the serial port.	RW	Y	Y		long	-	-	uint8	-		32	1	247
44	CommRspDlyPortB	Comm Port B response delay Communication Port B response delay. The communication port will wait the specified amount of time before sending a response.	RW	Y	Y		long	ms	ms	uint8	ms		0	0	100
		Comm Port B communication timeout value The meter must respond to Modbus request messages within this time limit; if it cannot it will not respond at all.	RW	Y	Y		long	Sec	sec	uint8	Sec		4	0	255
			R												
52	Reserved		R				long								
		Specifies the inactivity timeout (no TCP/IP packets) before the meter automatically disconnects a PPP connection (direct serial or modem connection) on Port B.			Y			SEC	sec		SEC			1	60
		Hardware protocol on Port B. This configuration is ignored when RS-232 or RS-485 Module is connected and needed when Expansion I/O Module is connected.			Y			-	-		-	RS-485 half-duplex (1)			1
60	BaudPortC	The baud rate used for serial port C.	RW	Y	Y		long	bits/sec	bits/sec	uint32	bits/sec	1200 (1200) 2400 (2400) 9600 (9600) 13200 (13200) 38400 (38400) 57600 (57600) 115200 (115200)	19200	1200	115200
62	ModbusIDPortC	Comm Port C Slave mode Modbus address The Modbus address used by communication Port C. The Modbus address is also used as a basis for the meter's IP address in the form 172.16.17.ModbusID when the meter is running a PPP server on the serial port.	RW	Y	Y		long	-	-	uint8	-		32	1	247
64	CommRspDlyPortC	Comm Port C response delay Communication Port C response delay. The communication port will wait the specified amount of time before sending a response.	RW	Y	Y		long	ms	ms	uint8	ms		0	0	100
		Comm Port C communication timeout value The meter must respond to Modbus request messages within this time limit; if it cannot it will not respond at all.	RW	Y	Y		long	SEC	Sec	uint8	SEC		4	0	255
		Hardware protocol on Port C Hardware protocol on Port C. This configuration is ignored when RS-232 or RS-485 Module is connected and needed when Expansion I/O Module is connected.	RW		Y		long	-	-	uint8	-	RS-232 (0) RS-485 half-duplex (1)	0	0	1
		TCP port used for HTTP server The TCP/IP out used by the HTTP server. The port cannot be set to any of the reserved or well-known ports 1, 7, 20, 21, 23, 42, 53, 67, 68, 502, 10000, 10001, 10002, 10003, 11000, or 11001. Also the HTTP port cannot be set equal to Modbus TCP alternate port (Eth IAMIddus)Sori) or TFP server control port (FTPServerControlPort). The HTTP server restarts when the port number is changed. The HTTP server terminates if the port is set to zero.	RW		Y	Y	long	-	-	uint16	-		80	0	65535
76	CommTCPTimeoutPortC	Inactivity timeout for PPP connections, port C Specifies the inactivity timeout (no TCP/IP packets) before the meter automatically disconnects a PPP connection (direct serial or modern connection) on Port C.	RW	Y	Y		long	Sec	sec	uint8	sec		15	1	60
	22 24 28 30 32 32 34 34 36 38 38 38 38 38 38 30 40 40 40 40 42 42 42 44 46 60 60 60 60 62 62 64 66 66 74	20 BaudPortA 21 ModbusIDPortA 22 ModbusIDPortA 24 CommTspDlyPortA 26 CommTimeoutPortA 28 IsHWFlowControlEnabledPortA 30 RTSOffDelayPortA 32 RTSOffDelayPortA 33 RTSOffDelayPortA 34 SetPortAToOverride 35 DriverSelectionPortA 36 CommTCPTimeoutPortA 37 BaudPortB 40 BaudPortB 41 CommTimeoutPortB 42 ModbusIDPortB 43 Reserved 50 Reserved 52 Reserved 53 DriverSelectionPortB 60 BaudPortC 60 BaudPortC 61 BaudPortC 62 ModbusIDPortC 64 CommTimeoutPortC 64 CommTimeoutPortC 65 CommTimeoutPortC 66 DriverSelectionPortC 67 ModbusIDPortC 68 DriverSelectionPortC	22 Modious/Point Commer Point A Modious address 23 Modious/Point Commer Point A Modious address 24 Commergia_DipPoint Commerciation Point A metors as using a PPP server on the starting point. 25 Modious/Point Commerciation Point A metors as using a PPP server on the starting point. 26 Commerciation Point A metoria aday. The communication point A metore aday. 26 Commerciation Point A metoria aday. The commerciation metors while a specific aday. 20 Interformation Point A mediation RPITS of daily time. The meter must respond at al. 28 INTSOTDINIPPOINT Commerciation Point A mediation RPITS of daily time. 29 INTSOTDINIPPOINT Commerciation Point A mediation RPITS of daily time. 20 INTSOTDINIPPOINT Commerciation Point A handmalain RPITS on daily time. 20 INTSOTDINIPPOINT Commerciation Point A handmalain RPITS on daily time. 21 INTSOTDINIPPOINT Commerciation Point A handmalain RPITS on daily time. 22 INTSOTDINIPPOINT Commerciation Response daily time. 23 Suffork Interpoint Point Point Amediation Response daily time. Thanemetor and hand weton the start address in the dain	2 Moduu0PurA Comm PurA Alledous address Per double address is about of a set basis for the meters IP address in the low PV 2 Moduu0PurA Comm PurA Alledous address Per double address is about address is	Participant The band mile used for sardig por A. File File	22 ModucaDPenA Comm Part A Modula address Provide a control provide a modula address is also used as basis for the metry (P address in the tom) PV V V 24 Comm Part A Modula address The Modula address is and to sand part to the work (P address in the tom) PV V V 24 Comm Part A Modula address The Modula address is and to sand part to the work (P address in the tom) PV V V 24 Comm Part A Modula address The modula modula is address in the communication part of the work (P address and Part Address address in the tom) PV V V 26 Comm Part A Modula address free correl address address in the tom Part A Modula address free correl address address in the tom Part A modula address free correl address address	22 MonetacPrive Comm Prior A Modelse sadees PM Y Y 23 MonetacPrive Comm Prior A Modelse sadees PM Y Y 24 Comm Prior A Modelse sadees PM V Y Y 24 Comm Prior A Modelse sadees PM V Y Y Y 25 Comm Prior A Modelse sadees PM V Y Y Y Y 26 Comm Prior A Modelse sadees PM Y	21 Mechanization for the Automatication from A. The Medica address is also to the interiar is address in the low in the Model address address in the low in the Model address into the interiar is address in the low in the Model address address address are in the Low in the Model address addres address addres address address address add	In the boot date used for send just A. In the boot date used just A. In th	No. Machines Committee A. Machine address PP Y Y Y No. Market 22 LookandPoist Committee A. Machine address PP Y Y Y No. No. PP 23 LookandPoist Committee A. Machine address PP No. PP Y Y No. No. PP PP No. PP PP No.	a) Badiney M Construction from A badine in proc. Biology M V V V Biology M Biology M Biology M V V Biology M	20 Subscription Distribution Distribut	Augustus Constructions of a set of a	Display Operation of the state of the	All Aurona All Aurona

Rosemou	nt™ Liqu	id Ultrasonic Firmware: 1.61	Database: 2.29.017													
The below	/ Modbus	map is applicable for Roser	nount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
40079	78	Eth1AltModbusPort	Alternate TCP port used for Modbus TCP In addition to port 502. The alternate port cannot be set to any of the reserved or well-known ports 1, 7, 20, 21, 23, 42, 53, 67, 68, 502, 10000, 10001, 10002, 10003, 11000 or 11001. The alternate port cannot be set equal to HTTP server port (HTTPServerPort) or FTP server control port (FTPServerControlPort). If the alternate port is changed while there are open connections on it, then the connections shall be closed. The alternate port cannot be set to zero when Modbus TCP alternate port save read and write mode (Eth 1AMdobusReadWirteMode) is set to a non-zero value.	RW	Y	Y		long	-	-	uint32	-		0	0	65535
40081	80	Eth1ModbusID	Ethernet port Modbus address The Modbus address for Modbus TCP/IP on the Ethernet port. This is the "unit identifier" that is used if the Modbus TCP/IP network has a bridge to a serial Modbus network.	RW	Y	Y		long	-	-	uint8	-		255	1	255
40083	82	CommTCPMaxDatagramSiz ePortA	Max datagram size port A The maximum MTU and MRU bytes in a datagram on serial port A.	RW	Y	Y		long	-	-	uint16	-		576	128	16384
40085	84	CommTCPMaxDatagramSiz ePortB	Max datagram size port B The maximum MTU and MRU bytes in a datagram on serial port B.	RW	Y	Y		long	-	-	uint16	-		576	128	16384
40087	86	CommTCPMaxDatagramSiz ePortC	Max datagram size port C The maximum MTU and MRU bytes in a datagram on serial port C.	RW	Y	Y		long	-	-	uint16	-		576	128	16384
40089		Reserved		R				long								
40091			Indicate serial port A access level. When Read-write mode (0) is set, all valid read and write request will be performed. When Read-only mode (1) is set, all valid read requests will be performed and all write requests will be rejected. The serial port can be configured to allow PPP protocol only or to allow Modbus and PPP protocols (ProtocolPortA).	RW	Y	Y	Y	long	-	-	uint8	-	Read-write mode (0) Read-only mode (1)	0	0	1
40093		ReadWriteModePortB	Indicate serial port B access level. When Read-write mode (0) is set, all valid read and write request will be performed. When Read-only mode (1) is set, all valid read requests will be performed and all write requests will be rejected. The serial port can be configured to allow PPP protocols (Protocol/PonB).	RW	Y	Y	Y	long	-	-	uint8	-	Read-write mode (0) Read-only mode (1)	0	0	1
40095		ReadWriteModePortC	Serial port C read and write mode Indicate serial port C access level. When Read-write mode (0) is set, all valid read and write request will be performed. When Read-only mode (1) is set, all valid read requests will be performed and all write requests will be rejected. The serial port can be configured to allow PPP protocol only or to allow Modbus and PPP protocols (ProtocolPortC).	RW	Y	Y	Y	long	-	-	uint8	-	Read-write mode (0) Read-only mode (1)	0	0	1
40097	96	FTPServerControlPort	FTP server control port The port on which the FTP server listens for client connection requests. The port cannot be set to any of the reserved or well-known ports 1, 7, 20, 23, 42, 53, 67, 68, 502, 10000, 10001, 10002, 10003, 11000, or 11001. Also, the port cannot be set equal to Modbus TCP alternate port (Eth1AtModbusPort) or HTTP server port (HTTPServerPort). The FTP server restarts when the port is changed. The FTP server terminates if the port is set to zero.	RW	Y	Ŷ	Ŷ	long	-	-	uint16	-		21	0	65535
40101		UnitsSystem	Modbus and local display units system Selects the units for Modbus communications and for the local display. Available options are U.S. Customary and Metric. Also, these are the units used by the Field Setup Wizard in MeterLink™. US customary units is the default setting.	RW	Y	Y	Y	int	-	-	uint8		U.S. Customary (0) Metric (1)	0	0	1
40102	101	VolFlowRateTimeUnit	Volumetric flow rate time unit for Modbus communication I Selects the Modbus communication volumetric flow rate time unit.	RW	Y	Y	Y	int		-	uint8	-	second (0) minute (3) hour (1) day (2)	1	0	3
40103	102	VolUnitMetric	Modbus metric volume unit Identifies the metric volume unit used for Modbus communication.	RW	Y	Y	Y	int	-	-	uint8	-	Cubic meters (0) Liters (1)	0	0	1
40104	103	VolUnitUS		RW	Y	Υ	Y	int	-	-	uint8	-	Barrels (1) Gallons (2)	1	1	2
40111		RTCSecondsSinceEpochSe t	Used to set the system time This is used to set the system time in POSIX-compliant "time_t" format (seconds elapsed since midnight January 1, 1970 local time) within the range from the firmware release date to midnight January 19, 2038. Use the real-time clock read data point (RTCSecondsSinceEpochRead) to read the system time. When the system time is set then the meter's real-time clock is also updated. The system time might be adjusted for the following reasons: 1. Clock drift (the system time is different from the required time). 2. The meter is installed in a time zone that is different from the meter manufacturer's time zone or if a replacement CPU Module is installed in a time zone that is different from the meter manufacturer's time zone. 3. Adjustments for the start and end of daylight saving time. (This may cause two hourly logs to be generated with the same timestamp or may cause hourly logs for an hour to be skipped.)	RW				long	Sec	sec	int32	Epoch sec		1041400800	1041400800	
40113		RTCMonth	This is used to read and write system time's month. The system time of the meter can be adjusted by writing to real-time obok day (RTCDate), year (RTCYear), hour (RTCHour), minute (RTCMinute) and second (RTCSecond). When the system time is set then the meter's real-time clock is also updated.	RW				long	-	-	uint8		Jan (1) Feb (2) Mar (3) Apr (4) May (5) Jun (6) Jul (7) Aug (8) Sep (9) Oct (10) Nov (11) Dec (12)	1	1	12
40115		RTCDate	This is used to read and write system time's day of the month. The system time of the meter can be adjusted by writing to real-time clock month (RTCMonth), year (RTCYear), hour (RTCHour), minute (RTCMinute) and second (RTCSecond). When the system time is set then the meter's real-time clock is also updated.	RW				long	-	-	uint8	-		1	1	31
40117			Real-time clock year (2 digit) This is used to read and write system time's year. This specifies the last two digits of the year, which are added to 2000 to derive the four- digit year. The year may be set to a value within the range of the firmware release year to 38. The system time of the meter can be adjusted by writing to real-time clock month (RTCMonth), day (RTCDate), hour (RTCHour), minute (RTCMinute) and second (RTCSecond). When the system time is set then the meter's real-time clock is also updated.	RW				long	-	-	uint8	-		3	0	99
40119		RTCHour	This is used to read and write system time's hour (in military time). The system time of the meter can be adjusted by writing to real-time clock month (RTCMonth), day (RTCDate), year (RTCYaer), minute (RTCMinute) and second (RTCSecond). When the system time is set then the meter's real-time clock is also updated.	RW				long	-	-	uint8	-		6	0	23
40121	120	RTCMinute	Real-time clock minute This is used to read and write system time's minute. The system time of the meter can be adjusted by writing to real-time clock month (RTCMonth), day (RTCDate), year (RTCYear), hour (RTCHour) and second (RTCSecond). When the system time is set then the meter's real-time clock is also updated.	κw				long	-	-	uint8	-		0	0	59

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moubu.			1			1 1			Modbus		1				
Reg Num	Label		Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
122	RTCSecond	Real-time clock second This is used to read and write system time's second. The system time of the meter can be adjusted by writing to real-time clock month (RTCMonth), day (RTCDate), year (RTCYear), hour (RTCHour) and minute (RTCMinute). When the system time is set then the meter's real-time clock is also updated.	RW				long	-	-	uint8	-		0	0	59
130	ContractHour	Hour of day to log daily record in 24-hour format Hour of day to log the daily record. This is expressed using 24-hour format (military time): midnight is 0 hours, noon is 12 hours, 11PM is 23 hours.	RW	Y	Y	Y	int	hr	hr	uint8	-		0	0	23
131	AlarmTurnOffHysterisisCoun t	Alarm log hysteresis filter number of occurrences Alarm log repetitive alarm filter count. This point, along with alarm log hysteresis filter time span (AlarmTurnOffHysterisisTimeSpan), is used to prevent the alarm log from filing up in the event of a very repetitive alarm (such as the flow temperature fluctuating around one of its alarm limits). It a data point being monitored for the alarm log has this number of alarms within a specified length of time (AlarmTurnOffHysterisSTimeSpan), then alarming is turned off for that point until no new alarms are received for that point within the specified length of time.	RW	Y	Y		int	-	-	uint16	-		4	2	20
	Span	Alarm log repetitive alarm filter time. This point, along with alarm log hysteresis filter number of occurrences (AlarmTunoffhysterissicCount), is used to prevent the alarm log from filting up in the event of a very repetitive alarm (such as the flow temperature fluctuating around one of its alarm limits). If a data point being monitored for the alarm log has alarm log hysteresis filter number of occurrences (AlarmTunOffHystersisSCount) alarms within this specified length of time, then alarming is turned off for that point until no new alarms are received for that point for this length of time.	RW	Y	Y		int	sec	sec	uint16	sec		600	1	3600
	g	Old (unread) alarm log records can be overwritten by new records when TRUE (1). If FALSE (0) and the log becomes full, logging will stop until oldest log records are marked as read to make room for new records.	RW		Y		int	-	-	boolean	-	Do not overwrite old records (FALSE) Overwrite old records (TRUE)	.,		TRUE (1)
	_	Old (unread) audit log records can be overwritten by new records when TRUE (1). If FALSE (0) and the log becomes full, logging will stop until oldest log records are marked as read to make room for new records.	RW	Y	Y		int	-	-	boolean	-	Do not overwrite old records (FALSE) Overwrite old records (TRUE)	TRUE (1)	FALSE (0)	TRUE (1)
135	DoOverwriteUnreadDailyLog	Old unread daily log records can be overwritten by new records when TRUE Old (unread) daily log records can be overwritten by new records when TRUE (1). If FALSE (0) and the log becomes full, logging will stop until oldest log records are marked as read to make room for new records.	RW	Y	Y		int	-	-	boolean	-	Do not overwrite old records (FALSE) Overwrite old records (TRUE)	TRUE (1)	FALSE (0)	TRUE (1)
136	DoOverwriteUnreadHourlyLo 9	Old unread hourly log records can be overwritten by new records when TRUE Old (unread) hourly log records can be overwritten by new records when TRUE (1). If FALSE (0) and the log becomes full, logging will stop until oldest log records are marked as read to make room for new records.	RW	Y	Y		int	-	-	boolean	-	Do not overwrite old records (FALSE) Overwrite old records (TRUE)	TRUE (1)	FALSE (0)	TRUE (1)
137	DoOverwriteUnreadSystemL og	Old unread system log records can be overwritten by new records when TRUE Old (unread) system log records can be overwritten by new records when TRUE (1). If FALSE (0) and the log becomes full, logging will stop until oldest log records are marked as read to make room for new records.	RW	Y	Y		int	-	-	boolean	-	Do not overwrite old records (FALSE) Overwrite old records (TRUE)	TRUE (1)	FALSE (0)	TRUE (1)
200	Freq1Content	Frequency Output 1 pair content Selects the data to be represented by the Frequency Output 1 pair (Freq1A (Freq1AnIA) and Freq1B (Freq1ChnB)) to be directed to Frequency/Digital Output 1 (FODO1Source), Frequency/Digital Output 2 (FODO2Source), Frequency/Digital Output 3 (FODO3Source), Frequency/Digital Output 4 (FODO4Source), Frequency/Digital Output 5 (FODOSSource) or Frequency/Digital Output 6 (FODO6Source). See Liquid Ultrasonic Installation, Operations or Maintenance and Troubleshooting manuals.	RW	Y	Y	Y	float	-	-	int32	-	Uncorrected volume flow rate (0) Profile factor (6)	0	0	6
202	Freq1Dir	Selects the flow direction represented by the Frequency Output 1 pair (Freq1A, Freq1B); Selects the flow direction represented by the Frequency Output 1 pair (Freq1A (Freq1And) and Freq1B (Freq1ChnIB)). When set to 'Reverse' or 'Forward', both channels A and B represent the specified content when the flow is in selected direction. When set to 'Absolute', both channels A and B represent the specified content regardless of the flow direction. When set to 'Bidirectional', channel A represents the specified content when the flow is in the forward direction and channel B represents the specified content when flow is in the reverse direction. See Liquid Ultrasonic Installation, Operations or Maintenance and Troubleshooting manuals.	RW	Y	Y	Y	float	-	-	int32	-	Reverse (0) Forward (1) Absolute (2) Bidirectional (3)	1	0	3
204	Freq1MaxFrequency	Frequency Output 1 pair maximum (full-scale) frequency Selects the Frequency Output 1 pair maximum (full-scale) frequency used in determining the K-factor and inverse K-factor.	RW	Y	Y	Y	float	Hz	Hz	uint16	Hz	1000 (1000) 5000 (5000)	1000	1000	5000
206	Freq1FullScaleVolFlowRate	Frequency Output 1 pair volumetric flow rate corresponding to the maximum frequency Specifies the Frequency Output 1 pair volumetric flow rate corresponding to the maximum frequency selected (Freq1MaxFrequency) when Frequency Output 1 pair content (Freq1Content) is set to a volumetric flow rate.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		200000	0	3.40E+38
		Frequency Output 1B phase relative to 1A Selects the Frequency Output 1 pair channel B phase relative to the channel A phase based on the flow direction.	RW		Y	Y	float	-	-	int32	-	Lag forward, Lead reverse (0) Lead forward, Lag reverse (1)	0	0	1
		Frequency Output 1B forced to zero when invalid control When TRUE (1), forces the Frequency Output 1 channel B frequency to zero when the frequency pair's data is invalid.	RW		Y	Y	float	-	-	boolean	-	Not forced to zero on error (FALSE) Forced to zero on error (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
220	Freq1FeedbackCorrectionP cnt	Frequency Output 1 pair volume feedback percentage Specifies the Frequency Output 1 pair percentage of error (determined by frequency feedback) to adjust for per batch. This only applies when the frequency pair content is selected to be a rate.	RW	Y	Y	Y	float	%	%	uint8	%		1	0	100
222	DO1AContent	Digital Output 14 content selector Selects the content (Freq1 Validity (0), Flow Direction (2), or Dual-Configuration meter flow rate range validity (3)) for Digital Output 1 A to be directed to Frequency/Digital Output 1 (FODO1Source), Frequency/Digital Output 2 (FODO2Source), Frequency/Digital Output 3 (FODO3Source), Frequency/Digital Output 4 (FODO4Source), Frequency/Digital Output 5 (FODOSSource) or Frequency/Digital Output 6 (FODO6Source), Frequency/Digital Output 4 (FODO4Source), Frequency/Digital Output 5 (FODO5Source) or Frequency/Digital Output 6 (FODO6Source), Frequency/Digital Output 4 (FODO4Source), Frequency/Digital Output 5 (FODO5Source) or Frequency/Digital Output 6 (FODO6Source), Frequency/Digital Output 4 (FODO4Source), Frequency/Digital Output 5 (FODO5Source) or Frequency/Digital Output 6 (FODO6Source), Frequency/Digital Output 4 (FODO4Source), Frequency/Digital Output 5 (FODO5Source) or Frequency/Digital Output 6 (FODO6Source), Frequency/Digital Output 4 (FODO4Source), Frequency/Digital Output 5 (FODO5Source) or Frequency/Digital Output 6 (FODO6Source), Frequency/Digital Output 4 (FODO4Source), Frequency/Digital Output 5 (FODO5Source) or Frequency/Digital Output 6 (FODO6Source), Frequency/Digital Output 5 (FODO4Source), Frequency/Digital 0 (tota) of the first or first	RW	Y	Y	Y	float	-	-	int32	-	Frequency Output 1 validity (0) Flow direction (2) Dual-Configuration meter flow rate range validity (3)	0	0	3
224	DO1AlsInvPolarity	Digital Output 1A polarity control Selects the Digital Output 1A polarity as "Normal" or "Inverted". For "Normal" polarity, a high output indicates either valid frequency data or forward flow (depending upon the Digital Output 1A content selector (DO1AContent)). For "Inverted" polarity, a low output indicates either valid frequency data or forward flow.	RW	Y	Y	Y	float	-	-	boolean	-	Normal (FALSE) Inverted (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
		Digital Output 18 content selector Selects the content (Freqt Validity (0), Flow Direction (2), or Dual-Configuration meter flow rate range validity (3)) for Digital Output 1 B to be directed to Frequency/Digital Output 1 (FODO1Source), Frequency/Digital Output 2 (FODO2Source), Frequency/Digital Output 3 (FODO3Source), Frequency/Digital Output 4 (FODO4Source), Frequency/Digital Output 5 (FODO5Source) or Frequency/Digital Output 6 (FODO6Source), Frequency/Digital Output 4 (FODO4Source), Frequency/Digital Output 5 (FODO5Source) or Frequency/Digital Output 6 (FODO6Source), Freqt Validity is Freqt DataValidity. Flow Direction is FlowDir. Dual-Configuration meter flow rate range validity is the inverse of IsColocMeterQFlowRangeErr.	RW		Y	Y	float	-	-	int32	-	Frequency Output 1 validity (0) Flow direction (2) Dual-Configuration meter flow rate range validity (3)	2	0	3
		Selects the Digital Output 1B polarity as "Normal" or "Inverted". For "Normal" polarity, a high output indicates either valid frequency data or forward flow (depending upon the Digital Output 1B content selector (DO1BContent)). For "Inverted" polarity, a low output indicates either valid frequency data or forward flow.	RW	Y	Ý	Y	float	-	-	boolean	-	Inverted (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
250	Freq2Content	Frequency Output 2 pair content Selects the data to be represented by the Frequency Output 2 pair (Freq2A (Freq2ChnIA) and Freq2B (Freq2ChnIB)) to be directed to Frequency/Digital Output 1 (FODO1Source), Frequency/Digital Output 2 (FODO2Source), Frequency/Digital Output 3 (FODO3Source), Frequency/Digital Output 4 (FODO4Source), Frequency/Digital Output 5 (FODOSSource) or Frequency/Digital Output 6 (FODO6Source). See Liquid Ultrasonic Installation, Operations or Maintenance and Troubleshooting manuals.	RW	Y	Y	Ŷ	float	-	-	int32	-	Uncorrected volume flow rate (0) Profile factor (6)	0	0	6
	v Modbus Reg Num 122 130 131 133 133 133 134 135 136 137 200 202 204 206 216 218 220 224 224 226 228	Wodbus map is applicable for Rose Reg Num Label 122 RTCSecond 130 ContractHour 131 AlarmTurnOffHysterisisCount 132 AlarmTurnOffHysterisisCount 133 DoOverwriteUnreadAlarmLog 134 DoOverwriteUnreadAlarmLog 135 DoOverwriteUnreadAlarmLog 136 DoOverwriteUnreadAlarmLog 137 DoOverwriteUnreadAlarmLog 138 DoOverwriteUnreadAlarmLog 139 DoOverwriteUnreadAlarmLog 130 DoOverwriteUnreadAlarmLog 131 DoOverwriteUnreadAlarmLog 132 DoOverwriteUnreadAlarmLog 133 DoOverwriteUnreadAlarmLog 134 DoOverwriteUnreadAlarmLog 135 DoOverwriteUnreadSystemL 137 DoOverwriteUnreadSystemL 200 Freq1Content 201 Freq1FullScaleVolFlowRate 202 Freq1FullScaleVolFlowRate 216 Freq1BPhase 218 IsFreq1BZeroedOnErr 220 <td< td=""><td>No. Abel 122 HCEscool Read-time dock accord The is used to read and with system time's spectrum, how (HCEsta) and muse (HCEsta) is interpreter dock all source in and and with system time's spectrum time's preter dock month that or dock accord 123 Constant/burnel/Meter dock accord The is used to read and with system time's spectrum time's preter dock month theor of yes, burnel to do the is used to read and with a system time's preter dock month theor of yes, burnel to do the is used to read and with a system time's preter dock month theor of yes, burnel to do the is used to read and yes and a set operation and the low temperature fluctuation accord accord to prevent to a dark to get the got to do the origin of the accord of the appreters fluctuation accord to the preters fluctuation ac</td><td>Debug Second Secon</td><td>Bit Status range apgelication for FlassmouthTH Lapids 4-2410 (Postcollumber 2410) part 2 Path (Doublechumber 2410) part 2 Path (Doublechumbe</td><td>2 Address maps applicable for Accounted Mugaci 4-Pair (DeviceMunder 2415) (InstanceMunder 2415) (Instance Ass. With Control 120 PROS Audit Description Audit Molecular PRO PRO</td><td>24-Detection range to appricicable for Antice And Part Districtabilized 2114 (and 14 Part Districtabilized 2114) (and 14 Part Districtabilized 2114) Note Note</td><td>Michae Anstein Association Association</td><td>NUMBER OF PROFESSION AND ADDRESS Number of the second of the</td><td>Number Network Description Note: Note:<!--</td--><td>Number of the stream of the start of the stream of t</td><td>Name Number of the structure of th</td><td>matrix matrix matrix</td><td></td><td>Number Number Num Number Number Number Number Number Number Number Num</td></td></td<>	No. Abel 122 HCEscool Read-time dock accord The is used to read and with system time's spectrum, how (HCEsta) and muse (HCEsta) is interpreter dock all source in and and with system time's spectrum time's preter dock month that or dock accord 123 Constant/burnel/Meter dock accord The is used to read and with system time's spectrum time's preter dock month theor of yes, burnel to do the is used to read and with a system time's preter dock month theor of yes, burnel to do the is used to read and with a system time's preter dock month theor of yes, burnel to do the is used to read and yes and a set operation and the low temperature fluctuation accord accord to prevent to a dark to get the got to do the origin of the accord of the appreters fluctuation accord to the preters fluctuation ac	Debug Second Secon	Bit Status range apgelication for Flassmouth TH Lapids 4-2410 (Postcollumber 2410) part 2 Path (Doublechumber 2410) part 2 Path (Doublechumbe	2 Address maps applicable for Accounted Mugaci 4-Pair (DeviceMunder 2415) (InstanceMunder 2415) (Instance Ass. With Control 120 PROS Audit Description Audit Molecular PRO PRO	24-Detection range to appricicable for Antice And Part Districtabilized 2114 (and 14 Part Districtabilized 2114) (and 14 Part Districtabilized 2114) Note Note	Michae Anstein Association Association	NUMBER OF PROFESSION AND ADDRESS Number of the second of the	Number Network Description Note: Note: </td <td>Number of the stream of the start of the stream of t</td> <td>Name Number of the structure of th</td> <td>matrix matrix matrix</td> <td></td> <td>Number Number Num Number Number Number Number Number Number Number Num</td>	Number of the stream of the start of the stream of t	Name Number of the structure of th	matrix matrix		Number Num Number Number Number Number Number Number Number Num

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The below I	Modbus	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
40253	252	Freq2Dir	Selects the flow direction represented by the Frequency Output 2 pair (Freq2A, Freq2B) Selects the flow direction represented by the Frequency Output 2 pair (Freq2A (Freq2AnIA) and Freq2B (Freq2AnIB)). When set to 'Reverse' or 'Forward', both Lannels A and B represent the specified content when the flow is in selected direction. When set to 'Absolute', both channels A and B represent the specified content regardless of the flow direction. When set to 'Bidirectional', channel A represents the specified content when the flow is in the forward direction and channel B represents the specified content when flow is in the reverse direction. See Liquid Ultrasonic Installation, Operations or Maintenance and Troubleshooting manuals.	RW	Y	Y	Y	float	-	-	int32	-	Reverse (0) Forward (1) Absolute (2) Bidirectional (3)	1	0	3
40255	254	Freq2MaxFrequency	Frequency Output 2 pair maximum (full-scale) frequency Selects the Frequency Output 2 pair maximum (full-scale) frequency used in determining the K-factor and inverse K-factor.	RW	Y	Y	Y	float	Hz	Hz	uint16	Hz	1000 (1000) 5000 (5000)	1000	1000	5000
40257	256	Freq2FullScaleVolFlowRate		RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		200000	0	3.40E+38
40267	266	Freq2BPhase	Frequency Output 2B phase relative to 2A Selects the Frequency Output 2 pair channel B phase relative to the channel A phase based on the flow direction.	RW	Y	Y	Y	float	-	-	int32	-	Lag forward, Lead reverse (0) Lead forward, Lag reverse (1)	0	0	1
40269	268	lsFreq2BZeroedOnErr	Frequency Output 2B forced to zero when invalid control When TRUE (1), forces the Frequency Output 2 channel B frequency to zero when the frequency pair's data is invalid.	RW	Y	Y	Y	float	-	-	boolean	-	Not forced to zero on error (FALSE) Forced to zero on error (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
40271	270	Freq2FeedbackCorrectionP cnt	Frequency Output 2 pair volume feedback percentage of error (determined by frequency feedback) to adjust for per batch. This only applies when the frequency Output 2 pair volume feedback percentage of error (determined by frequency feedback) to adjust for per batch. This only applies when the frequency pair content is selected to be a rate.	RW	Y	Y	Y	float	%	%	uint8	%		1	0	100
40273	272	DO2AContent	Digital Output 2A content selector Selects the content (Freq2 Validity (1), Flow Direction (2), or Dual-Configuration meter flow rate range validity (3)) for Digital Output 2A to be directed to Frequency/Digital Output 1 (FODO1Source), Frequency/Digital Output 2 (FODO2Source), Frequency/Digital Output 3 (FODO3Source), Frequency/Digital Output 4 (FODO4Source), Frequency/Digital Output 5 (FODO5Source) or Frequency/Digital Output 4 (FODO6Source), Frequency/Digital Output 4 (FODO4Source), Frequency/Digital Output 5 (FODO5Source) or Frequency/Digital Output 6 (FODO6Source), Frequency/Digital Output 4, FreqUency/Digital Output 5 (FODO5Source) or Frequency/Digital Output 6 (FODO6Source), Frequency/Digital Output 4, FreqUency/Digital Output 5 (FODO6Source), FreqUency/Digital Output 5 (FOD06Source), FreqUency/Digital Output 5	RW	Y	Y	Y	float	-	-	int32	-	Frequency Output 2 validity (1) Flow direction (2) Dual-Configuration meter flow rate range validity (3)	1	1	3
40275	274	DO2AlsInvPolarity	Digital Output 2A polarity control Selects the Digital Output 2A polarity as "Normal" or "Inverted". For "Normal" polarity, a high output indicates either valid frequency data or forward flow (depending upon the content DO2AContent). For "Inverted" polarity, a low output indicates either valid frequency data or forward flow.	RW	Y	Y	Y	float	-	-	boolean	-	Normal (FALSE) Inverted (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
40277	276	DO2BContent	Digital Output 2B content selector Selects the content (Freq2 Validity (1), Flow Direction (2), or Dual-Configuration meter flow rate range validity (3)) for Digital Output 2B to be directed to Frequency/Digital Output 1 (FODO1 Source), Frequency/Digital Output 2 (FODO2Source), Frequency/Digital Output 3 (FODO3Source), Frequency/Digital Output 4 (FODO4Source), Frequency/Digital Output 5 (FODO5Source) or Frequency/Digital Output 4 (FODO3Source), Freq2 Validity is Freq2DataValidity, Flow Direction is FlowDir. Dual-Configuration meter flow rate range validity is the inverse of IsColoMeterGFOwRangeErr.	RW	Y	Y	Y	float	-	-	int32	-	Frequency Output 2 validity (1) Flow direction (2) Dual-Configuration meter flow rate range validity (3)	2	1	3
40279	278	DO2BIsInvPolarity	Digital Output 2B polarity control Selects the Digital Output 2B polarity as "Normal" or "Inverted". For "Normal" polarity, a high output indicates either valid frequency data or forward flow (depending upon the content selected via the Digital Output 2B content (DO2BContent) data point). For "Inverted" polarity, a low output indicates either valid frequency data or forward flow.	RW	Y	Y	Y	float	-	-	boolean	-	Normal (FALSE) Inverted (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
40281	280	FODO1Source	Source for Frequency/Digital Output 1 in Frequency/Digital Output 1 available (IsFODO1Avail) is TRUE (1). The sources may be: Frequency Output 1A based on Freq1Content Frequency/Digital Output 1 available (IsFODO1Avail) is TRUE (1). The sources may be: Frequency Output 1B based on Freq2Content FreqUency/Digital Output 1 available (IsFODO1Avail) is TRUE (1). The sources may be: Frequency Output 1B based on Freq2Content and Freq1BPhase Frequency Output 2A based on Freq2Content and Freq2BPhase Digital Output 1A based on Freq2Content Digital Output 1B based on DO1AContent Digital Output 2A based on DO2AContent Digital Output 2A based on DO2AContent The output Events are selected by FODO1Mode.	RW	Y	Y	Y	float	-	-	uint8	-	Frequency Output 1A (0) Frequency Output 1B (1) Frequency Output 2A (2) Frequency Output 2B (3) Digital Output 1A (4) Digital Output 1B (5) Digital Output 2A (6) Digital Output 2A (7)	0	0	7
40283	282	FODO2Source	Source for Frequency/Digital Output 2 Selects the source for Frequency/Digital Output 2 if Frequency/Digital Output 2 available (IsFODO2Avail) is TRUE (1). The sources may be: Frequency Output 1A based on Freq1Content Frequency Output 1A based on Freq2Content Frequency Output 2B based on Freq2Content and Freq1BPhase Frequency Output 2B based on Or Freq2Content and Freq2BPhase Digital Output 1A based on D01AContent and Freq2BPhase Digital Output 1B based on D01BContent Digital Output 2B based on D01BContent Digital Output 2B based on D02BContent Digital Output 2B based on D02BCOntent	RW	Y	Y	Y	float	-	-	uint8	-	Frequency Output 1A (0) Frequency Output 1B (1) Frequency Output 2A (2) Frequency Output 2B (3) Digital Output 1A (4) Digital Output 1B (5) Digital Output 2A (6) Digital Output 2B (7)	2	0	7
40285	284	FODO3Source	Source for Frequency/Digital Output 3 Selects the source for Frequency/Digital Output 3 if Frequency/Digital Output 3 available (IsFODO3Avaii) is TRUE (1). The sources may be: Frequency Output 1A based on Freq1Content Frequency Output 1A based on Freq2Content and Freq1BPhase Frequency Output 2B based on Freq2Content and Freq1BPhase Oigital Output 1A based on OrFcq2Content and Freq2BPhase Digital Output 1A based on DO1AContent and Freq2BPhase Digital Output 2B based on DO1AContent Digital Output 2B based on DO1AContent Digital Output 2B based on DO2AContent Digital Output 2B based on DO2AContent	RW	Y	Y	Y	float	-	-	uint8	-	Frequency Output 1A (0) Frequency Output 1B (1) Frequency Output 2A (2) Frequency Output 2B (3) Digital Output 1A (4) Digital Output 1B (5) Digital Output 2A (6) Digital Output 2B (7)	3	0	7
40287		FODO1Mode	Mode for Frequency/Digital Output 1 Selects the output levels for Frequency/Digital Output 1 (FODO1Source) when Frequency/Digital Output 1 available (IsFODO1Avail) is TRUE (1).	RW		Y	Y	float	-	-	uint8	-	TTL (0) Open Collector (1)	1	0	1
40289		FODO2Mode	Node for Frequency/Digital Output 2 Selects the output levels for Frequency/Digital Output 2 (FODO2Source) when Frequency/Digital Output 2 available (IsFODO2Avail) is TRUE (1).	RW		Y	Y	float	-	-	uint8	-	TTL (0) Open Collector (1)	1	0	1
40291	290	FODO3Mode	Mode for Frequency/Digital Output 3 Selects the output levels for Frequency/Digital Output 3 (FODO3Source) when Frequency/Digital Output 3 available (IsFODO3Avail) is TRUE (1).	RW	Y	Y	Y	float	-	-	uint8	-	TTL (0) Open Collector (1)	1	0	1

Rosemour	nt™ Liqui	d Ultrasonic Firmware: 1.61	Database: 2.29.017													
The below	Modbus	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
40293	292	FODO4Source	Source for Frequency/Digital Output 4 Selects the source for Frequency/Digital Output 4 if Frequency/Digital Output 4 available (IsFODO4Avail) is TRUE (1). The sources may be: Frequency Output 1A based on Freq1Content and Freq1BPhase Frequency Output 2A based on Freq2Content and Freq1BPhase Digital Output 1A based on Freq2Content and Freq2BPhase Digital Output 1B based on D1AContent Digital Output 1B based on D01AContent Digital Output 2b based on D02ACcontent Digital Output 2b based on D02BContent	RW	Y	Y	Y	float	-	Unit	uint8	-	Frequency Output 1A (0) Frequency Output 1B (1) Frequency Output 2A (2) Frequency Output 2B (3) Digital Output 1A (4) Digital Output 1B (5) Digital Output 2A (6) Digital Output 2B (7)	6	0	7
40295	294	FODO5Source	The output levels are selected by FODO4Mode. Source for Frequency/Digital Output 5	RW	Y	Y	Y	float		-	uint8	-	Frequency Output 1A (0)	7	0	7
			Selects the source for Frequency/Digital Output 5 if Frequency/Digital Output 5 available (IsFODO5Avail) is TRUE (1). The sources may be: Frequency Output 1A based on Freq1Content and Freq1BPhase Frequency Output 2A based on Freq2Content and Freq2BPhase Digital Output 2A based on OF1eq2Content and Freq2BPhase Digital Output 1A based on D01AContent Digital Output 1B based on D01BContent Digital Output 2B based on D01BCOntent Digital Output 2B based on D02AContent Digital Output 2B based on D02AContent The output levels are selected by FODO5Mode.										Frequency Output 18 (1) Frequency Output 2A (2) Frequency Output 2B (3) Digital Output 1A (4) Digital Output 18 (5) Digital Output 2A (6) Digital Output 2B (7)			
40297	296	FODO6Source	Source for Frequency/Digital Output 6 Selects the source for Frequency/Digital Output 6 if Frequency/Digital Output 6 available (IsFODO6Avail) is TRUE (1). The sources may be: Frequency Output 1A based on Freq1Content Frequency Output 1B based on Freq2Content and Freq1BPhase Frequency Output 2B based on Freq2Content and Freq2BPhase Digital Output 2B based on Freq2Content and Freq2BPhase Digital Output 1A based on DO1AContent Digital Output 1B based on DO1BContent Digital Output 2A based on DO2Content Digital Output 2B based on DO2AContent Digital Output 2B based on DO2AContent	RW	Y	Y	Y	float		-	uint8	-	Frequency Output 1A (0) Frequency Output 1B (1) Frequency Output 2A (2) Frequency Output 2B (3) Digital Output 1A (4) Digital Output 1B (5) Digital Output 2A (6) Digital Output 2B (7)	4	0	7
40301	300	AO1Content	Analog Output 1 content (and HART primary variable) Selects the data to be represented by Analog Output 1. Is used for HART communication as the Primary Variable content.	RW	Y	Y	Y	float	-	-	int32	-	Uncorrected volume flow rate (0) Average flow velocity (2)	0	0	3
40303	302	AO1Dir	Selects the flow direction represented by the Analog Output 1 Selects the flow direction represented by Analog Output 1. When set to "Reverse" or "Forward", the analog output represents the specified content when the flow is in selected direction. When set to "Absolute", the analog output represents the specified content recardless of the flow direction.	RW	Y	Y	Y	float	-	-	int32	-	Average speed of sound (3) Reverse (0) Forward (1) Absolute (2)	2	0	2
40305	304	AO1FullScaleVolFlowRate	Analog Output 1 volumetric flow rate corresponding to the maximum current (20 mA) Specifies the Analog Output 1 volumetric flow rate corresponding to the maximum current (20 mA) (AO1Content) is set to uncorrected volume flow rate (QFlow) or corrected volume flow rate (QBase).	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		200000	0	3.40E+38
40307	306	FODO4Mode	Mode for Frequency/Digital Output 4 Selects the output levels for Frequency/Digital Output 4 (FODO4Source) when Frequency/Digital Output 4 available (IsFODO4Avai) is TRUE (1).	RW	Y	Y	Y	float	-	-	uint8	-	TTL (0) Open Collector (1)	1	0	1
40309		FODO5Mode	Mode for Frequency/Digital Output 5 Selects the output levels for Frequency/Digital Output 5 (FODO5Source) when Frequency/Digital Output 5 available (IsFODO5Avail) is TRUE (1).	RW	Y	Y	Y	float	-	-	uint8	-	TTL (0) Open Collector (1)	1	0	1
40311	310	FODO6Mode	Mode for Frequency/Digital Output 6 Selects the output levels for Frequency/Digital Output 6 (FODO6Source) when Frequency/Digital Output 6 available (IsFODO6Avail) is TRUE (1).	RW	Y	Y	Y	float	-	-	uint8	-	TTL (0) Open Collector (1)	1	0	1
40315	314	AO1ActionUponInvalidConte nt	Analog Output 1 current action upon invalid content Specifies the action for Analog Output 1 current when the content is invalid. No special action is taken when set to None.	RW	Y	Y	Y	float	-	-	uint8	-	High - 20 mA (0) Low -4 mA (1) Hold last value (239) Very low - 3.5 mA (240) Very high - 20.5 mA (241) None (251)	240	0	251
40321	320	AO1TrimCurrent	Analog Output 1 fixed current value (for trim) Specifies the Analog Output 1 Fixed Current Mode value for trimming the output. A value of zero causes the Fixed Current Mode to be exited. Cycling power also causes the Fixed Current Mode to be exited.	RW			Y	float	ma	ma	float32	ma		0	0	21
40323	322	AO1TrimZeroExtMeasCurre nt	Analog Output 1 zero trim externally measured current Analog Output 1 zero trim externally measured current.	RW	1		Y	float	ma	ma	float32	ma		4	3	5
40325	324	AO1TrimGainExtMeasCurre nt	Analog Output 1 gain trim externally measured current Analog Output 1 gain trim externally measured current.	RW	1		Y	float	ma	ma	float32	ma		20	19	21
40341	340	AO2Content	Analog Output 2 content (and HART secondary variable) Selects the data to be represented by Analog Output 2.Is used for HART communication as the Secondary Variable content.	RW	Y	Y	Y	float	-	-	int32	-	Uncorrected volume flow rate (0) Average flow velocity (2) Average speed of sound (3)	0	0	3
40343		AO2Dir	Selects the flow direction represented by the Analog Output 2 Selects the flow direction represented by Analog Output 2. When set to "Reverse" or "Forward", the analog output represents the specified content when the flow is in selected direction. When set to "Absolute", the analog output represents the specified content regardless of the flow direction.	RW		Y	Y	float	-	-	int32	-	Reverse (0) Forward (1) Absolute (2)	2	0	2
40345	344	AO2FullScaleVolFlowRate	Analog Output 2 volumetric flow rate corresponding to the maximum current (20 mA) Specifies the Analog Output 2 volumetric flow rate corresponding to the maximum current (20 mA) when the AO2Content data point is set to "Incorrected volume flow rate" (CFRw) or "Corrected volume flow rate" (CBase).	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		200000	0	3.40E+38
40355	354	AO2ActionUponInvalidConte nt	Analog Output 2 current action upon invalid content Specifies the action for Analog Output 2 current when the content is invalid. No special action is taken when set to None.	RW	Y	Y	Y	float	-	-	uint8	-	High - 20 mA (0) Low - 4 mA (1) Hold last value (239) Very low - 3.5 mA (240) Very high - 20.5 mA (241) None (251) None (251)	240	0	251
40361	360	AO2TrimCurrent	Analog Output 2 fixed current value (for tim) Specifies the Analog Output 2 Fixed Current Mode value for trimming the output. A value of zero causes the Fixed Current Mode to be exited. Cycling power also causes the Fixed Current Mode to be exited.	RW			Y	float	ma	ma	float32	ma		0	0	21

Holding Reg Register Num Label	Rosemount ¹¹⁰ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters Description	Acc RW RW RW RW RW	NV Y Y	Cnfg Y Y	Prot Y Y Y Y	Modbus Reg Type float float float float	Modbus Metric Unit ma ma	Modbus U.S. Customary Unit ma ma	Native Data Type float32 float32 uint8	Native Data Unit ma ma	Selections/Bitmap None (0) Live (1) Fixed (2) Transmitter Head 1 (3)	Default Value (native unit) 4 20 0	Minimum Value (native unit) 3 19 0	Maximum Value (native unit) 5 21 3
Holding Register Number Reg Num Label 40363 362 A02TrimZeroExtMea nt 40365 364 A02TrimGainExtMea nt 40419 418 Reserved 40421 420 EnablePressureInput 40423 422 InputPressureUnit 40425 424 AtmosphericPress	Description urree Analog Output 2 zero trim externally measured current. Analog Output 2 gain trim externally measured current. 'urre Analog Output 2 gain trim externally measured current. 'Analog Output 2 gain trim externally measured current. 'Bow-condition pressure input selector Selects the flow-condition pressure is specified (fixed) via the SpecFlowPressure data point. When set to "Transmitter Head 1", the flow-condition pressure is read from an analog input signal. When set to "Fixed", the flow-condition pressure is specified (fixed) via the SpecFlowPressure data point. When set to "Transmitter Head 1" only on Transmitter Head 2 (ColocMeterMode) of a data sharing Dual-Configuration meter. The flow-condition pressure is used for pressure expansion correction (if enabled). This value cannot be set to "None" if pressure expansion correction is enabled (EnableExpCorrPress). Input pressure absolute/gage selector Specifies whether the input pressure is 'Absolute' or "Gage". If the input pressure is gage, then the absolute pressure is calculated as the sum of the input gage pressure and the atmospheric pressure (MamosphericPress). When writing the HESO 1708 Modbus register then the input pressure is absolute pressure in the subolute pressure. Atmospheric pressure Specifies whether the input pressure. Atmospheric pressure Specifies the atmospheric pressure. This value is required when the input pressure absolute/gage selector (InputPressureUnit) is Gage, so that flow-condition absolute pressure. This value is required when the input p	RW RW R RW RW	NV Y Y	Cnfg Y Y	Prot Y Y Y Y	Reg Type float float float	Metric Unit ma	U.S. Customary Unit ma	Type float32 float32	Unit ma	None (0) Live (1) Fixed (2)	(native unit) 4 20	Value (native unit) 3 19	Value (native unit) 5 21
Register Number Reg Num Label 40363 362 A02TrimZeroExtMea nt 40365 364 A02TrimGainExtMea nt 40419 418 Reserved 40421 420 EnablePressureInput 40423 422 InputPressureUnit 40425 424 AtmosphericPress	Urre Analog Output 2 zero trim externally measured current Analog Output 2 zero trim externally measured current Analog Output 2 gain trim externally measured current Flow-condition pressure input selector Selects the flow-condition pressure is specified (fixed) via the Specifiev Pressure data point. When set to "Transmitter Head 1", the flow- condition pressure is used from Transmitter Head 1" only on Transmitter Head 2 (ColocMeterMode) of a data sharing Dual-Configuration meter. The flow-condition pressure is used for pressure expansion correction (if enabled). This value cannot be set to "None" if pressure expansion correction is enabled (EnableExpCorrPress). When writing the flow-condition absolute pressure is valued or "Gage". If the input pressure is gage, then the absolute pressure is calculated as the sum of the input gage pressure and the atmospheric pressure (in the first one officion condition absolute pressure values via the ISO 1709 Modbus register then the input pressure in thas no effect and value is absolute pressure. Atmospheric pressure Specifies the atmospheric pressure. This value is required when the input pressure absolute/gage selector (InputPressureIUnit) is Gage, so that flow-condition absolute pressure.	RW RW R RW RW	NV Y	Cnfg Y Y	Prot Y Y Y Y	Reg Type float float float	Metric Unit ma	U.S. Customary Unit ma	Type float32 float32	Unit ma	None (0) Live (1) Fixed (2)	(native unit) 4 20	Value (native unit) 3 19	Value (native unit) 5 21
nt 40365 364 AO2TrimGainExtMea nt 40419 418 Reserved 40421 420 EnablePressureInput 40421 420 EnablePressureInput 40423 422 InputPressureUnit 40425 424 AtmosphericPress	Analog Output 2 zero trim externally measured current. Analog Output 2 gain trim externally measured current Analog Output 2 gain trim externally measured current. Flow-condition pressure input selector Selects the flow-condition pressure is specified (fixed) via the SpecFlowPressure is read from an analog input signal. When set to "Fixed", the flow-condition pressure is specified (fixed) via the SpecFlowPressure data point. When set to "Transmitter Head 1", the flow-condition pressure is read from Transmitter Head 1 a Dual-Configuration meter (ColocMeter/PAddress). The flow-condition pressure is used for Transmitter Head 1 a Dual-Configuration meter. The flow-condition pressure is used for pressure expansion correction (if enabled). This value cannot be set to "None" if pressure expansion correction (if enabled). This value cannot be set to "None" if pressure expansion correction (if enabled). This value cannot be set to "None" if pressure expansion correction (if enabled). Input pressure absolute/gage selector Specifies whether the input pressure is 'Absolute' or "Gage". If the input pressure is gage, then the absolute pressure is value size onsidered as absolute pressure values values values value b ISO 17009 Modbus register then the input pressure int has no effect and value is always considered as absolute pressure values	RW R RW RW	Y	Y	Y Y Y	float float		ma	float32		Live (1) Fixed (2)	20	19	21
nt 40419 418 Reserved 40421 420 EnablePressureInput 40423 422 InputPressureUnit 40423 422 AtmosphericPress	Analog Output 2 gain trim externally measured current. Flow-condition pressure input selector Selects the flow-condition pressure input. When set to "Live", the flow-condition pressure is read from an analog input signal. When set to 'Fixed', the flow-condition pressure is second flow (by at the SpecFlowPressure data point. When set to 'Transmitter Head 1', the flow-condition pressure is read from Transmitter Head 1 of a Dual-Configuration meter (ColocMeter/Mode) of a data sharing Dual-Configuration meter. The flow-condition pressure is used for pressure expansion correction (if enabled). This value cannot be set to 'None' if pressure expansion correction is enabled (EnableExpCorrPress). Input pressure absolute/gage selector Specifies whether the input pressure is 'Absolute' or 'Gage'. If the input pressure is gage, then the absolute pressure is calculated as the sum of the input gage pressure and the atmospheric pressure (the timp the fixed rad). When writing the flow-condition absolute pressure. Atmospheric pressure Specifies the atmospheric pressure. This value is required when the input pressure absolute/gage selector (InputPressureUnit) is Gage, so that flow-condition absolute pressure. This value is required when the input pressure absolute/gage selector (InputPressureUnit) is Gage, so that flow-condition absolute pressure.	RW	Y	Y	Y Y Y	float	ma -	ma -		ma -	Live (1) Fixed (2)			
40421 420 EnablePressureInput 40423 422 InputPressureUnit 40425 424 AtmosphericPress	Flow-condition pressure input selector Selects the flow-condition pressure input. When set to "Live", the flow-condition pressure is read from an analog input signal. When set to "Fixed", the flow-condition pressure is specified (fixed) via the SpecFlowPressure data point. When set to "Transmitter Head 1", the flow- condition pressure is read from Transmitter Head 1 of a Dual-Configuration meter. (ColocMeterModdress). The flow-condition pressure input selector can be "Transmitter Head 1" only on Transmitter Head 2 (ColocMeterModd) of a data sharing Dual-Configuration meter. The flow-condition pressure is used for pressure expansion correction (if enabled). This value cannot be set to "None" if pressure expansion correction is enabled (EnableExpCorrPress). Input pressure absolute/gage selector Specifies whether the input pressure is "Absolute" or "Gage". If the input pressure is gage, then the absolute pressure is calculated as the sum of the input gage pressure is "Absolute" or "Gage". If the input pressure is gage, then writing the flow-condition absolute pressure values via the ISO 17089 Modbus register then the input pressure (AtmosphericPress). When writing the flow-condition absolute pressure. Atmospheric pressure Specifies the atmospheric pressure. This value is required when the input pressure absolute/gage selector (InputPressureUnit) is Gage, so that flow-condition absolute pressure (AbsFlowPressure) can be calculated. Pressure alarm low limit	RW	Y	Y	Y Y		-	-	uint8	-	Live (1) Fixed (2)	0	0	3
40421 420 EnablePressureInput 40423 422 InputPressureUnit 40425 424 AtmosphericPress	Selects the flow-condition pressure input. When set to "Live", the flow-condition pressure is read from an analog input signal. When set to "Fixed", the flow-condition pressure is specified (fixed) via the SpecFlowPressure data point. When set to "Transmitter Head 1 of a Dual-Configuration meter (ColocMeter/Address). The flow-condition pressure is read from Transmitter Head 1 of a Dual-Configuration meter (ColocMeter/Address). The flow-condition pressure is enable to "transmitter Head 1 of a Dual-Configuration meter (ColocMeter/Address). The flow-condition pressure is used for pressure aspansion correction (if enabled). This value cannot be set to "None" if pressure expansion correction is enabled (EnableExpCorrPress). Input pressure absolute/gage selector Specifies whether the input pressure is "Absolute" or "Gage". If the input pressure is gage, then the absolute pressure is calculated as the sum of the input gage pressure and the atmospheric pressure (Atmospheric/Press). When writing the flow-condition absolute pressure values via the ISO 1708 Modus register then the input pressure in that no effect and value is always considered as absolute pressure. Atmospheric pressure Specifies the atmospheric pressure. This value is required when the input pressure absolute/gage selector (InputPressureUnit) is Gage, to that flow-condition absolute pressure. This value is negative when the input pressure absolute/gage selector (InputPressureUnit) is Gage, so that flow-condition absolute pressure. This value is negative absolute. Pressure alarm low limit	RW	Y	Y	Y Y		-	-	uint8	-	Live (1) Fixed (2)	0	0	3
40425 424 AtmosphericPress	Specifies whether the input pressure is "Absolute" or "Cage". If the input pressure is gage, then the absolute pressure is calculated as the sum of the input gage pressure and the atmospheric pressure (Atmospheric/Press). When writing the flow-condition absolute pressure values via the ISO 17089 Modbus register then the input pressure unit has no effect and value is always considered as absolute pressure. Atmospheric pressure (Specifies the atmospheric pressure atmospheric pressure atmospheric pressure. This value is required when the input pressure absolute/gage selector (InputPressureUnit) is Gage, so that flow-condition absolute pressure (AbsFlowPressure) can be calculated. Pressure alarm low limit		Y	Y	Y									
	Specifies the atmospheric pressure. This value is required when the input pressure absolute/gage selector (InputPressureUnit) is Gage, so that flow-condition absolute pressure (AbsFlowPressure) can be calculated. Pressure alarm low limit	RW				float	-	-	boolean	-	Gage (FALSE) Absolute (TRUE)	TRUE (1)	FALSE (0)	TRUE (1)
40427 426 LowPressureAlarm			Y	Y	Y	float	MPa	psi	float32	MPa		0.101325	0.03	0.1084
	Pressure alarm low limit. The pressure is invalid (PressureValidity) when the input flow pressure (SpecFlowPressure, LiveFlowPressure) is at or below this limit.	RW	Y	Y	Y	float	MPa	psi	float32	MPa		0.001	0	280
40433 432 HighPressureAlarm	Pressure alarm high limit. Pressure alarm high limit. The pressure is invalid (PressureValidity) when the input flow pressure (SpecFlowPressure, LiveFlowPressure) is at or above this limit.	RW	Y	Y	Y	float	MPa	psi	float32	MPa		8.3	0	280
40435 434 MinInputPressure	Live flow pressure value corresponding to 4 mA input signal Specifies the input flow pressure value that corresponds to the minimum (4 mA) input signal.	RW	Y	Y	Y	float	MPa	psi	float32	MPa		0	0	280
40437 436 MaxInputPressure	Live flow pressure value corresponding to 20 mA input signal Specifies the input flow pressure value that corresponds to the maximum (20 mA) input signal.	RW	Y	Y	Y	float	MPa	psi	float32	MPa		100	0	280
40439 438 Reserved 40441 440 EnableTemperatureIr		R				float float								
	Selects the flow-condition temperature input. When set to "Lve", the flow-condition temperature is read from an analog input signal. When set to "Fixed", the flow-condition temperature is specified (tixed) via the SpeciFlowTemperature data point. When set to "Transmitter Head 1°, the flow-condition temperature is read from Transmitter Head 1 of a Dual-Configuration meter (ColocMeterIPAddress). The flow- condition temperature input selector can be "Transmitter Head 1 of a Dual-Configuration meter (ColocMeterIPAddress). The flow- condition temperature input selector can be "Transmitter Head 1 on your Transmitter Head 2 (ColocMeterIPAddress). The flow- condition temperature is used for temperature-expansion correction (if enabled). This value cannot be set to "None" if temperature					hour			uint8		None (0) Live (1) Fixed (2) Transmitter Head 1 (3)	0	0	3
40443 442 LowTemperatureAlar	expansion correction (EnableExpCorrTemp) is enabled. Temperature alarm low limit Temperature alarm low limit. The temperature is invalid (TemperatureValidity) when the input flow temperature is at or below this limit.	RW	Y	Y	Y	float	deg C	deg F	float32	к		233.15	60.15	473.15
40449 448 HighTemperatureAla	Temperature alarm high limit. Temperature alarm high limit. The temperature is invalid (TemperatureValidity) when the input flow temperature is at or above this limit.	RW	Y	Y	Y	float	deg C	deg F	float32	К		473.15	60.15	523.15
40451 450 MinInputTemperature	Live temperature value corresponding to 4 mA input signal Specifies the input flow temperature value that corresponds to the minimum (4 mA) input signal.	RW	Y	Y	Y	float	deg C	deg F	float32	к		233.15	0	473.15
40453 452 MaxInputTemperatur	Live temperature value corresponding to 20 mA input signal Specifies the input flow temperature value that corresponds to the maximum (20 mA) input signal.	RW	Y	Y	Y	float	deg C	deg F	float32	к		473.15	0	523.15
40455 454 FlowPOrTSrcUponAl		RW	Y	Y	Y	float	-	-	uint8	-	Use last good value (0) Use fixed value (1)	0	0	1
40461 460 EnableExpCorrPress	Enable pressure expansion correction Enables volumetric flow rate pressure expansion correction when set to TRUE (1). This requires the flow-condition pressure to be "Fixed" or "Live" or "Transmitter Head 1" (EnablePressureInput and SpecFlowPressure) and the pipe outside diameter (PipeOutsideDiameter), Young's Modulus (YoungsModulus) and Poisson's Ratio (PoissonsRatio) to be specified.	RW	Y	Y	Y	float	-	-	boolean	-	Disabled (FALSE) Enabled (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
40463 462 PipeOutsideDiameter	Pipe outside diameter Pipe outside diameter. This is used to calculate the pressure expansion correction factor (when the correction is enabled via the enable pressure expansion correction (EnableExpCorrPress)).	RW	Y	Y	Y	float	m	ft	float32	m		2	0	3
40465 464 YoungsModulus	Young's Modulus value (tensile stress to tensile strain ratio) Young's Modulus value (tensile stress to tensile strain ratio). This is used to calculate the strain per unit stress (StrainPerUnitStress) when expansion correction (EnableExpCorrPress) is enabled.	RW	Y	Y	Y	float	MPa	psi	float32	MPa		202000	137895	310264
40467 466 PoissonsRatio	Poisson's Ratio value (absolute ratio of lateral strain to axial strain) Poisson's Ratio value (absolute ratio of lateral strain to axial strain). This is used to calculate the strain per unit stress (StrainPerUnitStress) when expansion correction (EnableExpCorrPress) is enabled.	RW	Y	Y	Y	float	-	-	float32	-		0.3	0.2	0.4
40469 468 EnableExpCorrTemp	Enable temperature expansion correction Enables volumetric flow rate temperature expansion correction when set to TRUE (1). This requires the flow-condition temperature to be "Fixed" or "Live" or "Transmitter Head 1" (EnableTemperatureInput and SpecFlowTemperature) and the pipe material linear expansion coefficient with reference temperature (LinearExpansionCoef and RefTempLinearExpCoef) to be specified.	RW	Y	Y	Y	float	-	-	boolean	-	Disabled (FALSE) Enabled (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
40471 470 LinearExpansionCoe	Linear expansion coefficient Linear expansion coefficient. This is used to calculate the temperature expansion correction factor (when the correction is enabled via the enable temperature expansion correction (EnableExpCorrTemp)).	RW	Y	Y	Y	float	1/deg C	1/deg F	float32	1/K		0.0000115	0.00001	0.000018
40473 472 RefTempLinearExpC	Reference temperature for linear expansion. This is used to calculate the temperature expansion correction factor (when the correction is enabled via the enable temperature expansion correction (EnableExpCorrTemp)).	RW	Y	Y	Y	float	deg C	deg F	float32	к		293.15	60.15	473.15
40475 474 AO1MinVel	Analog Output 1 velocity corresponding to the minimum current (4 mA) Specifies the Analog Output 1 velocity corresponding to the minimum current (4 mA) when the Analog Output 1 (AO1Content) is set to average flow velocity (AvgFlow) or average speed of sound (AvgSndVe).	RW	Y	Y	Y	float	m/s	ft/s	float32	m/s		0	0	3000

Rosemour	ıt™ Liqui	d Ultrasonic Firmware: 1.61	1 Database: 2.29.017													
The below	Modbus	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
40477	476	AO1MaxVel	Analog Output 1 velocity corresponding to the maximum current (20 mA) Specifies the Analog Output 1 velocity corresponding to the maximum current (20 mA) when the Analog Output 1 (AO1Content) is set to average flow velocity (AvgFlow) or average speed of sound (AvgSndVe)).	RW	Y	Y	Y	float	m/s	ft/s	float32	m/s		50	0	3000
40479	478	AO2MinVel	Analog Output 2 velocity corresponding to the minimum current (4 mA) Specifies the Analog Output 2 velocity corresponding to the minimum current (4 mA) when the AO2Content data point is set to Average flow velocity (AvgFlow) or Average speed of sound (AvgSndVe).	RW	Y	Y	Y	float	m/s	ft/s	float32	m/s		0	0	3000
40481	480	AO2MaxVel	Analog Output 2 velocity corresponding to the maximum current (20 mA) Specifies the Analog Output 2 velocity corresponding to the maximum current (20 mA) when the Analog Output 2 (AO2Content) is set to average flow velocity (AvgFlow) or average speed of sound (AvgSndVel).	RW	Y	Y	Y	float	m/s	ft/s	float32	m/s		50	0	3000
40503		IsWarmStartReq	Meter warm start (restart) required The meter configuration has changed and requires a restart for the change to take effect. Recommended Actions: 1. If you are unaware of changes made to the meter's configuration, collect the Audit log using Archive Logs in MeterLink [™] to review the configuration changes. If the changes are valid, momentarily remove power from the meter to allow it to restart which will clear this alarm. 2. If the Audit log shows no changes, contact your local area Emerson Flow service representative for assistance.	R				int	-	-	boolean	-	No warm start required (FALSE) Warm start required (TRUE)			
40507	506	LiveFlowPressureCalCtrl	Selects the value to use when calibrating the live pressure input source This turns the live pressure input calibration mode on or off. This point also specifies which pressure value to use when calibrating (FlowFressureWhileCail) by either choosing the source to be the last live input value prior to entering the calibration mode (freezing) or using a specified (fixed) flow-condition pressure (SpecFlowFressure). When the pressure value source is selected, the meter remains in the calibration mode for a period of time set by non-normal operation timeout (NonNormalModeTimeout) unless the mode is explicitly exited by setting this point to Off (0).					float	-	-	uint8	-	Off (0) Cal - Freeze input (1) Cal - Use fixed (2)	0	0	2
40509	508	LiveFlowPressureOffset	Live flow-condition pressure calibration offset value. Live flow-condition pressure calibration offset value. The calibrated live pressure is calculated by multiplying the raw live pressure sample by the live flow-condition pressure calibration gain value (LiveFlowPressureGain) and then adding this offset.	RW	Y	Y	Y	float	MPa	psi	float32	MPa		0	-280	280
40511	510	LiveFlowPressureGain	Live flow-condition pressure calibration gain value. Live flow-condition pressure calibration gain value. The calibrated live pressure is calculated by multiplying the raw live pressure sample by this gain and then adding the live flow-condition pressure calibration offset value (LiveFlowPressureOffset).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
40513	512	LiveFlowTemperatureCalCtrl	Selects the value to use when calibrating the live temperature input source This turns the live temperature input calibration mode on or off. This point also specifies which temperature value to use when calibrating (FlowTemperatureVhileCa) by either choosing the source to be the last live input value prior to entering the calibration mode (freezing) or using a specified (fixed) flow-condition temperature (SpecFlowTemperature). When the temperature value source is selected, the meter remains in the calibration mode for a period of time set by non-normal operation timeout (NonNormalModeTimeout) unless the mode is explicitly exited by setting this point to Off (0).	RW				float	-	-	uint8	-	Off (0) Cal - Freeze input (1) Cal - Use fixed (2)	0	0	2
40515		LiveFlowTemperatureOffset	Live flow-condition temperature calibration offset value Live flow-condition temperature calibration offset value. The calibrated live temperature is calculated by multiplying the raw live temperature by the live flow-condition temperature calibration gain value (LiveFlowTemperatureGain) and then adding this offset. This value is applied to the temperature in Kelvin. Due to temperature conversion factors, use the MeterLink TM to set this parameter. MODIFYING THIS POINT VIA MODBUS IS NOT RECOMMENDED.		Y	Y	Y	float	deg C	deg F	float32	к		0	-273.15	473.15
40517	516	LiveFlowTemperatureGain	Live flow-condition temperature calibration gain value Live flow-condition temperature calibration gain value. The calibrated live temperature is calculated by multiplying the raw live temperature by this gain and then adding the live flow-condition temperature calibration offset value (LiveFlowTemperatureOffset).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
40601	600	StackSize	Stack size This indicates the number of transducer firings to be point-by-point averaged to generate a signal for a single transit time measurement. A value of 1 This indicates no stacking. When stacking is used, the batch period can differ from the user-specified value (SpecBatchUpdtPeriod). Stacking is primarily used to reduce random (white) noise on the received signal.	RW	Y	Y		int	-	-	uint8	-	None (1) 2 (2) 4 (4) 8 (8) 16 (16)	1	1	16
40602	601	Filter	Bandpass filter switch. Bandpass filter switch. When set to TRUE (1) the bandpass filter is used on the received transducer signal to remove unwanted frequencies.	RW	Y	Y	Y	int	-	-	boolean	-	Filter off (FALSE) Filter on (TRUE)	TRUE (1)	FALSE (0)	TRUE (1)
40603	602	VelHold	Number of batches to hold velocity constant when re-acquiring The number of batches the average flow velocity (AvgFlow) is held at the last measured value when meter is in acquisition mode (IsAcqMode).	RW		Y	Y	int	-	-	uint8	-		0	0	255
40604		MinChord	Minimum number of operating chords for valid measurement The minimum number of operating chords for a valid measurement. If the number of operating chords is less than this value, then the too few operating chords (IsTooFewOperChords) status is set. The range of values and default value are dependent upon the meter device number (DeviceNumber).	RW		Ŷ	Y	int	-	-	uint8	-		1	1	4
40605		AlarmDef	Number of consecutive batches before an alarm is set active The number of consecutive batches with active alarm condition before an alarm is set to active. This is used to activate chord A hard failed alarm (IsHardFailedA), chord B hard failed alarm (IsHardFailedB), chord C hard failed alarm (IsHardFailedC), chord D hard failed alarm (IsHardFailedD) and transducer firing synchronization alarm (IsXdcrFiringSyncError).	RW	Y	Y	Y	int	-	-	uint16	-		100	1	1000
40606		PerfStatusSuppressLmt	Chord performance status suppression limit Minimum percentage of chord performance to suppress chordal performance statuses. If the chord performance (PctGoodA_PctGoodD) is above this limit then the chordal performance statuses for the chord (DidDItTmChkFailA_DidDItTmChkFailD, IsSig0fbgadA_ISSig0fbgadD, DidExeedMaxNoseD, ISSIN8T fooLowA_ISSNRT fooLowA, DidTmDecKhFailA_DidTmDecKhFailD, ISSigDIstontedA_ISSigDistontedD, IsSig0FacA, IsSigClippedA_ISSigClippedD and IsStackingIncompleteA.IsStackingIncompleteD) are suppressed. This limit cannot be set less than or equal to percentage good threshold (MinPctGood).	RW	Y	Y		int	%	%	uint8	%		95	0	100
40607		MinPctGood	Minimum percentage of good measurements for working chord The minimum percentage of good measurements for a working chord. A chord with a percentage of good measurements less than this threshold is considered failed and its corresponding IsFailedForBatchA, IsFailedForBatchC, I	RW	Y	Y	Y	int	%	%	uint8	%		65	0	90
40608	607	SpecBatchUpdtPeriod	Specified batch update period (may be overridden if stacking is selected) Specifies the minimum batch update period when there is no stacking (StackSize).	RW	Y	Y	Y	int	ms	ms	uint16	ms	Standard - 1000 ms (1000) Rapid - 250 ms (250)	1000	250	1000

Rosemour	nt™ Liqu	id Ultrasonic Firmware: 1.61	Database: 2.29.017													
The below	Modbus	s map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
40609	608	BatchPercentSmoothing	Batch smoothing factor: specifies percentage total data to be taken from previous data Batch smoothing factor: This is used to "smooth" the velocity measurement by averaging "new" and "old" data. This specifies the percentage of a batch's total data to be taken from previous batch period(s). When set to zero, then only new data will be used for a batch update. For example, if the batch smoothing factor is set to 20% and there are 32 new data sequences (BatchNewSeq), then 8 sequences from the most recent batch(es) (BatchOldSeq) will also be used for the current batch (8=20% of (32+8)).	RW	Y	Y		int	%	Unit %	uint8	%	0 (0) 20 (20) 40 (40) 60 (60) 80 (80)	0	0	80
40610	609	PropUpdtBatches	Number of consecutive batches without chord failures required for updating chord proportions Number of consecutive batches without chord failures required for updating chord proportions. It is computed from the time that must elapse without chord failures required for updating chord proportions (PropUpdtSeconds) divided by the batch update period (BatchUpdatePeriod).	R	Y			int	-	-	uint16	-				
40611	610	NumVals	Chord proportion update factor. Chord proportion update factor. This controls how quickly the chord proportions change relative to the current velocity proportion values. The lower the factor, the more quickly the proportions change.	RW	Y	Y	Y	int	-	-	uint16	-		10	1	1000
40612	611	Pk1Thrsh	First peak amplitude threshold The minimum amplitude of first peak of the signal required for it to be used.	RW	Y	Y	Y	int	-	-	uint8	-		30	0	255
40613	612	TspfMatch	Track parameter auto reset threshold: 0=always reset, 100=disable auto reset When the differences between the magnitudes of the computed upstream and downstream TSPF to exceed this percentage, they are reset to the default tracking target PI distance (TSpI). When the differences between signal tracking targets (TspIA1.TspID2) and target TspI (TspI) value exceeds this percentage, then the tracking targets are reset to the default tracking target PI distance (TspI). A value of 100 forces the calculated values to never reset to the defaults. A value of zero forces them to remain at the defaults.	RW	Y	Y	Y	int	%	%	uint8	%		30	0	100
40614	613	SNRatio	Minimum signal-to-noise threshold The minimum signal-to-noise threshold. Conversion of this value to dechels is 10 * log10 (SNRatio). If the ratio of the signal energy to the noise energy is below this threshold, then the measurement is discarded. Discarded measurement data may cause a chord to be considered failed if the percentage of good measurements fails below the minimum percentage good threshold (MinPctGood). If, in a batch, a chord has at least one signal discarded due to too low SNR, the chord's signal-to-noise low alarm, IsSNRTooLowA, IsSNRTooLowB, IsSNRTooLowC, IsSNRTooLowD, is set to TRUE (1).	RW	Y	Y	Y	int	-	-	uint8	-		30	5	255
40615		FireSeq	Transducer fining sequence selector The order in which the transducers fire. The meter fires at the fastest possible rate only when each chord's upstream/downstream transducers are not fired successively.	RW	Y	Y	Y	int	-	-	uint8	-	A1-B1-C1-D1-A2-B2-C2-D2 (2)	2	2	2
40616		BatchSize	Sequences between gain/hold time/tracking updates Number of completed firing sequences between updating the signal gain, hold time and tracking values. The default value is 20 firing sequences (minimum is 5 and maximum is 120).	RW	Y	Y	Y	int	-	-	uint8	-		20	5	120
40617		MaxNoDataBatches	Maximum number of consecutive batches without new data Maximum number of consecutive batches without new data before no data received by batch System log is generated. This can be caused if the Acquisition Module is disconnected or not communicating with the CPU Module (IsAcqModuleError).	RW	Y	Y	Y	int	-	-	uint8	-		20	1	255
40618		FlowDir	Meter installed backwards control The meter installed backwards control used in setting the current flow direction indicator (FlowDirection). Set the meter installed backwards control to TRUE (1) if the meter is installed backwards from the normal (forward) flow direction.	RW	Y	Y	Y	int	-	-	boolean	-	Meter in normal direction (FALSE) Meter in reverse direction (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
40619		ChordInactvA	Chord A inactive control Chord A inactive control. When TRUE (1), Chord A is set to inactive and IsBatchinactiveA is set to TRUE (1). The chord's transducers are not fired. When made active (TRUE (1) to FALSE (0) transition) the meter will re-acquire.	RW	Y	Y	Y	int	-		boolean		Chord active (FALSE) Chord inactive (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
40620		ChordInactvB	Chord B inactive control Chord B inactive control When TRUE (1), Chord B is set to inactive and IsBatchInactiveB is set to TRUE (1). The chord's transducers are not fired. When made active (TRUE (1) to FALSE (0) transition) the meter will re-acquire.	RW	Y	Y	Y	int	-	-	boolean	-	Chord active (FALSE) Chord inactive (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
40621		ChordInactvC	Chord C inactive control Chord C inactive control When TRUE (1), Chord C is set to inactive and IsBatchInactiveC is set to TRUE (1). The chord's transducers are not fired. When made active (TRUE (1) to FALSE (0) transition) the meter will re-acquire.	RW	Y	Y	Y	int	-	-	boolean	-	Chord active (FALSE) Chord inactive (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
40622		ChordInactvD	Chord D inactive control Chord D inactive control When TRUE (1), Chord D is set to inactive and IsBatchInactiveD is set to TRUE (1). The chord's transducers are not fired. When made active (TRUE (1) to FALSE (0) transition) the meter will re-acquire.	RW	Y	Y	Y	int	-	-	boolean	-	Chord active (FALSE) Chord inactive (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
40623	622	DltChkSl	Maximum delta time check in sample intervals The maximum amount of time, in sample interval, allowed for delta times (the difference between the up stream and down stream signal transit time). Usually adjusted by setting the transducer type (SetXdcrType). When a chord's delta check value exceeds this limit, the chord's time check error status, DidDitTmChkFailA, DidDitTmChkFailB, DidDitTmChkFailC, DidDitTmChkFailD is set to TRUE (1).	RW	Y	Y	Y	int	sample intervals	sample intervals	uint16	sample intervals		7	4	320
40624	623	NegSpanSl	Minimum negative pulse width in sample intervals The minimum time, in sample interval, the signal must remain negative adjacent to a zero crossing. Usually adjusted by setting the transducer type (SetXdcrType). This parameter is used to detect distorted waveforms and incorrect measurements. This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	int	sample intervals	sample intervals	uint16	sample intervals		3	1	100
40625	624	PosSpanSl	Minimum positive pulse width in sample intervals The minimum time, in sample interval, the signal must remain positive adjacent to a zero crossing. Usually adjusted by setting the transducer type (SetXdcrType). This parameter is used to detect distorted waveforms and incorrect measurements. This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	int	sample intervals	sample intervals	uint16	sample intervals		4	1	100
40626	625	PkPlsWdthSI	Maximum selected peak pulse width in sample intervals Maximum selected peak pulse width in sample interval units. This value is converted internally to usec units (Pk1Wdth). Usually adjusted by setting the transducer type (SetXdcrType). This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	int	sample intervals	sample intervals	uint16	sample intervals		7	1	100
40627		TmDevLow1SI	Transit time standard deviation threshold for measurement quality check in sample intervals The minimum standard deviation value of the transit time in sample interval. It is converted to usec units (TmDevLow1) internally for use by the meter. Usually adjusted by setting the transducer type (SetXdcrType). This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW		Y	Y	int	sample intervals	sample intervals	uint16	sample intervals		2	0	100
40628		TmDevFctr1	Measurement Quality check deviation factor Measurement Quality check transit time standard deviation factor. When a path's transit time is more than this number of standard deviations from the path's median transit time for the batch, the individual measurement is flagged as bad and the corresponding chord's DidTmDevChkFailA, DidTmDevChkFailB, DidTmDevChkFailC and DidTmDevChkFailD are set to TRUE (1). This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW		Y	Ŷ	int	-	-	float32	-		2	1	100
40629		DitherEnable	Enables dithering (progressive jitter after each transducer fring). Turns dithering on when set to TRUE (1) which minutely alters the firing time to prevent problems associated with resonance from building up.	RW	Y	Y	Y	int	-	-	uint8	-	Disable (0) Enable (1)	1	0	1
40630		AsyncEnable	Enables asynchronous firing sequences (progressive jitter after each firing sequence) Enables asynchronous firing sequences (progressive jitter after each firing sequence).	RW	Y		Y	int	-	-	uint8	-	Disable (0) Enable (1)	0	0	1
40631	630	DampEnable	Enables firing transducer dampening Enables firing transducer dampening.	RW	Y		Y	int	-	-	uint8	-	Disable (0) Enable (1)	0	0	1

Rosemou	nt™ Liqu	id Ultrasonic Firmware: 1.61	Database: 2.29.017													
The below	Modbus	s map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
40651	650	2 ZeroCut	Flow velocity below which the flow rate is considered zero This value is used along with the pipe area (PipeArea) to compute the volumetric flow cutoff (QCutOff) below which the flow-condition volumetric flow rate (QFow) is considered zero, chord turbulence values are not calculated (TurbulenceA, TurbulenceD) and "flow gated" (FLOW_GATED) values are not accumulated. Also, when the average weighted flow velocity (AvgWtdFlowVel) is below this threshold the flow direction (FlowDirection) will not change. The flow analysis lower limit (FlowAnalysisLowFlowLmt) may not be set lower than this value.	RW	Y	Y	Y	float	m/s	Unit ft/s	float32	m/s		0.1	0	1
40653	652	SSMin	Minimum speed of sound Minimum speed of sound. This is used to define the area to search for a signal when in acquisition mode and is also used in emission rate determination. This minimum and the maximum speed of sound (SSMax) may need to be adjusted to prevent problems acquiring the signal.	RW	Y	Y	Y	float	m/s	ft/s	float32	m/s		350	350	3000
40655	654	SSMax	Maximum speed of sound Maximum speed of sound. This is used to define the area to search for a signal when in Acquisition mode. The minimum (SSMin) and this maximum speed of sound may need to be adjusted to prevent problems acquiring the signal.	RW	Y	Y	Y	float	m/s	ft/s	float32	m/s		1600	350	3000
40657	656	AvgSoundVelLoLmt	Speed of sound lo-alarm limit The low limit for the average speed of sound range error (IsAvgSoundVelRangeErr) alarm. It is used strictly for alarming purposes and does not impact any other meter functionality. This is different from the minimum acquisition mode speed of sound (SSMin).	RW	Y	Y	Y	float	m/s	ft/s	float32	m/s		1000	0	3000
40659	658	AvgSoundVelHiLmt	Speed of sound hi-alarm limit. The high limit for the average speed of sound range error (IsAvgSoundVelRangeErr) alarm. It is used strictly for alarming purposes and does not impact any other meter functionality. This is different from the maximum acquisition mode speed of sound (SSMax).	RW	Y	Y	Y	float	m/s	ft/s	float32	m/s		2000	0	3000
40661		SndSpdChkMinVel	Minimum flow velocity for CRange test Minimum flow velocity for performing the inter-chord speed of sound check (CRange) and calculating speed of sound path spread (SpdSndSpread).	RW	Y	Y	Y	float	m/s	ft/s	float32	m/s		1	0.1	50
40663	662	SndSpdChkMaxVel	Maximum flow velocity for CRange test Maximum flow velocity for performing the inter-chord speed of sound check (CRange) and calculating speed of sound path spread (SpdSndSpread).	RW	Y	Y	Y	float	m/s	ft/s	float32	m/s		15	1	50
40665	664	CRange	Maximum percentage chord speed of sound deviation Maximum percentage chord speed of sound deviation. If a chord's speed of sound measurement relative to the average speed of sound is above this threshold, IsMeasSndSpdRangeA, IsMeasSndSpdRangeB, IsMeasSndSpdRangeC, IsMeasSndSpdRangeD, is set to TRUE (1).	RW	Y	Y	Y	float	%	%	float32	%		0.25	0	10
40667	666	MeterMaxVel	Maximum meter velocity The maximum for the meter's average flow velocity (AvgFlow). This limit is used to generate an alarm meter velocity above maximum limit (IsMeterVelAboveMaxt.mt), when the average flow velocity magnitude is above this limit. Note, however, that this limit does not affect the meter's measurement.	RW	Y	Y	Y	float	m/s	ft/s	float32	m/s		15	1	50
40669	668	LowFlowLmt	Minimum velocity for updating chord proportions Minimum velocity for updating chord proportions. Chord proportions are not updated when the flow velocity is below this value.	RW	Y	Y	Y	float	m/s	ft/s	uint8	m/s		1	1	30
40673		? GainLowLmt	Minimum gain limit The minimum gain applied to the received signal. On power-up, this value is set to the minimum gain for the Acquisition Module (DSPBdRevNum).	RW	Y			float	gain (dB)	gain (dB)	float32	gain (h/w)		8.72101	0	3.40E+38
40675		GainHighLmt	Maximum gain limit The maximum gain applied to the received signal. On power-up, this value is set to the maximum gain for the Acquisition Module (DSPBdRevNum).	RW	Y			float	gain (dB)	gain (dB)	float32	gain (h/w)		17400.5	0	3.40E+38
40677		MinHoldTime	Minimum sampling hold time The minimum sampling hold time limit. This is the minimum amount of time the meter waits after firing a transducer before sampling the receiving transducer's signal. This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	float	us	us	float32	us		32	32	32000
40679	678	MaxHoldTm	Maximum sampling hold time The maximum sampling hold time limit. This is the maximum amount of time the meter waits after firing a transducer before sampling the receiving transducer's signal. This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	float	us	us	float32	us		3600	16	32000
40681	680	MaxNoise	Maximum noise energy threshold Maximum noise energy threshold. If the signal's noise energy is above this threshold, the signal for that transducer firing is discarded. If a chord has at least one signal for a batch discarded due to too large noise energy, the chord's max noise alarm, DidExceedMaxNoiseA, DidExceedMaxNoiseB, DidExceedMaxNoiseC, DidExceedMaxNoiseD is set to TRUE (1).	RW	Y	Y	Y	float	energy	energy	uint32	energy		195	24	391
40683	682	Pk1Pct	Parameter used to locate the signal start The percentage of the maximum signal amplitude used as a threshold to find the first peak which is then used to determine the starting position of the sampled waveform. If conditions exist that make the start of the signal difficult to detect (peak switching) this level may be adjusted to get a stable signal.	RW	Y	Y	Y	float	%	%	uint8	%		60	40	100
40685	684	MinSigQlty	Minimum acceptable signal quality The minimum acceptable signal quality based on signal and noise energies. When either path in a chord's signal quality (as measured by signal to noise ratios) is below inis threshold, the chord's signal quality status, IsSigQItyBadA, IsSigQItyBadB, IsSigQItyBadC, IsSigQItyBadD is set to TRUE (1).	RW	Y	Y	Y	float	-	-	uint8	-		25	5	30
40751	750	TspfLo	Tracking target Pf distance low limit The lower limit or floor for the default (Tspf) and the individual path (TspfA1, TspfA2, TspfB1, TspfB2, TspfC1, TspfC2, TspfD1, TspfD2) computed values. Usually adjusted by setting the transducer type (SetXdcrType). This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	float	sample intervals	sample intervals	uint8	sample intervals		8	0	37
40753	752	? TspeLo	Tracking target Pe distance low limit The lower limit or floor for the default (Tspe) and the individual path (TspeA1, TspeA2, TspeB1, TspeB2, TspeC1, TspeC2, TspeD1, TspeD2) computed values. This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	float	sample intervals	sample intervals	int8	sample intervals		-8	-25	25
40755	754	TampLo	Tracking target normalized amplitude low limit The lower limit or floor for the magnitude (absolute value of) the default (Tamp) and the individual path (TampA1, TampA2, TampB1, TampB2, TampC1, TampC2, TampD1, TampD2) computed values. This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	float	%	%	uint8	%		30	0	100
40757	756	Tspf	Default tracking target Pf distance The default for the targeted SPF which is the time in sample intervals (SI) or distance between the first motion (Pf) and the signal the zero crossing detection point (P1). When the meter is first started or when ResetTrkParam is set TRUE (1) this value is used as the initial value used to compute Tsp/A1, Tsp/A2, Tsp/B1, Tsp/B2, Tsp/C2, Tsp/C1, Tsp/C2, Tsp/D1 and Tsp/D2. It is also the value used for inactive paths. Usually adjusted by setting the transducer type (SetXdcType). This value should only be changed at the factory or under the direction of Emerson Flow Support. See also (Tsp/Lo) and (Tsp/Hi).	RW	Y	Y	Y	float	sample intervals	sample intervals	uint8	sample intervals		20	0	37

Rosemou	nt™ Liqu	id Ultrasonic Firmware: 1.6	1 Database: 2.29.017													
The below	Modbus	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
40759	758	Tspe	Default tracking target Pe distance The default for the targeted SPE which is the time in sample intervals (SI) or distance between the first energy position (Pe) and the signal the zero crossing detection point (P1). When the meter is first started or when ResetTrkParam is set TRUE (1) his value is used as the initial value used to compute TspeA1, TspeA2, TspeB1, TspeB2, TspeC1, TspeC2, TspeD1, TspeD2. It is also the value used for inactive paths. Usually adjusted by setting the transducer type (SetXdcType). This value should only be changed at the factory or under the direction of Emerson Flow Support. See also (TspeA), and (TspeH).	RW	Y	Y	Y	float	sample intervals	sample intervals	int8	sample intervals		8	-25	25
40761	760	Tamp	Default tracking target normalized amplitude The default for the targeted Amp which is the value of the peak following the zero crossing detection point (P1). When the meter is first started or when ResetTrkParent is set TRUE (1) this value is used as the initial value used to compute TampA1, TampA2, TampB1, TampB2, TampC1, TampC2, TampD1, TampD2. It is also the value used for inactive paths. Usually adjusted by setting the transducer type (SetXdcType). This value should only be changed at the factory or under the direction of Ernerson Flow Support. See also (TampLo) and (TampH3).	RW	Y	Y	Y	float	%	%	int8	%		-70	-100	100
40763	762	TspfSen	Tracking target Pf sensitivity The sensitivity applied to the comparison of the individual peaks SPF to the paths targeted SPF, TspIA1, TspIA2, TspIB1, TspIB2, TspIC1, TspIC2, TspID2, TspID2. The sensitivity is used to generate similar magnitudes to the SPE and Amp comparisons used to score peaks in the process of selecting P1. This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	float	sample intervals	sample intervals	uint8	sample intervals		10	6	37
40765	764	TspeSen	Tracking target Pe sensitivity The sensitivity applied to the comparison of the individual peaks SPE to the paths targeted SPE, TspeA1, TspeA2, TspeB1, TspeB2, TspeC1, TspeC2, TspeD1, TspeD2. The sensitivity is used to generate similar magnitudes to the SPF and Amp comparisons used to score peaks in the process of selecting P1. This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	float	sample intervals	sample intervals	uint8	sample intervals		18	6	37
40767	766	TampSen	Tracking target normalized amplitude sensitivity The sensitivity applied to the comparison of the individual peaks Amp to the paths targeted Amp, TampA1, TampA2, TampB1, TampB2, TampC1, TampC2, TampD1. The sensitivity is used to generate similar magnitudes to the SPE and SPF comparisons used to score peaks in the process of selecting P1. This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	float	%	%	uint8	%		30	5	100
40769	768	TspfWt	Tracking target Pf weighting factor The weighting applied to the score generated by TspfSen when summed with TspeWt * TspeSen score and TampWt * TampSen score to generate an overall rating to select P1. This value should only be changed at the factory or under the direction of Emerson Flow Support	RW	Y	Y	Y	float	-	-	float32	-		2	0	3
40771	770	TspeWt	Tracking target Pe weighting factor The weighting applied to the score generated by TspeSen when summed with TspfWt * TspfSen score and TampWt * TampSen score to generate an overall rating to select P1. This value should only be changed at the factory or under the direction of Emerson Flow Support	RW	Y	Y	Y	float	-	-	float32	-		0	0	3
40773	772	TampWt	Tracking target normalized amplitude weighting factor The weighting applied to the score generated by TampSen when summed with TspeWt * TspeSen score and TspfWt * TspfSen score to generate an overall rating to select P1. This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	float	-	-	float32	-		0.5	0	3
40775	774	TspfHi	Tracking target Pf distance high limit The upper limit or ceiling for the default (Tspf) and the individual path (TspfA1, TspfA2, TspfB1, TspfB2, TspfC1, TspfC2, TspfD1, TspfD2) computed values. Usually adjusted by setting the transducer type (SetXdcrType). This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	float	sample intervals	sample intervals	uint8	sample intervals		25	0	37
40777	776	TspeHi	Tracking target Pe distance high limit The upper limit or ceiling for the default (Tspe) and the individual path (TspeA1, TspeA2, TspeB1, TspeB2, TspeC1, TspeC2, TspeD1, TspeD2) computed values. This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	float	sample intervals	sample intervals	int8	sample intervals		20	-25	25
40779	778	TampHi	Tracking target normalized amplitude high limit The upper limit or ceiling for the magnitude (absolute value of) the default (Tamp) and the individual path (TampA1, TampA2, TampB1, TampB2, TampC1, TampC2, TampD1) computed values. This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	float	%	%	uint8	%		100	0	100
40781		TspeLmt	Tracking target abs(Pe-P) limit The Tspf and Tspe calculations are not performed if the distance (in SI) between Pe and Pf exceed this amount. This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW		Y	Y	float	sample intervals	sample intervals	uint16	sample intervals		25	0	30
40801	800	EmRateDesired	Desired transducer firing (emission) rate The desired emission rate or time between the firing of two transducers in sequence based on the firing order (FireSeq). The actual emission rate used (EmRateActual) will not be less than the meter's calculated minimum based on the meter's geometry (ope diameter (PipeDiam), distance between transducers (LA, LB, LC, LD), axial distance between transducers (XA, XB, XC, XO), the minimum speed o sound (SSMin) and the physical characteristics of the transducers themselves. The actual emission rate used may also be impacted by stacking (StackEmRateActual). A value of (0) ensures the use of fastest available rate determined by the meter.	RW	Y	Ŷ	Ŷ	float	ms	ms	float32	ms		0	0	64
40803	802	StackEmRateDesired	Desired stacking transducer firing (emission) rate The desired emission rate or time between firing of the same transducer when stacking is turned on, that is the stack size (StackSize) is not equal to (1). The actual emission rate used (StackErnRateActua) will not be less than the meter's calculated minimum based on the meter's geometry (bpe diameter (PipeDiam)), distance between transducers (LA, LB, LC, LD), axial distance between transducers (XA, KB, XC, XD), the minimum speed of sound (SSM) and the physical characteristics of the transducers themselves. This value may impact the overall transducer to transducer emission rate selected by the emission rate desired (EmRateDesired). A value of (0) ensures the use of fastest available rate determined by the meter.	RW	Y	Y	Y	float	ms	ms	float32	ms		0	0	64
40805	804	XdcrFreq	Transducer frequency The output frequency of the transducers. Usually adjusted by setting the transducer type (SetXdcrType).	RW	Y	Y	Y	float	KHz	KHz	float32	KHz		1000	430	1000
40807		SampInterval	Sampling (rate) interval. Changing this value requires re-booting the meter The duration in nanoseconds of the signal sampling period. It is also used to compute the system delay (SystemDelay). Usually adjusted by setting the transducer type (RextAcrType).	RW		Y	Y	float	ns	ns	float32	ns		100	100	200
40809		SetXdcrType	Set transducer type Sets the type of transducer installed. Changing this data point will overwrite transducer configuration parameters (XdcrFreq, XdcrNumDrwcCycles, DitChkSI, NegSpanSI, PkPIsWdthSI, PosSpanSI, SampPerCycle, SampInterval, TmDevLow1, Tspf, TspfLo, TspfHi Tspe and Tamp) with default values. Once these transducer configuration values are written, the value of this data point is saved in the transducer type data point (XdcrType), and then set transducer type is set to zero.	RW	Y		Y	float	-	-	uint8	-	Automatically reset by the meter (0) LT-01/LT-03/LT-06/LT-07/LT-08/LT-09/LT-14/LT-15 (1) LT-04 (2) LT-05 (3) LT-10/LT-11/LT-16/LT-17 (4)	0	0	4
40811	810	XdcrNumDriveCycles	Number of cycles for transducer Number of cycles for transducer. Will be overwritten when transducer type (SetXdcrType) changes.	RW	Y	Y	Y	float	-	-	uint8	-		1	1	2
40813	812	SampPerCycle	Samples per cycle The number of times the waveform is sampled between two zero crossings with the same slope (one cycle). Usually adjusted by setting the transducer type (SetXdcrType). This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	float	-	-	uint8	-	8 (8) 10 (10) 12 (12)	10	8	12

Rosemou	nt™ Liqu	id Ultrasonic Firmware: 1.6	Database: 2.29.017													
The below	Modbus	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding			Description							Modbus					Minimum	Maximum
Register Number	Reg Num	Label		Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Value (native unit)	Value (native unit)
40901	900	PipeDiam	Pipe inside diameter The pipe inside diameter used to calculate the pipe area (PipeArea) and port angle (PortAngle).	RW	Y	Y	Y	float	m	ft	float32	m		0.1524	0.0254	2
40903	902	XA	Chord A "X" dimension Chord A "X" dimension (component of LA in the direction of flow within the meter bore). The factory setting should only be changed when changing a transducer or after a meter cold start.	RW	Y	Y	Y	float	m	ft	float32	m		0.1778	0	2
40905	904	XB	Chord B "X" dimension Chord B "X" dimension (component of LB in the direction of flow within the meter bore). The factory setting should only be changed when changing a transducer or after a meter cold start.	RW	Y	Y	Y	float	m	ft	float32	m		0.28575	0	2
40907	906	xc	Chord C 'X' dimension Chord C 'X' dimension (component of LC in the direction of flow within the meter bore). The factory setting should only be changed when changing a transducer or after a meter cold start.	RW	Y	Y	Y	float	m	ft	float32	m		0.28575	0	2
40909	908	XD	Chord D*X* dimension Chord D*X* dimension (component of LD in the direction of flow within the meter bore). The factory setting should only be changed when changing a transducer or after a meter cold start.	RW	Y	Y	Y	float	m	ft	float32	m		0.1778	0	2
40911	910	LA	Chord A length ("L" dimension) The distance between the transducer faces on chord A. The factory setting should only be changed when changing a transducer or after a meter cold start.	RW	Y	Y	Y	float	m	ft	float32	m		0.3175	0	5
40913	912	LB	Chord B length ("L" dimension) The distance between the transducer faces on chord B. The factory setting should only be changed when changing a transducer or after a meter cold start.	RW	Y	Y	Y	float	m	ft	float32	m		0.4445	0	5
40915	914	LC	Chord C length ('L' dimension) The distance between the transducer faces on chord C. The factory setting should only be changed when changing a transducer or after a meter cold start.	RW	Y	Y	Y	float	m	ft	float32	m		0.4445	0	5
40917	916		Chord D length (L [*] dimension) The distance between the transducer faces on chord D. The factory setting should only be changed when changing a transducer or after a meter cold start.	RW	Y	Y	Y	float	m	ft	float32	m		0.3175	0	5
40919	918	AvgDlyA	Chord A average delay time The chord-specific delay for chord A primarily due to the signal processing algorithm and acoustic propagation time within the transducer including the matching layer. It is used in conjunction with the overall system delay (SystemDelay).	RW	Y	Y	Y	float	us	us	float32	us		0	0	50
40921	920	AvgDlyB	Chord B average delay time The chord-specific delay for chord B primarily due to the signal processing algorithm and acoustic propagation time within the transducer including the matching layer. It is used in conjunction with the overall system delay (SystemDelay).	RW	Y	Y	Y	float	us	us	float32	us		0	0	50
40923	922	AvgDlyC	Chord C average delay time The chord-specific delay for chord C primarily due to the signal processing algorithm and acoustic propagation time within the transducer including the matching layer. It is used in conjunction with the overall system delay (SystemDelay).	RW	Y	Y	Y	float	us	us	float32	us		0	0	50
40925	924	AvgDlyD	Chord D average delay time The chord-specific delay for chord D primarity due to the signal processing algorithm and acoustic propagation time within the transducer including the matching layer. It is used in conjunction with the overall system delay (SystemDelay).	RW	Y	Y	Y	float	us	us	float32	us		0	0	50
40927	926	DitDiyA	Chord A difference in upstream and downstream delay times The adjustment to the chord A delta times (the individual times used for DIrTmA (DIrTmA)) to ensure calibration at zero flow.	RW	Y	Y	Y	float	us	us	float32	us		0	-1	1
40929	928	DitDlyB	Chord B difference in upstream and downstream delay times The adjustment to the chord B delta times (the individual times used for DtTmB (DtTmB)) to ensure calibration at zero flow.	RW	Y	Y	Y	float	us	us	float32	us		0	-1	1
40931	930	DitDlyC	Chord C difference in upstream and downstream delay times The adjustment to the chord C delta times (the individual times used for DltTmC (DltTmC)) to ensure calibration at zero flow.	RW	Y	Y	Y	float	us	us	float32	us		0	-1	1
40933	932	DitDlyD	Chord D difference in upstream and downstream delay times The adjustment to the chord D delta times (the individual times used for DltTmD (DltTmD)) to ensure calibration at zero flow.	RW	Y	Y	Y	float	us	us	float32	us		0	-1	1
40935	934	SystemDelay	System delay time The portion of the signal transit time due to the physical characteristics of the electronics. It is computed as seven times the sample interval (Samphinterval) plus an electronics delay constant. It is used in conjunction with the chord specific delay times (AvgDlyA, AvgDlyB, AvgDlyC or AvgDlyD).	R	Y			float	us	us	float32	us				
40951	950	FwdA0	Factory calibration forward flow A0 coefficient The forward flow A0 coefficient used for factory calibration. The factory calibration "A" coefficients are applied to the average weighted flow velocity (AvgWtdrElowVe) to generate the factory calibrated flow velocity (DryCalVeI) when the high viscosity calibration method selector (High/viscosityMethod) is set to "Disabled".	RW	Y	Y	Y	float	m/s	ft/s	float32	m/s		0	-1	1
40953	952	FwdA1	Factory calibration forward flow A1 coefficient The forward flow A1 coefficient used for factory calibration. The factory calibration "A" coefficients are applied to the average weighted flow velocity (AvgWtdFlowVe) to generate the factory calibrated flow velocity (DryCalVe) when the high viscosity calibration method selector (HighViscosityMethod) is set to "Disabled".	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
40955	954	FwdA2	Factory calibration forward flow A2 coefficient The forward flow A2 coefficient used for factory calibration. The factory calibration "A" coefficients are applied to the average weighted flow velocity (AvgWtdFlowVe) to generate the factory calibrated flow velocity (DryCalVe) when the high viscosity calibration method selector (HighViscosit/Method) is set to "Disabled".	RW	Y	Y	Y	float	s/m	sec/ft	float32	s/m		0	-0.1	0.1
40957	956	FwdA3	Factory calibration forward flow A3 coefficient The forward flow A3 coefficient used for factory calibration. The factory calibration "A" coefficients are applied to the average weighted flow velocity (AvgWtdFlowVe) to generate the factory calibrated flow velocity (DryCalVe) when the high viscosity calibration method selector (High/Viscosit/Method) is set to "Disabled".	RW	Y	Y	Y	float	s2/m2	sec2/ft2	float32	s2/m2		0	-0.1	0.1
40959	958	RevA0	Factory calibration reverse flow A0 coefficient The reverse flow A0 coefficient used for factory calibration. The factory calibration "A" coefficients are applied to the average weighted flow velocity (AvgWtdFlowVe) to generate the factory calibrated flow velocity (DryCalVeI) when the high viscosity calibration method selector (HighViscosit/Method) is set to "Disabled".	RW	Y	Y	Y	float	m/s	ft/s	float32	m/s		0	-1	1
40961	960	RevA1	Factory calibration reverse flow A1 coefficient The reverse flow A1 coefficient used for factory calibration. The factory calibration "A" coefficients are applied to the average weighted flow velocity (AvgWtdFlowVe) to generate the factory calibrated flow velocity (DryCalVe) when the high viscosity calibration method selector (High/viscosit/Method) is set to "Disabled".	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
40963	962	RevA2	Factory calibration reverse flow A2 coefficient The reverse flow A2 coefficient used for factory calibration. The factory calibration "A" coefficients are applied to the average weighted flow velocity (AvgWtdFlowVe) to generate the factory calibrated flow velocity (DryCalVeI) when the high viscosity calibration method selector (HighViscosit/Method) is set to "Disabled".	RW	Y	Y	Y	float	s/m	sec/ft	float32	s/m		0	-0.1	0.1

Rosemou	nt™ Liqu	id Ultrasonic Firmware: 1.61	Database: 2.29.017													
The below	Modbus	s map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
40965	964	RevA3	Factory calibration reverse flow A3 coefficient The reverse flow A3 coefficient used for factory calibration. The factory calibration *A* coefficients are applied to the average weighted flow velocity (AvgWtdFlowVe) to generate the factory calibrated flow velocity (DryCalVeI) when the high viscosity calibration method selector (HighViscosityMethod) is set to "Disabled".	RW	Y	Y	Y	float	s2/m2	Unit sec2/ft2	float32	s2/m2		0	-0.1	0.1
40967	966	HARTPercentRange	HART percent range The percent range of the primary variable is calculated every time the primary variable is updated. The calculated value depends on the device variable assigned to the analog output 1 content (AO1Content) and its lower and upper range values.	R	Y			float	%	%	float32	%				
40969	968	HARTPercentRangeAO2	Analog output 2 HART percent range The percent range of the secondary variable is calculated every time the secondary variable is updated. The calculated value depends on the device variable assigned to the analog output 2 content (AO2Content) and its lower and upper range values.	R	Y			float	%	%	float32	%				
41000	999	DI1Mode	Digital Input 1 mode Specifies the Digital Input 1 (D11) operating mode. If Digital Input/Calibration Input is selected, general input or calibration is determined by the Digital Input 1 calibration control flag (IsD11 UsedForCal). I/O board type (IOBdType) 4 and above is required to select Frequency/Digital Output 6.	RW	Y	Y	Y	int	-	-	uint8	-	Digital Input/Calibration Input (0) Frequency/Digital Output 6 (2)	2	0	2
41001	1000	DI1IsInvPolarity	Digital Input 1 polarity control This value sets the polarity of Digital Input 1 (DI1). A TRUE (1) value is normal polarity (default). A FALSE (0) value is inverted polarity.	RW	Y	Y	Y	int	-	-	boolean	-	Normal (FALSE) Inverted (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
41002	1001	lsDI1UsedForCal	Determines digital input 1 functionality Specifies whether digital input 1 (D11) is used for general purpose when set to FALSE (0) or for synchronizing calibration when set to TRUE (1). If used for calibration, the polarity is determined by the IsDI1ForCalActiveLow data point and the gating edge is determined by the IsDI1ForCalStateGated data point.	RW				int	-	-	boolean	-	General purpose (FALSE) Used for calibration (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
41003	1002	IsDI1ForCalActiveLow	Determines digital input 1 polarity for calibration use This point specifies the polarity for digital input 1 (DI1) when it is configured via IsDI1UsedForCal for use in synchronizing a calibration. See also IsDI ForCaliStateGated.	RW	Y	Y		int	-	-	boolean	-	Digital Input 1 calibrate active high (FALSE) Digital Input 1 calibrate active low (TRUE)	TRUE (1)	FALSE (0)	TRUE (1)
41004	1003	IsDI1ForCalStateGated	Determines digital input 1 gating for calibration use This point specifies the calibration gating for digital input 1 (DI1) when it is configured via IsDI1 UsedForCal for use in synchronizing a calibration. When FALSE (0), the calibration is started/stopped via an inactive->active edge; when TRUE (1), the calibration is started/stopped via an inactive->active state change and stopped via an active->inactive state change. The active edge/state is specified via IsDI1 ForCalculvieLow.	RW	Y	Y		int	-	-	boolean	-	Digital Input 1 calibrate edge gated (FALSE) Digital Input 1 calibrate state gated (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
41005	1004	CalFlag	Flow calibration switch: calibration started on FALSE-to-TRUE transition and stopped on TRUE-to-FALSE transition Calibration function switch. When changed from FALSE (0) to TRUE (1), the calibration accumulated uncorrected volume CalVol and calibration elapsed time CalTime data points are reset. While TRUE (1), the flow volume and time are accumulated into the CalVol and CalTime data points.	RW				int	-	-	boolean	-	Stop calibration (FALSE) Start calibration (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
41021	1020	ZeroFlowCalReqControl	Zero-flow calibration requested control Specifies the desired zero-flow calibration action. A zero-flow calibration process must be inactive in order to be started. The "Accept Result and Exit" selection is only valid when the status indicates "Completed Successfully."	RW			Y	int	-	-	uint8	-	Exit/Abort (0) Start (1) Accept result and exit (2)	0	0	2
41022	1021	ZeroFlowCalReqDuration	Zero-flow calibration requested duration Specifies the zero-flow calibration duration.	RW	Y	Y	Y	int	min	min	uint8	min		4	2	10
41023	1022	HARTIsTemperatureGood	HART temperature calculated indicator This is used internally in determining the HART device variable status for the flow temperature (FlowTemperature).	R				int	-	-	boolean	-	Bad (FALSE) Good (TRUE)			
41024	1023	HARTIsPressureGood	HART pressure calculated indicator This is used internally in determining the HART device variable status for the flow pressure (FlowPressure).	R				int	-	-	boolean	-	Bad (FALSE) Good (TRUE)			
41025	1024	HARTConfigChangeCounter	HART configuration change counter HART configuration change counter maintains the count of how many times HART config data points changed. When a block of data comes for write which consists of one or more configuration data points, configuration change counter will increment once.	R	Y			int	-	-	uint16	-				
41026	1025	HARTDidPrimaryConfigCha nge	HART primary master configuration changed. HART primary master configuration changed. It is set to TRUE when configuration writable via HART is modified. It is reset to FALSE when command 38 is issued by primary master and received configuration changed counter matches the device configuration change counter.	R	Y			int	-	-	boolean	-	HART Primary Config Change reset (FALSE) HART Primary Config Change set (TRUE)			
41027	1026	HARTDidSecondaryConfigC hange	HART secondary master configuration changed. HART secondary master configuration changed. It is set to TRUE when configuration writable via HART is modified. It is reset to FALSE when command 38 is issued by secondary master and received configuration changed counter matches the device configuration change counter.	R	Y			int	-	-	boolean	-	HART Secondary Config Change reset (FALSE) HART Secondary Config Change set (TRUE)			
41028	1027	HARTIsMaintenanceReq	HART maintenance required This indicates (to a HART master) whether or not the device requires maintenance.	R				int	-	-	boolean	-	Maintenance not required (FALSE) Maintenance required (TRUE)			
41029	1028	HARTIsDeviceVarAlert	HART device status alert This indicates that, when one or more HART device variables are invalid. The host should identify the device variables causing this to be set using device variable calculated indicator status.	R				int	-	-	boolean	-	Not (FALSE) Yes (TRUE)			
41030	1029	HARTLoopCurrentMode	HART loop current mode It determines whether current signaling is being used by field device. Only HART can disable or enable the loop current mode, loop current is disabled when polling address is set to non-zero (i.e. field device is in multi-drop).	R	Y			int	-	-	uint8	-	Disabled (0) Enabled (1)			
41031	1030	HARTDidPowerFailPrimary	HART primary master power fail status This indicates the power fail status to the primary master. It is set to TRUE when the device is power cycled or reset.	R				int	-	-	boolean	-	Did not fail (FALSE) Did fail (TRUE)			
41032	1031	HARTDidPowerFailSeconda ry		R				int	-	-	boolean	-	Did not fail (FALSE) Did fail (TRUE)			
41051	1050	CalMethod	Customer-calibration method selector Selects whether or not to apply a meter factor for a customer calibration to the measurement.	RW	Y	Y	Y	float	-	-	uint8	-	None (0) Meter factor (3)	3	0	3
41053	1052	FwdMtrFctr	Calibration forward flow meter factor Calibration forward flow meter factor. The meter factor is applied when the customer-calibration method selector (CaliMethod) is set to Meter Factor.	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41055	1054	RevMtrFctr	Calibration reverse flow meter factor Calibration reverse flow meter factor. The meter factor is applied when the customer-calibration method selector (CalMethod) is set to Meter Factor.	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41057	1056	FwdFlwRt1	Piecewise linearization flow rate 1 The first and highest forward flow rate used for piecewise linearization. It is paired with forward meter factor 1 (FwdMtrFctr1) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to zero. Flow rates above this point will simply apply forward meter factor 1 (FwdMtrFctr1) as the linear meter factor (LinearMtrFctr).	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41059	1058	FwdFlwRt2	Piecewise linearization flwd vol flow rate 2 The second forward flow rate used for piecewise linearization. It is paired with forward meter factor 2 (FwdMtrFctr2) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000

Rosemou	nt™ Liqu	id Ultrasonic Firmware: 1.0	61 Database: 2.29.017													
The below	Modbus	map is applicable for Ros	emount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding	Reg	Label	Description			0.1	Devi	Modbus	Modbus	Modbus U.S.	Native Data	Native Data	O shari'ana (D'hana	Default Value	Minimum	Maximum
Register Number	Num	Label		Acc	NV	Cnfg	Prot	Reg Type	Metric Unit	Customary Unit	Туре	Unit	Selections/Bitmap	(native unit)	Value (native unit)	Value (native unit)
41061	1060	FwdFlwRt3	Piecewise linearization fwd vol flow rate 3 The third forward flow rate used for piecewise linearization. It is paired with forward meter factor 3 (FwdMtrFctr3) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr3) based on the dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41063	1062	FwdFlwRt4	Piecewise linearization fwd vol flow rate 4 The fourth forward flow rate used for piecewise linearization. It is paired with forward meter factor 4 (FwdMtrFctr4) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41065		FwdFlwRt5	Piecewise linearization fwd vol flow rate 5 The fifth forward flow rate used for piecewise linearization. It is paired with forward meter factor 5 (FwdMtrFctr5) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41067		FwdFlwRt6	Piccewise linearization fwd vol flow rate 6 The sixth forward flow rate used for piccewise linearization. It is paired with forward meter factor 6 (FwdMtrFctr6) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Ŷ	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41069		FwdFlwRt7	Piccewise linearization fwd vol flow rate 7 The seventh forward flow rate used for piecewise linearization. It is paired with forward meter factor 7 (FwdMtrFctr7) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to zero.	RW		Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41071		FwdFlwRt8	Piecewise linearization fwd vol flow rate 8 The eighth forward flow rate used for piecewise linearization. It is paired with forward meter factor 8 (FwdMtrFctr8) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to zero.			Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41073	1072	FwdFlwRt9	Piecewise linearization fwd vol flow rate 9 The ninh forward flow rate used for piecewise linearization. It is paired with forward meter factor 9 (FwdMtrFctr9) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41075	1074	FwdFlwRt10	Piecewise linearization fwd vol flow rate 10 The tenth forward flow rate used for piecewise linearization. It is paired with forward meter factor 10 (FwdMtrFctr10) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41077	1076	FwdFlwRt11	Piecewise linearization fwd vol flow rate 11 The deventh forward flow rate used for piecewise linearization. It is paired with forward meter factor 11 (FwdMtrFctr11) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) base on the dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41079	1078	FwdFlwRt12	Piecewise linearization fwd vol flow rate 12 The twelith and lowest forward flow rate used for piecewise linearization. It is paired with forward meter factor 12 (FwdMtrFctr12) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41081	1080	FwdMtrFctr1	Piecewise linearization forward meter factor 1 The first forward meter factor used for piecewise linearization. It is paired with forward flow rate 1 (FwdFlwRt1) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41083	1082	FwdMtrFctr2	Piecewise linearization forward meter factor 2 The second forward meter factor used for piecewise linearization. It is paired with forward flow rate 2 (FwdFlwRt2) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41085	1084	FwdMtrFctr3	Piecewise linearization forward meter factor 3 The third forward meter factor used for piecewise linearization. It is paired with forward flow rate 3 (FwdFlwRt3) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41087	1086	FwdMtrFctr4	Piecewise linearization forward meter factor 4 The fourth forward meter factor used for piecewise linearization. It is paired with forward flow rate 4 (FwdFlwRt4) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41089	1088	FwdMtrFctr5	Piecewise linearization forward meter factor 5 The fifth forward meter factor used for piecewise linearization. It is paired with forward flow rate 5 (FwdFlwRt5) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41091	1090	FwdMtrFctr6	Piecewise linearization forward meter factor 6 The sixth forward meter factor used for piecewise linearization. It is paired with forward flow rate 6 (FwdFlwRt6) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41093	1092	FwdMtrFctr7	Piecewise linearization forward meter factor 7 The seventh forward meter factor used for piecewise linearization. It is paired with forward flow rate 7 (FwdFlwRt7) to form an endpoint of a line segment to the next lowest endpoint. This fine segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41095	1094	FwdMtrFctr8	Piecewise linearization forward meter factor 8 The eighth forward meter factor used for piecewise linearization. It is paired with forward flow rate 8 (FwdFiwRt8) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41097	1096	FwdMtrFctr9	Piecewise linearization forward meter factor 9 The ninh forward meter factor used for piecewise linearization. It is paired with forward flow rate 9 (FwdFlwRt9) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41099	1098	FwdMtrFctr10	Piecewise linearization forward meter factor 10 The tenth forward meter factor used for piecewise linearization. It is paired with forward flow rate 10 (FwdFlwRt10) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41101	1100	FwdMtrFctr11	Piecewise linearization forward meter factor 11 The eleventh forward meter factor used for piecewise linearization. It is paired with forward flow rate 11 (FwdFlwR11) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1

Rosemou	nt™ Liau	id Ultrasonic Firmware:	1.61 Database: 2.29.017													
			tosemount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding		I	Description		1	1			1	Modbus					Minimum	Maximum
Register Number	Reg Num	Label		Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Value (native unit)	Value (native unit)
41103	1102	PwdMtrFctr12	Piecewise linearization forward meter factor 12 The twelfth forward meter factor used for piecewise linearization. It is paired with forward flow rate 12 (FwdFlwRt12) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41105		RevFlwRt1	Piecewise linearization rev vol flow rate 1 The first and highest reverse flow rate used for piecewise linearization. It is paired with reverse meter factor 1 (RevMtrFctr1) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) base on the dry calibration flow velocity. If it is unused it should be set to zero. Flow rates above this point will simply apply reverse meter factor (RevMtrFctr1) as the linear meter factor (LinearMtrFctr).		Y	Y	Y	float	volume/time		float32	m3/hr		0	0	200000
41107	1106	RevFlwRt2	Piecewise linearization rev vol flow rate 2 The second reverse flow rate used for piecewise linearization. It is paired with reverse meter factor 2 (RevMtrFctr2) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dr calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41109	1108	RevFlwRt3	Piecewise linearization rev vol flow rate 3 The third reverse flow rate used for piecewise linearization. It is paired with reverse meter factor 3 (RevMtrFctr3) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41111	1110	RevFlwRt4	Piecewise linearization rev vol flow rate 4 The fourth reverse flow rate used for piecewise linearization. It is paired with reverse meter factor 4 (RevMtrFctr4) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41113	1112	RevFlwRt5	Piecewise linearization rev vol flow rate 5 The fifth reverse flow rate used for piecewise linearization. It is paired with reverse meter factor 5 (RevMtrFctr5) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41115	1114	RevFlwRt6	Piecewise linearization rev vol flow rate 6 The sixth reverse flow rate used for piecewise linearization. It is paired with reverse meter factor 6 (RevMtrFctr6) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (Linear/MtrFctr6) as do not dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41117	1116	RevFlwRt7	Piecewise linearization rev vol flow rate 7 The seventh reverse flow rate used for piecewise linearization. It is paired with reverse meter factor 7 (RevMtrFctr7) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dr calibration flow velocity. If it is unused it should be set to zero.		Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41119	1118	RevFlwRt8	Piecewise linearization rev vol flow rate 8 The eighth reverse flow rate used for piecewise linearization. It is paired with reverse meter factor 8 (RevMtrFctr8) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41121	1120	RevFlwRt9	Piecewise linearization rev vol flow rate 9 The ninth reverse flow rate used for piecewise linearization. It is paired with reverse meter factor 9 (RevMtrFctr9) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41123	1122	RevFlwRt10	Piecewise linearization rev vol flow rate 10 The tenth reverse flow rate used for piecewise linearization. It is paired with reverse meter factor 10 (RevMtrFctr10) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (Linear/MtrFctr) based on the dr calibration flow velocity. If it is unused it should be set to zero.		Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41125	1124	RevFlwRt11	Piecewise linearization rev vol flow rate 11 The eleventh reverse flow rate used for piecewise linearization. It is paired with reverse meter factor 11 (RevMtrFctr11) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) base on the dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41127	1126	RevFlwRt12	Piecewise linearization rev vol flow rate 12 The twelfth and lowest reverse flow rate used for piecewise linearization. It is paired with reverse meter factor 12 (RevMtrFctr12) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to zero.	RW	Y	Y	Y	float	volume/time	volume/time	float32	m3/hr		0	0	200000
41129	1128	RevMtrFctr1	Piecewise linearization reverse meter factor 1 The first reverse meter factor used for piecewise linearization. It is paired with reverse flow rate 1 (RevFlwRt1) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41131	1130	RevMtrFctr2	Piecewise linearization reverse meter factor 2 The second reverse meter factor used for piecewise linearization. It is paired with reverse flow rate 2 (RevFlwRt2) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41133	1132	RevMtrFctr3	Piecewise linearization reverse meter factor 3 The third reverse meter factor used for piecewise linearization. It is paired with reverse flow rate 3 (RevFiwRt3) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41135	1134	RevMtrFctr4	Piecewise linearization reverse meter factor 4 The fourth reverse meter factor used for piecewise linearization. It is paired with reverse flow rate 4 (RevFlwRt4) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctt) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41137	1136	RevMtrFctr5	Piecewise linearization reverse meter factor 5 The fifth reverse meter factor used for piecewise linearization. It is paired with reverse flow rate 5 (RevFlwRt5) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41139		RevMtrFctr6	Piecewise linearization reverse meter factor 6 The sixth reverse meter factor used for piecewise linearization. It is paired with reverse flow rate 6 (RevFlwRt6) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41141		RevMtrFctr7	Piecewise linearization reverse meter factor 7 The seventh reverse meter factor used for piecewise linearization. It is paired with reverse flow rate 7 (RevFlwRt7) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dr calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41143	1142	RevMtrFctr8	Piecewise linearization reverse meter factor 8 The eighth reverse meter factor used for piecewise linearization. It is paired with reverse flow rate 8 (RevFlwRt8) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1

Basama	nt™ Lio	uid Ultrasonic Firmware: 1.	24 Database: 2 20 047													
			semount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
The below	v моари	s map is applicable for Ros	percount = Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters		1	1	1		T	Medhue	1	1				
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
41145		4 RevMtrFctr9	Piecewise linearization reverse meter factor 9 The ninth reverse meter factor used for piecewise linearization. It is paired with reverse flow rate 9 (RevFlwRt9) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41147		6 RevMtrFctr10	Piecewise linearization reverse meter factor 10 The tenth reverse meter factor used for piecewise linearization. It is paired with reverse flow rate 10 (RevFlwRt10) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
41149		B RevMtrFctr11	Piecewise linearization reverse meter factor 11 The eleventh reverse meter factor used for piecewise linearization. It is paired with reverse flow rate 11 (RevFlwRt11) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW		Y	Y	float	-	-	float32	-		1	0.9	1.1
41151		0 RevMtrFctr12	Piecewise linearization reverse meter factor 12 The twelfth reverse meter factor used for piecewise linearization. It is paired with reverse flow rate 12 (RevFlwRt12) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the linear meter factor (LinearMtrFctr) based on the dry calibration flow velocity. If it is unused it should be set to unity (1).	RW		Y	Y	float	-	-	float32	-		1	0.9	1.1
41253		2 SpecFlowPressure	Specified (fixed) flow-condition pressure Specifies the flow-condition pressure used in calculations when the enable pressure input (EnablePressureInput) is set to Fixed (2). This value is also required if the flow-condition pressure and/or temperature source when the corresponding input is in alarm (FlowPOrTSrcUponAlarm) is set to Use fixed value (1).	RW		Y		float	MPa	psi	float32	MPa		0.10156	0	280
41255		4 SpecFlowTemperature	Specified (tixed) flow-condition temperature Specifies the flow-condition temperature used in calculations when the enable temperature input (EnableTemperatureInput) is set to Fixed (2). This value is also required if the flow-condition pressure and/or temperature source when the corresponding input is in alarm (FlowPOrTSrcUponAlarm) is set to Use fixed value (1).	RW	Y	Y		float	deg C	deg F	float32	к		273.15	60.15	473.15
41257	125	6 SpecRhoMixFlow	Specified (fixed) flow-condition fluid mass density Specifies the flow-condition fluid mass density.	RW	Y	Y		float	kg/m3	lbm/ft3	float32	kg/m3		0	0	2000
41265		4 Viscosity	Liquid dynamic viscosity Liquid dynamic viscosity used for Reynolds Number calculation.	RW		Y		float	Pa.s	cPoise	float32	Pa.s		0.000012	0	3.40E+38
41299	129	8 DidResetUsers	User database reset, latched until acknowledged The user database has been reset to a single user "administrator" with the privilege to perform user management and default password as "Administrator-CPUBdSerialNumber". The default password is based on CPU Module serial number (CPUBdSerialNumber) mentioned on a label on the CPU Module.	RW	Y	Y		int	-	-	boolean	-	Reset users cleared (FALSE) Reset users indicated (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
			Recommended Actions: 1. Reconfigure the meter's users. It is recommended that the default Administrator password should be changed. Other users can be													
			reconfigured manually or imported from a previously exported encrypted user database file. 2. The alarm must be acknowledged to clear if from the list of alarms. 3. If facing any user management related issue, then contact your local area Emerson Flow service representative.													
41300	129	9 DidWarmStart	Meter warm started, latched until acknowledged The meter has warm started due to a Program Download, configuration data point change requiring meter warm start or due to a user- initiated meter warm start (DoWarmStart). The Audit log in the meter will indicate the meter reset time (MeterResetTime).	RW	Y	Y		int	-	-	boolean	-	Did not warm start or warm start acknowledged (FALSE) Did warm start (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
			Recommended Actions: 1. If this is due to Program Download, configuration change requiring meter warm start or user-initiated meter warm start just acknowledge this alarm.													
			 The alarm must be acknowledged to clear it from the list of alarms. If this was an unexpected restart of the meter, collect a complete Archive Log from the meter using MeterLink[™] and contact your local area Emerson Flow service representative. 													
41301	130	D DidColdStart	Meter cold started, latched until acknowledged The meter has performed a cold start. The meter configuration has reset to default values, meter archive logs are erased, user database is reset, and Smart Meter Verification reports are deleted. The meter is not configured correctly to measure flow. The user database has been reset to a single user "administrator" with the privilege to perform user management and default password is "Administrator- <cpubdserialnumbers". (cpubdserialnumber)="" based="" cpu="" default="" is="" label="" mentioned="" module="" number="" on="" on<br="" password="" serial="" the="">the CPU Module.</cpubdserialnumbers".>	RW	Y	Y		int	-	-	boolean	-	Cold start cleared (FALSE) Cold start indicated (TRUE)	TRUE (1)	FALSE (0)	TRUE (1)
			Recommended Actions: 1. If the cold start occurred unexpectedly, i.e. not due to firmware upgrade/downgrade or user-initiated in meter reset mode, we recommend replacing the CPU Module. Contact your local area Emerson Flow service representative. 2. If the cold start occurred after a firmware upgrade or is done using MeterLink™ to cold start the CPU Module, you must fully re-configure the meter from a previously saved configuration using EdI/Compare Configuration in MeterLink™ and reconfigure the meter's users using Manage Users in MeterLink™. 3. The alarm must be acknowledged to clear it from the list of alarms. 4. If the issue is unresolved, contact your local area Emerson Flow service representative.													
41302	130	1 DidPowerFail	Power failure, latched until acknowledged The meter has had power removed for a period of time. The Audit log in the meter will indicate the meter reset time (MeterResetTime).	RW	Y	Y		int	-	-	boolean	-	Did not fail or failure acknowledged (FALSE) Did fail (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
			Recommended Actions:		1	1										
			 If this was a known power fail of the meter, simply acknowledge this alarm. If this was a nuexpected power failer, verify the integrity of the power to the meter and make sure that the voltage level is in the range of 11-36 VDc at the meter. A long cable distance between power source and meter can induce a significant voltage drop at the meter. The alarm must be acknowledged to clear it from the list of alarms. If the issue is unresolved, collect a complete Archive Log from the meter using MeterLink™ and contact your local area Emerson Flow service representative. 													
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41321 1332 Reself RePuer Process the signal to delate when TRUE From the signal to delate when TRUE From the signal to delate when TRUE Do not reset update the site site when TRUE Do not reset update TRUE																	
Image: Forces the signal tracking ingests (Tg4A1, Tgp022, Tgp4A1, Tgp	11221	122	20 BosotTrkBorom		DW			_	int			booloon		Do not report tracking (EALSE)	TRUE (1)	EALSE (0)	TRUE (1)
4133 1332 DoUgaTrgDetaVde Forces the choice proportion bins (twoPropABin1. RevPropABin1, RevPr	1321	132	U Reset i rkParam	Forces the signal tracking targets (TspfA1TspfD2, TspeA1TspeD2 and TampA1TampD2) to be reset to the default values (Tspf,	ĸw	V Y			Int	-	-	boolean	-		TRUE (1)	FALSE (0)	TRUE (1)
Line begin (BPropUpdItAckee) will the required amount of time without chord failures has elapsed (PropUpdItSeconds). Image: Final Second Seco	1322	132	1 ResetProp	Forces the chord proportion bins (FwdPropABin1FwdPropDBin10, RevPropABin1RevPropDBin10, FwdPropVelABin1FwdPropVelDBin10 and RevPropVelABin1RevPropVelDBin10) to be reset to the default values when TRUE (1). The		V Y	,		int	-	-	boolean	-		TRUE (1)	FALSE (0)	TRUE (1)
41332 1331 DoWarmStert Forces the system to perform a warm-start. A wern start differs from a cold start (DuGCodStart) in that the nonvolatile configuration points nee beam opticated. RW Y Y Int - - Doolean - Do warm start (FALSE) 0 warm start Tigbe Transport of the system to perform a warm-start. RW Y Y Int - - Doolean - Do warm start (FALSE) 0 warm start Samphrencel Samphrencel Samphrencel RW Y Y Int - - Doolean - Dowardset (RUE) 41332 1331 DoWarmStert Forces the system to perform a warm-start. A wern start differs from a cold start (DuGCodStart) in that the nonvolatile configuration points neeted networks. A warm start required (sWarmStarReg) when changes are made to the transducer RW V V N Do warm start (FALSE) Do warm start (FALSE) <td></td> <td></td> <td></td> <td></td> <td>t</td> <td></td>					t												
Image: Section forces the system to perform a warm-start. A warm start at required (sWarmStartReq) when changes are made to the transducer characteristics, sample rates, the device number. Sec also: Sec also: </td <td>11331</td> <td>133</td> <td>0 DoUpdtTrigDeltaVols</td> <td>Trigger for updating "triggered" delta volumes. When set to TRUE (1), the triggered delta volume points, TrigDettaPosVo/Flow, TrigDettaNegVo/Flow, TrigDettaPosVo/Base, TrigDettaNegVo/Base, TrigPrev/OsVo/Flow, TrigPrev/OsVo/Flow, TrigPrev/OsVo/Flow, TrigPrev/RegVo/Base are updated with the appropriate volume since the previous trigger. The meter clears this point to FALSE (0) when</td> <td>RW</td> <td>v</td> <td></td> <td></td> <td>int</td> <td>-</td> <td>-</td> <td>boolean</td> <td>-</td> <td></td> <td>FALSE (0)</td> <td>FALSE (0)</td> <td>TRUE (1)</td>	11331	133	0 DoUpdtTrigDeltaVols	Trigger for updating "triggered" delta volumes. When set to TRUE (1), the triggered delta volume points, TrigDettaPosVo/Flow, TrigDettaNegVo/Flow, TrigDettaPosVo/Base, TrigDettaNegVo/Base, TrigPrev/OsVo/Flow, TrigPrev/OsVo/Flow, TrigPrev/OsVo/Flow, TrigPrev/RegVo/Base are updated with the appropriate volume since the previous trigger. The meter clears this point to FALSE (0) when	RW	v			int	-	-	boolean	-		FALSE (0)	FALSE (0)	TRUE (1)
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Image: Sampleterval Sampletval Sampletval Sampletval Sampleterval Sampleterval Sampleterval				XdcrFreq SetXdcrType													
Image: Non-NormalModeTimeout Non-normal operation timeout Request Note and the second se				SampInterval													
41333 1332 isAuditLogFixedDataPointsE nabled Enables or disables audit log for fixed value configuration data points When set to TRUE (1), audit logging of fixed value configuration data point is enabled. Enables audit logging of SpecFlowPressure, SpecFlowTemperature and SpecRhoMixFlow. RW Y Y Init - - boolean - Disabled (FALSE) Enabled (TRUE) 41351 1350 NonNormalModeTimeout notice Non-normal operation timeout not the test mode is stopped), the meter will automatically end the test mode after the non-normal operation timeout has expired. This can be from 1 to 30 minutes depending on its settings. By default, the timeout is set to two minutes. RW Y Y Init - - boolean - Disabled (FALSE) Enabled (TRUE) 41352 1350 NonNormalModeTimeout 30 minutes depending on its settings. By default, the timeout is set to two minutes. Init Y Y Init - - Disabled (FALSE) Enable (TRUE) 41352 1351 IsFreq1EnableTest Frequency Output 1 jair test mable Frequency Output 1 jair test mable Enable Frequency Output 1 jair test mable Enable test (TRUE) RW V V Init - - Disable test (FALSE) Enable test (TRUE)				DeviceNumber													
nabled When set to TRUE (1), audit logging of fixed value configuration data point is enabled. Enables audit logging of SpecFlowPressure, SpecFlowTemperature and SpecRhoMixFlow. Enabled (TRUE) 41351 1350 NonNormalModeTimeout Non-normal operation timeout normal operation timeout. The maximum length of time that a frequency output pair, digital output pair, analog output or calibration can remain in the test mode. In the event mode: a sopped), the meter will automatically end the test mode after the non-normal operation timeout. This can be from 1 to 30 minutes depending on its settings. By default, the timeout is set to two minutes. RW Y Y V int - - boolean - Disable test (FALSE) Enable (TRUE) 41352 1351 IsFreq1EnableTest Frequency Output 1 jair test mable) Frequency Output 1 jair test mable RW RW - - boolean - Disable test (FALSE) Enable test (FRUE)															511.05 (0)	E 11 O E (0)	
41352 1351 IsFreq1EnableTest Frequency Output 1 pair digital output pair, analog output or calibration can remain in the test mode. In the event mode stoeween the Ultrasonic meter software and the meter (before a test mode is stopped), the meter will automatically end the test mode after the non-normal operation timeout has expired. This can be from 1 to 30 minutes depending on its settings. By default, the timeout is set to two minutes. RW Int - - Doclean - Disable test (FALSE) Enable test (FRUE)			nabled	When set to TRUE (1), audit logging of fixed value configuration data point is enabled. Enables audit logging of SpecFlowPressure, SpecFlowTemperature and SpecRhoMixFlow.			Ý		int	-	-	boolean	-	Disabled (FALSE) Enabled (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
Frequency Output 1 is in test mode which means the pulses output do not reflect the process flow through the meter. Test mode allows Enable test (TRUE)	41351	135	0 NonNormalModeTimeout	Non-normal operation timeout. The maximum length of time that a frequency output pair, digital output pair, analog output or calibration can remain in the test mode. In the event communications are lost between the Ultrasonic meter software and the meter (before a test mode is stopped), the meter will automatically end the test mode after the non-normal operation timeout has expired. This can be from 1 to		V Y	Ý	Y	int	min	min	uint8	min		2	1	30
	11352	135	1 IsFreq1EnableTest	Frequency Output 1 is in test mode which means the pulses output do not reflect the process flow through the meter. Test mode allows the connection from this output to a flow computer to be verified. When the frequency output is in test mode, the frequency outputs are		v			int	-	-	boolean	-		FALSE (0)	FALSE (0)	TRUE (1)
fixed at the percentage of full scale specified by the test mode output percentage configuration point (Freq1TestModeOutputPercent). If a frequency pair remains in test mode for the length of time configured by the normal mode timeout (NonNormalModeTimeout), the test mode is automatically exited and the frequency output returns to normal operation.				frequency pair remains in test mode for the length of time configured by the normal mode timeout (NonNormalModeTimeout), the test mode is automatically exited and the frequency output returns to normal operation.													
Recommended Actions:																	
1. Use the Meter Outputs screen in MeterLink [™] to disable the test mode for Frequency Output 1 to clear this alarm and return the meter back to its normal mode of operation. 2. Unless MeterLink [™] or another application through Modbus is re-enabling the test mode, the output will revert back to the normal mode of operation in a user configured timeout period (NonNormalModeTimeout) which can be up to 30 minutes.				back to its normal mode of operation. 2. Unless MeterLink™ or another application through Modbus is re-enabling the test mode, the output will revert back to the normal mode													
41353 1352 Freq1TestModeOutputPerce Frequency Output 1 pair test mode percentage of full-scale nt Specifies the Frequency (Output 1 pair test mode percentage of full-scale. This specifies the frequency (as a percentage of the full-scale frequency (Freq1MaxFrequency) to force Freq1A (Freq1ChnIA) and Freq1B (Freq1ChnIB) when in the frequency test mode (ISFreq1Enable Test).	41353	135	i2 Freq1TestModeOutputPerc nt	Specifies the Frequency Output 1 pair test mode percentage of full-scale. This specifies the frequency (as a percentage of the full-scale frequency (Freq1MaxFrequency)) to force Freq1A (Freq1ChnIA) and Freq1B (Freq1ChnIB) when in the frequency test mode	RW	v			int	%	%	uint8	%		50	0	150

Rosemou	int™ Liq	uid Ultrasonic Firmware: 1.6	1 Database: 2.29.017													
The below	v Modbı	is map is applicable for Rose	emount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg F		Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
41354	135	3 DO1PairTestEnable	Enables test mode for Digital Output 1 pair Used to enable the test mode for Digital Output 1 pair (DO1A and DO1B). When set to TRUE (1), the test mode is enabled and digital outputs 1A and 1B are set to the levels specified by DO1A test mode value (DO1ATestVal) and DO1B test mode value (DO1BTestVal). When this point is set to TRUE (1), the digital output pair remains in the test mode for a period of time set by non-normal operation timeout (NonNormalModeTimeout) unless the test mode is explicitly exited by setting this point to FALSE (0).	RW				int	-	-	boolean	-	Disable test (FALSE) Enable test (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
41355		4 DO1ATestVal	Digital Output 1A test mode value Specifies the value (state) of Digital Output 1A when in the test mode (DO1PairTestEnable).	RW				int	-	-	uint8	-	Test low (0) Test high (1)	0	0	1
41356	135	5 DO1BTestVal	Digital Output 1B test mode value Specifies the value (state) of Digital Output 1B when in the test mode (DO1PairTestEnable).	RW				int	-	-	uint8	-	Test low (0) Test high (1)	0	0	1
41357	135	6 IsFreq2EnableTest	Frequency Output 2 pair test enable Frequency Output 2 is in test mode which means the pulses output do not reflect the process flow through the meter. Test mode allows the connection from this output to a flow computer to be verified. When the frequency output is in test mode, the frequency outputs are fixed at the percentage of full scale specified by the test mode output percentage configuration point (FreqZTestModeOutputPercent). If a frequency pair remains in test mode for the length of time configured by the normal mode timeout (NonNormalModeTimeout), the test mode is automatically exited and the frequency output returns to normal operation. Recommended Actions: 1. Use the Meter Outputs screen in MeterLink™ to disable the test mode for Frequency Output 2 to clear this alarm and return the meter back to its normal mode of operation. 2. Unless MeterLink™ or normal and of operation through Modbus is re-enabling the test mode, the output will revert back to the normal mode of operation in a user configured timeout period (NonNormalModeTimeout) which can be up to 30 minutes.	RW				int	-	-	boolean	-	Disable test (FALSE) Enable test (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
41358	135	7 Freq2TestModeOutputPercent	Frequency Output 2 pair test mode percentage of full-scale Specifies the Frequency Output 2 pair test mode percentage of full-scale. This specifies the frequency (as a percentage of the full-scale frequency (Freq2MaxFrequency)) to force Freq2A (Freq2ChnA) and Freq2B (Freq2ChnB) when in the frequency test mode (IsFreq2EnableTest).	RW				int	%	%	uint8	%		50	0	150
41359	135	8 DO2PairTestEnable	Enables test mode for Digital Output 2 pair Used to enable the test mode for Digital Output 2 pair (DO2A and DO2B). When set to TRUE, the test mode is enabled and digital outputs 2A and 2B are set to the levels specified by DO2A test mode value (DO2ATestVal) and DO2B test mode value (DO2BTestVal). When this point is set to TRUE (1), the digital output pair remains in the test mode for a period of time set by non-normal operation timeout (NonNormalModeTimeout) unless the test mode is explicitly exited by setting this point to FALSE (0).	RW				int	-	-	boolean	-	Disable test (FALSE) Enable test (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
41360	135	9 DO2ATestVal	Digital Output 2A test mode value Specifies the value (state) of Digital Output 2A when in the test mode (DO2PairTestEnable).	RW				int	-	-	uint8	-	Test low (0) Test high (1)	0	0	1
41361	136	0 DO2BTestVal	Digital Output 2B test mode value Specifies the value (state) of Digital Output 2B when in the test mode (DO2PairTestEnable).	RW				int	-	-	uint8	-	Test low (0) Test high (1)	0	0	1
41362	136	1 IsAO1EnableTest	Analog Output 1 test enable Enables the Analog Output Test mode for Analog Output 1. When in the Analog Output Test mode, Analog Output 1 is fixed at the percentage of full scale specified via the Analog Output 1 test mode output percent configuration point (AO1TestModeOutputPercent) (regardless of the actual data content value). If Analog Output 1 remains in Analog Output Test mode for longer than the non-normal mode timeout (NonNormalModeTimeout), Analog Output 1 automatically exits Analog Output Test mode and returns to normal operation.	RW				int	-	-	boolean	-	Disable test (FALSE) Enable test (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
41363	136	2 AO1TestModeOutputPercer t	Analog Output 1 test mode percentage of full-scale Specifies the Analog Output 1 Test mode percentage of full-scale. This specifies the analog current (as a percentage of the current output range, 4-20 mA) to force Analog Output 1 when in the Analog Output Test mode enabled via the IsAO1EnableTest data point.	RW				int	%	%	uint8	%		50	0	105
41364	136	3 IsAO2EnableTest	Analog Output 2 test enable Enables the Analog Output Test mode for Analog Output 2. When in the Analog Output Test mode, Analog Output 2 is fixed at the percentage of full scale specified via the Analog Output 2 test mode output percent configuration point (AO2TestModeOutputPercent) (regardless of the actual data content value). If Analog Output 2 remains in Analog Output Test mode for longer than the non-normal mode timeout (NonNormalModeTimeout), Analog Output 2 automatically exits Analog Output Test mode and returns to normal operation.	RW				int	-	-	boolean	-	Disable test (FALSE) Enable test (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
41365	136	4 AO2TestModeOutputPercent	Analog Output 2 test mode percentage of full-scale Specifies the Analog Output 2 test mode percentage of full-scale. This specifies the analog current (as a percentage of the current output range, 4-20 mA) to force Analog Output 2 when in the Analog Output Test mode (enabled via the IsAO2EnableTest data point).	RW				int	%	%	uint8	%		50	0	105
41401	140	0 HARTNumPreambleBytesFi omSlave	HART (via AO1) number of Slave response preamble bytes HART, via AO1, number of Slave response preamble bytes.	RW	Y	Y	Y	int	•	-	uint8	-		5	5	20
41404	140	3 HARTSlot0Content	HART Command 33 Slot 0 content Specifies the Device Variable mapped to the HART Command 33 Slot 0.	RW	Y	Y	Y	int	-	-	uint8	-	Uncorrected volume flow rate (0) Average flow velocity (2) Average speed of sound (3) Pressure (6) Temperature (7) Not Used (250)	250	0	250
41405	140	4 HARTSlot1Content	HART Command 33 Slot 1 content Specifies the Device Variable mapped to the HART Command 33 Slot 1.	RW	Y	Y	Y	int	-	-	uint8	-	Uncorrected volume flow rate (0) Average flow velocity (2) Average speed of sound (3) Pressure (6) Temperature (7) Not Used (250)	250	0	250
41406	140	5 HARTSlot2Content	HART Command 33 Slot 2 content Specifies the Device Variable mapped to the HART Command 33 Slot 2.	RW	Y	Y	Y	int	-	-	uint8	-	Uncorrected volume flow rate (0) Average flow velocity (2) Average speed of sound (3) Pressure (6) Temperature (7) Not Used (250)	250	0	250
41407	140	6 HARTSlot3Content	HART Command 33 Slot 3 content Specifies the Device Variable mapped to the HART Command 33 Slot 3.	RW	Y	Y	Y	int	-	-	uint8	-	Uncorrected volume flow rate (0) Average flow velocity (2) Average speed of sound (3) Pressure (6) Temperature (7) Not Used (250)	250	0	250
41411	141	0 AO2Content	Analog Output 2 content (and HART secondary variable) Selects the data to be represented by Analog Output 2.Is used for HART communication as the Secondary Variable content.	RW	Y	Y	Y	int	-	-	int32	-	Uncorrected volume flow rate (0) Average flow velocity (2) Average speed of sound (3)	0	0	3
				1									· · · · · · · · · · · · · · · · · · ·			

Rosemou	nt™ Liqui	d Ultrasonic Firmware: 1.61	Database: 2.29.017													
			mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding			Description							Modbus					Minimum	Maximum
Register	Reg Num	Label		Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Value	Value
Number 41412	1411	Reserved		R				int		Unit				, ,	(native unit)	(native unit)
41412		HARTTVContent	HART Third Variable content	RW	Y	Y	Y	int	-		uint8	-	Uncorrected volume flow rate (0)	0	0	7
			HART Third Variable content.										Average flow velocity (2) Average speed of sound (3)			
													Pressure (6)			
	1110		LADT Front Model Instant	DW	V	V	V	54					Temperature (7)			
41414	1413	HARTQVContent	HART Fourth Variable content HART Fourth Variable content.	RW	Ŷ	Ŷ	Ŷ	int	-	-	uint8	-	Uncorrected volume flow rate (0) Average flow velocity (2)	0	0	7
													Average speed of sound (3) Pressure (6)			
													Temperature (7)			
41415	1414	HARTMinNumPreambles	HART (via AO1) minimum number of Master command preamble bytes HART, via AO1, minimum number of Master command preamble bytes.	RW	Y	Y	Y	int	-	-	uint8	-		5	5	20
41421	1420	HARTVolUnit	HART volume unit	RW	Y	Y	Y	int			uint8		m3 (43)	43	40	46
			Selects the HART communication volume unit. The volumetric flow rate unit (HARTVolFlowRateUnit) is derived from this.										L (41) bbl (46)			
													gal (40)			
41422	1421	HARTRateTimeUnit	HART flow rate time unit	RW	Y	Υ	Y	int	-	-	uint8	-	sec (51)	52	50	53
			Selects the HART communication time unit for volumetric flow rate (HARTVolFlowRateUnit).										min (50) hour (52)			
													day (53)			
41423	1422	HARTPressureUnit	HART pressure unit Selects the HART communication unit for pressure.	RW	Y	Y	Y	int	-	-	uint8	-	Pa (11) KPa (12)	237	6	237
													MPa (237)			
41424	1423	HARTTemperatureUnit	HART temperature unit	RW	Y	Y	Y	int	-		uint8	-	psi (6) C (32)	32	32	35
	-		Selects the HART communication unit for temperature.										K (35) F (33)	_	-	
41425	1424	HARTVelUnit	HART velocity unit	RW	Y	Y	Y	int			uint8	-	r (33) m/s (21)	21	20	21
			Selects the HART communication unit for flow velocity.										ft/s (20)			
41426	1425	HARTLengthUnit	HART length unit Selects the HART communication unit for length.	RW	Y	Y	Y	int	-	-	uint8	-	m (45) in (47)	45	45	47
41427	1426	HARTViscosityUnit	HART viscosity unit	RW	Y	Y	Y	int	-	-	uint8	-		55	55	170
			Selects the HART communication unit for dynamic viscosity.								1.0			100	10	
41428	1427	HAR I YoungsModulusPress ureUnit	HART Young's modulus pressure unit Selects the HART communication unit for Young's Modulus (YoungsModulus).	RW	Ŷ	Y	Y	int	-	-	uint8	-	KPa (12) MPa (237)	180	12	237
		114 March 1 MT 14 11									1.00		1E6 psi (180)			
41441	1440	HARTDeviceFinalAssyNum	HART device final assembly number HART device final assembly number. The final assembly number is used for identifying the materials and electronics that comprise the	RW	Ŷ	Ŷ	Ŷ	long	-	-	uint32	-		0	0	16777215
		111 March 101 A 11	field device.								1.0					
41443	1442	HARTPollingAddress	HART (via AO1) polling address Specifies the HART polling address for Analog Output 1.	RW	Ŷ	Y	Y	long	-	-	uint8	-		0	0	63
41445	1444	HARTDate	HART date code used by the master for record keeping	RW	Y	Υ	Υ	long	-	-	uint32	-		65792	0	16777215
41447	1446	HARTQFlowUpdateTime	HART date code used by the master for record keeping (such as last or next calibration date). HART flow-condition volumetric flow rate update time	R				long	ms	ms	uint32	ms				
		n ar r ar ionopadio nino	The flow-condition volumetric flow rate (QFlow) timestamp. It updates every time the flow-condition volumetric flow rate (QFlow) is	, in				long	110		unitor					
			updated and status is good within 24 hours. timestamp is set to 0 if it is not updated within 24 hours or it is updated but status is not good.													
41451	1450	HARTPressureUpdateTime		R				long	ms	ms	uint32	ms				
			The Flow pressure (FlowPressure) timestamp. It updates every time the flow pressure (FlowPressure) is calculated and status is good within 24 hours. timestamp is set to 0 if it is not updated within the last 24 hours or it is updated but status is not good.													
41453	1452	HARTTemperatureUpdateTi me	HART flow temperature update time The Flow Temperature (FlowTemperature) timestamp. It updates every time the flow Temperature (FlowTemperature) is calculated and	R				long	ms	ms	uint32	ms				
			status is good within 24 hours. timestamp is set to 0 if it is not updated within the last 24 hours or it is updated but status is not good.													
41455	1454	HARTAO1OutputUpdateTim	HART analog output 1 update time	R				long	ms	ms	uint32	ms				
	-	е	The Analog Output 1 current value (AO1Output) timestamp. It updates every time the analog output 1 current value (AO1Output) is calculated and status is good within 24 hours, timestamp is set to 0 if it is not updated within the last 24 hours or it is updated but status is						-			-				
			not good.													
41457	1456	HARTPercentRangeUpdate Time		R				long	ms	ms	uint32	ms				
		Time	The percent range (HARTPercentRange) timestamp. It updates every time the HART percent range (HARTPercentRange) is calculated and status is good within 24 hours. Timestamp is set to 0 if it is not updated within the last 24 hours or it is updated but status is not good.													
44.450	1450	Descard														
41459 41461		Reserved HARTAvgFlowUpdateTime	HART average flow velocity update time	R				long long	ms	ms	uint32	ms				
		5	The Average flow velocity (AvgFlow) timestamp. It updates every time the average flow velocity (AvgFlow) is calculated and status is good	1												
			within 24 hours. timestamp is set to 0 if it is not updated within the last 24 hours or it is updated but status is not good.													
41463	1462	HARTAvgSndVelUpdateTim	HART average speed of sound update time	R				long	ms	ms	uint32	ms				
		e	The Average speed of sound (AvgSndVel) timestamp. It updates every time the average speed of sound (AvgSndVel) is calculated and status is good within 24 hours. timestamp is set to 0 if it is not updated within the last 24 hours or it is updated but status is not good.							1						
44504	4500	lat e colDianto: (A 1		5				ia (hasher		Not excitable (CALCE)		ļ	\mid
41501	1500	IsLocalDisplayAvail	Local display is available When TRUE (1) the system has detected the presence of the local display.	R				int	-	-	boolean	-	Not available (FALSE) Available (TRUE)			
41502	1501	lsLocalDisplayEnableTest	Test mode for local display	RW				int	-	- 1	boolean	-	Disable test (FALSE)	FALSE (0)	FALSE (0)	TRUE (1)
			When set TRUE (1) the local display will perform a series of tests to exercise all the segments of the display. This value will automatically return to FALSE (0) when the test is complete.										Enable test (TRUE)			
41503	1502	LocalDisplayScrollDelay	Scroll delay time for local display	RW	Y	Υ	Y	int	sec	sec	uint8	sec		5	1	100
			The time interval in seconds used to change which item (LocalDisplayItem1, LocalDisplayItem2, LocalDisplayItem3, LocalDisplayItem4, LocalDisplayItem5, LocalDisplayItem6, LocalDisplayItem7, LocalDisplayItem8, LocalDisplayItem9, LocalDisplayItem10) is shown on the							1						
			local display.													

Rosemou	nt™ Liqu	d Ultrasonic Firmware: 1.6	1 Database: 2.29.017													
The below	Modbus	map is applicable for Ros	emount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
41504	1503	LocalDisplayFlowRateTimeL nit	Local display time units The time units used by the local display, if applicable, to display the current item (LocalDisplayItem1, LocalDisplayItem2, LocalDisplayItem3, LocalDisplayItem4, LocalDisplayItem5, LocalDisplayItem6, LocalDisplayItem7, LocalDisplayItem8, LocalDisplayItem10). This data point is only applicable when local display mode (LocalDisplayIde) is set to "Scroll items 1-10".	RW	Y	Y	Y	int	-	-	uint8	-	second (0) minute (3) hour (1) day (2)	1	0	3
41505	1504	LocalDisplayVolUnitUS	Local display U.S. Customary volume unit The volumetric units used by the local display, if applicable, to display the current item (LocalDisplayItem1, LocalDisplayItem2, LocalDisplayItem3, LocalDisplayItem4, LocalDisplayItem5, LocalDisplayItem6, LocalDisplayItem7, LocalDisplayItem8, LocalDisplayItem10) when the units system (UnitsSystem) is selected to U.S. Customary (0). This data point is only applicable when local display mode (LocalDisplayMode) is set to "Scroll items 1-10".	RW	Y	Y	Y	int	-	-	uint8	-	Barrels (1) Gallons (2)	1	1	2
41506	1505	LocalDisplayVolUnitMetric	Local display metric volume unit The volumetric units used by the local display, if applicable, to display the current item (LocalDisplayItem1, LocalDisplayItem2, LocalDisplayItem3, LocalDesplayItem4, LocalDisplayItem5, LocalDisplayItem6, LocalDisplayItem7, LocalDisplayItem8, LocalDisplayItem10) when the units system (UnitsSystem) is selected to Metric (1). This data point is only applicable when local display mode (LocalDisplayItem6 is set to "Scroll items 1-10".	RW	Y	Y	Y	int	-		uint8	-	Cubic meters (0) Liters (1) Thousand cubic meters (2)	0	0	2
41507	1506	LocalDisplayItem1	Local display item 1 This selects the first value to be shown on the local display. Other display items (LocalDisplayItem2, LocalDisplayItem3, LocalDisplayItem4, LocalDisplayItem5, LocalDisplayItem6, LocalDisplayItem7, LocalDisplayItem9, LocalDisplayItem9, LocalDisplayItem10) will be displayed in sequence at a rate determined by the delay time (LocalDisplayIcem2). When selected as None (0), this item will be skipped. The units this item is displayed in are determined by the units system (UnitSsystem), the corresponding volume units (LocalDisplayVolUnitUS, LocalDisplayVolUnitMetric) and/or the time units (LocalDisplayFowRateTmeUnit). This data point is only applicable when local display mode (LocalDisplayMode) is set to "Scroll items 1-10".	RW	Y	Y	Ŷ	int	-	-	uint8		None (0) QFLOW - Uncorrected volume flow rate (1) TDVUL - Current day's forward uncorrected volume (2) TDVUL - Current day's reverse uncorrected volume (3) YSTUL - Previous day's forward uncorrected volume (5) TOTUL - Forward uncorrected volume (6) TOTUL - Average flow volume (7) VEL - Average flow volume (7) VEL - Average speed of sound (9) TEMP - flow-condition pressure (11) PRCSS - flow-condition pressure (11) PRCSS - flow-condition pressure (11) PRC1A - Frequency channel 1A (12) FRC1B - Frequency channel 1A (13) KFCT1 - Frequency 1K-factor (14) FRC2B - Frequency channel 2B (16) KFCT2 - Frequency channel 2B (16) KFCT3 - Frequency channel 2B (16) KFCT4	1	0	25
41508	1507	LocalDisplay/tem2	Local display item 2 This selects the second value to be shown on the local display. Other display items (LocalDisplayItem3, LocalDisplayItem4, LocalDisplayItem5, LocalDisplayItem6, LocalDisplayItem7, LocalDisplayItem8, LocalDisplayItem9, LocalDisplayItem10, LocalDisplayItem10, localDisplayItem6, LocalDisplayItem6	RW	Y	Y	Ŷ	int	-	-	uint8		None (i) OFLOW - Incorrected volume flow rate (1) DTV/L - Current day's forward uncorrected volume (3) YSTVL - Previous day's forward uncorrected volume (3) YSTVL - Previous day's reverse uncorrected volume (6) TOTVL - Forward uncorrected volume (6) TOTVL - Reverse uncorrected volume (7) VEL - Average speed of sound (9) TOTVE - Average speed of sound (9) TEMP - flow-condition trepsarture (10) PRESS - flow-condition pressure (11) FR01A - Frequency channel 18 (13) KFC11 - Frequency channel 18 (13) KFC1 - Frequency channel 28 (16) FR02B - Frequency channel 28 (16) KFC12 - Frequency channel 28 (16)	6	0	25
41509	1508	LocalDisplayItem3	Local display item 3 This selects the third value to be shown on the local display. Other display items (LocalDisplayItem4, LocalDisplayItem5, LocalDisplayItem6, LocalDisplayItem7, LocalDisplayItem8, LocalDisplayItem9, LocalDisplayItem10, LocalDisplayItem5, LocalDisplayItem6, LocalDisplayItem7, LocalDisplayItem9, LocalDisplayScrolDelay). When selected as None (0), this item will be skipped. The units this item is displayed in are determined by the units system (I/UnitSsystem), the corresponding volume units (LocalDisplay/oUnitUS, LocalDisplay/VoUnitIVetric) and/or the time units (LocalDisplayForR)FowRateTimeUnit). This data point is only applicable when local display mode (LocalDisplayMode) is set to "Scroll items 1-10".	RW	Y	Y	Ŷ	int			uint8		None (0) OFLOW - Uncorrected volume flow rate (1) TDVVL - Current day's forward uncorrected volume (2) TDVVL - Current day's reverse uncorrected volume (3) YSTVL - Previous day's forward uncorrected volume (5) TOTVL - Forward uncorrected volume (6) TOTVL - Average flow velocity (8) SOS - Average flow velocity (8) SOS - Average speed of sound (9) TEMP - flow-condition pressure (11) FRC18 - Frequency channel 1A (12) FRC18 - Frequency channel 1B (13) KFC11 - Frequency channel 2A (15) FRC28 - Frequency channel 2B (16) KFC12 - Frequency channel 2B (16) KFC12 - Frequency 2C (17) A01 - Analog Output 1 Current (24) A02 - Analog Output 2 Current (25)	14	0	25

Rosemou	nt™ Liqu	id Ultrasonic Firmware	1.61 Database: 2.29.017													
The below	/ Modbus	s map is applicable for I	osemount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters					I						1		
Holding Register Number	Reg Num	Label	Description	Aco	nv	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
41510		LocalDisplayItem4	Local display item 4 This selects the fourth value to be shown on the local display. Other display items (LocalDisplayItem5, LocalDisplayItem6, LocalDisplayItem7, LocalDisplayItem8, LocalDisplayItem9, LocalDisplayTem10, LocalDisplayItem1, LocalDisplayItem2, LocalDisplayItem3) will be displayed in sequence at a rate determined by the delay time (LocalDisplayScrollDelay). When selected as None (0), this item will be skpped. The units this item is displayed in are determined by the units system (UnaS)Stear (UnaS)LocalDisplayTem3). (LocalDisplayVolUnitUS, LocalDisplayVolUnitWetric) and/or the time units (LocalDisplayForwRateTmeUnit). This data point is only applicable when local display mode (LocalDisplayMode) is set to "Scroll items 1-10".		Y	Y	Ŷ	int	-	-	uint8	-	None (0) QFLOW - Uncorrected volume flow rate (1) TDYVL - Current day's forward uncorrected volume (2) TDYVL - Current day's reverse uncorrected volume (3) YSTVL - Previous day's forward uncorrected volume (5) TOTVL - Previous day's reverse uncorrected volume (6) TOTVL - Reverse uncorrected volume (6) TOTVL - Reverse uncorrected volume (7) VEL - Average flow velocity (8) SOS - Average flow velocity (8) PRESS - flow-condition pressure (11) FRC1A - Frequency channel 1A (12) FRC1B - Frequency channel 1B (13) KFC11 - Frequency channel 1B (13) KFC11 - Frequency channel 2B (16) KFC12 - Frequency	0	0	25
41511	1510	LocalDisplayItem5	Local display item 5 This selects the fifth value to be shown on the local display. Other display items (LocalDisplayItem6, LocalDisplayItem7, LocalDisplayItem8, LocalDisplayItem9, LocalDisplayItem1, LocalDisplayItem1, LocalDisplayItem2, LocalDisplayItem3, LocalDisplayItem3, LocalDisplayItem3, LocalDisplayItem3, LocalDisplayItem3, LocalDisplayItem4, LocalDisplayItem4, LocalDisplayItem3, L	RW	/ Y	Y	Y	int	-	-	uint8	-	None (i) OFLOW - Uncorrected volume flow rate (1) TDYUL - Current day's forward uncorrected volume (2) TDYUL - Current day's forward uncorrected volume (3) YSTUL - Previous day's forward uncorrected volume (6) TOTVL - Forward uncorrected volume (6) TOTVL - Forward uncorrected volume (7) VEL - Average flow velocity (8) SOS - Average speed of sound (9) TEMP - flow-condition temperature (10) PRESS - flow-condition pressure (11) FR01A - Frequency channel 18 (13) KFC11 - Frequency Infanct (14) FR02B - Frequency thannel 2A (15) FR02B - Frequency thannel 2B (16) KFC12 - Frequency thannel 2B (16)	0	0	25
41512	1511	LocalDisplayItem6	Local display item 6 This selects the sixth value to be shown on the local display. Other display items (LocalDisplayItem7, LocalDisplayItem8, LocalDisplayItem9, LocalDisplayItem10, LocalDisplayItem1, LocalDisplayItem2, LocalDisplayItem7, LocalDisplayItem4, LocalDisplayItem5) will be displayed in sequence at a rate determined by the delay time (LocalDisplayScrollDelay). When selected as None (0), this item will be skpped. The units this item is displayed in are determined by the units system (UnitsSystem), the corresponding volume units (LocalDisplayVolUnitUS, LocalDisplayVolUnitMetric) and/or the time units (LocalDisplayFormRateTimeUnit). This data point is only applicable when local display mode (LocalDisplayMode) is set to "Scroll items 1-10".	RW	Y	Y	Ŷ	int	-	-	uint8	-	None (i) OFLOW - Uncorrected volume flow rate (1) TDYVL - Current day's forward uncorrected volume (2) TDYVL - Current day's reverse uncorrected volume (3) YSTVL - Previous day's forward uncorrected volume (3) YSTVL - Previous day's reverse uncorrected volume (5) TOTVL - Forward uncorrected volume (6) TOTVL - Average flow elocity (8) SOS - Average speed of sound (9) TEMP - flow-condition pressure (11) FRC16 - Frequency channel 1A (12) FRC16 - Frequency channel 1B (13) KFC11 - Frequency 1K-factor (14) FRC28 - Frequency channel 2B (15) FRC28 - Frequency channel 2B (16) KFC12 - Frequency 2B (16) KFC12 - Frequency 2B (16) KFC12 - Frequency 2B (16) KFC12 - Fre	0	0	25
41513	1512	LocalDisplayItem7	Local display item 7 This selects the seventh value to be shown on the local display. Other display items (LocalDisplayItem8, LocalDisplayItem9, LocalDisplayItem10, LocalDisplayItem1, LocalDisplayItem2, LocalDisplayItem3, LocalDisplayItem6, LocalDisplayItem6, will be displayed in sequence at a rate determined by the delay time (LocalDisplayScrollDelay). When selected as None (0), this item will be skpped. The units this item is displayed in are determined by the units system (UnitsSystem), the corresponding volume units (LocalDisplayVolUnitUS, LocalDisplayVolUnitMetric) and/or the time units (LocalDisplayForwRateTimeUnit). This data point is only applicable when local display mode (LocalDisplayMode) is set to "Scroll items 1-10".	RW	ÝÝ	Ŷ	Y	int	-		uint8		None (0) OFLOW - Uncorrected volume flow rate (1) TDVVL - Current day's torward uncorrected volume (2) TDVVL - Current day's reverse uncorrected volume (3) YSTVL - Previous day's forward uncorrected volume (5) TOTVL - Forward uncorrected volume (5) TOTVL - Reverse uncorrected volume (7) VEL - Average flow velocity (8) SOS - Average speed of sound (9) TEMP - flow-condition pressure (11) PRCS5 - flow-condition pressure (11) PRC14 - Frequency channel 1A (12) FRC18 - Frequency channel 1B (13) KFCT1 - Frequency channel 2A (15) FRC28 - Frequency 2K-factor (17) AO1 - Analog Output 1 Current (24) AO2 - Analog Output 2 Current (25)	0	0	25

Rosemour	t™ Liqui	d Ultrasonic Firmware: 1.61	Database: 2.29.017													
The below	Modbus	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
41514		LocalDisplayItem8	Local display item 8 This selects the eighth value to be shown on the local display. Other display items (LocalDisplayItem9, LocalDisplayItem10, LocalDisplayItem1, LocalDisplayItem2, LocalDisplayItem3, LocalDisplayItem4, LocalDisplayItem5, LocalDisplayItem6, LocalDisplayItem7) will be displayed in sequence at a rate determined by the delay time (LocalDisplayItem5, LocalDisplayItem6, LocalDisplayItem7) will be displayed in sequence at a rate determined by the delay time (LocalDisplayItem7), the corresponding volume units display. Units this tem is displayed in are determined by the units system (UnitsSystem), the corresponding volume units (LocalDisplayVolUnitUS, LocalDisplayVolUnitMetric) and/or the time units (LocalDisplayFowRateTmeUnit). This data point is only applicable when local display mode (LocalDisplayMode) is set to "Scroll items 1-10".	RW	Y	Y	Y	int	-	-	uint8	-	None (0) OFLOW - Uncorrected volume flow rate (1) TDYVL - Current day's forward uncorrected volume (2) TDYVL - Current day's reverse uncorrected volume (3) YSTVL - Previous day's reverse uncorrected volume (4) YSTVL - Previous day's reverse uncorrected volume (5) TOTVL - Forward uncorrected volume (7) VEL - Average flow velocity (8) SOS - Average speed of sound (9) TEMP - flow-condition temperature (10) PRESS - flow-condition temperature (11) FR018 - Frequency channel 1A (12) FR018 - Frequency channel 1A (13) KFC11 - Frequency channel 1A (13) KFC11 - Frequency channel 2A (15) FR028 - Frequency channel 2A (15) FR028 - Frequency channel 2B (16) KFC12 - Frequency 2K-factor (17) AO1 - Analog Output 1 Current (24) AO2 - Analog Output 2 Current (25)	0	0	25
41515	1514	LocalDisplayItem9	Local display item 9 This selects the ninh value to be shown on the local display. Other display items (LocalDisplayItem10, LocalDisplayItem1, LocalDisplayItem2, LocalDisplayItem3, LocalDisplayItem4, LocalDisplayItem5, LocalDisplayItem6, LocalDisplayItem6, LocalDisplayItem3, Mill be displayed in sequence at rate determined by the delay time (LocalDisplayScruIDea)U. When selected as None (0), this item will be skipped. The units this item is displayed in are determined by the units system (UnitSystem), the corresponding volume units (LocalDisplayIOUInItUS, LocalDisplayIOUInItHeric) and/or the time units (LocalDisplayForMAETTmeUnit). This data point is only applicable when local display mode (LocalDisplayMode) is set to "Scroll items 1-10".	RW	Ŷ	Y	Ŷ	int	-	-	uint8		None (i) QFLOW - Uncorrected volume flow rate (1) TDYUL - Current day's forward uncorrected volume (2) TDYUL - Current day's forward uncorrected volume (3) YSTUL - Previous day's forward uncorrected volume (3) YSTUL - Forward uncorrected volume (7) VEL - Average succorrected volume (7) VEL - Average speed of sound (9) TGM- filew-condition temperature (10) PRESS - flow-condition temperature (11) FRO1A - Frequency channel 1B (13) KFC11 - Forquency 1K-factor (14) FRO2B - Frequency channel 2B (15) FRO2B - Frequency channel 2B (15) KFC12 - Frequency channel 2B (16) KFC12 - Frequency channel 2B	0	0	25
41516	1515	LocalDisplayItem10	Local display item 10 This selects the tenth value to be shown on the local display. Other display items (LocalDisplayItem1, LocalDisplayItem2, LocalDisplayItem3, LocalDisplayItem4, LocalDisplayItem5, LocalDisplayItem6, LocalDisplayItem7, LocalDisplayItem8, LocalDisplayItem9) will be displayed in sequence at a rate determined by the delay time (LocalDisplayItem6, LocalDisplayItem6, Local	RW	Y	Y	Y	int	-	-	uint8		None (0) OFLOW - Uncorrected volume flow rate (1) TD/VL - Current day's forward uncorrected volume (2) TD/VL - Current day's reverse uncorrected volume (3) YSTVL - Previous day's reverse uncorrected volume (6) TO/TVL - Forward uncorrected volume (6) TO/TVL - Reverse uncorrected volume (7) VEL - Average speed of sound (9) TDMP - flow-condition temperature (10) PRESS - flow-condition pressure (11) FR01A - Frequency channel 1B (13) KFCT1 - Forguency 1K-factor (14) FR02B - Frequency channel 2A (15) FR02B - Frequency channel 2B (16) KFCT2 - Frequency channel 2B	0	0	25
41517	1516	LocalDisplaySquawkMode	Local display squawk mode When squawk mode is set to Squawk On (1) the local display will display the pattern O-O-O-O until squawk mode is set to Squawk Off (0). When squawk mode is set to Squawk Once (2) the local display will display the pattern O-O-O for 60 seconds.	RW	Y			int	-	-	uint8	-	Squawk Off (0) Squawk On (1) Squawk Once (2)	0	0	2
41518		LocalDisplayMode	Local display mode When set to "Uncorrected volume only", the local display alternately shows the forward flow-condition volume (PosVoIFlow) and the reverse flow-condition volume (NegVoIFlow) in m3 or ft3/gal depending on the units system (UnitsSystem). The non-resettable running totals will be displayed as multiplier of 10 or 100 (depending upon the meter size) and only 7 least significant digits will be displayed. When set to "ScroIf terms 1-10", the local display will display items configured by local display item 1-10 (LocalDisplayItem7, LocalDisplayItem2, LocalDisplayItem3, LocalDisplayItem4, LocalDisplayItem5, LocalDisplayItem6, LocalDisplayItem7, LocalDisplayItem8, LocalDisplayItem9, LocalDisplayItem10). In both modes, items will be updated on the local display using the scroIf delay time interval (LocalDisplayScroIIDelay).	RW	Y	Y	Y	int		-	uint8	-	Scroll items 1-10 (0) Uncorrected volume only (1)	0	0	1
41522			Peak switch detection mode Determines what action to take if a peak switch is detected by the pattern of computed eta values (EtaBA, EtaBA, EtaCA, EtaCD). Both the "Status Only" and the "Status and Discard" modes set the peak switch detection indicators (IsPeakSwitchDetectedA, IsPeakSwitchDetectedB, IsPeakSwitchDetectedC, IsPeakSwitchDetectedD). If "Status and Discard" is selected the waveforms with peak switching detected will not be included in the flow calculations. Discarded measurement data may cause a chord to be considered failed if the percentage of good measurements fails below the minimum percentage good threshold (MinPctGood). If "Disabled" no status will be updated nor waveforms discarded.	RW	Y	Y	Y	int	-	-	uint8	-	Disabled (0) Status Only (1) Status and Discard (2)	0	0	2
41523	1522	IsPeakSwitchDetected	Peak switch detected A peak switch liming error was detected on at least one chord (IsPeakSwitchDetectedA, IsPeakSwitchDetectedB, IsPeakSwitchDetectedC, IsPeakSwitchDetectedD).	R				int	-	-	boolean	-				

Rosemou	nt™ Liqui	d Ultrasonic Firmware: 1.61	Database: 2.29.017													1
			mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
			Description					I		Modbus					Minia	Mauir
Holding Register	Reg	Label		Ac	c NV	Cnfg	Prot	Modbus	Modbus	U.S.	Native Data	Native Data	Selections/Bitmap	Default Value	Minimum Value	Maximum Value
Number	Num							Reg Type	Metric Unit	Customary Unit	Туре	Unit		(native unit)	(native unit)	(native unit)
41524		IsPeakSwitchDetectedA	Peak switch detected for chord A A peak switch timing error was detected in the measurement data, if the peak switch detect mode (PeakSwitchDetectMode) is set to display status. If the peak switch detect mode (PeakSwitchDetectMode) is configured to discard data, then this value indicates measurement data from one or more transducer fring was discarded due to a peak switch timing error. If this value indicates proportion bin update will not be allowed and the proportional update indicator (BrPopUpdAtcNet) will be FALSE (IO). Discarded measurement data may cause a chord to be considered failed if the percentage of good measurements falls below the minimum percentage good threshot (MinPeCIGood). The indication is suppressed if the average of path performance (PctGoodA1, PctGoodA2) is above the chord performance status suppression limit (PerfStatusSuppressLmt). Recommended Actions: 1. This alarm is typically disabled. If it was enabled unintentionally then the peak switch detect mode (PeakSwitchDetectMode) should be set to disable the alarm again. 2. Verify that the transducers are working properly. All chords should have similar dB gains and low noise levels. If the meter is reporting SNR below minimum or noise exceeded limit for any chords, address those alarms first. 3. Adjusting the tracking parameters may address this sube but we do not recommend changes without input from a Emerson Flow service representative. Collect a Maintenance Log, a Waveform stream file and configuration file with MeterLink TM while the meter is experiencing the issue and contact your local area Emerson Flow service representative.	R				int	-	-	boolean	-				
41525	1524	IsPeakSwitchDetectedB	Peak switch detected for chord B A peak switch iming error was detected in the measurement data, if the peak switch detect mode (PeakSwitchDetectMode) is set to display status. If the peak switch detect mode (PeakSwitchDetectMode) is configured to discard data, then this value indicates measurement data from one or more transducer firing was discarded due to a peak switch timing error. If this value is TRUE (1), the chord proportion bin update will not be allowed and the proportional update indicator (IsPropUpdtActive) will be FALSE (0). Discarded measurement data may cause a chord to be considered failed if the percentage of good measurements falls below the minimum percentage good threshot (MinPerCiGood). The indication is suppressed if the average of path performance (PctGoodB1, PctGoodB2) is above the chord performance status suppression limit (PerfStatusSuppressLmt). Recommended Actions: 1. This alarm is typically disabled. If it was enabled unintentionally then the peak switch detect mode (PeakSwitchDetectMode) should be set to disable the alarm gapin. 2. Verify that the transducers are working properly. All chords should have similar dB gains and low noise levels. If the meter is reporting SNR below minimum or noise exceeded limit for any chords, address those alarms first. 3. Adjusting the tracking parameters may address this issue but we do not recommend changes without input from a Emerson Flow service representative. Collect a Maintenance Log, a Waveform stream file and configuration file with MeterLink [™] while the meter is experiencing the issue and contact your local area Emerson Flow service representative.	R				int	-		boolean	-				
41526		IsPeakSwitchDetectedC	Peak switch detected for chord C A peak switch timing error was detected in the measurement data, if the peak switch detect mode (PeakSwitchDetectMode) is set to display staus. If the peak switch detect mode (PeakSwitchDetectMode) is configured to discard data, then this value indicates measurement data from one or more transducer firing was discarded due to a peak switch timing error. If this value is TRUE (1), the chord proportion bin update will not be allowed and the proportional update incitactic (BropUpdAtchive) will be FALSE (0). Discarded measurement data may cause a chord to be considered failed if the percentage of good measurements falls below the minimum percentage good threshot (MinPCIGood). The indication is suppressed if the average of path performance (PctGoodC1, PctGoodC2) is above the chord performance status suppression limit (PerfStatusSuppressLmt). Recommended Actions: 1. This alarm is typically disabled. If it was enabled unintentionally then the peak switch detect mode (PeakSwitchDetectMode) should be set to disable the alarm again. 2. Verify that the transducers are working properly. All chords should have similar dB gains and low noise levels. If the meter is reporting SNR below minimum or noise exceeded limit for any chords, address those alarms first. 3. Adjusting the tracking parameters may address this sube but we do not recommend changes without input from a Emerson Flow service representative. Collect a Maintenance Log, a Waveform stream file and configuration file with MeterLink TM while the meter is experiencing the issue and contact your local area Emerson Flow service representative.	R				int		-	boolean	-				
41527	1526	IsPeakSwitchDetectedD	Peak switch detected for chord D A peak switch timing error was detected in the measurement data, if the peak switch detect mode (PeakSwitchDetectMode) is set to display status. If the peak switch detect mode (PeakSwitchDetectMode) is configured to discard data, then this value indicates measurement data from one or more transducer fring was discarded due to a peak switch timing error. If this value is TRUE (1), the chord proportion bin update will not be allowed and the proportional update indicator (BPropUpdAtcHve) will be FALSE (0). Discarded measurement data may cause a chord to be considered failed if the percentage of good measurements falls below the minimum percentage good threshot (MinPerCiGood). The indication is suppressed if the average of path performance (PctGoodD1, PctGoodD2) is above the chord performance status suppression limit (PerfStatusSuppressLmt). Recommended Actions: 1. This alarm is typically disabled. If it was enabled unintentionally then the peak switch detect mode (PeakSwitchDetectMode) should be set to disable the alarm again. 2. Verify that the transducers are working properly. All chords should have similar dB gains and low noise levels. If the meter is reporting SNR below minimum or noise exceeded limit for any chords, address those alarms first. 3. Adjusting the tracking parameters may address this subs but we do not recommend changes without input from a Emerson Flow service representative. Collect a Maintenance Log, a Waveform stream file and configuration file with MeterLink [™] while the meter is experiencing the issue and contact your local area Emerson Flow service representative.	R				int	-	-	boolean	-				

Bosomou	nt™ Liqu	id Ultrasonic Firmware: 1.61	Database: 2 20 047													
The below	woodbus	map is applicable for Rosei	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters								1					
Holding Register Number	Reg Num	Label	Description 4	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Val (native un		Maximum Value (native unit)
41528	1527	IsXdcrMaintenanceRequired A	Transducer maintenance required for chord A At least one of the paths for chord A has been outside the maintenance gain range (XdcrMaintenanceGainRange) or the maintenance SNR range (XdcrMaintenanceSNRRange) for a time period longer than the number of failure free seconds required for updating the chord proportions (PropUpdtSeconds). If this value is TRUE (1), the chord proportion is m will not be updated and the proportional update indicator (IsPropUpdtXettee) will be FALSE (0). This alarm is not set when the average weightend flow velocity (AvgWtdFlowVel) or the flow velocity of the chord (FlowVelA FlowVelD) is below the bw flow limit value (LowFlowLmt). Recommended Actions: 1. If no other transducers are failed or are reporting status alarms, the issue is most likely isolated to this pair of transducers or its cabling. Check the transducer wing for this pair of transducers to make sure connections are secure and wired correctly. 2. Verify that the meter run is not partially full where this top transducer pair is not submerged in the process fluid. 3. Verify the average gain of this transducer pair is not above 908L. The gain value can be read on the Meter Monitor of MeterLink™. If so, remove the transducers, clean and reapply the coupling fluid to the front face of the transducers. If this does not correct the issue, at least one of the transducers are eaking allows, swap the cabling of the failed transducer pair with a pair with equal path lengths. If the alarm remains active for this chord, then the transducers are working properly and there could be a problem with either the cabling or the acquisition board. If this alard, then the chord that was swapped now fails, the issue is with the transducers. 5. If this issue is unresolved, collect a Maintenance Log. Configuration file and Waveform stream file with MeterLink™ and contact your local area Emerson Flow service representative.	R	Y	Y		int			boolean			FALSE (C		
41529	1528	IsXdcrMaintenanceRequired B	Transducer maintenance required for chord B At least one of the paths for chord B has been outside the maintenance gain range (XdcrMaintenanceGainRange) or the maintenance At least one of the paths for chord B has been outside the maintenance gain range (XdcrMaintenanceGainRange) or the maintenance SNR range (XdcrMaintenanceSNRRAnge) for a time period longer than the number of failure free seconds required for updating the chord proportions (PropUpdtSeconds). If this value is TRUE (1), the chord proportion bin will not be updated and the proportional update indicator (IsPropUpdtSeconds). If this value is TRUE (1), the chord proportion bin will not be updated and the proportional update indicator (IsPropUpdtSeconds). This paths in to set when the average weighted flow velocity (AvgWtdFlowVel) or the flow velocity of the chord (FlowVelA FlowVelD) is below the low flow limit value (LowFlowLmt). Recommended Actions: 1. If no other transducers are failed or are reporting status alarms, the issue is most likely isolated to this pair of transducers or its cabling. Check the transducers are failed or are reporting status alarms, the issue connections are secure and wired correctly. 2. Verify that the meter run is not partially full where this top transducer pair is not submerged in the process fluid. 3. Verify the average gain of this transducer pair is not above 90dB. The gain value can be read on the Meter Monitor of MeterLink [™] . If so, remove the transducers, in the pair should be replaced. 4. It transducer the cabling allows, swape the cabling of the failed transducer pair with equal path lengths. If the alarm remains active for this chord, then the chord that was swapped now fails, the issue is with the transducers. 5. If this issue is unresolved, collect a Maintenance Log. Configuration file and Waveform stream file with MeterLink [™] and contact your local area Emerson Flow service representative.	R	Y	Y		int			boolean			FALSE (C	FALSE (0)	TRUE (1)
41530	1529	IsXdcrMaintenanceRequired C	Transducer maintenance required for chord C At least one of the paths for chord C has been outside the maintenance gain range (XdcrMaintenanceGainRange) or the maintenance SNR range (XdcrMaintenanceSNRRange) for a time period longer than the number of failure free seconds required for updating the chord proportions (PropUpdtSeconds). If this value is TRUE (1), the chord proportion bin will not be updated and the proportional update indicator (IsPropUpdtSeconds). If this value is TRUE (1), the chord proportion bin will not be updated and the proportional update indicator (IsPropUpdtSeconds). This pains in on test when the average weighted flow velocity (AvgWtdFlowVel) or the flow velocity of the chord (FlowVelA FlowVelD) is below the low flow limit value (LowFlowLmt). Recommended Actions: 1. If no other transducers are failed or are reporting status alarms, the issue is most likely isolated to this pair of transducers or its cabling. Check the transducer wing for this pair of transducers to make sure connections are secure and wired correctly. 2. Verity that the meter run is not partially full where this top transducer pair is not subwerged in the process fluid. 3. Verity the average gain of this transducer pair is not abve 90618. The gain value can be read on the Meter Monitor of MeterLink [™] . If so, remove the transducers in the pair should be replaced. 4. If transducer the cabling alows, swap the cabling of the failed transducer pair with a pair with equal path lengths. If the alarm remains active for this chord, then the chord that was swapped now flas, the issue is with the transducers. 5. If this issue is unresolved, collect a Maintenance Log. Configuration file and Waveform stream file with MeterLink [™] and contact your local area Ermerson Flow service representative.	R	Y	Y		int	-		boolean			FALSE (C) FALSE (0)	TRUE (1)

Rosemour	nt™ Liqui	d Ultrasonic Firmware: 1.61	Database: 2.29.017												
The below	Modbus	map is applicable for Roser	nount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters		_										
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg Pr	Dt Reg Typ		Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
41531	1530	IsXdcrMaintenanceRequired D	Transducer maintenance required for chord D At least one of the paths for chord D has been outside the maintenance gain range (XdcrMaintenanceGainRange) or the maintenance SNR range (XdcrMaintenanceSNRRange) for a time period longer than the number of failure free seconds required for updating the chord proportions (PropUpdtSeconds). If this value is TRUE (1), the chord proportion bin will not be updated and the proportional update indicator (IBropUpdtSeconds). If this value is TRUE (1), the chord proportion bin will not be updated and the proportional update indicator (IBropUpdtSeconds). If this value is TRUE (1), the chord proportion bin will not be updated and the proportional update indicator (IBropUpdtSeconds). If this value is TRUE (1), the chord proportion bin will not be updated and the proportional update indicator (IBropUpdtSeconds). If this value is TRUE (1), the chord proportion bin will not be updated and the proportional update indicator (IBropUpdtSeconds). If this value is the set when the average weighted to welocity (AvgWtdFlowVel) or the flow velocity of the chord (FlowVelA FlowVelD) is below the low flow limit value (LowFlowLmt). Recommended Actions: 1. If no other transducers are failed or are reporting status alarms, the issue is most likely isolated to this pair of transducers or its cabling. Check the transducer wing for this pair of transducers to make sure connections are secure and wired correctly. 2. Verify that the meter run is not partially full where this top transducer pair is not submerged in the process fluid. 3. Verify that average gain of this transducer pairs is not above 80048. The gain value can be read on the Meter Monitor of MeterLink TM . If so, remove the transducers is, clean and reappy the coupling fluid to the front face of the transducers. If this does not correct the issue, at least one of the transducers is developed and the failed transducer pair with a pair with equal path lengths. If the alarm remains active for this chord, then the transd	R	Y	Y	int			boolean			FALSE (0)	FALSE (0)	TRUE (1)
41532		-	Transducer maintenance required One or more of the chords requires transducer maintenance (IsXdcrMaintenanceRequiredA, IsXdcrMaintenanceRequiredB, IsXdcrMaintenanceRequiredC, IsXdcrMaintenanceRequiredD).	R			int	-	-	boolean	-				
42001	2000	PortAngle	Meter port angle for speed of sound correction The meter port angle for the speed of sound port angle factor correction. The port angle is computed from chord "X" dimension (XA) and pipe ID dimension (PipeDiam). See also the speed of sound correction factor (SOSGeometryCorrFctrA, SOSGeometryCorrFctrB, SOSGeometryCorrFctrC, SOSGeometryCorrFctrD) data points.	R			float	deg	deg	float32	deg				
42003	2002		Chord A weight for calculating average weighted velocity Chord A weight for calculating average weighted velocity (set by the meter based on the device number (DeviceNumber)).	R	Y		float	-	-	float32	÷				
42005	2004		Chord B weight for calculating average weighted velocity Chord B weight for calculating average weighted velocity (set by the meter based on the device number (DeviceNumber)).	R	Y		float	-	-	float32	-				
42007	2006		Chord C weight for calculating average weighted velocity Chord C weight for calculating average weighted velocity (set by the meter based on the device number (DeviceNumber)).	R	Y		float	-	-	float32	-				
42009	2008		Chord D weight for calculating average weighted velocity Chord D weight for calculating average weighted velocity (set by the meter based on the device number (DeviceNumber)).	R	Y		float	-	-	float32	-				
42011		FlowVelA	Flow velocity for chord A Chord A flow velocity.	R			float	m/s	ft/s	float32	m/s				
42013		FlowVelB	Flow velocity for chord B Chord B flow velocity. Flow velocity for chord C	R			float	m/s	ft/s	float32	m/s				
42015		FlowVelC	Flow velocity of crowd C Flow velocity.	R			float	m/s m/s	ft/s ft/s	float32 float32	m/s				
			Chord D flow velocity.												
42019	2018	AvgWtdFlowVel	Average weighted flow velocity (no calibration applied) Average weighted flow velocity (per batch). When all active chords are non-failed, the average weighted flow velocity is a weighted sum of the chord velocity measurements, WtA, WtB, WtC, WtD, where the chord weights are determined by the meter geometry. See also FlowVelA, FlowVelB, FlowVelC, FlowVelD.	R			float	m/s	ft/s	float32	m/s				
42021		DryCalVel	Factory calibrated flow velocity (customer cal not applied) If the high viscosity calibration method selector (HighViscosityMethod) is "Disabled", then this is the result of applying the factory calibration coefficients (A coefficients FwdA0, FwdA1, FwdA2, FwdA3, RevA0, RevA1, RevA2 and RevA3) to the average weighted flow velocity (AvgWtdFlowVel). If the high viscosity calibration method selector (HighViscosityMethod) is "Enabled", then this is the result of applying the zero calibration high viscosity flow offset (FwdA0HighViscosity or RevA0HighViscosity) to the average weighted flow velocity (AvgWtdFlowVel).	R			float	m/s	ft/s	float32	m/s				
42025		AvgFlow	Average flow velocity (dactory and customer cal applied) Average flow velocity (por batch). This is the dry cal velocity (DryCalVel) with any selected flow calibration method (CalMethod) as well as linear meter (actor (LinearMtrFctr) when high viscosity method (High/%cosityMethod) is "Disabled" or linear meter factor high viscosity (LinearMtrFctrHigh/%cosity) when high viscosity method (High/%cosityMethod) is "Enabled" applied.	R			float	m/s	ft/s	float32	m/s				
42027		SndVelA	Speed of sound for chord A Speed of sound for chord A including any adjustment for speed of sound correction factor (SOSGeometryCorrFctrA).	R			float	m/s	ft/s	float32	m/s				
42029		SndVelB	Speed of sound for chord B Speed of sound for chord B including any adjustment for speed of sound correction factor (SOSGeometryCorrFctrB).	R			float	m/s	ft/s	float32	m/s				
42031		SndVelC	Speed of sound for chord C Speed of sound for chord C including any adjustment for speed of sound correction factor (SOSGeometryCorrFctrC).	R			float	m/s	ft/s	float32	m/s				
42033		SndVelD	Speed of sound for chord D Speed of sound for chord D including any adjustment for speed of sound correction factor (SOSGeometryCorrFctrD).	R			float	m/s	ft/s	float32	m/s				
42035		AvgSndVel	Average speed of sound Average speed of sound (per batch) of all non-failed velocity measurement chords.	R	Y		float	m/s	ft/s	float32	m/s				
42041		QCutOff	Volumetric flow rate threshold below which the flow rate is considered zero The volumetric flow rate below which the flow-condition volumetric flow rate (CPiow) is considered zero, chord turbulence values are not calculated (TurbulenceA.TurbulenceD) and 'flow gated' (FLOW_GATED) values are not accumulated. This value is computed by multiplying the flow velocity low cutoff (ZeroCut) by the meter inside pipe area (PipeArea). When the flow rate is above this threshold, the cutoff indicator (IsFicwAboveCutoff) is TRUE (1).	R			float	volume/time	volume/time	float32	m3/hr				
42043	2042	QMeter	Volumetric flow rate (no expansion correction) Volumetric flow rate (no expansion correction). Computed as average flow (AvgFlow) times pipe area (PipeArea).	R			float	volume/time	volume/time	float32	m3/hr				

Rosemou	nt™ Liqu	id Ultrasonic Firmware: 1.61	Database: 2.29.017													
The below	Modbus	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg Pr	ot Reg		lodbus etric Unit	Modbus U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
42045	2044	QMeterValidity	Uncorrected flow-condition volumetric flow rate invalid Uncorrected flow-condition volumetric flow rate invalid. The meter is either not in measurement mode (i.e. no chords acquired) or the number of operating chords is below the minimum number required (MinChord)) or, for a measurement chord, the in-use chord length does not match the calculated chord length (IsChordLengthMismatched). If the high viscosity calibration method selector (HighViscosityMethod) is enabled, then either the profile factor measurement (ProfileFactor) cannot be reliably calculated use to one or more chord failures or the average weighted flow velocity (AvgWtdFlowVel) is below the zero	R	Y		flo	at	-	Unit -	boolean	-	Invalid (FALSE) Valid (TRUE)			
			culture to be ready declared use to the or more crisic or more crisic and ready and the ready and the ready (Argental Servery is below the zero culture first-should (ZeroCut). Recommended Actions: 1. From the alarm list, determine which chords are failed and resolve these alarm(s) first. Resolving the chord failures will clear this alarm. 2. If the issue is unresolved, collect a Maintenance Log with MeterLink™ and contact your local area Emerson Flow service representative.													
			See also: IsAcqMode, IsTooFewOperChords													
42047	2046	StrainPerUnitStress	Calculated strain per unit stress due to pressure Calculated strain per unit stress due to pressure. This is calculated if pressure expansion correction (ExpCorrPressure) is enabled via the Enable for pressure expansion correction (EnableExpCorrPress).	R			flo	at 1	/MPa	1/psi	float32	1/MPa				
42049	2048	ExpCorrPressure	Pressure expansion correction factor Pressure expansion correction factor. If pressure expansion correction is enabled via the Enable for pressure expansion correction (EnableExpCorrPress), then this value, is computed as (1.0 + (3.0 x strain per unit stress (StrainPerUnitStress) x (absolute flow pressure (AbsFlowPressure) - reference pressure (RelPressExpCoef)))), otherwise this value is unity (1.0) Along with temperature expansion correction factor (ExpCorrTemperature), this value is used to compute the corrected flow (QExpCorr)	R			flo	at	-	-	float32	-				
42051	2050	ExpCorrTemperature	from the uncorrected flow (QMeter). Temperature expansion correction factor in three dimensions The temperature expansion correction factor used to correct volumes. If temperature expansion correction is enabled (EnableExpCorrTemp), then this value is calculated, otherwise it is set to 1. This correction factor is computed from the linear expansion coefficient (Linear Expansion Coefficient) (flow temperature (RefrempLinearExpCoef) and the flow temperature (FlowTemperature) (1 + 3 ' linear expansion coefficient ' (flow temperature - reference temperature)) Typically, this correction factor is applied to the volumetric flows (QExpCorr and those derived from it, QFlow and QBase).	R			flo	at	-	-	float32	-				
42053	2052	QExpCorr	Expansion corrected (flow-condition) vol flow Expansion corrected (flow-condition) volumetric flow rate, the volumetric flow rate with no expansion correction (QMeter) with pressure expansion correction (ExpCorrPressure) and temperature expansion correction (ExpCorrTemperature) applied.	R			flo	at volu	ume/time	volume/time	float32	m3/hr				
42055	2054	RefPressExpCoef	Pressure expansion correction reference coefficient Reference coefficient used to compute pressure expansion correction (ExpCorrPressure). Normally this is one atmosphere.	R	Y	Y	r flo	at	MPa	psi	float32	MPa		0.101325	-3.40E+38	3.40E+38
42057	2056	QFlow	Volumetric flow rate at flow condition Flow-condition volumetric flow rate, corrected for flow-condition expansion (QExpCorr).	R			flo	at volu	ume/time	volume/time	float32	m3/hr				
42059	2058	QFlowValidity	Flow-condition volumetric flow rate invalid The meter either has not collected enough information from the chords to make an accurate measurement or the pressure and/or temperature are invalid and meter is performing pressure or temperature expansion corrections on the meter internal diameter. This is an alarm condition that shows the validity of the flow-condition volumetric flow rate (CPFow). The flow-condition volumetric flow rate (CPFow) becomes invalid if the uncorrected flow-condition volumetric flow rate (Variev). The flow-condition volumetric flow rate (CPFow) becomes invalid if the uncorrected flow-condition volumetric flow rate validity (MeterValidity), temperature expansion correction validity (ExpCorrTempValidity), and/or pressure expansion correction validity (ExpCorrTenssValidity) is invalid. Recommended Actions: 1. If the pressure expansion correction validity alarm is present, correcting it may clear this alarm. 2. If the temperature expansion correction validity alarm is present, correcting it may clear this alarm. 3. If the uncorrected flow-condition volumetric flow rate validity validity alarm. 4. If the issue is unresolved, collect a Maintenance Log with MeterLink. [™] and contact your local area Emerson Flow service representative.	R	Y		flo	at	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
42061	2060	ExpCorrTemperatureForVel	Temperature expansion correction factor in a single dimension The temperature expansion correction factor for linear measurements. If temperature expansion correction is enabled (Enable:ExpCortTemp), then this value is caclutated, otherwise it is set to 1. This correction factor is computed from the linear expansion coefficient (LinearExpansionCoef), the reference temperature (RefTempLinearExpCoef) and the flow temperature (FlowTemperature) as: (1 + linear expansion coefficient * (flow temperature - reference temperature)) Typically, this correction factor is applied to the speeds of sound (SndVeIA, SndVeIB, SndVeIC, SndVeID) to correct for changes in the L distances (LA, LB, LC, LD).	R			flo	at	-	-	float32	-				
42065	2064	FlowPressure	Flow-condition pressure This is either gage or absolute pressure depending upon input pressure absolute/gage selector (InputPressureUnit). If flow-condition pressure input selector (EnablePressureInput) is "Fixed", flow-condition pressure = specified (fixed) flow-condition pressure (SpecFlowPressure) when written via a non-ISC 17089 Modbus register or via the HART Command-132 or via DB API protocol. When the flow-condition absolute pressure is written via the ISC 17089 Modbus register or via the HART Command-132 or via DB API protocol. When the flow-condition pressure a specified (fixed) flow-condition pressure - Atmospheric pressure (AtmosphericPress). If flow-condition "Gage", flow-condition pressure = specified (fixed) flow-condition pressure - Atmospheric pressure (AtmosphericPress). If flow-condition pressure input selector is "Live", flow-condition pressure = of the flow-condition pressure (LiveFlowPressure) values for the past five seconds. If flow-condition pressure input selector is "Transmitter Head 1*, flow-condition pressure is read from Transmitter Head 1 of a Dual-Configuration meter (ColocMeterIPAddress).	R	Y		flo	at	MPa	psi	float32	MPa				
42067	2066	AbsFlowPressure	Flow-condition absolute pressure Flow-condition absolute pressure. If input pressure absolute/gage selector (InputPressureUnit) is "Gage", flow-condition absolute pressure = flow-condition pressure (FlowPressure) + specified atmospheric pressure (AtmosphericPress). Otherwise, if input pressure absolute/gage selector (InputPressureUnit) is "Absolute", flow-condition absolute pressure = flow-condition pressure (FlowPressure).	R			flo	at	MPa	psi	float32	MPa				

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The below	Modbus	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg P	Nodbus eg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
42069	2068	PressureValidity	Flow pressure invalid Pressure is invalid if the flow pressure (FlowPressure) is outside the limits defined by the low and high pressure alarm limits (LowPressureAlarm, HighPressureAlarm). Pressure is invalid if the meter is configured to read the flow-condition pressure from Transmitter Head 1 of a Dual-Configuration meter and Dual-Configuration meters are not communicating (IsColocMeterCommErr), either due to incorrect configuration or the Transmitter Head 1 is not reachable. Recommended Actions:	R			float	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
			First Time Startup Issues: 1. Verify that there is voltage to the pressure sensor, either from the terminal on the meter's power supply board or from an external power supply.												
			2. If using an analog pressure device, verify that the pressure sensor is properly wired to the connector TB2-B pins 1 & 2 (ANALOG IN PT- & PT+). 3. Run the Field Setup Wizard in MeterLink [™] to properly configure the input including: Source (Live Analog or Fixed). Min and Max input limits corresponding to 4 mA and 20 An respectively and the Low and High alarm limits. 4. If using an external source to write pressure to the meter, verify that it is properly writing to fixed flow pressure (SpecFlowPressure) in the proper units. The current value will be displayed as Fixed pressure in the Field Setup Wizard in MeterLink [™] . 5. If the meter is configured to read how-condition pressure from Transmitter Head 1 of a Dual-Configuration meter, make sure that Ethernet connection between the Dual-Configuration meters is setup correctly and the Dual-Configuration meter if address (ColcoMeterl/Address) on head 1 is same as the Ethernet IP address (EntIPAddr) of head 2 and vice versa. Check if flow-condition pressure is invalid on Transmitter Head 1 of a Dual-Configuration meter. 6. If the issue is unresolved, collect a Maintenance Log using MeterLink [™] and contact your local area Emerson Flow service representative.												
			Run Time Issues: 1. Adjust the pressure of the process fluid to within alarm limits. 2. If using an analog pressure device and the input reading is 0, check if IsAl2Avail is equal to 1 in the Meter Information dialog in MeterLink [™] . If it is not 1, either the I/O Board has been removed or is damaged. Reinstall or replace the board if this value is 0. 3. If using an analog pressure device, enry that the pressure sensor is working properly. 4. If using an analog pressure device, recheck wiring and switch settings as noted above under First Time Setup Issues. 5. If the external source is writing values to the fixed flow pressure (SpecFivePressure), enry that the external source is still writing valid values without Modbus write errors. 6. Rerun the Field Setup Wizard in MeterLink [™] to verify that the configuration for the pressure input has not changed. 7. If the issue is unresolved, collect Meter Archive Logs (Daily, Hourly, Audit, Alarm and System) and Maintenance Log using MeterLink [™] .												
42071	2070	FlowTemperature	Flow-condition temperature	R	Y		float	deg C	deg F	float32	К		1		
			If flow-condition temperature input selector (EnableTemperatureInput) is "Fixed", flow-condition temperature especified (fixed) flow- condition temperature (SpecFlowTemperature) when written via a Modbus register or via the HART Command-132 or via DB API protocol. Otherwise, if flow-condition temperature input selector is "Live", flow-condition temperature = average of live flow-condition temperature (LiveFlowTemperature) values for the past five seconds. If flow-condition temperature input selector is "Transmitter Head 1", flow-condition temperature is read from Transmitter Head 1 of a Dual-Configuration meter (ColocMeterlPAddress).												
42073	2072	TemperatureValidity	Flow temperature invalid Temperature is invalid if the flow-condition temperature (FlowTemperature) is outside the limits defined by the low and high temperature alarm limits (LowTemperatureAlarm, HighTemperature/Alarm). Temperature is invalid if the meter is configured to read the flow-condition temperature from Transmitter Head 1 of a Dual-Configuration meter and Dual-Configuration meters are not communicating (IsColocMeterCommErr), either due to incorrect configuration or the Transmitter Head 1 is not reachable. Recommended Actions:	R			float	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
			First Time Startup issues: 1. Verify that there is voltage to the temperature sensor, either from the terminal on the meter's power supply board or from an external power supply. 2. If using an analog temperature device, verify that the temperature sensor is properly wired to connector TB2-B pins 3 & 4 (ANALOG IN TT-& TT-).												
			 Run the Field Setup Wizard in MeterLink™ to properly configure the input including: Source (Live Analog or Fixed). Min and Max input limits corresponding to 4 md and 2 DM respectively and the Low and High alarm limits. It using an external source to write temperature to the meter, verify that it is properly writing the fixed flow temperature (SpecFlowTemperature) in the proper units. The current value will be displayed as Fixed temperature in the Field Setup Wizard in Meter Link™. If the meter is configured to read the flow-condition temperature from Transmitter Head 1 of a Dual-Configuration meter, make sure that the Ethernet connection between the Dual-Configuration meters is setup correctly and the Dual-Configuration meter IP address (ColcMeterIPAddress) on head 1 is an eas the Ethernet IP address (Eth1IPAddr) of head 2 and vice versa. Check if the flow-condition temperature in sinvalion or Transmitter Head 1 of a Dual-Configuration meter. If the issue is unresolved, collect a Maintenance Log using MeterLink™ and contact your local area Emerson Flow service representative. 												
			Run Time Issues: 1. Adjust the temperature of the process fluid to within alarm limits. 2. If using an analog temperature device and input reading is 0, check if ISA11Avail is equal to 1 in the Meter Information dialog in MeterLink [™] . If its not 1, either the I/O Board has been removed or it is damaged. Reinstall or replace I/O board if this value is 0. 3. If using an analog temperature device, verify that the temperature servor is working properly. 4. If using an analog temperature device, recheck the wiring and switch settings as noted above under First Time Setup Issues. 5. If an external source is wirling values to the fixed flow temperature (SpecFlowTemperature), verify that the external source is still writing values without Modbus write errors. 6. Revun the Field Setup Wizzeri in MeterLink [™] to verify that the configuration for the temperature input has not changed.												
42075	2074	ReynoldsNumber	7. If the issue is unresolved, collect Meter Archive Logs (Daily, Hourly, Audit, Alarm and System) and Maintenance Log using MeterLink™ Reynolds Number (measure of turbulence) The Reynolds Number is the ratio of inertial forces to viscous forces. A low values indicates laminar flow while a high value indicates turbulent flow.	R			float	-	-	float32	-				
42077 42079		Reserved		R R			float float								
42079 42081		Reserved SpdSndSpread	Speed of sound path spread The difference between the maximum and minimum speeds of sound of the velocity measurement chords (SndVelA, SndVelD). It is not calculated when the average flow velocity (AvgFlow) is not between the minimum flow velocity for CRange test (SndSpdChkMinVel) and the maximum flow velocity for CRange test (SndSpdChkMaxVe).	R			float	m/s	ft/s	float32	m/s				
42083	2082	SndVelDiffA	Chord A speed of sound difference from average speed of sound The chord A speed of sound (SndVelA) difference from the average speed of sound (AvgSndVel).	R	1		float	m/s	ft/s	float32	m/s				
42085	2084	SndVelDiffB	Chord B speed of sound difference from average speed of sound The chord B speed of sound (SndVelB) difference from the average speed of sound (AvgSndVel).	R			float	m/s	ft/s	float32	m/s				
L				1									1		

Rosemou	nt™ Liaui	id Ultrasonic Firmware: 1.61	Database: 2.29.017												
			mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
42087	2086	SndVelDiffC	Chord C speed of sound difference from average speed of sound The chord C speed of sound (SndVelC) difference from the average speed of sound (AvgSndVel).	R			float	m/s	Unit ft/s	float32	m/s				
42089	2088	SndVelDiffD	Chord D speed of sound difference from average speed of sound The chord D speed of sound (SndVelD) difference from the average speed of sound (AvgSndVel).	R			float	m/s	ft/s	float32	m/s				
42091	2090	FlowVelRatioA	Chord A flow velocity ratio Ratio of chord A flow velocity (FlowVelA) to the average flow velocity (AvgFlow). It is calculated as 0 when the uncorrected volumetric flow rate (QMeter) is below the volumetric flow rate threshold (QCutOff).	R			float	-	-	float32	-				
42093	2092	FlowVelRatioB	Chord B flow velocity ratio Ratio of chord B flow velocity (FlowVelB) to the average flow velocity (AvgFlow). It is calculated as 0 when the uncorrected volumetric flow rate (OMeter) is below the volumetric flow rate threshold (QCurOff).	R			float	-	-	float32	-				
42095	2094	FlowVelRatioC	Chord C flow velocity ratio Ratio of chord C flow velocity (FlowVelC) to the average flow velocity (AvgFlow). It is calculated as 0 when the uncorrected volumetric flow rate (QMeter) is below the volumetric flow rate threshold (QCutOff).	R			float	÷	-	float32	-				
42097		FlowVelRatioD	Chord D flow velocity ratio Ratio of chord D flow velocity (FlowVelD) to the average flow velocity (AvgFlow). It is calculated as 0 when the uncorrected volumetric flow rate (QMeter) is below the volumetric flow rate threshold (QCutOff).	R			float	-	-	float32	-				
42105		AccumFlowTime	Accumulated flow time Accumulated time when flow is greater than the cutoff.	R			float	Sec	sec	uint32	Sec				
42107	2106	CurrHourFlowTime	Current hour's flow time Amount of time during the current hour that flow is above the cutoff value.	R	Y		float	min	min	float32	min				
42109	2108	CurrDayFlowTime	Current day's flow time Amount of time during the current day that flow is above the cutoff value. The start of the day is defined by the 'ContractHour' data point.	R	Y		float	min	min	float32	min				
42111	2110	Symmetry	Symmetry measurement Meter measure of symmetry. This compares the upper chord velocities (FlowVeIA + FlowVeIB) to the lower chord velocities (FlowVeIC+ FlowVeID). For perfectly symmetrical flow, this value equals 1.0. See also CrossFlow and ProfileFactor. This is only applicable when meter device number (DeviceNumber) is 3814.	R			float	-	-	float32	-				
42113	2112	CrossFlow	Cross-flow measurement Measure of cross-flow. This compares the flow velocities from one side of the meter (FlowVeIA + FlowVeIC) to the other side (FlowVeIB + FlowVeID). This value is equal to 1.0 when there is no cross-flow. See also Symmetry and ProfileFactor. This is only applicable when meter device number (DeviceNumber) is 3814.	R			float	-	-	float32	-				
42115	2114	TurbulenceA	Chord A turbulence measurement Meter turbulence A is the standard deviation of delta time (SDevDITmA) as a percentage of delta time (DITmA) for chord A. The turbulence value for chord is calculated when the volumetric flow rate (QMeter) is above the cutoff (QCutOff). A value of 0% indicates no turbulence.	R			float	%	%	float32	%				
42117	2116	TurbulenceB	Chord B turbulence measurement Meter turbulence B is the standard deviation of delta time (SDevDItTmB) as a percentage of delta time (DItTmB) for chord B. The turbulence value for chord is calculated when the volumetric flow rate (QMeter) is above the cutoff (QCutOff). A value of 0% indicates no turbulence.	R			float	%	%	float32	%				
42119	2118	TurbulenceC	Chord C turbulence measurement Meter turbulence C is the standard deviation of delta time (SDevDItTmC) as a percentage of delta time (DItTmC) for chord C. The turbulence value for chord is calculated when the volumetric flow rate (QMeter) is above the cutoff (QCutOff). A value of 0% indicates no turbulence.	R			float	%	%	float32	%				
42121	2120	TurbulenceD	Chord D turbulence measurement Meter turbulence D is the standard deviation of delta time (SDevDITmD) as a percentage of delta time (DITmD) for chord D. The turbulence value for chord is calculated when the volumetric flow rate (QMeter) is above the cutoff (QCutOff). A value of 0% indicates no turbulence.	R			float	%	%	float32	%				
42123	2122	ProfileFactor	Profile factor measurement The ratio of the sum of the velocities of the inner chords (FlowVelB and FlowVelC) to the sum of the velocities of the outer chords (FlowVelA and FlowVelD). This ratio is a numerical representation of the velocities taken in cross section in the direction of flow. This is only applicable when meter device number (DeviceNumber) is 3814.	R			float	-	-	float32	-				
42125	2124	SwirlAngle	Swirt angle measurement The arctangent of the ratio of the tangential velocity, computed from the individual chordal velocities (FlowVelA, FlowVelB, FlowVelC and FlowVelD, the average flow velocity (AvgFlow). See also CrossFlow, Symmetry and ProfileFactor. This is only applicable when meter device number (DeviceNumber) is 3814 and the high viscosity calibration method selector (HighViscosityMethod) is disabled.	R			float	deg	deg	int8	deg				
42129	2128	Reserved		R			float								
42131 42133	2130 2132	Reserved Reserved		R	\vdash		float float								I
42135	2134	EtaStatusBA	Peak switch detection status - BA (3814 meters only) Peak switch detection status - BA (3814 meters only).	R			float	-	-	uint8	-	Success (0) Not a BG style meter (1) Invalid chord lengths (2) Chord inactive (3) Speed of sound unusable (4) No valid sequences (5)			
42137	2136	EtaStatusCA	Peak switch detection status - CA (3814 meters only) Peak switch detection status - CA (3814 meters only).	R			float	-	-	uint8	-	Success (0) Not a BG style meter (1) Invalid chord lengths (2) Chord inactive (3) Speed of sound unusable (4) No valid sequences (5)			
42139	2138	EtaStatusBD	Peak switch detection status - BD (3814 meters only) Peak switch detection status - BD (3814 meters only).	R			float	-	-	uint8	-	Success (0) Not a BG style meter (1) Invalid chord lengths (2) Chord inactive (3) Speed of sound unusable (4) No valid sequences (5)			
42141	2140	EtaStatusCD	Peak switch detection status - CD (3814 meters only) Peak switch detection status - CD (3814 meters only).	R			float	-	-	uint8	-	Success (0) Not a BG style meter (1) Invalid chord lengths (2) Chord inactive (3) Speed of sound nunusable (4) No valid sequences (5)			

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			emount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
	moubus		Description	T						Modbus		1				
Holding Register Number	Reg Num	Label		Acc	NV	Cnfg F		lodbus eg Type	Modbus Metric Unit	U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
42203	2202	LiveFlowPressure	Live flow-condition pressure This is the live flow pressure calculated from analog input 2 (Al2Input) and applying the calibration coefficients (LiveFlowPressureOffset and LiveFlowPressureGain). The flow-condition pressure (FlowPressure) can be set to this value depending on the selector (EnablePressureInput). This value is logged in the alarm log depending on the low and high pressure alarm limits (LowPressureAlarm, HighPressureAlarm). The connectors for this input are designated as ANALOG IN PT- and PT+.	R	Y			float	MPa	psi	float32	MPa				
42205	2204	LiveFlowTemperature	Live flow-condition temperature This is the live flow temperature calculated from analog input 1 (Al11nput) and applying the calibration coefficients (LiveFlowTemperatureOfsteand LiveFlowTemperatureGain). The flow-condition temperature (FlowTemperature) can be set to this value depending on the selector (EnableTemperatureInput). This value is bogged in the alarm log depending on the bw and high temperature alarm limits (LowTemperatureAlarm, HighTemperatureAlarm). The connectors for this input are designated as ANALOG IN TT- and TT+.	R	Y			float	deg C	deg F	float32	к				
42207		Reserved		R				float								
42209 42217		Reserved IsCalOn	Identifies when the meter is in the calibration mode	R R				float float	-	-	boolean	-	Off (FALSE)			
	224.0	la CalOs Datab	Identifies when the meter is in the calibration mode.	Р				flagt					On (TRUE)			
42219	2218	IsCalOnBatch	Identifies when the CalVol and CalTime data points are being updated Identifies when the CalVol and CalTime data points are being updated.	R				float			boolean		Batch calibration off (FALSE) Batch calibration on (TRUE)			
42221		CalTime	Calibration elapsed time Calibration elapsed time. This is the elapsed time while the CalFlag data point is set to TRUE (1) or the DI1 gates the calibration with ISD11UsedForCal as indicated by IsCalOnBatch. Note that while the native units UNIT_MKIIL_PULSES are counted in 1000 pulses/second the Modbus UNIT_MKIIL_PULSE_SEC are returned as seconds in floating point format.	R				float	Sec	sec	float32	Time pulses				
42223	2222	CalVol	Calibration accumulated uncorrected volume. Calibration accumulated uncorrected volume. This is the accumulation of the uncorrected volume while the CalFlag data point is set to TRUE (1) or the D11 gates the calibration with IsDi1UsedForCal as indicated by IsCalOnBatch.	R				float	volume	volume	float32	m3				
42241	2240	ZeroFlowCalStatus	Zero-flow calibration status Current zero-flow calibration status indicator.	R				float	-	-	uint8	-	Inactive (0) In progress (1) Completed successfully (2) Failed - Chord failure (3) Failed - Too large offset (4) Failed - Too large offset (4) Failed - Californiation method change (6)			
42243	2242	ZeroFlowCalProgress	Zero-flow calibration progress (percent complete) Zero-flow calibration progress (percent complete).	R				float	%	%	uint8	%				1
42245	2244	ZeroFlowCalResult	Zero-flow calibration result (proposed offset) Zero-flow calibration result. This value is only valid and can only be accepted when the zero-flow calibration status (Zero-FlowCalStatus) is "Completed Successfully." When accepted, this value is used to update the dry calibration forward and reverse flow A0 coefficients (FwdA0, RevA0). This value is not retained through a power cycle.	R				float	m/s	ft/s	float32	m/s				
42247	2246	SndVelDiffPctA	Percentage of chord A speed of sound difference from average speed of sound The percentage of chord A speed of sound (SndVelA) difference from the average speed of sound (AvgSndVel).	R				float	%	%	float32	%				
42249	2248	SndVelDiffPctB	Percentage of chord B speed of sound difference from average speed of sound (NgSNetG). The percentage of chord B speed of sound (SndVelB) difference from the average speed of sound (AvgSndVel).	R				float	%	%	float32	%				·
42251	2250	SndVelDiffPctC	Percentage of chord C speed of sound difference from average speed of sound The percentage of chord C speed of sound (SndVelC) difference from the average speed of sound (AvgSndVel).	R				float	%	%	float32	%				1
42253	2252	SndVelDiffPctD	Percentage of chord D speed of sound difference from average speed of sound The percentage of chord D speed of sound (SndVeID) difference from the average speed of sound (AvgSndVeI).	R				float	%	%	float32	%				
42261	2260	SNRatioDB	Minimum signal-to-noise threshold in decibels Represents the conversion of the minimum signal-to-noise threshold (SNRatio) to decibels by multiplying ten times the log base ten.	R				float	dB	dB	float32	dB				
42269	2268	PeakSwitchDetectMode	Peak switch detection mode Determines what action to take if a peak switch is detected by the pattern of computed eta values (EtaBA, EtaBD, EtaCA, EtaCD). Both the "Status Ohy" and the "Status and Discard" modes set the peak switch detection indicators (IsPeakSwitchDetectedA, IsPeakSwitchDetectedB, IsPeakSwitchDetectedC, IsPeakSwitchDetectedD). If "Status and Discard" is selected the waveforms with peak switching detected will not be included in the flow calculations. Discarded measurement data may cause a chord to be considered failed if the percentage of good measurements fails below the minimum percentage good threshold (MinPctGood). If "Disabled" no status will be updated nor waveforms discarded.	RW	Y	Y	Y	float	-	-	uint8	-	Disabled (0) Status Only (1) Status and Discard (2)	0	0	2
42271	2270	IsPeakSwitchDetected	Peak switch detected A peak switch timing error was detected on at least one chord (IsPeakSwitchDetectedA, IsPeakSwitchDetectedB, IsPeakSwitchDetectedC, IsPeakSwitchDetectedD).	R				float	-	-	boolean	-				1
42273	2272	IsPeakSwitchDetectedA	Peak switch detected for chord A A peak switch timing error was detected in the measurement data, if the peak switch detect mode (PeakSwitchDetectMode) is set to display status. If the peak switch detect mode (PeakSwitchDetectMode) is configured to discard data, then this value indicates measurement data from one or more transducer firing was discarded due to a peak switch timing error. If this value is TRUE (1), the chord proportion bin update will not be allowed and the proportional update indicator (SlPropUpdAtckiev) will be FALSE (0). Discarded measurement data may cause a chord to be considered failed if the percentage of good measurements fails below the minimum percentage good threshold (MinPetGood). The indication is suppressed if the average of path performance (PctGoodA1, PctGoodA2) is above the chord performance status suppression limit (PerfStatusSuppressLmt). Recommended Actions: 1. This alarm is typically disabled. If it was enabled unintentionally then the peak switch detect mode (PeakSwitchDetectMode) should be set to disable the alarm again. 2. Verify that the transducers are working properly. All chords should have similar dB gains and low noise levels. If the meter is reporting SNR below minimum or noise exceeded limit for any chords, address those alarms first. 3. Adjusting the tracking parameters may address this issue but we do not recommend changes without input from a Emerson Flow service representative. Collect a Maintenance Log, a Waveform stream file and configuration file with MeterLink [™] while the meter is experiencing the issue and contact your local area Ermerson Flow service representative.	R				float	-	-	boolean	-				

Rosemou	nt™ Liqu	id Ultrasonic Firmware: 1.6	1 Database: 2.29.017											
The below	Modbu	map is applicable for Ros	emount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters											
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg P	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Maximum Value (native unit)
42275	2274	IsPeakSwitchDetectedB	Peak switch detected for chord B A peak switch timing error was detected in the measurement data, if the peak switch detect mode (PeakSwitchDetectMode) is set to display status. If the peak switch detect mode (PeakSwitchDetectMode) is configured to discard data, then this value indicates measurement data from one or more transducer firing was discarded due to a peak switch timing error. If this value is TRUE (1), the chord proportion bin update will not be allowed and the proportional update indicator (slPropUpdtActive) will be FALSE (0). Discarded measurement data may cause a chord to be considered failed if the percentage of good measurements fails below the minimum percentage good threshold (MinPetGood). The indication is suppressed if the average of path performance (PctGoodB1, PctGoodB2) is above the chord performance status suppression limit (PerfStatusSuppressLmt). Recommended Actions: 1. This alarm is typically disabled. If it was enabled unintentionally then the peak switch detect mode (PeakSwitchDetectMode) should be set to disable the alarm again. 2. Verify that the transducers are working properly. All chords should have similar dB gains and low noise levels. If the meter is reporting SNR below minimum or noise exceeded limit for any chords, address those alarms first. 3. Adjusting the tracking parameters may address this issue but we do not recommend changes without input from a Emerson Flow service representative. Collect a Maintenance Log, a Waveform stream file and configuration file with MeterLink™ while the meter is experiencing the issue and contact your local area Emerson Flow service representative.	R			float		-	boolean	-			
42277	2276	IsPeakSwitchDetectedC	Peak switch detected for chord C A peak switch immig error was detected in the measurement data, if the peak switch detect mode (PeakSwitchDetectMode) is set to display status. If the peak switch detect mode (PeakSwitchDetectMode) is configured to discard data, then this value indicates measurement data from one or more transducer fining was discarded due to a peak switch timing error, if this value indicates measurement data from one or more transducer fining was discarded due to a peak switch timing error, if this value indicates measurement data may cause a chord to be considered failed if the percentage of good measurements fails below the minimum percentage good threshold (MinPetGood). The indication is suppressed if the average of path performance (PctGoodC1, PctGoodC2) is above the chord performance status suppression limit (PerfStatusSuppressLmt). Recommended Actions: 1. This alarm is typically disabled. If it was enabled unintentionally then the peak switch detect mode (PeakSwitchDetectMode) should be set to disable the alarm again. 2. Verify that the transducers are working properly. All chords should have similar dB gains and low noise levels. If the meter is reporting SNR below minimum or noise exceeded limit for any chords, address those alarms first. 3. Adjusting the tracking parameters may address this issue but we do not recommend changes without input from a Emerson Flow service representative. Collect a Maintenance Log, a Waveform stream file and configuration file with MeterLink™ while the meter is experiencing the issue and contact your local area Emerson Flow service representative.	R			float		-	boolean	•			
42279	2278	IsPeakSwitchDetectedD	Peak switch detected for chord D A peak switch timing error was detected in the measurement data, if the peak switch detect mode (PeakSwitchDetectMode) is set to display status. If the peak switch detect mode (PeakSwitchDetectMode) is configured to discard data, then this value indicates measurement data from one or more transducer firing was discarded due to a peak switch timing error. If this value is TRUE (1), the chord proportion bin update will not be allowed and the proportional update indicator (slPropUpdAtckee) will be FALSE (0). Discarded measurement data may cause a chord to be considered failed if the percentage of good measurements fails below the minimum percentage good threshold (MinPetGood). The indication is suppressed if the average of path performance (PctGoodD1, PctGoodD2) is above the chord performance status suppression limit (PerfStatusSuppressLmt). Recommended Actions: 1. This alarm is typically disabled. If it was enabled unintentionally then the peak switch detect mode (PeakSwitchDetectMode) should be set to disable the alarm again. 2. Verify that the transducers are working properly. All chords should have similar dB gains and low noise levels. If the meter is reporting SNR below minimum or noise exceeded limit for any chords, address those alarms first. 3. Adjusting the tracking parameters may address this issue but we do not recommend changes without input from a Ernerson Flow service representative. Collect a Maintenance Log, a Waveform stream file and configuration file with MeterLink™ while the meter is experiencing the issue and contact your local area Ernerson Flow service representative.	R			float	-	-	boolean	-			
42281	2280	EtaBA	Chord B to chord A peak switch detector value Value computed by comparing chords A and B which is used to detect peak switching as indicated by IsPeakSwitchDetectedA, IsPeakSwitchDetectedB, IsPeakSwitchDetectedC and IsPeakSwitchDetectedD. The status of this comparison is found in EtaStatusBA. This value is computed for BG style meters only. Note: Starting with firmware version (CPUBdSwVer) 1.18 the value is normalized based on the transducer frequency (XdcrFreq) and may be substantially different from the value reported by earlier firmware versions.	R			float	-	-	float32	-			
42283	2282	EtaCA	Chord C to chord A peak switch detector value Value computed by comparing chords A and C which is used to detect peak switching as indicated by IsPeakSwitchDetectedA, IsPeakSwitchDetectedB, IsPeakSwitchDetectedC and IsPeakSwitchDetectedD. The status of this comparison is found in EtaStatusCA. This value is computed for BG style meters only. Note: Starting with firmware version (CPUBdSwVer) 1.18 the value is normalized based on the transducer frequency (XdcrFreq) and may be substantially different from the value reported by earlier firmware versions.	R			float	-	-	float32	-			
42285 42287		EtaBD EtaCD	Chord B to chord D peak switch detector value Value computed by comparing chords B and D which is used to detect peak switching as indicated by IsPeakSwitchDetectedA, IsPeakSwitchDetectedB, IsPeakSwitchDetectedC and IsPeakSwitchDetectedD. The status of this comparison is found in EtaStatusBD. This value is computed for BG style meters only. Note: Starting with firmware version (CPUBdSwVer) 1.18 the value is normalized based on the transducer frequency (XdcrFreq) and may be substantially different from the value reported by earlier firmware versions. Chord C to chord D peak switch detector value Value computed by comparing chords C and D which is used to detect peak switching as indicated by IsPeakSwitchDetectedA, IsPeakSwitchDetectedB, IsPeakSwitchDetectedC and BrPeakSwitchDetectedD. The status of this comparison is found in EtaStatusCD. This value is computed for SG style meters only. Note: Starting with firmware version (CPUBdSwVer) 1.18 the value is normalized based on the transducer frequency (XdcrFreq) and may be substantiatly different from the twalue reported of a stift immare versions.	R			float	-	-	float32 float32	-			

Rosemou	nt™ Liqu	id Ultrasonic Firmware: 1.61	Database: 2.29.017													
The below	Modbus	s map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
42289	2288	XdcrMaintenanceGainRang e	Gain range for transducer maintenance The maximum allowed difference between a path's gain (GainA1GainD2) in dB from the lowest gain path. If chordal configuration (ChordalConfig) set to "BG", the gain value of inner chord path is compared with lowest path gain from the inner chords (Chord B, Chord C) and the gain value of outer chord path is compared with lowest gain from the other chords (Chord A, Chord D). If chordal configuration set to "Dual-X" or "NA", the path gain is compared with lowest gain path from all meter type chords. This check is used to set the chord's transducer maintenance required indicator (IsXdcrMaintenanceRequiredAIsXdcrMaintenanceRequiredD).	RW	Y	Y	Y	float	gain (dB)	Unit gain (dB)	float32	gain (dB)		20	1	40
42291	2290	XdcrMaintenanceSNRRang e	SNR range for transducer maintenance The maximum allowed difference between a path's SNR (SNRA1. SNRD2) in dB from the highest SNR of any other path. If chordal configuration (ChordalConfig) set to "BG", the SNR value of inner chord path is compared with highest path SNR from the inner chords (Chord G, Chord C) and the SNR value of outer chord path is compared with highest SNR from the other chords (Chord A, Chord D). If chord a Configuration set to "Dual" or "NA", the path SNR is compared with highest SNR path from all meter type chords. This check is used to set the chord's transducer maintenance required indicator (IsXdcrMaintenanceRequiredAIsXdcrMaintenanceRequiredD).	RW	Y	Y	Y	float	dB	dB	float32	dB		20	1	3.40E+38
42301	2300	DataQlty	Flow data quality Flow data quality indicator. This is a bitfield consisting of multiple Boolean data point values and indicates the meter is operating at less than optimal performance.	R	*	*	*	long	-	-	bitfield	-	0 IsHardFailedA (NV) 1 IsHardFailedB (NV) 2 IsHardFailedC (NV) 3 IsHardFailedD (NV) 16 IsTooFevOperChords (NV) 17 IsMeterVelAboveMaxLmt (NV)			
42303	2302	TimeLapse2	Accumulated time pulses (1000 pulses/sec) Accumulated time pulses (1000 pulses/sec).	R	Y			long	sec	sec	uint64	Time pulses				
42305	2304	PosVolUncorr	Forward uncorrected volume Accumulation of uncorrected volume in the forward direction. Note that this value is incremented using internal units which may be different than those displayed and rolls over at an unsigned 64 bit integer (18,446,744,073,709,551,615 liters). However, when read via Modbus, the value rolls from 999,999,999 to 0.	R	Y			long	volume (lower)	volume (lower)	uint64	L				
42307		PosVolUncorr	Forward uncorrected volume Accumulation of uncorrected volume in the forward direction. Note that this value is incremented using internal units which may be different than those displayed and rolls over at an unsigned 64 bit integer (18,446,744,073,709,551,615 liters). However, when read via Modbus, the value rolls from 999,999,999 to 0.	R	Y			long	volume (overflow)	volume (overflow)	uint64	L				
42309	2308	NegVolUncorr	Reverse uncorrected volume Accumulation of uncorrected volume in the reverse direction. Note that this value is incremented using internal units which may be different than those displayed and rolls over at an unsigned 64 bit integer (18,446,744,073,709,551,615 liters). However, when read via Modbus, the value rolls from 999,999,999 to 0.	R	Y			long	volume (lower)	volume (lower)	uint64	L				
42311		NegVolUncorr	Reverse uncorrected volume Accumulation of uncorrected volume in the reverse direction. Note that this value is incremented using internal units which may be different than those displayed and rolls over at an unsigned 64 bit integer (18,446,744,073,709,551,615 liters). However, when read via Modbus, the value rolls from 999,999,999 to 0.	R	Y			long	volume (overflow)	volume (overflow)	uint64	L				
42313		PosVolFlow	Forward flow-condition volume Accumulation of flow-condition volume in the forward direction. Note that this value is incremented using internal units which may be different than those displayed and rolls over at an unsigned 64 bit integer (18,446,744,073,709,551,615 liters). However, when read via Modbus, the value rolls from 999,999,999 to 0.	R	Y			long	volume (lower)	volume (lower)	uint64	L				
42315		PosVolFlow	Forward flow-condition volume Accumulation of flow-condition volume in the forward direction. Note that this value is incremented using internal units which may be different than those displayed and rolls over at an unsigned 64 bit integer (18,446,744,073,709,551,615 liters). However, when read via Modbus, the value rolls from 999,999,999 to 0.	R	Y			long	volume (overflow)	volume (overflow)	uint64	L				
42317		NegVolFlow	Reverse flow-condition volume Accumulation of flow-condition volume in the reverse direction. Note that this value is incremented using internal units which may be different than those displayed and rolls over at an unsigned 64 bit integer (18,446,744,073,709,551,615 liters). However, when read via Modbus, the value rolls from 999,999,999 to 0.	R	Y			long	volume (lower)	volume (lower)	uint64	L				
42319		NegVolFlow	Reverse flow-condition volume Accumulation of flow-condition volume in the reverse direction. Note that this value is incremented using internal units which may be different than those displayed and rolls over at an unsigned 64 bit integer (18,446,744,073,709,551,615 liters). However, when read via Modbus, the value rolls from 999,999,999 to 0.	R	Y			long	volume (overflow)	volume (overflow)	uint64	L				
42361	2360	TrigDeltaPosVolFlow	Amount of forward flow-condition volume between the last two delta volume triggers The value is updated only while the update triggered delta volumes control (DoUpdtTrigDeltaVols) is TRUE (1).	R	Y			long	volume (lower)	volume (lower)	float64	L				
42363	2362	TrigDeltaPosVolFlow	Amount of forward flow-condition volume between the last two delta volume triggers The value is updated only while the update triggered delta volumes control (DoUpdtTrigDeltaVols) is TRUE (1).	R	Y			long	volume (overflow)	volume (overflow)	float64	L				
42365	2364	TrigDeltaNegVolFlow	Amount of reverse flow-condition volume between the last two delta volume triggers The value is updated only while the update triggered delta volumes control (DoUpdtTrigDeltaVols) is TRUE (1).	R	Y			long	volume (lower)	volume (lower)	float64	L				
42367	2366	TrigDeltaNegVolFlow	Amount of reverse flow-condition volume between the last two delta volume triggers The value is updated only while the update triggered delta volumes control (DoUpdtTrigDeltaVols) is TRUE (1).	R	Y			long	volume (overflow)	volume (overflow)	float64	L				
42401	2400	TrigDeltaPosVolFlow	Amount of forward flow-condition volume between the last two delta volume triggers The value is updated only while the update triggered delta volumes control (DoUpdTrigDeltaVols) is TRUE (1).	R	Y			float	volume	volume	float64	L				
42403	2402	TrigDeltaNegVolFlow	Amount of reverse flow-condition volume between the last two delta volumes control (DoUpd11)genavols) is TRUE (1). The value is updated only while the update triggered delta volumes control (DoUpd11)genavols) is TRUE (1).	R	Y			float	volume	volume	float64	L				
42442	2441	AvgPctGood	The value is updated only while the update triggered detta volumes control (UoUpd1 ngUeta vols) is TRUE (1). Performance of active measurement chords The average performance of the paths of active velocity measurement chords (PctGoodA1, PctGoodA2, PctGoodB1, PctGoodB2, PctGoodC1, PctGoodC2, PctGoodD1, and PctGoodD2). Any diagnostic chord is not included in the average.	R				int	%	%	uint8	%				
42443	2442	PctGoodA	Average performance of chord A The average performance of chord A indicated as the percentage of good signals in those received from upstream and downstream transducers in a batch. It is calculated as average of performance of path A1 (PctGoodA1) and performance of path A2 (PctGoodA2).	R				int	%	%	uint8	%				
42444	2443	PctGoodB	Average performance of chord B The average performance of chord B indicated as the percentage of good signals in those received from upstream and downstream transducers in a batch. It is calculated as average of performance of path B1 (PctGoodB1) and performance of path B2 (PctGoodB2).	R				int	%	%	uint8	%				
42445	2444	PctGoodC	Average performance of chord C The average performance of chord C indicated as the percentage of good signals in those received from upstream and downstream transducers in a batch. It is calculated as average of performance of path C1 (PctGoodC1) and performance of path C2 (PctGoodC2).	R				int	%	%	uint8	%				
42446	2445	PctGoodD	Average performance of chord D The average performance of chord D indicated as the percentage of good signals in those received from upstream and downstream transducers in a batch. It is calculated as average of performance of path D1 (PctGoodD1) and performance of path D2 (PctGoodD2).	R				int	%	%	uint8	%				

Rosemou	nt™ Liqui	id Ultrasonic Firmware: 1.61	Database: 2.29.017													
The below	Modbus	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
42451	2450	PctGoodA1	Performance of path A1 The performance of path A1 indicated as the percentage of good signals in those received from that transducer in a batch. See also the minimum percentage of good measurements for working chord (MinPctGood).	R				int	%	%	uint8	%				
42452		PctGoodA2	Performance of path A2 The performance of path A2 indicated as the percentage of good signals in those received from that transducer in a batch. See also the minimum percentage of good measurements for working chord (MinPctGood).	R				int	%	%	uint8	%				
42453		PctGoodB1	Performance of path B1 The performance of path B1 indicated as the percentage of good signals in those received from that transducer in a batch. See also the minimum percentage of good measurements for working chord (MinPctGood).	R				int	%	%	uint8	%				
42454		PctGoodB2	Performance of path B2 The performance of path B2 The performance of path B2 minimum percentage of good measurements for working chord (MinPctGood).	R				int	%	%	uint8	%				
42455		PctGoodC1	Performance of path C1 The performance of path C1 The performance of path C1 indicated as the percentage of good signals in those received from that transducer in a batch. See also the minimum percentage of good measurements for working chord (MinPctGood).	R				int	%	%	uint8	%				
42456		PctGoodC2	Performance of path C2 The performance of path C2 indicated as the percentage of good signals in those received from that transducer in a batch. See also the minimum percentage of good measurements for working chord (MinPctGood).	R				int	%	%	uint8	%				
42457		PctGoodD1	Performance of path D1 The performance of path D1 indicated as the percentage of good signals in those received from that transducer in a batch. See also the minimum percentage of good measurements for working chord (MinPctGood).	R				int	%	%	uint8	%				
42458 42459		PctGoodD2 StatusA	Performance of path D2 The performance of path D2 indicated as the percentage of good signals in those received from that transducer in a batch. See also the minimum percentage of good measurements for working chord (MinPctGood). Chord A status	R				int	%	%	uint8 bitfield	%	0 DidExceedMaxNoiseA (NV)			
42459			Chord A status Chord A status indicator. This is a bitfield consisting of multiple Boolean data point values.	ĸ				int	-		Diuleid		0 DisCustenina NoiseA (NV) 2 DdT mDevChkFala(NV) 2 DdT mDevChkFala(NV) 5 IsXdcMaintenanceRequired (NV, Cnfg) 6 IsStackinghtompleteA (NV) 7 IsChordLengthMismatchedA (NV) 9 IsSigDityBadA (NV) 10 IsSigDistrotedA (NV) 11 IsPeakSwitchDetectedA (NV) 12 IsMeasShofpRangeA (NV) 13 IsBatchinactiveA (NV) 13 IsBatchinactiveA (NV) 14 IsFailedTostachA (NV) 15 IsAcqMode (NV)			
42460	2459	StatusB	Chord B status Chord B status indicator. This is a bitfield consisting of multiple Boolean data point values.	R	*	*	*	int		-	bitfield	-	DidExceedMaxNoseB (NV) 1 IsSNRTooLowB (NV) 2 DidTmDexChkrailB (NV) 4 DidDITmChKrailB (NV) 5 IsXdrAMainenanceRequiredB (NV, Cnfg) 6 IsStackingIncompleteB (NV) 7 IsChordLengthMismatchedB (NV) 9 IsSigClipbedB (NV) 10 IsSigDistortedB (NV) 11 IsPeakSwitchDetctedB (NV) 12 IsMasSAndSpRangeB (NV) 13 IsBatchInactiveB (NV) 14 IsFailedForBatchB (NV) 14 IsFailedForBatchB (NV) 15 IsAcqMode (NV)			
42461	2460	StatusC	Chord C status Chord C status indicator. This is a bitfield consisting of multiple Boolean data point values.	R	*	*	*	int	-	-	bitfield	-	0 DidExceedMaxNoiseC (NV) 1 IsSNRTooLowC (NV) 2 DidTmDcVkFailC (NV) 4 DidDITmChKFailC (NV) 5 IsXdarMainenanceRequiredC (NV, Cntg) 6 IsStackingIncompleteC (NV) 7 IsChordLengthMismatchedC (NV) 8 IsSigClippedC (NV) 9 IsSigDithedC (NV) 10 IsSigDistrotedC (NV) 11 IsPeakSwitchDetectedC (NV) 12 IsMeasShopRangeC (NV) 13 IsBatchinactiveC (NV) 13 IsBatchinactiveC (NV) 14 IsFailedToatchC (NV) 15 IsAcqMode (NV)			
42462	2461	StatusD	Chord D status Chord D status indicator. This is a bitfield consisting of multiple Boolean data point values.	R	*	*	*	int	-	-	bitfield	-	0 DidExceedMaxNoiseD (NV) 1 IsSNRTooLowD (NV) 2 DidTmDCrkRailD (NV) 4 DidDITmCrkRailD (NV) 5 IsXdrdMainenanceRequiredD (NV, Cnfg) 6 IsStackingIncompleteD (NV) 7 IsChordLengthMismatchedD (NV) 8 IsSigClippedD (NV) 9 IsSigQlistotedD (NV) 10 IsSigQlistotedD (NV) 11 IsPeaKswitchDetectedD (NV) 11 IsPeaKswitchDetectedD (NV) 13 IsBatchinactiveD (NV) 14 IsFailedTostachD (NV) 15 IsAcqMode (NV)			

Rosemou	nt™ Liq	uid Ultrasonic Firmware: 1.	61 Database: 2.29.017													
The below	v Modbu	s map is applicable for Ro	semount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg I	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
42463	246	SystemStatus	General system status General system status indicator. This is a bitfield consisting of multiple Boolean data point values.	R	*	*	*	int	-	-	bitfield	-	1 AreSwComponentsIncompatible (NV) 2 DidPowerFail (NV, Cnfg) 3 IsAcqModuleIncompatible (NV) 4 IsXdarFiringSyncError (NV) 5 IsEstimatedFlowVelocityInUse (NV) 6 DidWarmStart (NV, Cnfg) 7 IsColocMeterQFlowRangeErr (NV) 9 IsMeterVeIAboveMaxLmt (NV) 14 IsReverseFlowDetected (NV) 15 WatchDogReset (NV, Cnfg)			
42464	246	3 FlowDirection	Flow direction indicator.	R				int	-	-	boolean	-	Reverse (FALSE) Forward (TRUE)			
42465	246	QMeterValidity	Uncorrected flow-condition volumetric flow rate invalid The volumetric flow rate (no expansion correction) is invalid. The meter is either not in measurement mode (i.e. no chords acquired) or the number of operating chords is below the minimum number required (MinChord)) or, for a measurement chord, the in-use chord length does not match the calculated chord length (IsChordLengthMismatched). If the high viscosity calibration method selector (HighViscosityMethod) is enabled, then either the profile factor measurement (ProfileFactor) cannot be reliably calculated due to one or more chord failures or the average weighted flow velocity (AvgWtdFlowVel) is below the zero cutoff threshold (ZeroCut). Recommended Actions: 1. From the alarm list, determine which chords are failed and resolve these alarm(s) first. Resolving the chord failures will clear this alarm. 2. If the issue is unresolved, collect a Maintenance Log with MeterLink [™] and contact your local area Emerson Flow service representative. See also: IsAcqMode, IsTooFewOperChords	R	Y			int	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
42466	246	GRFlowValidity	Flow-condition volumetric flow rate invalid The meter either has not collected enough information from the chords to make an accurate measurement or the pressure and/or temperature are invalid and meter is performing pressure or temperature expansion corrections on the meter internal diameter. This is an alarm condition that shows the validity of the flow-condition volumetric flow rate (OFIow). The flow-condition volumetric flow rate (OFIow) becomes invalid if the uncorrected flow-condition volumetric flow rate validity (QMeter/Validity), temperature expansion correction validity (ExpCorrTempValidity), and/or pressure expansion correction validity (ExpCorrPressValidity) is invalid. Recommended Actions: 1. If the pressure expansion correction validity alarm is present, correcting it may clear this alarm. 2. If the temperature expansion correction validity alarm is present, correcting it may clear this alarm. 3. If the uncorrected flow-condition volumetric flow rate validity alarm is present, correcting it may clear this alarm. 4. If the issue is unresolved, collect a Maintenance Log with MeterLink [™] and contact your local area Emerson Flow service representative.	R	Y			int	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
42467	246	6 MeterStatusLevel	Overall meter status indication This indicates the highest meter status, green (0), yellow(1) or red (2) currently in the meter.	R				int	-	-	uint8	-	Green (0) Yellow (1) Red (2)			
42468		7 IsQFlowInvalid PressureValidity	Flow-condition volumetric flow rate invalid This indicates when the flow-condition volumetric flow rate (QFlow) is invalid. See also: QFlowValidity Flow pressure invalid	R				int	-	-	boolean	-	Invalid (TRUE) Valid (FALSE) Invalid (FALSE)			
			Pressure is invalid if the flow pressure (FlowPressure) is outside the limits defined by the low and high pressure alarm limits (LowPressureAlarm, HighPressureAlarm), Pressure is invalid if the meter is configured to read the flow-condition pressure from Transmitter Head 1 of a Dual-Configuration meter and Dual-Configuration meters are not communicating (IsColocMeterCommErr), either due to incorrect configuration or the Transmitter Head 1 is not reachable. Recommended Actions: First Time Startup Issues: 1. Verity that there is voltage to the pressure sensor, either from the terminal on the meter's power supply board or from an external power supply. 2. If using an analog pressure device, verify that the pressure sensor is properly wired to the connector TB2-B pins 1 & 2 (ANALOG IN PT- & PT+). 3. Run the Field Setup Wizard in MeterLink™ to properly configure the input including: Source (Live Analog or Fixed), Min and Max input limits corresponding to 4 mA ad 20 mA respectively and the Low and High alarm limits. 4. If using an external source to write pressure to the meter, verify that it is properly writing to fixed flow pressure (SpecFlowPressure) in the proper units. The current value will be displayed as Fixed pressure in the Field Setup Wizard in MeterLink™. 5. If the meter is configured to read flow-condition pressure from Transmitter Head 1 of a Dual-Configuration meter, make sure that Ethernet connection between the Dual-Configuration meters is setup correctly and the Dual-Configuration meter, make sure that Ethernet configured to read flow-condition pressure is setup correctly and the Qual-Configuration meter, and to Dual-Configuration meter and the Dual-Configuration meter and the setup envelowed or is damaged. Reinstall or replace the board if this value is 0. 6. If the issue is unresolved, collect a Maintenance Log using MeterLink™ and contact your local area Emerson Flow service representative. Run Time Issues: 1. Adjust the pressure of the process fluid to within alarm limits. 2. If using										Valid (TRUE)			

Rosemoun	t™ Liqui	d Ultrasonic Firmware: 1.61	Database: 2.29.017												
The below	Modbus	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg Pr	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
42472	2471	TemperatureValidity	Flow temperature invalid Temperature is invalid if the flow-condition temperature (FlowTemperature) is outside the limits defined by the low and high temperature alarm limits (LowTemperatureAlarm, HighTemperatureAlarm). Temperature is invalid if the meter is configured to read the flow-condition temperature from Transmitter Head 1 of a Dual-Configuration meter and Dual-Configuration meters are not communicating (IsColocMeterCommErr), either due to incorrect configuration or the Transmitter Head 1 is not reachable.	R			int	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
			Recommended Actions: First Time Startup Issues: 1. Verify that there is voltage to the temperature sensor, either from the terminal on the meter's power supply board or from an external power supply. 2. If using an analog temperature device, verify that the temperature sensor is properly wired to connector TB2-B pins 3 & 4 (ANALOG IN TT - & TT-). 3. Run the Field Setup Wizard in MeterLink [™] to properly configure the input including: Source (Live Analog or Fixed). Min and Max input limits corresponding to 4 mA and 20 mA respectively and the Low and High alarm limits. 4. If using an external source to write temperature to the meter, verify that it is properly writing the fixed flow temperature (SpecFlowTemperature) in the proper units. The current value will be displayed as Fixed temperature in the Field Setup Wizard in MeterLink [™] . 5. If the meter is configured to read the flow-condition temperature from Transmitter Head 1 of a Dual-Configuration meter P address (ColoCMeterIPAddress) on head 1 is same as the Ethernet IP address (Eth1IPAddr) of head 2 and vice versa. Check if the flow-condition temperature into meters is setup. Correctly and the Dual-Configuration meter IP address (ColoCMeterIPAddress) on head 1 is asme as the Ethernet IP address (Eth1IPAddr) of head 2 and vice versa. Check if the flow-condition temperature is unresolved, collect a Maintenance Log using MeterLink [™] and contact your local area Emerson Flow service representative. 8. If the issue is unresolved, collect a Maintenance Log using MeterLink [™] and contact your local area Emerson Flow service representative. 2. If using an analog temperature device and input reading is 0, check if IsA11Avail is equal to 1 in the Meter Information dialog in MeterLink [™] It is not 1, either the I/O Board Has been removed or it is damaged. Reinstal or replace I/O Board if this value is 0. 3. If using an analog temperature device, recheck the wring advice swirking san tote above under First Time Setup Issues. 5. If an external source is writing values to												
42475	2474	ExpCorrPressValidity	6. Rerun the Field Setup Wizard in MeterLink™ to verify that the configuration for the temperature input has not changed. 7. If the issue is unresolved, collect Meter Archive Logs (Daily, Hourly, Audit, Alarm and System) and Maintenance Log using MeterLink™ Pressure expansion correction invalid	R			int	-	-	boolean		Invalid (FALSE)			
42476	2475	ExpCorrTempValidity	This indicates the validity of the pressure expansion correction equation used to correct the internal diameter of the meter for changes in pressure. Temperature expansion correction invalid This indicates the validity of the temperature expansion correction equation used to correct the internal diameter of the meter for changes	R			int	-	-	boolean	-	Valid (TRUE) Invalid (FALSE) Valid (TRUE)			<u> </u>
42477	2476	IsEstimatedFlowVelocityInUs e	In a matching to the temperature of particular concentration of the matching of the method of the me	R			int	-	-	boolean	-	Flow velocity estimation is in use (TRUE) Flow velocity estimation is not in use (FALSE)			
			1. Check that if a chord is manually set to inactive (IsBatchInactiveA, IsBatchInactiveB, IsBatchInactiveC, IsBatchInactiveD) using the Statu Summary from the Meter Monitor in MeterLink™. If a chord is manually set to inactive then use Edit/Compare Configuration dialog in MeterLink™ to set chord active. 2. Check that if a chord has failed for batch (IsFailedForBatchA, IsFailedForBatchB, IsFailedForBatchC, IsFailedForBatchD) using the Status Summary from the Meter Monitor in MeterLink™. If failed, try to resolve the issue. 3. If this issue is unresolved, collect a Maintenance Log. Configuration file, and Waveform stream file with MeterLink™ and contact your local area Emerson Flow service representative.	s											
42478	2477	lsMeterVelAboveMaxLmt	Meter velocity is above the maximum limit Valocity is above the meter maximum velocity (MeterMaxVel) limit. Recommended Actions: 1. This alarm indicates that you are running above a safe velocity limit which could damage the meter run or it could indicate that you are running above your upper calibration limit where the meter uncertainty could increase. Lower the velocity of the meter. 2. Use the Edit/Compare configuration screen in MeterLink [™] to change the value of the meter maximum velocity (MeterMaxVel) if desired. It is recommended to set this either to the maximum calibrated velocity of the meter or to the maximum safe operating velocity is typically meant to prevent erosion of the internal diameter of the pipe and to prevent damage to protrusions such as thermal wells.				int	-	-	boolean	-	Meter velocity not above maximum limit (FALSE) Meter velocity above maximum limit (TRUE)			
42479	2478	IsAvgSoundVelRangeErr	Average speed of sound out of limits The average speed of sound (AvgSndVel) measured by the meter is outside the user determined high or low speed of sound limits (AvgSoundVelLoLmt, AvgSoundVelHiLmt). Recommended Actions: 1. Compare the average speed of sound of the meter to a typical speed of sound for the process fluid to make sure the meter is measuring a reasonable value. If the values match, it is recommended that you move the limits to position the average speed of sound within the limits Use the Edit/Compare Configuration in MeterLink™ to modify AvgSoundVelHitm and AvgSoundVelLoLmt. 2. If the issue is unresolved, collect a Maintenance Log with MeterLink™ and contact your local area Emerson Flow service representative.	•			int	-		boolean	-	SOS within range (FALSE) SOS out of range (TRUE)			
42480	2479	IsSNRTooLow	Logical OR of SNR of active chords This alarm indicates Signal-b-noise ratio is below the minimum threshold for at least one chord. See also IsSNRTooLowA, IsSNRTooLowB, IsSNRTooLowC, IsSNRTooLowD.	R			int	-	-	boolean	-	SNR is acceptable (FALSE) SNR is too low (TRUE)			
42481	2480	lsMeasSndSpdRange	Logical OR of active chords SOS out of range errors Logical ORing of measurement speed of sound out of range error for chords A, B, C, D. See also: IsMeasSndSpdRangeA, IsMeasSndSpdRangeB, IsMeasSndSpdRangeC, IsMeasSndSpdRangeD.	R			int	-	-	boolean	-	Chords SOS in range (FALSE) Chord SOS out of range (TRUE)			
42482	2481	IsBatchDataRcvFailed	See also: simeasonicspontainger, isimeasonicspontaingeb, isimeasonicspontaingeb, isimeasonicspontaingeb. No data received by "batch" processing task This is used internally to reset the Acquisition Module when the "batch" processing task does not receive waveforms. Acquisition Module error (IsAcqModuleError) will always be present when this is set to TRUE (1).	R	Y		int	-	-	boolean		Batch receiving data (FALSE) Batch not receiving data (TRUE)			

Rosemou	nt™ Liqui	d Ultrasonic Firmware: 1.61	Database: 2.29.017												
The below	Modbus	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding Register Number	Reg Num	Label	Description	Acc	: NV	Cnfg P	Modbus leg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
42483	2482	IsHardFailedA	Chord A hard failed The meter is unable to obtain measurement data from this pair of transducers for multiple consecutive batches (AlarmDef). Recommended Actions: 1. If no other transducers are failed or are reporting status alarms, the issue is most likely isolated to this pair of transducers or its cabling. Check the transducers are failed or are reporting status alarms, the issue is most likely isolated to this pair of transducers or its cabling. Check the transducers are failed or are reporting status alarms, the issue is most likely isolated to this pair of transducers or its cabling. Check the transducers are failed or are reporting status alarms, the issue is most likely isolated to this pair of transducers or its cabling. Check the transducers are failed or are reporting status above 90dB. The gain value can be read on the Meter Monitor of MeterLink [™] . If so, remove the transducers, lit this transducer pair is not above 90dB. The gain value can be read on the Meter Monitor of MeterLink [™] . If so, remove the transducers is the pair should be replaced. 4. If the transducer cabling allows, swap the cabling of the failed transducer pair with a pair with equal path lengths. If the alarm remains active for this chord, then the transducers are working properly. If this alarm clears but the chord that was swapped now fails, the issue is with the transducer. 5. If this issue is unresolved, collect a Maintenance Log, Configuration file and Waveform stream file with MeterLink [™] and contact your local area Emerson Flow service representative. See also (DataQity).	R			int		-	boolean		Chord not hard failed (FALSE) Chord hard failed (TRUE)			
42484	2483	IsHardFailedB	Chord B hard failed The meter is unable to obtain measurement data from this pair of transducers for multiple consecutive batches (AlarmDef). Recommended Actions: 1. If no other transducers are failed or are reporting status alarms, the issue is most likely isolated to this pair of transducers or its cabling. Check the transducer wing for this pair of transducers to make sure connections are secure and wired correctly. 2. Verify the average gain of this transducer pair is not above 90dB. The gain value can be read on the Meter Monitor of MeterLink™. If so, remove the transducers in the pair should be replaced. 3. If the transducers can and reapply the coupling fluid to the front face of the transducers. If this does not correct the issue, at least one of the transducer of hord, then the transducer avorking properly. If this alarm clears but the chord that was swapped now fails, the issue is with the transducer. 4. If this saus is unresolved, collect a Maintenance Log, Configuration file and Waveform stream file with MeterLink™ and contact your local area Emerson Flow service representative. See also (DataQlty).	R			int		-	boolean	-	Chord not hard failed (FALSE) Chord hard failed (TRUE)			
42485	2484	IsHardFailedC	Chord C hard failed The meter is unable to obtain measurement data from this pair of transducers for multiple consecutive batches (AlarmDef). Recommended Actions: 1. If no other transducers are failed or are reporting status alarms, the issue is most likely isolated to this pair of transducers or its cabling. Check the transducer wining for this pair of transducers to make sure connections are secure and wired correctly. 2. Verify the average gain of this transducer pair is not above 90d8. The gain value can be read on the Meter Monitor of MeterLink [™] . If so, remove the transducers in the pair should be replaced. 3. If the transducer cabling allows, swap the cabling of the failed transducer pair with a pair with equal path lengths. If the alarm remains active for this chord, then the transducers are working properly. If this alarm clears but the chord that was swaped now fails, the issue is with the transducer. 4. If this sue is unresolved, collect a Maintenance Log, Configuration file and Waveform stream file with MeterLink [™] and contact your local area Emerson Flow service representative. See also (DataQity).	R			int		-	boolean	-	Chord not hard failed (FALSE) Chord hard failed (TRUE)			
42486		IsHardFailedD	Chord D hard failed The meter is unable to obtain measurement data from this pair of transducers for multiple consecutive batches (AlarmDef). Recommended Actions: 1. If no other transducers are failed or are reporting status alarms, the issue is most likely isolated to this pair of transducers or its cabling. Check the transducer wing for this pair of transducers to make sure connections are secure and wired correctly. 2. Verify the average gain of this transducer pair is not above 90dB. The gain value can be read on the Meter Monitor of MeterLink™. If so, remove the transducers in the pair should be replaced. 3. If the transducers can and reapply the coupling fluid to the front face of the transducers. If this does not correct the issue, at least one of the transducer cabling allows, swap the cabling of the failed transducer pair with a pair with equal path lengths. If the alarm remains active for this transducers. 4. If this sales is unresolved, collect a Maintenance Log, Configuration file and Waveform stream file with MeterLink™ and contact your local area Emerson Flow service representative. See also (DataQity).	R			int	-	-	boolean	-	Chord not hard failed (FALSE) Chord hard failed (TRUE)			
42487	2486	IsTooFewOperChords	Too few operating chords The number of operating chords is less than the minimum number required for a valid measurement (MinChord). Operating chords are those which are not manually set to inactive and not marked as failed. Recommended Actions: 1. Check the other alarms that indicate why a chord is hard failed (IsHardFailedA, IsHardFailedB, IsHardFailedC, IsHardFailedD). Resolving these should resolve this issue. 2. If this issue is unresolved, collect a Maintenance Log and Archive Log and contact your local area Emerson Flow service representative. See also MinChord and SystemStatus.	R			int	-	-	boolean	-	No error (FALSE) Error (TRUE)			

		d Ultrasonic Firmware: 1.61														
The below	Modbus	map is applicable for Rosei	nount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding	Rea		Description		$ \top$			Modbus	Modbus	Modbus U.S.	Native Data	Native Data		Default Value	Minimum	Maximum
Register	Reg Num	Label		Acc	NV	Cnfg I	Prot	Modbus Reg Type	Modbus Metric Unit	U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	(native unit)	Value (native unit)	Value
Number										Unit				· ,	(native unit)	(native unit)
42489	∠488	PressureInvalid	Flow pressure invalid Pressure is invalid if the flow pressure (FlowPressure) is outside the limits defined by the low and high pressure alarm limits	к				int	-	-	boolean	-	Pressure valid (FALSE) Pressure invalid (TRUE)			
			(LowPressureAlarm, HighPressureAlarm). Pressure is invalid if the meter is configured to read the flow-condition pressure from Transmitter													
			Head 1 of a Dual-Configuration meter and Dual-Configuration meters are not communicating (IsColocMeterCommErr), either due to incorrect configuration or the Transmitter Head 1 is not reachable.													
			inconcer configuration of the transmitter fread in a not reachable.													
			Recommended Actions:													
			First Time Startup Issues:													
			1. Verify that there is voltage to the pressure sensor, either from the terminal on the meter's power supply board or from an external power													
			supply. 2. If using an analog pressure device, verify that the pressure sensor is properly wired to the connector TB2-B pins 1 & 2 (ANALOG IN PT-													
			& PT+).													
			 Run the Field Setup Wizard in MeterLink™ to properly configure the input including: Source (Live Analog or Fixed), Min and Max input limits corresponding to 4 mA and 20 mA respectively and the Low and High alarm limits. 													
			4. If using an external source to write pressure to the meter, verify that it is properly writing to fixed flow pressure (SpecFlowPressure) in the													
			proper units. The current value will be displayed as Fixed pressure in the Field Setup Wizard in MeterLink™. 5. If the meter is configured to read flow-condition pressure from Transmitter Head 1 of a Dual-Configuration meter, make sure that													
			Ethernet connection between the Dual-Configuration meters is setup correctly and the Dual-Configuration meter IP address													
			(ColocMeterIPAddress) on head 1 is same as the Ethernet IP address (Eth1IPAddr) of head 2 and vice versa. Check if flow-condition pressure is invalid on Transmitter Head 1 of a Dual-Configuration meter.													
			6. If the issue is unresolved, collect a Maintenance Log using MeterLink™ and contact your local area Emerson Flow service													
			representative.													
			Run Time Issues:	1												
			1. Adjust the pressure of the process fluid to within alarm limits.	1												
			 If using an analog pressure device and the input reading is 0, check if IsAl2Avail is equal to 1 in the Meter Information dialog in MeterLink™. If it is not 1, either the I/O Board has been removed or is damaged. Reinstall or replace the board if this value is 0. 	1												
			If using an analog pressure device, verify that the pressure sensor is working properly.													
			 If using an analog pressure device, recheck wiring and switch settings as noted above under First Time Setup Issues. If the external source is writing values to the fixed flow pressure (SpecFlowPressure), verify that the external source is still writing valid 	1												
			values without Modbus write errors.	1												
			6. Rerun the Field Setup Wizard in MeterLink™ to verify that the configuration for the pressure input has not changed. 7. If the issue is unresolved, collect Meter Archive Logs (Daily, Hourly, Audit, Alarm and System) and Maintenance Log using MeterLink™	1												
			and contact your local area Emerson Flow service representative.													
42490	2489	TemperatureInvalid	Flow temperature invalid	R				int	•		boolean		Temperature valid (FALSE)			
			Temperature is invalid if the flow-condition temperature (FlowTemperature) is outside the limits defined by the low and high temperature alarm limits (LowTemperatureAlarm, HighTemperatureAlarm). Temperature is invalid if the meter is configured to read the flow-condition										Temperature invalid (TRUE)			
			temperature from Transmitter Head 1 of a Dual-Configuration meter and Dual-Configuration meters are not communicating													
			(IsColocMeterCommErr), either due to incorrect configuration or the Transmitter Head 1 is not reachable.													
			Recommended Actions:													
			First Time Startup Issues:													
			1. Verify that there is voltage to the temperature sensor, either from the terminal on the meter's power supply board or from an external													
			power supply. 2. If using an analog temperature device, verify that the temperature sensor is properly wired to connector TB2-B pins 3 & 4 (ANALOG IN													
			TT-& TT+).													
			 Run the Field Setup Wizard in MeterLink™ to properly configure the input including: Source (Live Analog or Fixed), Min and Max input limits corresponding to 4 mA and 20 mA respectively and the Low and High alarm limits. 													
			4. If using an external source to write temperature to the meter, verify that it is properly writing the fixed flow temperature													
			(SpecFlowTemperature) in the proper units. The current value will be displayed as Fixed temperature in the Field Setup Wizard in MeterLink™.													
			5. If the meter is configured to read the flow-condition temperature from Transmitter Head 1 of a Dual-Configuration meter, make sure that													
			the Ethernet connection between the Dual-Configuration meters is setup correctly and the Dual-Configuration meter IP address (ColocMeterIPAddress) on head 1 is same as the Ethernet IP address (Eth1IPAddr) of head 2 and vice versa. Check if the flow-condition													
			temperature is invalid on Transmitter Head 1 of a Dual-Configuration meter.													
			6. If the issue is unresolved, collect a Maintenance Log using MeterLink™ and contact your local area Emerson Flow service	1												
			representative.	1												
			Run Time Issues:	1												
			 Adjust the temperature of the process fluid to within alarm limits. If using an analog temperature device and input reading is 0, check if IsAl1Avail is equal to 1 in the Meter Information dialog in 	1												
			MeterLink™. If it is not 1, either the I/O Board has been removed or it is damaged. Reinstall or replace I/O board if this value is 0.	1												
			 If using an analog temperature device, verify that the temperature sensor is working properly. If using an analog temperature device, recheck the wiring and switch settings as noted above under First Time Setup Issues. 	1												
			5. If an external source is writing values to the fixed flow temperature (SpecFlowTemperature), verify that the external source is still writing	1												
			valid values without Modbus write errors. 6. Rerun the Field Setup Wizard in MeterLink™ to verify that the configuration for the temperature input has not changed.	1												
			7. If the issue is unresolved, collect Meter Archive Logs (Daily, Hourty, Audit, Alarm and System) and Maintenance Log using MeterLink ™													
42491 42492		Reserved Reserved		R				int int								
42492			General system status	R	*	*	*	int	-	-	bitfield	-	7 IsColocMeterQFlowRangeErrLatched (NV)	+		
		,	General system status indicator. This is a bitfield consisting of multiple Boolean data point values.	1									8 IsTooFewOperChordsLatched (NV)			
				1									9 IsMeterVelAboveMaxLmtLatched (NV) 14 IsReverseFlowDetectedLatched (NV)			
42494	2493	FieldIOStatusLatched	Latched status of field IO	R	*	*	*	int	-	-	bitfield	-	0 lsColocMeterCommErrLatched (NV)			
			Latched field IO indicator. This is a bitfield consisting of multiple latched Boolean data point values corresponding to the field I/O status (FieldIOStatus).	1									1 PressureInvalidLatched (NV) 2 TemperatureInvalidLatched (NV)			
42496	2495	ChordInactv	Chord inactive	R	*	*	*	int	-		bitfield	-	0 ChordInactvA (NV, Cnfg, Prot)			
			Chord inactive indicator. Used to set one or more chords to be inactive. At least one chord must be active. The range and default value	1									1 ChordInactvB (NV, Cnfg, Prot)			
			are dependent upon the meter type (indicated by the DeviceNumber). If a chord is set to be inactive, its corresponding IsBatchInactiveA, IsBatchInactiveB, IsBatchInactiveC, IsBatchInactiveD, data point(s) is set to TRUE (1).	1									2 ChordInactvC (NV, Cnfg, Prot) 3 ChordInactvD (NV, Cnfg, Prot)			
42497	2496	SOSCompareStatus	Status of SOS comparison	R	*	*	*	int	-	-	bitfield	-	3 IsColocMeterSndSpdRangeErr (NV)			
			Speed of sound comparison indicator. This is a biffield consisting of multiple Boolean data point values corresponding to the speed of sound comparison group.	1												
42498	2497	SOSCompareStatusLatched	Latched status of SOS comparison	R	*	*	*	int		-	bitfield	-	3 IsColocMeterSndSpdRangeErrLatched (NV)			
.2.100	/		Latched speed of sound comparison status indicator. This is a bitfield consisting of multiple latched Boolean data point values								2		generation a first			
42501	0500	and the st	corresponding to the speed of sound compare status (SOSCompareStatus).	R				float			boolean		Reverse (FALSE)			

R

float

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2500 FlowDirection

42501

Flow direction Flow direction indicator. Reverse (FALSE) Forward (TRUE)

boolean

Rosemour	nt™ Liau	id Ultrasonic Firmware: 1.6	1 Database: 2 29.017													
			emount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
			Description	1					- 1	Modbus					Minimum	Maximum
Holding Register Number	Reg Num	Label		Acc	NV	Cnfg P	rot Reg 1		Modbus Metric Unit	U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Value (native unit)
42503	2502	Freq1DataValidity	Frequency Output 1 data invalid The parameter which the Frequency Output 1 is configured to represent is invalid or the output is currently in test mode.	R			floa	at	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
			Recommended Actions:													1
			 You can determine whether the output is in test mode by using Meter Outputs in MeterLink[™]. If the parameter for which Frequency Output 1 is configured is invalid, other alarms will be present that will help you resolve the issue. If the issue is unresolved, collect a Maintenance Log and Archive Log from the meter using MeterLink[™] and contact your local area Ermerson Flow service representative. 													
42505		Freq1ChnIA	Frequency Output 1A value Frequency Output 1 channel A value.	R			floa	at	Hz	Hz	float32	Hz				
42507	2506	Freq1ChnlB	Frequency Output 1B value Frequency Output 1 channel B value.	R			floa	at	Hz	Hz	float32	Hz				
42509		DO1A	Digital Output 1A value Digital Output 1A value. This value is based on the selected content (DO1AContent) and polarity (DO1AIsInvPolarity).	R			floa	at	-	-	uint8	-				1
42511		DO1B	Digital Output 1B value Digital Output 1B value. This value is based on the selected content (DO1BContent) and polarity (DO1BIsInvPolarity).	R			floa	-	-	-	uint8	-				
42513		AO1Output	Analog Output 1 current value Analog Output 1 current value.	R			floa		ma	ma	float32	ma				
42515	2514		Digital Input 1 value Digital Input 1 value.	R			floa		-	-	boolean	-				
42517		Freq1KFactor	Frequency Output 1 pair K-Factor Frequency Output 1 pair K-Factor.	R			floa	, in the second se	e e	pulses/volum e	float32	pulses/m3				
42519		Freq1InvKFactor	Frequency Output 1 pair inverse K-Factor Frequency Output 1 pair inverse K-Factor.	R			floa		olume/pulse	volume/pulse	float32	m3/pulse				
42521		Freq1OutputVFR	Frequency Output 1 pair output volumetric flow rate Frequency Output 1 pair output volumetric flow rate. This includes frequency feedback correction if applicable.	R			floa	at v	/olume/time	volume/time	float32	m3/hr				
42523	2522	AO1 IsFixed	Analog Output 1 (HART PV) is fixed Analog Output 1 current is in test mode and fixed. The current can be fixed by using the Outputs Test dialog of MeterLink™ by placing the output in test mode.	R			floa	at	-	-	boolean	-	Current not fixed (FALSE) Current fixed (TRUE)			
			Recommended Actions:													
			1. Once the Analog Output 1 is removed from test mode, this alarm will clear.													
			See also IsAO1EnableTest data point.													
42525	2524	AO1 IsSaturated	Analog Output 1 (HART PV) is saturated Analog Output 1 is saturated (i.e. the loop current has reached its upper or lower endpoint and cannot increase or decrease any further). Recommended Actions:	к			floa	at	-	-	boolean	-	Current not saturated (FALSE) Current saturated (TRUE)			
			1. The analog output may need to be rescaled to prevent it from saturating. Use the Field Setup Wizard in MeterLink™ to configure Analog													
			Output 1.													
42527	2526	AO2Output	Analog Output 2 current value Analog Output 2 current value.	R			floa	at	ma	ma	float32	ma				
42529	2528	AO2IsFixed	Analog Output 2 (HART SV) is fixed Analog Output 2 current is in test mode and fixed. The current can be fixed by using the Outputs Test dialog of MeterLink [™] by placing the output in test mode.	R			floa	at	-	-	boolean	-	Current not fixed (FALSE) Current fixed (TRUE)			
			Recommended Actions:													
			1. Once the Analog Output 2 is removed from test mode, this alarm will clear.													
10504	0500	A Oole Ontransia d	See also IsAO2EnableTest data point.				0.				h a chi a c					
42531	2530	AO2IsSaturated	Analog Output 2 (HART SV) is saturated Analog Output 2 is saturated (i.e. the loop current has reached its upper or lower endpoint and cannot increase or decrease any further). Recommended Actions:	ĸ			floa	at	-	-	boolean	-	Current not saturated (FALSE) Current saturated (TRUE)			
			1. The analog output may need to be rescaled to prevent it from saturating. Use the Field Setup Wizard in MeterLink™ to configure Analog Output 2.													
				<u> </u>	\downarrow							ļ		_		
42533	2532	AO1 DataValidity	Analog Output 1 data invalid Analog Output 1 (AO1) is invalid. The analog output is considered invalid if the analog output is in test mode or the content the analog output is trying to drive is invalid or the loop current mode is disabled via HART. The content of AO1 is specified by AO1Content.	R			floa	at	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
			Recommended Actions:													1
			 If an alarm exists for the content selected to be output on Analog Output 1 (AO1Content), resolving that issue should clear this alarm. If the content selected for Analog Output 1 is not in alarm, then verify that the output is not fixed or set in test mode or the loop current mode has been not been disabled via HART. If the issue is unresolved, collect a Maintenance Log using MeterLink™ and contact your local area Emerson Flow service 													
			representative.													1

Rosemou	nt™ Liau	uid Ultrasonic Firmware: 1.6	51 Database: 2.29.017												
			emount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding			Description						Modbus	T				Minimum	Maximum
Register Number	Reg Num	Label		Acc	NV	Cnfg Pr	Nodb Reg Ty		U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Value (native unit)	Value (native unit)
42535	2534	4 AO2DataValidity	Analog Output 2 data invalid Analog Output 2 (AO2) is invalid. The analog output is considered invalid if the analog output is in test mode or the content the analog output is trying to drive is invalid. The content of AO2 is specified by AO2Content.	R			float	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
			Recommended Actions:												1
			 If an alarm exists for the content selected to be output on Analog Output 2 (AO2Content), resolving that issue should clear this alarm. If the content selected for Analog Output 2 is not in alarm, then verify that the output is not fixed or set in test mode. If the issue is unresolved, collect a Maintenance Log using MeterLink.[™] and contact your local area Emerson Flow service representative. 												
42551	2550	FlowDirection	Flow direction Flow direction indicator.	R			float	-	-	boolean	-	Reverse (FALSE) Forward (TRUE)			
42553	2552	2 Freq2DataValidity	Frequency Output 2 data invalid	R			float	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
			The parameter which the Frequency Output 2 is configured to represent is invalid or the output is currently in test mode. Recommended Actions:									Valid (TKOE)			1
			1. You can determine whether the output is in test mode by using Meter Outputs in MeterLink™. 2. If the parameter for which Frequency Output 2 is configured is invalid, other alarms will be present that will help you resolve the issue. 3. If the issue is unresolved, collect a Maintenance Log and Archive Log from the meter using MeterLink™ and contact your local area Emerson Flow service representative.												
42555	2554	Freq2ChnIA	Frequency Output 2A value Frequency Output 2 channel A value.	R			float	Hz	Hz	float32	Hz				
42557	2556	Freq2ChnIB	Frequency Output 2B value Frequency Output 2 channel B value.	R			float	Hz	Hz	float32	Hz				
42559	2558	B DO2A	Digital Output 2A value Digital Output 2A value. Digital Output 2A value. This value is based on the selected content (DO2AContent) and polarity (DO2AIsInvPolarity).	R			float	-	-	uint8	-				
42561	2560	DO2B	Digital Output 2B value Digital Output 2B value. Digital Output 2B value. This value is based on the selected content (DO2BContent) and polarity (DO2BIsInvPolarity).	R			float	-	-	uint8	-				
42563	2562	2 AO1Output	Analog Output 1 current value Analog Output 1 current value	R			float	ma	ma	float32	ma				
42565	2564	I DI1	Digital Input 1 value Digital Juput 1 value Digital Juput 1 value Digital Juput 1 value Digital Juput 1 value	R			float	-	-	boolean	-				
42567	2566	Freq2KFactor	Frequency Output 2 pair K-Factor	R			float	pulses/volur	n pulses/volum	float32	pulses/m3				
42569	2568	Freq2InvKFactor	Frequency Output 2 pair K-Factor. Frequency Output 2 pair inverse K-Factor	R			float	e volume/puls	e volume/pulse	float32	m3/pulse				
42571	2570	Freq2OutputVFR	Frequency Output 2 pair inverse K-Factor. Frequency Output 2 pair output volumetric flow rate	R			float	volume/time	e volume/time	float32	m3/hr				<u> </u>
42573	2572	AO1IsFixed	Frequency Output 2 pair output volumetric flow rate. This includes frequency feedback correction if applicable. Analog Output 1 (HART PV) is fixed	R			float	-	-	boolean	-	Current not fixed (FALSE)			
			Analog Output 1 current is in test mode and fixed. The current can be fixed by using the Outputs Test dialog of MeterLink™ by placing the output in test mode.									Current fixed (TRUE)			
			Recommended Actions: 1. Once the Analog Output 1 is removed from test mode, this alarm will clear.												
			See also IsAO1EnableTest data point.												
42575	2574	AO1IsSaturated	Analog Output 1 (HART PV) is saturated Analog Output 1 is saturated (i.e. the loop current has reached its upper or lower endpoint and cannot increase or decrease any further).	R			float	-	-	boolean	-	Current not saturated (FALSE) Current saturated (TRUE)			
			Recommended Actions:												1
			1. The analog output may need to be rescaled to prevent it from saturating. Use the Field Setup Wizard in MeterLink™ to configure Analog Output 1.												
42577	2576	6 AO2Output	Analog Output 2 current value Analog Output 2 current value.	R			float	ma	ma	float32	ma				
42579	2578	3 AO2IsFixed	Analog Output 2 (HART SV) is fixed Analog Output 2 current is in test mode and fixed. The current can be fixed by using the Outputs Test dialog of MeterLink™ by placing the output in test mode.	R			float	-	-	boolean	-	Current not fixed (FALSE) Current fixed (TRUE)			
			Recommended Actions:												i I
			1. Once the Analog Output 2 is removed from test mode, this alarm will clear.												i I
			See also IsAO2EnableTest data point.												
42581	2580	AO2IsSaturated	Analog Output 2 (HART SV) is saturated Analog Output 2 is saturated (i.e. the loop current has reached its upper or lower endpoint and cannot increase or decrease any further).	R			float	-	-	boolean	-	Current not saturated (FALSE) Current saturated (TRUE)			
			Recommended Actions: 1. The analog output may need to be rescaled to prevent it from saturating. Use the Field Setup Wizard in MeterLink™ to configure Analog												
			Output 2.												

Holding Rea	dbus n	nap is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Register Num Number		abel	Description	Acc	NV C	nfg Pro	t Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
42583 25	2582 A	AO1 DataValidity	Analog Output 1 data invalid Analog Output 1 (AO1) is invalid. The analog output is considered invalid if the analog output is in test mode or the content the analog output is trying to drive is invalid or the loop current mode is disabled via HART. The content of AO1 is specified by AO1Content.	R			float	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
			Recommended Actions: 1. 1. If an alarm exists for the content selected to be output on Analog Output 1 (AO1Content), resolving that issue should clear this alarm.												
			 If the content selected for Analog Output 1 is not in alarm, then verify that the output is not fixed or set in test mode or the loop current mode has been not been disabled via HART. If the issue is unresolved, collect a Maintenance Log using MeterLink™ and contact your local area Emerson Flow service representative. 												
42585 25	2584 A	AO2DataValidity	Analog Output 2 data invalid	R			float			boolean	-	Invalid (FALSE)			
			Analog Output 2 (AO2) is invalid. The analog output is considered invalid if the analog output is in test mode or the content the analog output is trying to drive is invalid. The content of AO2 is specified by AO2Content.									Valid (TRUE)			
			Recommended Actions:												
			 If an alarm exists for the content selected to be output on Analog Output 2 (AO2Content), resolving that issue should clear this alarm. If the content selected for Analog Output 2 is not in alarm, then verify that the output is not fixed or set in test mode. If the sisue is unresolved, collect a Maintenance Log using MeterLink™ and contact your local area Emerson Flow service representative. 												
42601 26	2600 0	GainA1	Gain when transducer A1 is receiving a signal Gain when transducer A1 is receiving a signal. Gain is applied to the received signal in hardware in volts/volt (hardware gain units). Conversion from hardware gain to decibels is gain (db) = 20 * log10(gain(hw)). Alarm limits for gain alarms are GainLowLmt and GainHighLmt.	R	Y		float	gain (dB)	gain (dB)	float32	gain (h/w)				
42603 26	2602 0	GainA2	Gain when transducer A2 is receiving a signal Gain when transducer A2 is receiving a signal. Gain is applied to the received signal in hardware in volts/volt (hardware gain units). Conversion from hardware gain to decibels is gain (db) = 20 * log10(gain(hw)). Alarm limits for gain alarms are GainLowLmt and GainHighLmt.	R	Y		float	gain (dB)	gain (dB)	float32	gain (h/w)				
42605 26	2604 0	GainB1	Gain when transducer B1 is receiving a signal Gain when transducer B1 is receiving a signal. Gain is applied to the received signal in hardware in volts/volt (hardware gain units). Conversion from hardware gain to decibels is gain (db) = 20 * log10(gain(hw)). Alarm limits for gain alarms are GainLowLmt and GainHighLmt.	R	Y		float	gain (dB)	gain (dB)	float32	gain (h/w)				
42607 26	2606 0	GainB2	Gain when transducer B2 is receiving a signal Gain when transducer B2 is receiving a signal. Gain is applied to the received signal in hardware in volts/volt (hardware gain units). Conversion from hardware gain to decibels is gain (db) = 20 * log10(gain(hw)). Alarm limits for gain alarms are GainLowLmt and GainHighLmt.	R	Y		float	gain (dB)	gain (dB)	float32	gain (h/w)				
42609 26	2608 0	GainC1	Gain when transducer C1 is receiving a signal Gain when transducer C1 is receiving a signal. Gain is applied to the received signal in hardware in volts/volt (hardware gain units). Conversion from hardware gain to decibels is gain (db) = 20 * log10(gain(hw)). Alarm limits for gain alarms are GainLowLmt and GainHighLmt.	R	Y		float	gain (dB)	gain (dB)	float32	gain (h/w)				
42611 26	2610 0	GainC2	Gain when transducer C2 is receiving a signal Gain when transducer C2 is receiving a signal. Gain is applied to the received signal in hardware in volts/volt (hardware gain units). Conversion from hardware gain to decibels is gain (db) = 20 * log10(gain(hw)). Alarm limits for gain alarms are GainLowLmt and GainHighLmt.	R	Y		float	gain (dB)	gain (dB)	float32	gain (h/w)				
42613 26	2612 0	GainD1	Gain when transducer D1 is receiving a signal Gain when transducer D1 is receiving a signal. Gain is applied to the received signal in hardware in volts/volt (hardware gain units). Conversion from hardware gain to decibels is gain (db) = 20 " log10(gain(hw)). Alarm limits for gain alarms are GainLowLmt and GainHighLmt.	R	Y		float	gain (dB)	gain (dB)	float32	gain (h/w)				
42615 26	2614 0	GainD2	Gain when transducer D2 is receiving a signal Gain when transducer D2 is receiving a signal. Gain is applied to the received signal in hardware in volts/volt (hardware gain units). Conversion from hardware gain to decibels is gain (db) = 20 * log10(gain(hw)). Alarm limits for gain alarms are GainLowLmt and GainHighLmt.	R	Y		float	gain (dB)	gain (dB)	float32	gain (h/w)				
42617 26	2616 +	HoldTmA1	Hold time (A1) Hold time (A1).	R			float	us	us	float32	us				
		HoldTmA2	Hold time (A2) Hold time (A2).	R			float	us	us	float32	us				
		HoldTmB1	Hold time (B1) Hold time (B1).	R			float	us	us	float32	us				
42623 26	2622	HoldTmB2	Hold time (B2) Hold time (B2).	R			float	us	us	float32	us				
		HoldTmC1	Hold time (C1) Hold time (C1).	R			float	us	us	float32	us				
		HoldTmC2	Hold time (C2) Hold time (C2).	R			float	us	us	float32	us				
		HoldTmD1	Hold time (D1) Hold time (D1).	R			float	us	us	float32	us				
		HoldTmD2	Hold time (D2) Hold time (D2).	R			float	us	us	float32	us				
	2650 S		Batch average signal energy (A1) Average batch signal energy (A1).	R			float	energy	energy	float32	energy				
	2652 S		Batch average signal energy (A2) Average batch signal energy (A2).	R			float	energy	energy	float32	energy				
	2654 S		Batch average signal energy (B1) Average batch signal energy (B1).	R			float	energy	energy	float32	energy				
	2656 S		Batch average signal energy (B2) Average batch signal energy (B2).	R			float	energy	energy	float32	energy				
	2658 S		Batch average signal energy (C1) Average batch signal energy (C1).	R			float	energy	energy	float32	energy				
42661 26	2660 S	SEC2	Batch average signal energy (C2) Average batch signal energy (C2).	R			float	energy	energy	float32	energy				

Rosemou	nt™ Liqu	id Ultrasonic Firmware: 1.61	Database: 2.29.017												
The below	Modbus	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding Register Number	Reg Num	Label	Description	Acc	NV Cr	nfg Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
42663	2662	SED1	Batch average signal energy (D1) Average batch signal energy (D1).	R			float	energy	energy	float32	energy				
42665	2664	SED2	Batch average signal energy (D2) Average batch signal energy (D2).	R			float	energy	energy	float32	energy				
42667	2666	NEA1	Batch average noise energy (A1) Average batch noise energy (A1).	R			float	energy	energy	float32	energy				
42669	2668	NEA2	Batch average noise energy (A2) Average batch noise energy (A2).	R			float	energy	energy	float32	energy				
42671	2670	NEB1	Batch average noise energy (B1) Average batch noise energy (B1).	R			float	energy	energy	float32	energy				
42673	2672	NEB2	Batch average noise energy (B2) Average batch noise energy (B2).	R			float	energy	energy	float32	energy				
42675	2674	NEC1	Batch average noise energy (C1) Average batch noise energy (C1).	R			float	energy	energy	float32	energy				
42677	2676	NEC2	Batch average noise energy (C2) Average batch noise energy (C2).	R			float	energy	energy	float32	energy				
42679	2678	NED1	Bath average noise energy (D1) Average batch noise energy (D1).	R			float	energy	energy	float32	energy				
42681	2680	NED2	Batch average noise energy (D2) Average batch noise energy (D2).	R			float	energy	energy	float32	energy				
42683	2682	SNRA1	Average signal-to-noise ratio (A1) Average signal-to-noise ratio (A1).	R			float	dB	dB	float32	dB				
42685	2684	SNRA2	Average signal-to-noise ratio (A2) Average signal-to-noise ratio (A2).	R			float	dB	dB	float32	dB				
42687	2686	SNRB1	Average signal-to-noise ratio (B1) Average signal-to-noise ratio (B1).	R			float	dB	dB	float32	dB				
42689	2688	SNRB2	Average signal-to-noise ratio (B2) Average signal-to-noise ratio (B2).	R			float	dB	dB	float32	dB				
42691	2690	SNRC1	Average signal-to-noise ratio (C1) Average signal-to-noise ratio (C1).	R			float	dB	dB	float32	dB				
42693	2692	SNRC2	Average signal-to-noise ratio (C2) Average signal-to-noise ratio (C2).	R			float	dB	dB	float32	dB				
42695	2694	SNRD1	Average signal-to-noise ratio (D1) Average signal-to-noise ratio (D1).	R			float	dB	dB	float32	dB				
42697	2696	SNRD2	Average signal-to-noise ratio (D2) Average signal-to-noise ratio (D2).	R			float	dB	dB	float32	dB				
42701	2700	MeanTmA1	Average transit time upstream for chord A Mean batch transit time (A1).	R			float	us	us	float32	us				
42703	2702	MeanTmA2	Average transit time downstream for chord A Mean batch transit time (A2).	R			float	us	us	float32	us				
42705	2704	MeanTmB1	Average transit time upstream for chord B Mean batch transit time (B1).	R			float	us	us	float32	us				
42707	2706	MeanTmB2	Average transit time downstream for chord B Mean batch transit time (B2).	R			float	US	us	float32	us				
42709	2708	MeanTmC1	Average transit time upstream for chord C Mean batch transit time (C1).	R			float	us	us	float32	us				
42711	2710	MeanTmC2	Average transit time downstream for chord C Mean batch transit time (C2).	R			float	us	us	float32	us				
42713	2712	MeanTmD1	Average transit time upstream for chord D Mean batch transit time (D1).	R			float	us	us	float32	us				
42715	2714	MeanTmD2	Average transit time downstream for chord D Mean batch transit time (D2).	R			float	US	us	float32	us				
42717	2716	DltTmA	Mean batch delta time for chord A Mean batch delta time for chord A.	R			float	us	us	float32	us				
42719	2718	DltTmB	Mean batch delta time for chord B Mean batch delta time for chord B.	R			float	us	us	float32	us				
42721	2720	DltTmC	Mean batch delta time for chord C Mean batch delta time for chord C.	R			float	us	us	float32	us				
42723	2722	DltTmD	Mean batch deita time for chord D Mean batch deita time for chord D.	R			float	us	us	float32	us				
42725	2724	SDevTmA1	Std. deviation of transit times for chord A upstream Batch transit time standard deviation (A1). It is calculated from transit times of waveforms used for measurement.	R			float	ns	ns	float32	us				
42727	2726	SDevTmA2	Std. deviation of transit times for chord A downstream Batch transit time standard deviation (A2), it is calculated from transit times of waveforms used for measurement.	R			float	ns	ns	float32	us				
42729	2728	SDevTmB1	Std. deviation of transit times for chord B upstream Batch transit time standard deviation (B1). It is calculated from transit times of waveforms used for measurement.	R			float	ns	ns	float32	us				
42731	2730	SDevTmB2	Std. deviation of transit times for chord B downstream Batch transit time standard deviation (B2). It is calculated from transit times of waveforms used for measurement.	R			float	ns	ns	float32	us				
42733	2732	SDevTmC1	Std. deviation of transit times for chord C upstream Batch transit time standard deviation (C1). It is calculated from transit times of waveforms used for measurement.	R			float	ns	ns	float32	us				
42735	2734	SDevTmC2	Std. deviation of transit times for chord C downstream Batch transit times tandard deviation (C2). It is calculated from transit times of waveforms used for measurement.	R			float	ns	ns	float32	us				
42737	2736	SDevTmD1	Std. deviation of transit times for chord D upstream Std. deviation of transit times for chord D upstream Batch transit time standard deviation (D1). It is calculated from transit times of waveforms used for measurement.	R			float	ns	ns	float32	us				
42739	2738	SDevTmD2	Std. deviation of transit times for chord D downstream Batch transit time standard deviation (D2), it is calculated from transit times of waveforms used for measurement.	R			float	ns	ns	float32	us				
42741	2740	SDevDltTmA	Batch delta time standard deviation for chord A Batch delta time standard deviation for chord A	R			float	ns	ns	float32	us				
42743	2742	SDevDltTmB	Batch delta time standard deviation for chord B Batch delta time standard deviation for chord B Batch delta time standard deviation for chord B.	R			float	ns	ns	float32	us				
				1					I	I	1				

Rosemou	nt™ Liqui	d Ultrasonic Firmware: 1.61	Database: 2.29.017												
The below	Modbus	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding Register Number	Reg Num	Label	Description	Acc	NV C	infg Pro	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
42745	2744	SDevDltTmC	Batch delta time standard deviation for chord C Batch delta time standard deviation for chord C.	R			float	ns	ns	float32	us				
42747	2746	SDevDltTmD	Batch delta time standard deviation for chord D Batch delta time standard deviation for chord D.	R			float	ns	ns	float32	us				
42749	2748	MinTmA1	Minimum batch transit time (A1).	R			float	us	us	float32	us				
42751	2750	MinTmA2	Minimum batch transit time (A2) Minimum batch transit time (A2)	R			float	us	us	float32	us				
42753	2752	MinTmB1	Minimum batch transit time (B1) Minimum batch transit time (B1)	R			float	us	us	float32	us				
42755	2754	MinTmB2	Minimum batch transit time (B2)	R			float	us	us	float32	us				
42757	2756	MinTmC1	Minimum batch transit time (B2). Minimum batch transit time (C1)	R			float	us	us	float32	us				[]
42759	2758	MinTmC2	Minimum batch transit time (C1). Minimum batch transit time (C2)	R		+	float	us	us	float32	us				
42761	2760	MinTmD1	Minimum batch transit time (C2). Minimum batch transit time (D1)	R		_	float	us	us	float32	us				
42763	2762	MinTmD2	Minimum batch transit time (D1). Minimum batch transit time (D2)	R	_		float	us	us	float32	us				
42765	2764	MaxTmA1	Minimum batch transit time (D2). Maximum batch transit time (A1)	R		_	float	us	us	float32	us				
42767	2766	MaxTmA2	Maximum batch transit time (A1). Maximum batch transit time (A2)	R		_	float	us	us	float32	us				<u> </u>
42769		MaxTmB1	Maximum batch transit time (A2). Maximum batch transit time (B1)	R		+	float	us	us	float32	us				<u> </u>
42771		MaxTmB2	Maximum batch transit time (B1). Maximum batch transit time (B2)	R			float	us	us	float32	us				
42773		MaxTmC1	Maximum batch transit ine (B2), Maximum batch transit ine (B2), Maximum batch transit ine (C1)	R			float	us	us	float32					
			Maximum batch transit time (C1).								us				<u> </u>
42775		MaxTmC2	Maximum batch transit time (C2) Maximum batch transit time (C2).	R			float	us	us	float32	us				
42777		MaxTmD1	Maximum batch transit time (D1) Maximum batch transit time (D1).	R			float	us	us	float32	us				
42779		MaxTmD2	Maximum batch transit time (D2) Maximum batch transit time (D2).	R			float	us	us	float32	us				
42781		MinDltTmA	Minimum batch delta time for chord A Minimum batch delta time for chord A.	R			float	us	us	float32	us				
42783	2782	MinDltTmB	Minimum batch delta time for chord B Minimum batch delta time for chord B.	R			float	us	us	float32	us				
42785	2784	MinDltTmC	Minimum batch delta time for chord C Minimum batch delta time for chord C.	R			float	us	us	float32	us				
42787	2786	MinDltTmD	Minimum batch delta time for chord D Minimum batch delta time for chord D.	R			float	us	us	float32	us				
42789	2788	MaxDltTmA	Maximum batch delta time for chord A Maximum batch delta time for chord A.	R			float	us	us	float32	us				
42791	2790	MaxDltTmB	Maximum batch delta time for chord B Maximum batch delta time for chord B.	R			float	us	us	float32	us				
42793	2792	MaxDltTmC	Maximum batch delta time for chord C Maximum batch delta time for chord C.	R			float	us	us	float32	us				
42795	2794	MaxDltTmD	Maximum batch delta time for chord D Maximum batch delta time for chord D.	R			float	us	us	float32	us				
43003	3002	BatchTimeSec	Elapsed time for all firing sequences processed in batch cycle This is calculated as difference of the timestamps of the last sequence of previous batch cycle and the last sequence of current batch cycle. This will vary from batch to batch around the desired duration (BatchUpdatePeriod) and depends on number of new sequences received by batch (BatchNewSeq).	R			float	sec	sec	float32	sec				
43005	3004	AvgBatchTimeHours	Average batch time Average that hime. The average is computed over the previous 8 batches.	R	\uparrow	+	float	hr	hr	float32	hr				1
43007	3006	Freq1FeedbackStatus	Frequency Output 1 pair feedback status	R		+	float	-	-	uint8	-	Forward (0) Reverse (1)			I
43009	3008	Freq1FeedbackPulseCnt	Frequency Output 1 pair feedback pulse count Frequency Output 1 pair feedback pulse count	R			float	Time pulses	Time pulses	uint16	Time pulses				
43011	3010	Freq1InvKFactor	Frequency Output 1 pair inverse K-Factor	R			float	volume/pulse	volume/pulse	float32	m3/pulse				
43013	3012	Freq1FeedbackVol	Frequency Output 1 pair inverse K-Factor. Frequency Output 1 pair feedback volume	R			float	volume	volume	float32	m3				I
43015	3014	Freq1FeedbackPrevDesired		R		+	float	volume	volume	float32	m3				I
43017	3016	Vol Freq1FeedbackVolErr	Frequency Output 1 pair previous desired volume. Frequency Output 1 pair feedback volume error	R	+	+	float	volume	volume	float32	m3		+]
43019	3018	Freq1FeedbackDesiredVol	Frequency Output 1 pair feedback volume error. Frequency Output 1 pair desired volume	R	+	+	float	volume	volume	float32	m3		+]
43021	3020	Freq1TTLVFRErr	Frequency Output 1 pair desired volume. Frequency Output 1 pair total volumetric flow rate error	R		+	float	volume/time	volume/time	float32	m3/hr				<u> </u>
43023	3022	Freq1VFRErrComp	Frequency Output 1 pair total volumetric flow rate error. Frequency Output 1 pair volumetric flow rate error compensation	R		+	float	volume/time	volume/time	float32	m3/hr				<u> </u>
43025		Freq1AbsVFR	Frequency Output 1 pair volumetric flow rate error compensation. Frequency Output 1 pair absolute volumetric flow rate Frequency Output 1 pair absolute volumetric flow rate. This is the absolute value of the volumetric flow rate represented by the Frequency	R		+	float	volume/time	volume/time	float32	m3/hr				
43027	3026	Freq1OutputVFR	Output 1 pair and does not include any feedback error compensation. Frequency Output 1 pair output volumetric flow rate	R	\rightarrow	+	float	volume/time	volume/time	float32	m3/hr				<u> </u>
		, .	Frequency Output 1 pair output volumetric flow rate. This includes frequency feedback correction if applicable.			1						1			

Rosemou	nt™ Liqu	d Ultrasonic Firmware: 1.61	Database: 2.29.017												
The below	/ Modbus	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters	_											
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg F	Modbus leg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
43103	3102	BatchTimeSec	Elapsed time for all firing sequences processed in batch cycle This is calculated as difference of the timestamps of the last sequence of previous batch cycle and the last sequence of current batch cycle. This will vary from batch to batch around the desired duration (BatchUpdatePeriod) and depends on number of new sequences received by batch (BatchNewSeq).	R			float	Sec	sec	float32	sec				
43105	3104	AvgBatchTimeHours	Average batch time Average batch time. The average is computed over the previous 8 batches.	R			float	hr	hr	float32	hr				
43107	3106	Freq2FeedbackStatus	Frequency Output 2 pair feedback status Frequency Output 2 pair feedback status.	R			float	-	-	uint8	-	Forward (0) Reverse (1)			
43109	3108	Freq2FeedbackPulseCnt	Frequency Output 2 pair feedback pulse count Frequency Output 2 pair feedback pulse count.	R			float	Time pulses	Time pulses	uint16	Time pulses				
43111	3110	Freq2InvKFactor	Frequency Output 2 pair inverse K-Factor Frequency Output 2 pair inverse K-Factor.	R			float	volume/pulse	volume/pulse	float32	m3/pulse				
43113	3112	Freq2FeedbackVol	Frequency Output 2 pair feedback volume Frequency Output 2 pair feedback volume.	R			float	volume	volume	float32	m3				
43115		Freq2FeedbackPrevDesired Vol	Frequency Output 2 pair previous desired volume Frequency Output 2 pair previous desired volume.	R			float	volume	volume	float32	m3				
43117	3116	Freq2FeedbackVolErr	Frequency Output 2 pair feedback volume error Frequency Output 2 pair feedback volume error.	R			float	volume	volume	float32	m3				
43119	3118	Freq2FeedbackDesiredVol	Frequency Output 2 pair desired volume Frequency Output 2 pair desired volume.	R			float	volume	volume	float32	m3				
43121	3120	Freq2TTLVFRErr	Frequency Output 2 pair total volumetric flow rate error Frequency Output 2 pair total volumetric flow rate error.	R			float	volume/time	volume/time	float32	m3/hr				
43123	3122	Freq2VFRErrComp	Frequency Output 2 pair volumetric flow rate error compensation Frequency Output 2 pair volumetric flow rate error compensation.	R			float	volume/time	volume/time	float32	m3/hr				
43125		Freq2AbsVFR	Frequency Output 2 pair absolute volumetric flow rate. This is the absolute value of the volumetric flow rate represented by the Frequency Frequency Output 2 pair absolute volumetric flow rate. This is the absolute value of the volumetric flow rate represented by the Frequency Output 2 pair and does not include any feedback error compensation.	R			float	volume/time	volume/time	float32	m3/hr				
43127		Freq2OutputVFR	Frequency Output 2 pair output volumetric flow rate Frequency Output 2 pair output volumetric flow rate. This includes frequency feedback correction if applicable.	R			float	volume/time	volume/time	float32	m3/hr				
43201	3200	TspfA1	Tracking target Pf value (A1) Tracking target Pf value (A1).	R	Y		float	sample intervals	sample intervals	float32	sample intervals				
43203	3202	TspfA2	Tracking target Pf value (A2) Tracking target Pf value (A2).	R	Y		float	sample intervals	sample intervals	float32	sample intervals				
43205	3204	TspfB1	Tracking target Pf value (B1) Tracking target Pf value (B1).	R	Y		float	sample intervals	sample intervals	float32	sample intervals				
43207	3206	TspfB2	Tracking target Pf value (B2) Tracking target Pf value (B2).	R	Y		float	sample intervals	sample intervals	float32	sample intervals				
43209	3208	TspfC1	Tracking target Pf value (C1) Tracking target Pf value (C1).	R	Y		float	sample intervals	sample intervals	float32	sample intervals				
43211	3210	TspfC2	Tracking target Pf value (C2) Tracking target Pf value (C2).	R	Y		float	sample intervals	sample intervals	float32	sample intervals				
43213	3212	TspfD1	Tracking target Pf value (D1) Tracking target Pf value (D1).	R	Y		float	sample intervals	sample intervals	float32	sample intervals				
43215	3214	TspfD2	Tracking target Pf value (D2) Tracking target Pf value (D2).	R	Y		float	sample intervals	sample intervals	float32	sample intervals				
43217	3216	TspeA1	Tracking target Pe value (A1) Tracking target Pe value (A1).	R	Y		float	sample intervals	sample intervals	float32	sample intervals				
43219	3218	TspeA2	Tracking target Pe value (A2) Tracking target Pe value (A2).	R	Y		float	sample intervals	sample intervals	float32	sample intervals				
43221	3220	TspeB1	Tracking target Pe value (B1) Tracking target Pe value (B1).	R	Y		float	sample intervals	sample intervals	float32	sample intervals				
43223	3222	TspeB2	Tracking target Pe value (B2) Tracking target Pe value (B2).	R	Y		float	sample intervals	sample intervals	float32	sample intervals				
43225	3224	TspeC1	Tracking target Pe value (C1) Tracking target Pe value (C1).	R	Y		float	sample intervals	sample intervals	float32	sample intervals				
43227	3226	TspeC2	Tracking target Pe value (C2) Tracking target Pe value (C2).	R	Y		float	sample intervals	sample intervals	float32	sample intervals				
43229	3228	TspeD1	Tracking target Pe value (D1) Tracking target Pe value (D1).	R	Y		float	sample intervals	sample intervals	float32	sample intervals				
43231	3230	TspeD2	Tracking target Pe value (D2) Tracking target Pe value (D2).	R	Y		float	sample intervals	sample intervals	float32	sample intervals				
43233		TampA1	Tracking target normalized amplitude value (A1) Tracking target normalized amplitude value (A1).	R	Y		float	%	%	float32	%				
43235	3234	TampA2	Tracking target normalized amplitude value (A2) Tracking target normalized amplitude value (A2).	R	Y		float	%	%	float32	%				
43237	3236	TampB1	Tracking target normalized amplitude value (B1) Tracking target normalized amplitude value (B1).	R	Y		float	%	%	float32	%				
43239	3238	TampB2	Tracking target normalized amplitude value (B2) Tracking target normalized amplitude value (B2).	R	Y		float	%	%	float32	%				
43241	3240	TampC1	Tracking target normalized amplitude value (C1) Tracking target normalized amplitude value (C1).	R	Y		float	%	%	float32	%				
43243	3242	TampC2	Tracking target normalized amplitude value (C2) Tracking target normalized amplitude value (C2).	R	Y		float	%	%	float32	%				
43245	3244	TampD1	Tracking target normalized amplitude value (D1) Tracking target normalized amplitude value (D1).	R	Y		float	%	%	float32	%				
43247	3246	TampD2	Tracking target normalized amplitude value (D2) Tracking target normalized amplitude value (D2).	R	Y		float	%	%	float32	%				
43501	3500	IsFwdPropADfltBin1	Fwd chord A bin 1 default proportion indicator Forward direction chord A bin 1 default proportion indicator.	R	Y		float	-	-	boolean	-				
43503	3502	FwdPropVelABin1	Proportion update fwd direction chord A bin 1 velocity Proportion update forward direction chord A bin 1 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
					<u> </u>					•					

Rosemou	nt™ Liqui	id Ultrasonic Firmware: 1.61	Database: 2.29.017		—										
The below	Modbus	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
43505	3504	FwdPropABin1	Fwd direction chord A bin 1 proportion Forward direction chord A bin 1 proportion.	R	Y		float	-	-	float32	-				
43507	3506	lsFwdPropBDfltBin1	Fwd chord B bin 1 default proportion indicator Forward direction chord B bin 1 default proportion indicator.	R	Y		float	-	-	boolean	-				
43509	3508	FwdPropVelBBin1	Proportion update fwd direction chord B bin 1 velocity Proportion update forward direction chord B bin 1 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43511	3510	FwdPropBBin1	Fived direction chord B bin 1 proportion.	R	Y		float	-	-	float32	-				
43513	3512	lsFwdPropCDfltBin1	Forward direction chord C bin 1 default proportion indicator Forward direction chord C bin 1 default proportion indicator.	R	Y		float	-	-	boolean	-				
43515	3514	FwdPropVelCBin1	Proportion update forward direction chord C bin 1 velocity Proportion update forward direction chord C bin 1 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43517	3516	FwdPropCBin1	Find one operation of the second of the relationst the second of the sec	R	Y		float	-	-	float32	-				
43519	3518	lsFwdPropDDfltBin1	Forward unection critical to fully proportion indicator Forward direction chord D bin 1 default proportion indicator.	R	Y		float	-	-	boolean	-				
43521	3520	FwdPropVelDBin1	Proportion update forward direction chord D bin 1 velocity Proportion update forward direction chord D bin 1 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43523	3522	FwdPropDBin1	Figure 1 and a lace of the barry reactly. Find direction chord D bin 1 proportion Forward direction chord D bin 1 proportion.	R	Y		float	-	-	float32	-				
43525	3524	lsFwdPropADfltBin2	Fwd chord A bin 2 default proportion indicator	R	Y		float	-	-	boolean	-				
43527	3526	FwdPropVelABin2	Forward direction chord A bin 2 default proportion indicator. Proportion update fwd direction chord A bin 2 velocity Proportion update forward direction chord A bin 2 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43529	3528	FwdPropABin2	Froportion update investor factor from 2 vericity. Fwd direction chord A bin 2 proportion Forward direction chord A bin 2 proportion.	R	Y		float	-	-	float32	-				
43531	3530	lsFwdPropBDfltBin2	Forward unection critical proportion indicator Forward direction chord B bin 2 default proportion indicator.	R	Y		float	-	-	boolean	-				
43533	3532	FwdPropVelBBin2	Proportion update fwd direction chord B bin 2 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43535	3534	FwdPropBBin2	Proportion update forward direction chord B bin 2 velocity. Fwd direction chord B bin 2 proportion Fwd direction chord B bin 2 proporti	R	Y		float	-	-	float32	-				
43537	3536	lsFwdPropCDfltBin2	Forward direction chord B bin 2 proportion. Fwd chord C bin 2 default proportion indicator France of Provide and the state of the state	R	Y		float	-	-	boolean	-				
43539	3538	FwdPropVelCBin2	Forward direction chord C bin 2 default proportion indicator. Proportion update fwd direction chord C bin 2 velocity Constraint of the direction chord C bin 2 velocity Con	R	Y		float	m/s	ft/s	float32	m/s				
43541	3540	FwdPropCBin2	Proportion update forward direction chord C bin 2 velocity. Fwd direction chord C bin 2 proportion	R	Y		float	-	-	float32	-				
43543	3542	lsFwdPropDDfltBin2	Forward direction chord C bin 2 proportion. Fwd chord D bin 2 default proportion indicator	R	Y		float	-	-	boolean	-				
43545	3544	FwdPropVelDBin2	Forward direction chord D bin 2 default proportion indicator. Proportion update fwd direction chord D bin 2 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43547	3546	FwdPropDBin2	Proportion update forward direction chord D bin 2 velocity. Fwd direction chord D bin 2 proportion	R	Y		float	-	-	float32					
43549	3548	lsFwdPropADfltBin3	Forward direction chord D bin 2 proportion. Fwd chord A bin 3 default proportion indicator	R	Y		float	-	-	boolean	-				
43551	3550	FwdPropVelABin3	Forward direction chord A bin 3 default proportion indicator. Proportion update fwd direction chord A bin 3 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43553	3552	FwdPropABin3	Proportion update forward direction chord A bin 3 velocity. Fwd direction chord A bin 3 proportion	R	Y		float	-	-	float32	-				<u> </u>
43555	3554	IsFwdPropBDfltBin3	Forward direction chord A bin 3 proportion. Fwd chord B bin 3 default proportion indicator	R	Y		float	-	-	boolean	-				
43557	3556	FwdPropVelBBin3	Forward direction chord B bin 3 default proportion indicator. Proportion update fwd direction chord B bin 3 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43559	3558	FwdPropBBin3	Proportion update forward direction chord B bin 3 velocity. Fwd direction chord B bin 3 proportion	R	Y		float	-	-	float32	-				<u> </u>
43561	3560	IsFwdPropCDfltBin3	Forward direction chord B bin 3 proportion. Fwd chord C bin 3 default proportion indicator	R	Y		float	-	-	boolean	-				<u> </u>
43563	3562	FwdPropVelCBin3	Forward direction chord C bin 3 default proportion indicator. Proportion update fwd direction chord C bin 3 velocity	R	Y		float	m/s	ft/s	float32	m/s				├
43565	3564	FwdPropCBin3	Proportion update forward direction chord C bin 3 velocity. Fwd direction chord C bin 3 proportion	R	Y		float		-	float32	-				├
43567	3566	lsFwdPropDDfltBin3	Forward direction chord C bin 3 proportion. Fwd chord D bin 3 default proportion indicator	R	Y		float	-	-	boolean	-				├──┤
43569	3568	FwdPropVelDBin3	Forward direction chord D bin 3 default proportion indicator. Proportion update fwd direction chord D bin 3 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43571	3570	FwdPropDBin3	Proportion update forward direction chord D bin 3 velocity. Fwd direction chord D bin 3 proportion	R	Y		float	-	-	float32	-				├──┤
43573		IsFwdPropADfltBin4	Forward direction chord D bin 3 proportion. Fwd chord A bin 4 default proportion indicator	R	Y		float	-	-	boolean	-				├──┨
43575		FwdPropVelABin4	Forward direction chord A bin 4 default proportion indicator. Proportion update fwd direction chord A bin 4 velocity	R	Y		float	m/s	ft/s	float32	m/s				┝──┨
43577		FwdPropABin4	Proportion update forward direction chord A bin 4 velocity. Fwd direction chord A bin 4 proportion	R	Y		float		-	float32	-				┝──┨
43579		IsFwdPropBDfltBin4	Forward direction chord A bin 4 proportion. Fwd chord B bin 4 default proportion indicator	R	Y		float	-	-	boolean	-				├── ┨
43581		FwdPropVelBBin4	Forward direction chord B bin 4 default proportion indicator. Proportion update fwd direction chord B bin 4 velocity	R			float	m/s	ft/s	float32	m/s		_		<u> </u>
43583		FwdPropBBin4	Froportion update forward direction chord B bin 4 velocity. Fwd direction chord B bin 4 proportion Fwd direction chord B bin 4 proportion	R	Y		float	-	-	float32	-				
.0000	5502		Forward direction chord B bin 4 proportion.		<u> </u>			-	_	nodioz	-				

Rosemou	nt™ Liqui	id Ultrasonic Firmware: 1.61	Database: 2.29.017		—										—
			nount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding Register Number	Reg Num	Label	Description	Acc	NV /	Cnfg Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
43585	3584	IsFwdPropCDfltBin4	Fwd chord C bin 4 default proportion indicator Forward direction chord C bin 4 default proportion indicator.	R	Y		float	-	-	boolean	-				
43587	3586	FwdPropVelCBin4	Proportion update fwd direction chord C bin 4 velocity Proportion update forward direction chord C bin 4 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43589	3588	FwdPropCBin4	Fwd direction chord C bin 4 proportion Forward direction chord C bin 4 proportion.	R	Y		float	-	-	float32					
43591	3590	lsFwdPropDDfltBin4	Fwd chord D bin 4 default proportion indicator Forward direction chord D bin 4 default proportion indicator.	R	Y		float	-	-	boolean					
43593	3592	FwdPropVelDBin4	Proportion update fwd direction chord D bin 4 velocity Proportion update forward direction chord D bin 4 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43595	3594	FwdPropDBin4	Fwd direction chord D bin 4 proportion Forward direction chord D bin 4 proportion.	R	Y		float	-	-	float32	-				
43597	3596	lsFwdPropADfltBin5	Fwd chord A bin 5 default proportion indicator Forward direction chord A bin 5 default proportion indicator.	R	Y		float	-	-	boolean					
43599	3598	FwdPropVelABin5	Proportion update fwd direction chord A bin 5 velocity Proportion update forward direction chord A bin 5 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43601	3600	FwdPropABin5	Fwd direction chord A bin 5 proportion Forward direction chord A bin 5 proportion.	R	Y		float	-	-	float32					
43603	3602	lsFwdPropBDfltBin5	Fwd chord B bin 5 default proportion indicator Forward direction chord B bin 5 default proportion indicator.	R	Y		float	-	-	boolean	-				
43605	3604	FwdPropVelBBin5	Proportion update fwd direction chord B bin 5 velocity Proportion update forward direction chord B bin 5 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43607	3606	FwdPropBBin5	Fwd direction chord B bin 5 proportion Forward direction chord B bin 5 proportion.	R	Y		float	-	-	float32	-				
43609	3608	lsFwdPropCDfltBin5	Fwd chord C bin 5 default proportion indicator Forward direction chord C bin 5 default proportion indicator.	R	Y		float	-	-	boolean					
43611	3610	FwdPropVelCBin5	Proportion update fwd direction chord C bin 5 velocity Proportion update forward direction chord C bin 5 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43613	3612	FwdPropCBin5	Find direction chord C bin 5 proportion Forward direction chord C bin 5 proportion.	R	Y		float	-	-	float32					
43615	3614	lsFwdPropDDfltBin5	Fwd chord D bin 5 default proportion indicator Forward direction chord D bin 5 default proportion indicator.	R	Y		float	-	-	boolean					
43617	3616	FwdPropVelDBin5	Proportion update fwd direction chord D bin 5 velocity Proportion update forward direction chord D bin 5 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43619	3618	FwdPropDBin5	Fwd direction chord D bin 5 proportion Forward direction chord D bin 5 proportion.	R	Y		float	-	-	float32	-				
43621	3620	lsFwdPropADfltBin6	Fwd chord A bin 6 default proportion indicator Forward direction chord A bin 6 default proportion indicator.	R	Y		float	-	-	boolean	-				
43623	3622	FwdPropVelABin6	Proportion update forward direction chord A bin 6 velocity Proportion update forward direction chord A bin 6 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43625	3624	FwdPropABin6	Five direction chord A bin 6 proportion Forward direction chord A bin 6 proportion.	R	Y		float	-	-	float32	-				
43627	3626	lsFwdPropBDfltBin6	Fwd chord B bin 6 default proportion indicator Forward direction chord B bin 6 default proportion indicator.	R	Y		float	-	-	boolean					
43629	3628	FwdPropVelBBin6	Proportion update forward direction chord B bin 6 velocity Proportion update forward direction chord B bin 6 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43631	3630	FwdPropBBin6	Five direction chord B bin 6 proportion Forward direction chord B bin 6 proportion	R	Y		float	-	-	float32					
43633	3632	IsFwdPropCDfltBin6	Fwd chord C bin 6 default proportion indicator Forward direction chord C bin 6 default proportion indicator.	R	Y		float	-	-	boolean	-				
43635	3634	FwdPropVelCBin6	Proportion update fived direction chord C bin 6 velocity Proportion update forward direction chord C bin 6 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43637	3636	FwdPropCBin6	Five direction chord C bin 6 proportion Forward direction chord C bin 6 proportion	R	Y		float	-	-	float32					
43639	3638	lsFwdPropDDfltBin6	Find chock of the other propriate. Find chock D bin 6 default proportion indicator Forward direction chord D bin 6 default proportion indicator.	R	Y		float	-	-	boolean					
43641	3640	FwdPropVelDBin6	Proportion update forward direction chord D bin 6 velocity Proportion update forward direction chord D bin 6 velocity	R	Y	+	float	m/s	ft/s	float32	m/s				
43643	3642	FwdPropDBin6	Find direction choice of the foreportion Forward direction choird D bin 6 proportion Forward direction choird D bin 6 proportion.	R	Y	+	float	-	-	float32	-				
43645	3644	lsFwdPropADfltBin7	Fwd chord A bin 7 default proportion indicator Forward direction chord A bin 7 default proportion indicator.	R	Y		float	-	-	boolean	-				
43647	3646	FwdPropVelABin7	Proportion update forward direction chord A bin 7 velocity Proportion update forward direction chord A bin 7 velocity.	R	Y	+	float	m/s	ft/s	float32	m/s				
43649	3648	FwdPropABin7	Propriori update forward direction choid A bin 7 velocity. Fwd direction chord A bin 7 proportion Forward direction chord A bin 7 oroportion.	R	Y		float	-	-	float32	-				
43651	3650	lsFwdPropBDfltBin7	Forward oriection child A bin 7 propriodit. Fwd chord B bin 7 default proportion indicator Forward direction chord B bin 7 default proportion indicator.	R	Y		float	-	-	boolean	-				
43653	3652	FwdPropVelBBin7	Propertion update forward direction chord B bin 7 velocity Proportion update forward direction chord B bin 7 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43655	3654	FwdPropBBin7	Proprion update torward direction chord a bin 7 velocity. Fwd direction chord B bin 7 proportion Forward direction chord B bin 7 proportion.	R	Y		float		-	float32					
43657	3656	lsFwdPropCDfltBin7	Forward direction child 5 bit / proportion. Fwd chord C bit 7 default proportion indicator Forward direction chord C bit 7 default proportion indicator.	R	Y		float	-	-	boolean	-				
43659	3658	FwdPropVelCBin7	Propertion update forward direction chord C bin 7 velocity Proportion update forward direction chord C bin 7 velocity	R	Y	+	float	m/s	ft/s	float32	m/s				
43661	3660	FwdPropCBin7	Fwd direction chord C bin 7 proportion	R	Y		float	-	-	float32	-				<u> </u>]
43663	3662	lsFwdPropDDfltBin7	Forward direction chord C bin 7 proportion. Five chord D bin 7 default proportion indicator Five chord D bin 7 default proportion indicator	R	Y		float	-	-	boolean	-				<u> </u>
			Forward direction chord D bin 7 default proportion indicator.												

Rosemou	nt™ Liqu	id Ultrasonic Firmware: 1.61	Database: 2.29.017		—										
The below	/ Modbus	map is applicable for Rose	nount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
43665	3664	FwdPropVelDBin7	Proportion update fwd direction chord D bin 7 velocity Proportion update forward direction chord D bin 7 velocity.	R	Y		float	m/s	Unit ft/s	float32	m/s				
43667	3666	FwdPropDBin7	Fwd direction chord D bin 7 proportion Forward direction chord D bin 7 proportion.	R	Y		float	-	-	float32	-				
43669	3668	lsFwdPropADfltBin8	Fwd chord A bin 8 default proportion indicator Forward direction chord A bin 8 default proportion indicator.	R	Y		float	-	-	boolean	-				
43671	3670	FwdPropVelABin8	Proportion update forward direction chord A bin 8 velocity Proportion update forward direction chord A bin 8 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43673	3672	FwdPropABin8	Five direction chord A bin 8 proportion Forward direction chord A bin 8 proportion	R	Y		float	-	-	float32	-				
43675	3674	lsFwdPropBDfltBin8	Fwd chord B bin 8 default proportion indicator Forward direction chord B bin 8 default proportion indicator.	R	Y		float	-	-	boolean	-				
43677	3676	FwdPropVelBBin8	Proportion update forward direction chord B bin 8 velocity Proportion update forward direction chord B bin 8 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43679	3678	FwdPropBBin8	Five direction chord B bin 8 proportion Forward direction chord B bin 8 proportion.	R	Y		float	-	-	float32	-				
43681	3680	IsFwdPropCDfltBin8	Fwd chord C bin 8 default proportion indicator Forward direction chord C bin 8 default proportion indicator.	R	Y		float	-	-	boolean	-				
43683	3682	FwdPropVelCBin8	Proportion update fived direction chord C bin 8 velocity Proportion update fived direction chord C bin 8 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43685	3684	FwdPropCBin8	Five direction chord C bin 8 proportion Forward direction chord C bin 8 proportion	R	Y		float	-	-	float32	-				
43687	3686	lsFwdPropDDfltBin8	Fived chord D bin 8 default proportion indicator Forward direction chord D bin 8 default proportion indicator.	R	Y		float	-	-	boolean	-				
43689	3688	FwdPropVelDBin8	Proportion update fowd direction chord D bin 8 velocity Proportion update fowd direction chord D bin 8 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43691	3690	FwdPropDBin8	First of the second sec	R	Y		float	-		float32	-				
43693	3692	lsFwdPropADfltBin9	Five chord A bin 9 default proportion indicator Forward direction chord A bin 9 default proportion indicator.	R	Y		float	-	-	boolean	-				
43695	3694	FwdPropVelABin9	Proportion update forward election chord A bin 9 velocity Proportion update forward election chord A bin 9 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43697	3696	FwdPropABin9	Five direction chord A bin 9 proportion Forward direction chord A bin 9 proportion Forward direction chord A bin 9 proportion.	R	Y		float	-	-	float32	-				
43699	3698	lsFwdPropBDfltBin9	Fwad chord B bin 9 default proportion indicator Forward direction chord B bin 9 default proportion indicator.	R	Y		float	-	-	boolean	-				
43701	3700	FwdPropVelBBin9	Proportion update forward direction chord B bin 9 velocity Proportion update forward direction chord B bin 9 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43703	3702	FwdPropBBin9	Fwd direction chord B bin 9 proportion	R	Y		float	-	-	float32	-				
43705	3704	lsFwdPropCDfltBin9	Forward direction chord B bin 9 proportion. Find chord C bin 9 default proportion indicator Found chord being being C bin to default and the indicator Found direction being C bin to default and the indicator	R	Y		float	-	-	boolean	-				
43707	3706	FwdPropVelCBin9	Forward direction chord C bin 9 default proportion indicator. Proportion update fwd direction chord C bin 9 velocity Proportion update foward direction chord C bin 9 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43709	3708	FwdPropCBin9	Fwd direction chord C bin 9 proportion	R	Y		float	-	-	float32	-				
43711	3710	lsFwdPropDDfltBin9	Forward direction chord C bin 9 proportion. Five chord D bin 9 default proportion indicator Five chord D bin 9 default proportion indicator	R	Y		float	-	-	boolean	-				
43713	3712	FwdPropVelDBin9	Forward direction chord D bin 9 default proportion indicator. Proportion update fixed direction chord D bin 9 velocity Description update fixed direction chord D bin 9 velocity Description update fixed direction chord D bin 9 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43715	3714	FwdPropDBin9	Proportion update forward direction chord D bin 9 velocity. Fwd direction chord D bin 9 proportion Forward direction chord D bin 9 proportion.	R	Y		float	-	-	float32					
43717	3716	lsFwdPropADfltBin10	Fwd chord A bin 10 default proportion indicator	R	Y		float	-	-	boolean	-				
43719	3718	FwdPropVelABin10	Forward direction chord A bin 10 default proportion indicator. Proportion update fwd direction chord A bin 10 velocity Proportion update forward direction chord A bin 10 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43721	3720	FwdPropABin10	Fwd direction chord A bin 10 proportion	R	Y		float	-	-	float32	-				
43723	3722	lsFwdPropBDfltBin10	Forward direction chord A bin 10 proportion. Find chord B bin 10 default proportion indicator Found direction chord B bin 10 default proportion indicator Found direction chord B bin 6 default proportion indicator	R	Y		float	-	-	boolean	-				
43725	3724	FwdPropVelBBin10	Forward direction chord B bin 10 default proportion indicator. Proportion update fwd direction chord B bin 10 velocity Proportion update forward direction chord B bin 10 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43727	3726	FwdPropBBin10	Fwd direction chord B bin 10 proportion	R	Y		float	-	-	float32	-				
43729	3728	lsFwdPropCDfltBin10	Forward direction chord B bin 10 proportion. Fwd chord C bin 10 default proportion indicator Forward direction chord C bin 10 default proportion indicator.	R	Y		float	-	-	boolean	-				I
43731	3730	FwdPropVelCBin10	Proportion update fwd direction chord C bin 10 velocity	R	Y		float	m/s	ft/s	float32	m/s				I
43733	3732	FwdPropCBin10	Proportion update forward direction chord C bin 10 velocity. Fwd direction chord C bin 10 proportion Fwd direction chord C bin	R	Y		float	-	-	float32	-				
43735	3734	lsFwdPropDDfltBin10	Forward direction chord C bin 10 proportion. Find chord D bin 10 default proportion indicator Found doing to be of D bin 0 default proportion indicator Found doing the best D bin 6 default proportion indicator	R	Y		float	-	-	boolean	-				<u> </u>
43737	3736	FwdPropVelDBin10	Forward direction chord D bin 10 default proportion indicator. Proportion update find direction chord D bin 10 velocity Description to direct the direction chord D bin 10 velocity	R	Y	_	float	m/s	ft/s	float32	m/s				
43739	3738	FwdPropDBin10	Proportion update forward direction chord D bin 10 velocity. Fwd direction chord D bin 10 proportion Fwd direction chord D bin	R	Y		float	-	-	float32	-				
43801	3800	IsRevPropADfltBin1	Forward direction chord D bin 10 proportion. Rev chord A bin 1 default proportion indicator	R	Y		float	-	-	boolean	-				
43803	3802	RevPropVelABin1	Reverse direction chord A bin 1 default proportion indicator. Proportion update rev direction chord A bin 1 velocity	R	Y	_	float	m/s	ft/s	float32	m/s				┌───┨
			Proportion update reverse direction chord A bin 1 velocity.												

Rosemou	nt™ Liqui	d Ultrasonic Firmware: 1.61	Database: 2.29.017												
The below	Modbus	map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
43805	3804	RevPropABin1	Rev direction chord A bin 1 proportion Reverse direction chord A bin 1 proportion.	R	Y		float	-	-	float32	-				
43807	3806	IsRevPropBDfltBin1	Rev chord B bin 1 default proportion indicator Reverse direction chord B bin 1 default proportion indicator.	R	Υ		float	-	-	boolean	-				
43809	3808	RevPropVelBBin1	Proportion update rev direction chord B bin 1 velocity Proportion update reverse direction chord B bin 1 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43811	3810	RevPropBBin1	Rev direction chord B bin 1 proportion Reverse direction chord B bin 1 proportion.	R	Y		float	-	-	float32	-				
43813	3812	IsRevPropCDfltBin1	Rev chord C bin 1 default proportion indicator Reverse direction chord C bin 1 default proportion indicator.	R	Y		float	-	-	boolean	-				
43815	3814	RevPropVelCBin1	Proportion update reverse direction chord C bin 1 velocity Proportion update reverse direction chord C bin 1 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43817	3816	RevPropCBin1	Rev direction chord C bin 1 proportion.	R	Y		float		-	float32	-				
43819	3818	IsRevPropDDfltBin1	Rev chord D bin 1 default proportion indicator Reverse direction chord D bin 1 default proportion indicator.	R	Y		float	-	-	boolean	-				
43821	3820	RevPropVelDBin1	Proportion update reverse direction chord D bin 1 velocity Proportion update reverse direction chord D bin 1 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43823	3822	RevPropDBin1	Rev direction chord D bin 1 proportion Reverse direction chord D bin 1 proportion	R	Y		float	-	-	float32	-				
43825	3824	lsRevPropADfltBin2	Rev chord A bin 2 default proportion indicator	R	Y		float	-	-	boolean	-				[]
43827	3826	RevPropVelABin2	Reverse direction chord A bin 2 default proportion indicator. Proportion update rev direction chord A bin 2 velocity Proportion update reverse direction chord A bin 2 velocity.	R	Y		float	m/s	ft/s	float32	m/s				[]
43829	3828	RevPropABin2	Propriori update reverse directioni chicità a bin 2 veracity. Rev direction chord A bin 2 proportion Reverse direction chord A bin 2 proportion.	R	Y		float	-	-	float32	-				
43831	3830	lsRevPropBDfltBin2	Reverse direction china v bin 2 propriation. Rev chord B bin 2 default proportion indicator Reverse direction chord B bin 2 default proportion indicator.	R	Y		float	-	-	boolean					
43833	3832	RevPropVelBBin2	Proportion update rev direction chord B bin 2 velocity	R	Y		float	m/s	ft/s	float32	m/s				[]
43835	3834	RevPropBBin2	Proportion update reverse direction chord B bin 2 velocity. Rev direction chord B bin 2 proportion	R	Y		float	-	-	float32	-				
43837	3836	lsRevPropCDfltBin2	Reverse direction chord B bin 2 proportion. Rev chord C bin 2 default proportion indicator	R	Y		float	-	-	boolean	-				
43839	3838	RevPropVelCBin2	Reverse direction chord C bin 2 default proportion indicator. Proportion update rev direction chord C bin 2 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43841	3840	RevPropCBin2	Proportion update reverse direction chord C bin 2 velocity. Rev direction chord C bin 2 proportion	R	Y		float	-	-	float32	-				<u> </u>
43843	3842	IsRevPropDDfltBin2	Reverse direction chord C bin 2 proportion. Rev chord D bin 2 default proportion indicator	R	Y		float	-	-	boolean	-				<u> </u>
43845	3844	RevPropVelDBin2	Reverse direction chord D bin 2 default proportion indicator. Proportion update rev direction chord D bin 2 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43847	3846	RevPropDBin2	Proportion update reverse direction chord D bin 2 velocity. Rev direction chord D bin 2 proportion	R	Y		float	-	-	float32	-				<u> </u>
43849	3848	lsRevPropADfltBin3	Reverse direction chord D bin 2 proportion. Rev chord A bin 3 default proportion indicator	R	Y		float	-	-	boolean	-				<u> </u>
43851	3850	RevPropVelABin3	Reverse direction chord A bin 3 default proportion indicator. Proportion update rev direction chord A bin 3 velocity	R	Y		float	m/s	ft/s	float32	m/s				<u> </u>
43853	3852	RevPropABin3	Proportion update reverse direction chord A bin 3 velocity. Rev direction chord A bin 3 proportion	R	Y		float	-	-	float32	-				<u> </u>
43855	3854	IsRevPropBDfltBin3	Reverse direction chord A bin 3 proportion. Rev chord B bin 3 default proportion indicator	R	Y		float	-	-	boolean	-				<u> </u>
43857		RevPropVelBBin3	Reverse direction chord B bin 3 default proportion indicator. Proportion update rev direction chord B bin 3 velocity	R	Y		float	m/s	ft/s	float32	m/s				<u> </u>
43859		RevPropBBin3	Proportion update reverse direction chord B bin 3 velocity. Rev direction chord B bin 3 proportion	R	Y		float	-	-	float32					<u> </u>
43861		IsRevPropCDfltBin3	Reverse direction chord B bin 3 proportion. Rev chord C bin 3 default proportion indicator	R	Y		float	-	-	boolean	-				<u> </u>
43863		RevPropVelCBin3	Reverse direction chord C bin 3 default proportion indicator. Proportion update rev direction chord C bin 3 velocity	R	Y		float	m/s	ft/s	float32	m/s				<u> </u>
43865		RevPropCBin3	Proportion update reversa direction chard C bin 3 velocity Proportion update reversa direction chard C bin 3 velocity. Rev direction chard C bin 3 proportion	R	Y		float			float32	-				⊢]
43003	0000		Reverse direction chord C bin 3 proportion.	P	~		float	_	-	hardson					ļ]
43869		RevPropVelDBin3	Kev chord D bn 3 default proportion indicator Reverse direction chord D bin 3 default proportion indicator. Proportion update rev direction chord D bin 3 velocity	R	Y		float	- m/s	- ft/s	float32	- m/s		_		⊢]
43809			Proportion update reverse direction chord D bin 3 velocity.	R	' V			/5	1/3		1105				⊢]
		RevPropDBin3	Rev direction chord D bin 3 proportion Reverse direction chord D bin 3 proportion.		T		float	-	-	float32	-				<u> </u>
43873		IsRevPropADfltBin4	Rev chord A bin 4 default proportion indicator Reverse direction chord A bin 4 default proportion indicator.	R	Y		float	-	-	boolean	-				<u> </u>
43875		RevPropVelABin4	Proportion update rev direction chord A bin 4 velocity Proportion update reverse direction chord A bin 4 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43877		RevPropABin4	Rev direction chord A bin 4 proportion Reverse direction chord A bin 4 proportion.	R	Y		float	-	-	float32	-				
43879		IsRevPropBDfltBin4	Rev chord B bin 4 default proportion indicator Reverse direction chord B bin 4 default proportion indicator.	R	Y		float	-	-	boolean	-				
43881		RevPropVelBBin4	Proportion update rev direction chord B bin 4 velocity Proportion update reverse direction chord B bin 4 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43883	3882	RevPropBBin4	Rev direction chord B bin 4 proportion Reverse direction chord B bin 4 proportion.	R	Y		float	-	-	float32	-				

Rosemour	ıt™ Liqui	d Ultrasonic Firmware: 1.61	Database: 2.29.017												
The below	Modbus	map is applicable for Rose	nount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
43885	3884	IsRevPropCDfltBin4	Rev chord C bin 4 default proportion indicator Reverse direction chord C bin 4 default proportion indicator.	R	Y		float	-	-	boolean	-				
43887	3886	RevPropVelCBin4	Proportion update rev direction chord C bin 4 velocity Proportion update reverse direction chord C bin 4 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43889	3888	RevPropCBin4	Rev direction chord C bin 4 proportion Reverse direction chord C bin 4 proportion.	R	Y		float	-	-	float32	-				
43891	3890	IsRevPropDDfltBin4	Rev chord D bin 4 default proportion indicator Reverse direction chord D bin 4 default proportion indicator.	R	Y		float	-	-	boolean	-				
43893	3892	RevPropVelDBin4	Proportion update rev direction chord D bin 4 velocity Proportion update reverse direction chord D bin 4 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43895	3894	RevPropDBin4	Rev direction chord D bin 4 proportion.	R	Y		float	-	-	float32	-				
43897	3896	IsRevPropADfltBin5	Rev chord A bin 5 default proportion indicator Reverse direction chord A bin 5 default proportion indicator.	R	Y		float	-	-	boolean	-				
43899	3898	RevPropVelABin5	Proportion update reverse direction chord A bin 5 velocity Proportion update reverse direction chord A bin 5 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43901	3900	RevPropABin5	Rev direction chord A bin 5 proportion Reverse direction chord A bin 5 proportion	R	Y		float	-	-	float32	-				
43903	3902	IsRevPropBDfltBin5	Rev chord B bin 5 default proportion indicator	R	Y		float	-	-	boolean	-				
43905	3904	RevPropVelBBin5	Reverse direction chord B bin 5 default proportion indicator. Proportion update rev direction chord B bin 5 velocity Proportion update reverse direction chord B bin 5 velocity	R	Y		float	m/s	ft/s	float32	m/s]
43907	3906	RevPropBBin5	Proportion update reverse direction chord B bin 5 velocity. Rev direction chord B bin 5 proportion Reverse direction chord B bin 5 proportion.	R	Y		float	-	-	float32	-]
43909	3908	IsRevPropCDfltBin5	Rev chord C bin 5 default proportion indicator	R	Y		float	-	-	boolean	-]
43911	3910	RevPropVelCBin5	Reverse direction chord C bin 5 default proportion indicator. Proportion update rev direction chord C bin 5 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43913	3912	RevPropCBin5	Proportion update reverse direction chord C bin 5 velocity. Rev direction chord C bin 5 proportion	R	Y	-	float	-	-	float32	-				
43915	3914	IsRevPropDDfltBin5	Reverse direction chord C bin 5 proportion. Rev chord D bin 5 default proportion indicator	R	Y	-	float	-	-	boolean	-				
43917	3916	RevPropVelDBin5	Reverse direction chord D bin 5 default proportion indicator. Proportion update rev direction chord D bin 5 velocity	R	Y	-	float	m/s	ft/s	float32	m/s				
43919	3918	RevPropDBin5	Proportion update reverse direction chord D bin 5 velocity. Rev direction chord D bin 5 proportion	R	Y	-	float	-	-	float32	-				
43921	3920	IsRevPropADfltBin6	Reverse direction chord D bin 5 proportion. Rev chord A bin 6 default proportion indicator	R	Y		float	-	-	boolean	-				
43923	3922	RevPropVelABin6	Reverse direction chord A bin 6 default proportion indicator. Proportion update rev direction chord A bin 6 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43925	3924	RevPropABin6	Proportion update reverse direction chord A bin 6 velocity. Rev direction chord A bin 6 proportion	R	Y	_	float	-	-	float32	-				
43927	3926	IsRevPropBDfltBin6	Reverse direction chord A bin 6 proportion. Rev chord B bin 6 default proportion indicator	R	Y	_	float	-	-	boolean	-				
43929	3928	RevPropVelBBin6	Reverse direction chord B bin 6 default proportion indicator. Proportion update rev direction chord B bin 6 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43931	3930	RevPropBBin6	Proportion update reverse direction chord B bin 6 velocity. Rev direction chord B bin 6 proportion	R	Y		float	-	-	float32	-				
43933	3932	IsRevPropCDfltBin6	Reverse direction chord B bin 6 proportion. Rev chord C bin 6 default proportion indicator	R	Y		float	-	-	boolean	-				
43935	3934	RevPropVelCBin6	Reverse direction chord C bin 6 default proportion indicator. Proportion update rev direction chord C bin 6 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43937		RevPropCBin6	Proportion update reverse direction chord C bin 6 velocity. Rev direction chord C bin 6 proportion	R	Y	_	float	-	-	float32	-				
43939		IsRevPropDDfltBin6	Reverse direction chord C bin 6 proportion. Rev chord D bin 6 default proportion indicator	R	Y	_	float	-	-	boolean	-				
43941		RevPropVelDBin6	Reverse direction chord D bin 6 default proportion indicator. Proportion update rev direction chord D bin 6 velocity	R	Y		float	m/s	ft/s	float32	m/s				
43943		RevPropDBin6	Proportion update reverse direction chord D bin 6 velocity. Rev direction chord D bin 6 proportion	R	Y		float	-	-	float32	-				┟───┨
43945		IsRevPropADfltBin7	Reverse direction chord D bin 6 proportion. Rev chord A bin 7 default proportion indicator	R	Y		float		-	boolean	-				ļ
43947	3946	D. D	Reverse direction chord A bin 7 default proportion indicator. Proportion update rev direction chord A bin 7 velocity	R	· Y	_	float	m/s	ft/s	float32	m/s				
43947		RevPropABin7	Proportion update reverse direction chord A bin 7 velocity. Proportion update reverse direction chord A bin 7 velocity. Rev direction chord A bin 7 proportion	R	Y	-+	float			float32	-				<u> </u>
43951		IsRevPropBDfltBin7	Reverse direction choid A bin 7 proportion. Rev chord B bin 7 default proportion indicator	R	v		float								
43951			Reverse direction chord B bin 7 default proportion indicator.	R	' V					float32			_		ļ]
43953		RevPropVelBBin7 RevPropBBin7	Proportion update rev direction chord B bin 7 velocity Proportion update reverse direction chord B bin 7 velocity. Rev direction chord B bin 7 proportion		' V		float float	m/s	ft/s	float32	m/s		_		<u> </u>
			Rev arisection chord B bin 7 proportion. Reverse direction chord B bin 7 proportion. Rev chord C bin 7 default proportion indicator	R	' V			-	-	float32	-		_		<u> </u>
43957		IsRevPropCDfltBin7	Reverse direction chord C bin 7 default proportion indicator.	R	T	\square	float	-	-	boolean	-				ļ]
43959		RevPropVelCBin7	Proportion update rev direction chord C bin 7 velocity Proportion update reverse direction chord C bin 7 velocity.	R	Y		float	m/s	ft/s	float32	m/s				<u> </u>
43961		RevPropCBin7	Rev direction chord C bin 7 proportion Reverse direction chord C bin 7 proportion.	R	Y		float	-	-	float32	-				
43963	3962	IsRevPropDDfltBin7	Rev chord D bin 7 default proportion indicator Reverse direction chord D bin 7 default proportion indicator.	R	Y		float	-	-	boolean	-				j

Rosemou	nt™ Liqu	id Ultrasonic Firmware: 1.61	Database: 2.29.017												
			mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
43965	3964	RevPropVelDBin7	Proportion update rev direction chord D bin 7 velocity Proportion update reverse direction chord D bin 7 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43967	3966	RevPropDBin7	Rev direction chord D bin 7 proportion Reverse direction chord D bin 7 proportion.	R	Y		float	-	-	float32	-				
43969	3968	IsRevPropADfltBin8	Rev chord A bin 8 default proportion indicator Reverse direction chord A bin 8 default proportion indicator.	R	Y		float	-	-	boolean	-				
43971	3970	RevPropVelABin8	Proportion update rev direction chord A bin 8 velocity Proportion update reverse direction chord A bin 8 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43973	3972	RevPropABin8	Rev direction chord A bin 8 proportion Reverse direction chord A bin 8 proportion.	R	Y		float	-	-	float32	-				
43975	3974	lsRevPropBDfltBin8	Rev chord B bin 8 default proportion indicator Reverse direction chord B bin 8 default proportion indicator.	R	Y		float	-	-	boolean	-				
43977	3976	RevPropVelBBin8	Proportion update rev direction chord B bin 8 velocity Proportion update reverse direction chord B bin 8 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43979	3978	RevPropBBin8	Rev direction chord B bin 8 proportion Reverse direction chord B bin 8 proportion.	R	Y		float	-	-	float32	-				
43981	3980	IsRevPropCDfltBin8	Rev chord C bin 8 default proportion indicator Reverse direction chord C bin 8 default proportion indicator.	R	Y		float	-	-	boolean	-				
43983	3982	RevPropVelCBin8	Proportion update rev direction chord C bin 8 velocity Proportion update reverse direction chord C bin 8 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43985	3984	RevPropCBin8	Rev direction chord C bin 8 proportion Reverse direction chord C bin 8 proportion.	R	Y		float	-	-	float32	-				
43987	3986	lsRevPropDDfltBin8	Rev chord D bin 8 default proportion indicator Reverse direction chord D bin 8 default proportion indicator.	R	Y		float	-	-	boolean	-				
43989	3988	RevPropVelDBin8	Proportion update rev direction chord D bin 8 velocity Proportion update reverse direction chord D bin 8 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43991	3990	RevPropDBin8	Rev direction chord D bin 8 proportion Reverse direction chord D bin 8 proportion.	R	Y		float	-	-	float32	-				
43993	3992	lsRevPropADfltBin9	Rev chord A bin 9 default proportion indicator Reverse direction chord A bin 9 default proportion indicator.	R	Y		float	-	-	boolean	-				
43995	3994	RevPropVelABin9	Proportion update rev direction chord A bin 9 velocity Proportion update reverse direction chord A bin 9 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
43997	3996	RevPropABin9	Rev direction chord A bin 9 proportion Reverse direction chord A bin 9 proportion.	R	Y		float	-	-	float32	-				
43999	3998	lsRevPropBDfltBin9	Rev chord B bin 9 default proportion indicator Reverse direction chord B bin 9 default proportion indicator.	R	Y		float	-	-	boolean	-				
44001	4000	RevPropVelBBin9	Proportion update rev direction chord B bin 9 velocity Proportion update reverse direction chord B bin 9 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
44003	4002	RevPropBBin9	Rev direction chord B bin 9 proportion Reverse direction chord B bin 9 proportion.	R	Y		float	-	-	float32	-				
44005	4004	IsRevPropCDfltBin9	Rev chord C bin 9 default proportion indicator Reverse direction chord C bin 9 default proportion indicator.	R	Y		float	-	-	boolean	-				
44007	4006	RevPropVelCBin9	Proportion update rev direction chord C bin 9 velocity Proportion update reverse direction chord C bin 9 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
44009	4008	RevPropCBin9	Rev direction chord C bin 9 proportion Reverse direction chord C bin 9 proportion.	R	Y		float	-	-	float32	-				
44011	4010	lsRevPropDDfltBin9	Rev chord D bin 9 default proportion indicator Reverse direction chord D bin 9 default proportion indicator.	R	Y		float	-	-	boolean	-				
44013	4012	RevPropVelDBin9	Proportion update rev direction chord D bin 9 velocity Proportion update reverse direction chord D bin 9 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
44015	4014	RevPropDBin9	Rev direction chord D bin 9 proportion Reverse direction chord D bin 9 proportion.	R	Y		float	-	-	float32	-				
44017	4016	IsRevPropADfltBin10	Rev chord A bin 10 default proportion indicator Reverse direction chord A bin 10 default proportion indicator.	R	Y		float	-	-	boolean	-				
44019	4018	RevPropVelABin10	Proportion update reverse direction chord A bin 10 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
44021	4020	RevPropABin10	Rev direction chord A bin 10 proportion.	R	Y		float	-	-	float32	-				
44023	4022	IsRevPropBDfltBin10	Rev chord B bin 10 default proportion indicator Reverse direction chord B bin 10 default proportion indicator.	R	Y		float	-	-	boolean	-				
44025	4024	RevPropVelBBin10	Proportion update reverse direction chord B bin 10 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
44027	4026	RevPropBBin10	Rev direction chord B bin 10 proportion.	R	Y		float	-	-	float32	-				
44029	4028	IsRevPropCDfltBin10	Reverse direction chord C bin 10 default proportion indicator.	R	Y		float	-	-	boolean	-				
44031	4030	RevPropVelCBin10	Proportion update rev direction chord C bin 10 velocity Proportion update reverse direction chord C bin 10 velocity	R	Y		float	m/s	ft/s	float32	m/s				
44033	4032	RevPropCBin10	Rev direction chord C bin 10 proportion.	R	Y		float	-	-	float32	-				
44035	4034	lsRevPropDDfltBin10	Reverse direction chord D bin 10 default proportion indicator.	R	Y		float	-	-	boolean	-				
44037	4036	RevPropVelDBin10	Proportion update reverse direction chord D bin 10 velocity.	R	Y		float	m/s	ft/s	float32	m/s				
44039	4038	RevPropDBin10	Rev direction chord D bin 10 proportion.	R	Y		float	-	-	float32	-				
44101	4100	HourlyMacro1	Newseconection Control 5 on 1 o proportion: Hourly log macro 1 Hourly log macro 1 Hourly log macro status indicator 1. This is a biffield that contains a variety of alarms bits that were active in the last logging hour. Each bit is "sticky" for the logging period and clears for the next hour if the condition cleared in that period. Consult the alarm log for further information.	R	Y		long	-	-	uint32	-				

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			emount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding			Description						N	Modbus	No. 7	Marker W. J.			Minimum	Maximum
Register Number	Reg Num	Label		Acc	NV	Cnfg P		odbus eg Type	Modbus Metric Unit	U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Value (native unit)	Value (native unit)
44103	4102	PHourlyMacro2	Hourly log macro 2 Hourly log macro status indicator 2. This is a bitfield that contains a variety of alarms bits that were active in the last logging hour. Each bit is "sticky" for the logging period and clears for the next hour if the condition cleared in that period. Consult the alarm log for further information.	R	Y			long	-	Unit -	uint32	-			(naive unit)	
44105	4104	PrevHourFlowTime	Previous hour's flow time Amount of time during the previous hour that flow was above the cutoff value.	R	Y		1	long	ms	ms	float32	min				
44107		Reserved		R				long								
44109 44111	4108	Reserved PrevHourFlowPosVol	Previous hour's forward volume at flow condition	R R	Y			long long	volume	volume	uint32	L				
		Des das Else Nación	Previous hour's flow-condition positive volume (int). Previous hour's reverse volume at flow condition	R												
44113	4112	PrevHourFlowNegVol	Previous hour's flow-condition negative volume (int).	ĸ	Ŷ			long	volume	volume	uint32	L				
44115		HourlyMacro1	Hourly log macro 1 Hourly log macro 1 and the logging hour. Each bit s'sticky' for the logging period and clears for the next hour if the condition cleared in that period. Consult the alarm log for further information.	R	Y			long	-	-	uint32	-				
44117		HourlyMacro2	Hourly log macro 2 Hourly log macro 2 Hourly log macro status indicator 2. This is a bitfield that contains a variety of alarms bits that were active in the last logging hour. Each bit is "sitcky" for the logging period and clears for the next hour if the condition cleared in that period. Consult the alarm log for further information.	R	Y			long	-	-	uint32	-				
44119		3 HourlyMacro3	Hourly log macro 3 Hourly log macro status indicator 3. This is a bitfield that contains a variety of alarms bits that were active in the last logging hour. Each bit is "sticky" for the logging period and clears for the next hour if the condition cleared in that period. Consult the alarm log for further information.	R	Y			long	-	-	uint32	-				
44121		HourlyMacro4	Hourly log macro 4 Hourly log macro 4 Hourly log macro status indicator 4. This is a bitfield that contains a variety of alarms bits that were active in the last logging hour. Each bit is "sitcky" for the logging period and clears for the next hour if the condition cleared in that period. Consult the alarm log for further information.	R	Ŷ			long	-	-	uint32	-				
44123		2 HourlyMacro5	Hourly log macro 5 Hourly log macro status indicator 5. This is a bitfield that contains a variety of alarms bits that were active in the last logging hour. Each bit is "sitcky" for the logging period and clears for the next hour if the condition cleared in that period. Consult the alarm log for further information.	R	Y			long	-	-	uint32	-				
44125	4124	HourlyMacro6	Hourly log macro 6 Hourly log macro status indicator 6. This is a bitfield that contains a variety of alarms bits that were active in the last logging hour. Each bit is "sticky" for the logging period and clears for the next hour if the condition cleared in that period. Consult the alarm log for further information.	R	Y			long	-	-	uint32	-				
44129	4128	3 DailyMacro1	Daily log macro 1 Daily log macro status indicator 1. This is a bitfield that contains a variety of alarms bits that were active in the last logging day. Each bit is "sticky" for the logging period and clears for the next day if the condition cleared in that period. Consult the alarm log for further information.	R	Y			long	-	-	uint32	-				
44131	4130	DailyMacro2	Daily log macro 2 Daily log macro status indicator 2. This is a bitfield that contains a variety of alarms bits not contained in status 1 that were active in the last logging day. Each bit is "sticky" for the logging period and clears for the next day if the condition cleared in that period. Consult the alarm log for further information.	R	Y		I	long	-	-	uint32	-				
44133	4132	2 DailyMacro3	Daily log macro 3 Daily log macro status indicator 3. This is a bitfield that contains a variety of alarms bits that were active in the last logging day. Each bit is "sticky" for the logging period and clears for the next day if the condition cleared in that period. Consult the alarm log for further information.	R	Y			long	-	-	uint32	-				
44135	4134	4 DailyMacro4	Daily log macro 4 Daily log macro status indicator 4. This is a bitfield that contains a variety of alarms bits not contained in status 1 that were active in the last logging day. Each bit is "sticky" for the logging period and clears for the next day if the condition cleared in that period. Consult the alarm log for further information.	R	Y		1	long	-	-	uint32	-				
44137	4136	DailyMacro5	Daily log macro 5 Daily log macro status indicator 5. This is a bitfield that contains a variety of alarms bits that were active in the last logging day. Each bit is "sticky" for the logging period and clears for the next day if the condition cleared in that period. Consult the alarm log for further information.	R	Y			long	-	-	uint32	-				
44139		3 DailyMacro6	Daily log macro 6 Daily log macro status indicator 6. This is a bitfield that contains a variety of alarms bits not contained in status 1 that were active in the last logging day. Each bit is 'sticky' for the logging period and clears for the next day if the condition cleared in that period. Consult the alarm log for further information.	R	Y			long	-	-	uint32	-				
44151	4150	DailyMacro1	Daily log macro 1 Daily log macro status indicator 1. This is a bitfield that contains a variety of alarms bits that were active in the last logging day. Each bit is "sticky" for the logging period and clears for the next day if the condition cleared in that period. Consult the alarm log for further information.	R	Y			long	-	-	uint32	-				
44153	4152	2 DailyMacro2	Daily bog macro 2 Daily bog macro status indicator 2. This is a bitfield that contains a variety of alarms bits not contained in status 1 that were active in the last logging day. Each bit is 'sticky' for the logging period and clears for the next day if the condition cleared in that period. Consult the alarm log for further information.	R	Y			long	-	-	uint32	-				
44155	4154	PrevDayFlowTime	Previous day's flow time Amount of time during the previous day that flow was above the cutoff value.	R	Y	$ \top$		long	ms	ms	float32	min				1
44157		Reserved		R				long								
44159 44161		Reserved PrevDayFlowPosVol	Previous day's forward volume at flow condition	R R	Y	\vdash		long long	volume	volume	uint32	L				
44163	4163	PrevDayFlowNegVol	Previous day's flow-condition positive volume (int). Previous day's reverse volume at flow condition	R	Y	\vdash	_	long	volume	volume	uint32	L				
			Previous day's flow-condition negative volume (int).		Ľ.											<u> </u>
44205		CurrHourFlowTime	Current hour's flow time Amount of time during the current hour that flow is above the cutoff value.	R	Ý			long	ms	ms	float32	min				
44207 44209		Reserved Reserved		R R	\square	\square		long long								⊢]
44209		CurrHourFlowPosVol	Current hour's flow-condition positive volume (int)	R	Y			long	volume	volume	uint32	L				
44213	4212	2 CurrHourFlowNegVol	Current hour's flow-condition positive volume (int). Current hour's flow-condition negative volume (int)	R	Y	\vdash		long	volume	volume	uint32	L				<u> </u>
		÷	Current hour's flow-condition negative volume (int).					-								

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			mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
			Description						Mo	odbus						
Holding Register Number	Reg Num	Label		Acc	NV	Cnfg Pr	ot Reg	Ibus Modb Type Metric I	us U Unit Cust	J.S. tomary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
44255	4254	CurrDayFlowTime	Current day's flow time Amount of time during the current day that flow is above the cutoff value. The start of the day is defined by the 'ContractHour' data point.	R	Y		lor	ng ms		ms	float32	min				
44257		Reserved		R			lor	-								
44259 44261		Reserved CurrDayFlowPosVol	Current day's flow-condition positive volume (int)	R	v		lor	-	e vol	olume	uint32	L				
44263		CurrDayFlowNegVol	Current day's flow-condition positive volume (int) Current day's flow-condition negative volume (int) Current day's flow-condition negative volume (int)	R	Y		lor			olume	uint32	L				ļ
			Current day's flow-condition negative volume (int).		Ċ			5		Jamo		-				
44265 44267		FieldIOStatus	Ancillary devices and device status Externally connected devices and device status Reason for Acquisition Module error	R	*	* '	lor lor			-	bitfield uint32	-	0 IsColocMeterCommErr (NV) 1 PressureInvalid (NV) 2 TemperatureInvalid (NV) 8 DidResetUsers (NV, Cnfg) 18 IsCorePresent (NV, Cnfg)			
			Reason for Acquisition Module error when (IsAcqModuleError) is indicated. A value of zero indicates no error. Bit Value Description: 0x0000001 AcqModuleExtendedStatusAvailable - Acquisition Module extended status is available. Check the further data in AcqModuleExtendedStatus 0x00000004 AcqModuleEprogrammingFailed - Acquisition Module extended status is available. Check the further data in 0x00000004 AcqModuleEprogrammingFailed - Acquisition Module reprogramming error. Check the AcqModuleMaxReprogramFail bit (below) to see if all attempts have failed. 0x00000004 AcqModuleCommNoLink - No Ethernet connection to the Acquisition Module / unable to ping. Check the interconnect cable between the Acquisition Module and the CPU Module and the CPU Module and/or cycle power to the meter. 0x00000010 AcqModuleCommFail - Acquisition Module communications failure. A command or response has failed. Check the interconnect cable between the Acquisition Module and the CPU Module and/or cycle power to the meter. 0x00000010 AcqModuleCommFail - Acquisition Module communications failure. A command or response has failed. Check the interconnect cable between the Acquisition Module and the CPU Module and/or cycle power to the meter. 0x00000010 AcqModuleError - Acquisition Module and the CPU Module and/or cycle power to the meter. 0x00000200 AcqModuleError - Acquisition Module and the CPU Module and/or cycle power to the meter. 0x00000200 AcqModuleError - Acquisition Module and the CPU Module and/or cycle power to the meter.													
			0x00000400 AcqModuleMaxReprogramFail - The maximum number of Acquisition Module reprogramming retries has been exceeded. Replace the Acquisition Module. If the issue is unresolved, contact your local area Emerson Flow service representative.													
44269	4268	AcqModuleExtendedStatus	Extended status returned from Acquisition Module Status returned from Acquisition Module when the reason for the Acquisition Module error (AcqModuleErrorReasons) is ExtendedStatusAvailable (0x01) Bit Value Description: 0x0000000 ACQUISITION_NO_EXTENDED_ERROR 0x0000000 ACQUISITION_FLASH_POLL_TIMEOUT_ERROR 0x0000000 ACQUISITION_FLASH_POLL_TIMEOUT_ERROR 0x0000000 ACQUISITION_FLASH_BUFFER_IS_NULL_ERROR 0x0000000 Not used 0x0000000 ACQUISITION_FLASH_BUFFER_IS_NUL_ERROR 0x0000000 ACQUISITION_FLASH_BUFFER_IS_NUL_ERROR 0x0000000 ACQUISITION_FLASH_MOLEXE_ERROR 0x0000000 ACQUISITION_FLASH_NO_ACCESS_SECTOMAND_ERR_ERROR 0x0000000 Not used 0x000000 Not used 0x000000 Not used 0x000000 Not used 0x0000000 Not used 0x000000 Not used 0x000000	R			lor	ng -			uint32	-				
44501	4500	EmRateActual	Ox1000000 Not used Actual transducer firing (emission) rate Actual transducer firing (emission) rate. This is the time between firing two different transducers.	R	Y		flo	at ms	n	ms	float32	ms				
44503	4502	StackEmRateActual	Actual stacking transducer firing (emission) rate. The vertice were environment and uncerne transducers. Actual stacking transducer firing (emission) rate. The meter will wait this amount of time before firing the same transducer if stacking is set to >1.	R	Y		flo	at ms	n	ms	float32	ms				
44505		BatchUpdatePeriod	Desired batch update period Desired batch update period based on the configured batch update period (SpecBatchUpdtPeriod) and stack size (StackSize). The actual duration (BatchTimeSec) will vary slightly around this value from batch to batch.	R			flo	at ms	n	ms	float32	sec				
44521	4520	BatchNewSeq	Number of new sequences in a batch The number of firing sequences since the previous Batch.	R		\square	lor	ng -		-	uint16	-				, 1
44523	4522	BatchOldSeq	Number of old sequences in a batch The number of firing sequences from previous Batches used by (BatchPercentSmoothing).	R	1		lor	ng -		•	uint16	-				
44525		SeqPerUpdateNew	Expected number of new sequences per update Expected number of new sequences per batch update period (BatchUpdatePeriod). This value is determined from the (actual) emission rate (EmRateActual), (actual) stack emission rate (StackEmRateActual), stack size (StackSize) and active chords.	R			lor			-	uint16	-				
44527	4526	SeqPerUpdateTotal	Expected number of total sequences (new+old) per update Expected number of total sequences per batch update period (BatchUpdatePeriod). It is the sum of new sequences (BatchNewSeq) and number of old sequences (BatchOldSeq) in a batch.	R	Y		lor	ng -		-	uint16	-				

Rosemoun	t™ Liqui	d Ultrasonic Firmware: 1.61	Database: 2.29.017													
	-		mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding			Description							Modbus					Minimum	Maximum
Register Number	Reg Num	Label		Acc	NV	Cnfg P		Modbus Reg Type	Modbus Metric Unit	U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Value (native unit)	Value (native unit)
44529	4528	PropUpdtBatches	Number of consecutive batches without chord failures required for updating chord proportions Number of consecutive batches without chord failures required for updating chord proportions. It is computed from the time that must elapse without chord failures required for updating chord proportions (PropUpdtSeconds) divided by the batch update period (BatchUpdatePeriod).	R	Y			long		-	uint16	-				
44531	4530	PropUpdtSeconds	Time that must elapse without chord failures required for updating chord proportions The number of seconds that must elapse without any chord failures before changes to the chord proportion bins for velocity estimation will occurr (IBroyDdrAtche) set to TRUE). This time is converted to the number of equivalent batch cycles (PropUpdtBatches) for comparison to the number of consecutive batches without chord failures (CurrPropUpdateBatches).	RW	Y	Y	Y	long	sec	sec	uint16	sec		3600	10	3600
			This also specifies the number of seconds that must elapse while transducer maintenance is suspected (IsXdcrMaintenanceSuspectedAIsXdcrMaintenanceSuspectedD) before the transducer maintenance required alarm is activated ((IsXdcrMaintenanceRequired) is set to TRUE).													
44533	4532	PropUpdtSecondsOverride	Override time required for updating chord proportions When enabled, the number of failure free seconds required (PropUpdtSeconds) is overridden such that chord proportion bins shall be updated (IsPropUpdtActive) whenever the number of consecutive batches without chord failures (CurrPropUpdateBatches) is greater than 24.	RW			Y	long	-	-	uint16	-		0	0	65535
			The purpose of this override is to allow testing of chord proportions before the required time has elapsed since the last chord failure (PropUpdtSeconds). This should only be enabled under the direction of Emerson Flow Support.													
44601	4600	DampingValue	Damping value (outputs and data points) Specifies the damping value for all outputs and measurement data points. The damping value is the (worst case) time for the outputs and measurement data points to reach 63% of the steady-state value in response to a step input. This is a function of the desired batch update period (BatchUpdatePeriod).	R				float	Sec	sec	float32	sec				
44603	4602	AO1CurrentTrimZero	Analog Output 1 current calibration zero (offset) Analog Output 1 current calibration zero (offset).	R	Y			float	ma	ma	float32	ma				
44605		AO1CurrentTrimGain	Analog Output 1 current calibration gain Analog Output 1 current calibration gain.	R	Y			float	-	-	float32	-				
44607	4606	AO2CurrentTrimZero	Analog Output 2 current calibration zero (offset) Analog Output 2 current calibration zero (offset).	R	Y			float	ma	ma	float32	ma				
44609	4608	AO2CurrentTrimGain	Analog Output 2 current calibration gain Analog Output 2 current calibration gain.	R	Y			float	-	-	float32	-				
44611	4610	Reserved		R	┝──┼			float								
44613		Reserved		R				float								
44651	4650	HARTVolUnit	HART volume unit Selects the HART communication volume unit. The volumetric flow rate unit (HARTVolFlowRateUnit) is derived from this.	R	Y	Y	Y	int	-	-	uint8		m3 (43) L (41) bbl (46) gal (40)	43	40	46
44652	4651	HARTRateTimeUnit	HART flow rate time unit Selects the HART communication time unit for volumetric flow rate (HARTVolFlowRateUnit).	R	Y	Y	Y	int	-	-	uint8	-	sec (51) min (50) hour (52) day (53)	52	50	53
44653	4652	HARTPressureUnit	HART pressure unit Selects the HART communication unit for pressure.	R	Y	Y	Y	int	-	-	uint8	-	Pa (11) KPa (12) MPa (237) psi (6)	237	6	237
44654	4653	HARTTemperatureUnit	HART temperature unit Selects the HART communication unit for temperature.	R	Y	Y	Y	int	-	-	uint8	-	C (32) K (35) F (33)	32	32	35
44655	4654	HARTVelUnit	HART velocity unit Selects the HART communication unit for flow velocity.	R	Y	Y	Y	int	-	-	uint8	-	m/s (21) ft/s (20)	21	20	21
44658	4657	HARTVolFlowRateUnit	HART volumetric flow rate unit Specifies the HART communication unit for volumetric flow rate. This unit is derived from the volume unit (HARTVolUnit) and the flow rate time unit (HARTRateTimeUnit).	R				int		-	uint8		m3/sec (28) m3/min (131) m3/min (19) m3/day (29) Uz (24) Ur/min (17) Ur/m (17) Ur/m (138) Ur/day (246) bb//s (132) bb//s (132) bb//s (133)			
	17.0	-											gal/s (22) gal/min (16) gal/hr (136) gal/day (235)			
44701 44703		Reserved Reserved		R R	┢──┼		+	int int								<u> </u>
44704	4703	Reserved		R				int								
44705 44706		Reserved Reserved		R R	┝─┤		-	int int								┝───┨
44707	4706	Reserved		R	\vdash			int								
44708		Reserved		R	\square			int								\square
44751 44753		Reserved Reserved		R R	┢──┤	-+	+	int int								├
44754	4753	Reserved		R	\square			int								
44755 44756		Reserved Reserved		R R	┢──┤		+	int int								<u> </u>
44757	4756	Reserved		R				int								
44758	4757	Reserved		R			Г	int								

Rosemou	nt™ Liqu	id Ultrasonic Firmware: 1.61	Database: 2.29.017												
The below	Modbus	a map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg F	lodbus eg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
45001	5000	IsConfigProtected	Indicates the state of the write protect switch This indicates the state of the write protect switch (CPU Module switch position 3). When CPU Module switch position 3 is in the "ON" position, data points protected by the switch (Write Protected by Switch=Yes) cannot be written to the meter and this data point is TRUE (1). This is also applied to write protecting HART parameters.	R	Y		int	-	-	boolean	-	Configuration not protected (FALSE) Configuration protected (TRUE)			<u> </u>
45002	5001	DhcpServerEnabledStatus	Is the DHCP Server enabled Shows the current status of the DHCP server switch (CPU Module switch position 2). When the switch is in the "ON" position, the meter has IP address 192.168.135.100 and is enabled to act as a DHCP server for DHCP clients connected to the Ethernet port. A maximum of 10 DHCP clients can connect to the meter and the range of client IP addresses assigned is 192.168.135.35 to 192.168.135.44. This can be used for direct or stand alone local network connections between the meter and client PCs.	R			int	-	-	boolean	-	DHCP disabled (FALSE) DHCP enabled (TRUE)			
45004	5003	IsCikinvalid	Clock is not set correctly The meter's real-time clock is set to a date in the past. Recommended Actions: 1. The real-time clock has a power backup of about 2 weeks. If the meter has been without power for more than 2 weeks, the real-time clock will first stop updating and later reset back to January 1, 2000. If this is the issue, use either the Field Setup Wizard or the Meter Monitor in MeterLink [™] to set the correct date and time. If this does not correct the problem, the real-time clock or its backup power source may be damaged, and the CPU Module should be replaced. 2. The real-time clock has been set to a date that is older than the CPU Module's firmware, i.e. a date in the past. Use either the Field Setup Wizard or the Meter Monitor in MeterLink [™] to set the correct date and time. 3. Contact your local area Emerson Fibw service representative for assistance in getting a replacement CPU Module.	R			int	-	-	boolean	-	Clock is valid (FALSE) Clock is invalid (TRUE)			
45005	5004	IsAcqModuleError	Acquisition Module error An Acquisition Module-rotet error has been detected. The CPU Module's measurement LED (MEAS) will flash green when proper communications with the Acquisition Module are restored. Recommended Actions: 1. If the CPU Module's measurement LED (MEAS) is not flashing green, check the acquisition cable between the Acquisition Module and the CPU Module's measurement LED (MEAS) is not flashing green, check the acquisition cable between the Acquisition Module and the CPU Module's measurement LED (MEAS) is so that a screwdriver to verify all the connections are secure. 2. If the CPU Module's measurement LED (MEAS) is still not flashing green, check the Acquisition Module error reasons (AcqModuleErrorReasons). 3. Replace the Acquisition Module. Contact your local area Emerson Flow service representative for a replacement module if a spare is not available. 4. If the issue is unresolved, collect a complete Archive Log from the meter using MeterLink [™] and contact your local area Emerson Flow service representative.	R			int	-	-	boolean	-	No Acquisition Module error (FALSE) Acquisition Module error detected (TRUE)			
45006	5005	IsAlarmLogFull	Alarm archive log is full The alarm archive log is full and the log is not configured to be overwritten automatically. This feature is configured using DoOverwriteUnreadAlarmLog. Recommended Actions: 1. Collect the alarm archive log records using MeterLink [™] and allow MeterLink [™] to mark them as read which will allow them to be overwritten. 2. If it desirable to let the meter automatically overwrite the oldest log record once the log is full, use the Edit/Compare configuration in MeterLink [™] to change DoOverwriteUnreadAlarmLog to overwrite lod records.	R			int	-	-	boolean	-	Log not full (FALSE) Log full (TRUE)			
45007	5006	IsAuditLogFull	Audit archive log is full The audit archive log is full and the log is not configured to be overwritten automatically. This feature is configured using DoOverwritelyneradAuditLog. Recommended Actions: 1. Collect the audit archive log records using MeterLink [™] and allow MeterLink [™] to mark them as read which will allow them to be overwritten. 2. If it desirable to let the meter automatically overwrite the oldest log record once the log is full, use the Edil/Compare configuration in MeterLink [™] to change DoOverwriteUnreadAuditLog to overwrite old records.	R			int	-	-	boolean	-	Log not full (FALSE) Log full (TRUE)			
45008	5007	IsDailyLogFull	Daily archive log is full The daily archive log is full and the log is not configured to be overwritten automatically. This feature is configured using Do/verwriteDureadDailyLog. Recommended Actions: 1. Collect the daily archive log records using MeterLink [™] and allow MeterLink [™] to mark them as read which will allow them to be overwritten. 2. If it is desirable to let the meter automatically overwrite the oldest log record once the log is full, use the Edit/Compare configuration in MeterLink [™] to change Do/VerwriteUnreadDailyLog to overwritte oid records.	R			int	-	-	boolean	-	Log not full (FALSE) Log full (TRUE)			
45009	5008	lsHourlyLogFull	Hourly archive log is full The hourly archive log is full and the log is not configured to be overwritten automatically. This feature is configured using DoOverwriteUnreadHourlyLog. Recommended Actions: 1. Collect the hourly archive log records using MeterLink™ and allow MeterLink™ to mark them as read which will allow them to be overwritten. 2. If it is desirable to let the meter automatically overwrite the oldest log record once the log is full, use the Edit/Compare configuration in MeterLink™ to change DoOverwriteUnreadHourlyLog to overwrite old records.	R			int	-	-	boolean	-	Log not full (FALSE) Log full (TRUE)			
45010	5009	IsSystemLogFull	System archive log is full The system archive log is full and the log is not configured to be overwritten automatically. This feature is configured using DoOverwriteUnreadSystemLog. Recommended Actions: 1. Collect the system archive log records using MeterLink™ and allow MeterLink™ to mark them as read which will allow them to be overwriten. 2. If it is desirable to let the meter automatically overwrite the oldest log record once the log is full, use the Edit/Compare configuration in MeterLink™ to change DoOverwriteUnreadSystemLog to overwrite old records.	R			int	-	-	boolean	-	Log not full (FALSE) Log full (TRUE)			

Rosemour	t™ Liqui	d Ultrasonic Firmware: 1.6	1 Database: 2.29.017												
The below	Modbus	map is applicable for Ros	emount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg Pro	t Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
45011	5010	IsElecTempOutOfRange	Electronics temperature is out of nominal range The temperature of the electronics is out of its nominal operating range. There are separate limits for the CPU and Acquisition Modules. For the CPU Module, the range is from the CPU temperature low limit (SysTempLoLmt) to the CPU temperature high limit (SysTempHiLmt). For the Acquisition Module, the range is from the Acquisition Module temperature low limit (SysTempAcqModuleLLmt) to the Acquisition Module temperature high limit (SysTempAcqModuleHiLmt). Operating outside the nominal operating range could lead to a system failure. Recommended Actions: 1. Attempt to warm or cool the meter electronics housing. 2. If the electronics is mounted to the meter and the process fluid in the meter is over 65 °C, you must remote mount the electronics off from the meter body. 3. Collect a Maintenance Log using MeterLink [™] while the meter is experiencing the issue, collect an Archive Log (Daily/Hourly/Alarm/Audit/System) using MeterLink [™] from the meter and contact your local area Emerson Flow service representative.	R			int	-	Unit	boolean	-	Electronics temperature within range (FALSE) Electronics temperature out of range (TRUE)			
45012	5011	IsElecVoltOutOfRange	Electronics voltage out of range The CPU Module system voltages or the Acquisition Module system voltages are out-of-range. Valid CPU Module voltages are SysVoltage1V, SysVoltage1V2, SysVoltage2V5, SysVoltage3V3 and valid Acquisition Module System voltages are SysVoltageAcqModule1V2, SysVoltageAcqModule2V5, SysVoltageAcqModule3V3. Recommended Actions: 1. Replace the CPU Module if one or more of the CPU voltages (SysVoltage1V, SysVoltage1V2, SysVoltage2V5 or SysVoltage3V3) is out- of-range. 2. Replace the Acquisition Module if one or more of the Acquisition Module voltages (SysVoltageAcqModule1V2, SysVoltageAcqModule2V5 or SysVoltageAcqModule3V3) is out- of-range. 3. If the issue is unresolved, contact you local area Emerson Flow service representative.	R			int	-	-	boolean	-	All electronics voltages within range (FALSE) One or more electronics voltages out of range (TRUE)			
45048	5047	IsFODO4Avail	Frequency/Digital Output 4 available Frequency/Digital Output 4 available indicator based on the CPU Module's I/O board revision. The content is selected by the Frequency/Digital Output 4 source selector (FODO4Source) and the output levels by the Frequency/Digital Output 4 mode selector (FODO4Mode).	R			int	-	-	boolean	-	Not available (FALSE) Available (TRUE)			
45049	5048	lsFODO5Avail	Frequency/Digital Output 5 available Frequency/Digital Output 5 available indicator based on the CPU Module's I/O board revision. The content is selected by the Frequency/Digital Output 5 source selector (FODO5Source) and the output levels by the Frequency/Digital Output 5 mode selector (FODOSMode).	R			int	-	-	boolean	-	Not available (FALSE) Available (TRUE)			
45050	5049	IsFODO6Avail	Frequency/Digital Output 6 available Frequency/Digital Output 6 available indicator based on the CPU Module's I/O board revision. The content is selected by the Frequency/Digital Output 6 source selector (FODO6Source) and the output levels by the Frequency/Digital Output 6 mode selector (FODO6Mode).	R			int	-	-	boolean	-	Not available (FALSE) Available (TRUE)			
45051	5050	IsPortAAvail	Communication port A available Communication port A available indicator based on the CPU Module's I/O board revision.	R			int	-	-	boolean	-	Not available (FALSE) Available (TRUE)			
45052	5051	IsPortBAvail	Communication port B available Communication port B available indicator based on the optional I/O Module (Opt/OModule1Type) configuration.	R			int	-	-	boolean	-	Not available (FALSE) Available (TRUE)			
45053	5052	IsPortCAvail	Communication port C available Communication port C available indicator based on the optional I/O Module (OptIOModule2Type) configuration.	R			int	•	-	boolean	-	Not available (FALSE) Available (TRUE)			
45054	5053	IsFODO1Avail	Frequency/Digital Output 1 available Frequency/Digital Output 1 available Frequency/Digital Output 1 available Frequency/Digital Output 1 available Frequency/Digital Output 1 source selector (FODO1Source) and the output levels by the Frequency/Digital Output 1 mode selector (FODO1Mode).	R			int	-	-	boolean	-	Not available (FALSE) Available (TRUE)			
45055	5054	lsEth1Avail	Ethernet port 1 available Ethernet port 1 available indicator based on the CPU Module's I/O Board revision.	R			int	-	-	boolean	-	Not available (FALSE) Available (TRUE)			
45056	5055	MaxConnDBAPI	Maximum number of DB API connections This is the upper limit to the number of DB API connections.	RW	Y	Y	int	-	-	uint8	-		10	10	40
45057		Reserved		R			int								
45058 45059	5057 5058	Reserved Reserved		R			int						-		
45060	5059	Reserved		R			int								
45061 45062	5060 5061	Reserved IsFODO2Avail	Frequency/Digital Output 2 available Frequency/Digital Output 2 available indicator based on the CPU Module's I/O board revision. The content is selected by the Frequency/Digital Output 2 source selector (FODO2Source) and the output levels by the Frequency/Digital Output 2 mode selector (FODO2Mode).	R			int	-	-	boolean	-	Not available (FALSE) Available (TRUE)			
45063	5062	lsFODO3Avail	Frequency/Digital Output 3 available Frequency/Digital Output 3 available indicator based on the CPU Module's I/O board revision. The content is selected by the Frequency/Digital Output 3 source selector (FODO3Source) and the output levels by the Frequency/Digital Output 3 (FODO3Mode).	R			int	-	-	boolean	-	Not available (FALSE) Available (TRUE)			
45064	5063	IsAO1Avail	Analog Output 1 available Analog Output 1 available indicator based on the CPU Module's I/O board revision.	R			int	-	-	boolean	-	Not available (FALSE) Available (TRUE)			
45065		IsAl1Avail	Analog Input 1 (temperature) available Analog Input 1, live flow-condition temperature (LiveFlowTemperature), available indicator based on the CPU Module's I/O board revision. The connectors for this input are designated as ANALOG IN TT- and TT+.	R			int	-	-	boolean	-	Not available (FALSE) Available (TRUE)			
45066 45067		IsAl2Avail IsAl3Avail	Analog Input 2 (pressure) available Analog Input 2 (pressure) available connectors for this input are designated as ANALOG IN PT- and PT+. Analog input 3 available	R			int	-	-	boolean	-	Not available (FALSE) Available (TRUE) Not available (FALSE)			
45067		IsDI1Avail	Analog input 3 available Analog input 3 available indicator based on the Optional I/O Module (OptIOModule1Type, OptIOModule2Type) configuration. The connectors for this nput are designated as ANALOG IN AI3- and AI3+. Digital Input 1 available	R			int			boolean	-	Not available (FALSE) Available (TRUE) Not available (FALSE)			
45069		IsAO2Avail	Digital Input 1 available indicator based on the CPU Module's I/O board revision. Analog Output 2 available	R		\vdash	int	 .	-	boolean		Available (TRUE) Not available (FALSE)			
			Analog Output 2 available indicator based on the CPU Module's I/O board revision. Analog Output 1 HART functionality available								-	Available (TRUE)			
45070	5069	IsAO1HARTAvail	Analog Output 1 HAK 11 unctionality available Indicates whether HART functionality is available on Analog Output 1. It is set to "Not available" when the HART slave is disabled (IsHARTSlaveEnabled) or Analog Output 1 is not available (IsAO1Avail).	R			int	-	-	boolean	-	Not available (FALSE) Available (TRUE)			

Bosomou	at™ Liqu	id Ultrasonic Firmware: 1.6	1 Detabase: 2.20.017												
			n Database: 2.23.017 smount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
The below	woubus	map is applicable for Ros		1					Medhue	1					
Holding Register Number	Reg Num	Label	Description	Acc	NV C	infg Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
45071		IsAO2HARTAvail	Analog Output 2 HART functionality available Indicates whether HART functionality is available on Analog Output 2. It is set to "Not available" when the HART slave is disabled (IsHART SlaveEnabled) or Analog Output 2 is not available (IsAO2Avail).	R			int	-	-	boolean	-	Not available (FALSE) Available (TRUE)			
45072		Reserved		R			int								
45073 45074		Reserved IsPPPSupported	PPP connections are supported	R		_	int			boolean					
1007 1	0070	ion n oupportou	Boolean that indicates if PPP is supported or not. If variable does not exist on a meter, assumed that PPP is not supported.							booloan					
45075		Reserved		R			int								
45076	5075	HARTTVValidity	HART Third Variable invalid The HART Third Variable value as defined by the HART device variable selection (HARTTVContent) is invalid.	R			int	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
			Recommended Actions:												
			 If an alarm exists for the content selected to be output, resolving that issue should clear this alarm. If the issue is unresolved, collect a Maintenance Log using MeterLink™ and contact your local area Emerson Flow service representative. 												
45077	5076	HARTQVValidity	HART Fourth Variable invalid The HART Fourth Variable value as defined by the HART device variable selection (HARTQVContent) is invalid.	R			int	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
			Recommended Actions:												
			 If an alarm exists for the content selected to be output, resolving that issue should clear this alarm. If the issue is unresolved, collect a Maintenance Log using MeterLink[™] and contact your local area Emerson Flow service representative. 												
45078	5077	HARTSlot0Validity	HART Command 33 Slot 0 invalid The HART Slot 0 value as defined by the HART device variable selection (HARTSlot0Content) is invalid.	R			int	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
			Recommended Actions:												
			 If an alarm exists for the content selected to be output, resolving that issue should clear this alarm. If the issue is unresolved, collect a Maintenance Log using MeterLink[™] and contact your local area Emerson Flow service representative. 												
45079	5078	HARTSlot1Validity	HART Command 33 Slot 1 invalid The HART Slot 1 value as defined by the HART device variable selection (HARTSlot1Content) is invalid.	R			int	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
			Recommended Actions:												
			 If an alarm exists for the content selected to be output, resolving that issue should clear this alarm. If the issue is unresolved, collect a Maintenance Log using MeterLink™ and contact your local area Emerson Flow service representative. 												
45080	5079	HARTSlot2Validity	HART Command 33 Slot 2 invalid The HART Slot 2 value as defined by the HART device variable selection (HARTSlot2Content) is invalid.	R			int	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
			Recommended Actions:												
			 If an alarm exists for the content selected to be output, resolving that issue should clear this alarm. If the issue is unresolved, collect a Maintenance Log using MeterLink™ and contact your local area Emerson Flow service representative. 												
45081	5080	HARTSlot3Validity	HART Command 33 Slot 3 invalid The HART Slot 3 value as defined by the HART device variable selection (HARTSlot3Content) is invalid.	R			int	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
			Recommended Actions:												
			 If an alarm exists for the content selected to be output, resolving that issue should clear this alarm. If the issue is unresolved, collect a Maintenance Log using MeterLink[™] and contact your local area Emerson Flow service 												
			representative.												
45082	5081	IsAcqModuleIncompatible	Acquisition Module is not compatible with the firmware/configuration The firmware cannot work with the installed Acquisition Module. The Acquisition Module may be newer than the firmware and the	R			int	-	-	boolean	-	Compatible Acquisition Module (FALSE) Incompatible Acquisition Module (TRUE)			
			firmware does not recognize it. The Acquisition Module may be installed on a meter running firmware for the opposite product (Gas/Liquid). The Acquisition Module may be installed on a meter configured with a transducer frequency (XdcrFreq) or sample interval (SampInterval) that is not supported by the module.									·····,			
			Recommended Actions:												
			 Verify that the transducer frequency and sample interval are set to values supported by the installed Acquisition Module. Upgrade the firmware in the meter to the latest version using MeterLink™. Contact your local area Emerson Flow service representative to a basis the letter forware. 												
			to obtain the latest firmware. 3. If the latest firmware revision did not resolve the issue, replace the Acquisition Module.												
			 If the issue is unresolved, collect a Maintenance Log using MeterLink[™] and contact your local area Emerson Flow service representative. 												
45083	5082	AvgSndVellsOutOfLimits	Average speed of sound out of limits (HART-specific)	R			int	-	-	boolean	-	Within limits (FALSE)			
	5002	gener en souchennik	The meter's measured average speed of sound (AvgSndVel) is out of limits (SSMin, SSMax). This alarm is used for HART applications. The non-HART average speed of sound out of limits alarm (IsAvgSoundVelRangeErr) is used for other applications.							220rouri		Out of limits (TRUE)			
			Recommended Actions:												
			1. Verify that all chords are measuring the same Speed of Sound within about 0.15%. Look for alarms that indicate transducer problems												
			and resolve any of these issues. This could include failing transducers, debris buildup on transducers or incorrectly entered path lengths in the configuration.												
			2. If the chords agree well, it is recommended that the minimum (SSMin) or maximum (SSMax) speed of sound be adjusted so the meter's												
			average speed of sound fails within these limits. 3. If the issue is unresolved, collect a Maintenance Log using MeterLink™ and contact your local area Emerson Flow service												
			representative.												
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Rosemour	nt™ Liaui	d Ultrasonic Firmware: 1.61	Database: 2.29.017													
			nount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
			Description							Modbus					Minia	Maxim
Holding Register Number	Reg Num	Label		Acc	NV (Cnfg P		Modbus teg Type	Modbus Metric Unit	U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
45084	5083	FlowPressureIsOutOfLimits	Flow-condition pressure out-of-limits The flow-condition pressure (FlowPressure) is outside the limits (MinInputPressure to MaxInputPressure). Recommended Actions: 1. If connected to a pressure transducer, verify that the transducer is functioning properly. Verify that the wring is correctly connected to TB2-B pin 14 & 2 (ANALOG IN PT- and PT+). Verify that the current is between 4 mA and 20 mA. 2. Run the Field Setup Wizard in MeterLink™ to properly configure the input including: Source (Live Analog or Fixed), Min and Max input limits (MinInputPressure and MaxInputPressure) corresponding to 4 mA and 20 mA respectively and the Low and High alarm limits. 3. Adjust the gain and offset (LiveFlowPressureGain and LiveFlowPressureOffset) so the flow-condition pressure (FlowPressure) is correct. 4. If the issue is unresolved, collect a complete Archive Log from the meter using MeterLink™ and contact your local area Emerson Flow service representative.	R				int		-	boolean	-	Within limits (FALSE) Out of limits (TRUE)			
45085	5084	FlowTemperatureIsOutOfLi mits	Service representative. Flow-condition temperature out-of-limits The flow-condition temperature (FlowTemperature) is outside the limits (MinInputTemperature to MaxInputTemperature).	R				int	-	-	boolean	-	Within limits (FALSE) Out of limits (TRUE)			
			Recommended Actions: 1. If connected to a temperature transducer, verify that the transducer is functioning properly. Verify that the wiring is correctly connected to 128-26 pins 3 & 4 (ANALOG IN TT- and TT+). Verify that the current is between 4 mA and 20 mA. 2. Run the Field Setup Wizard in MeterLink™ to properly configure the input including: Source (Live Analog or Fixed), Min and Max input limits (Mininput)Temperature and MaxinputTemperature) corresponding to 4 mA and 20 mA respectively and the Low and High alarm limits. 3. Adjust the gain and offset (LiveFlowTemperatureGain and LiveFlowTemperatureOffset) so the flow-condition temperature (FlowTemperature) is correct. 4. If the issue is unresolved, collect a complete Archive Log from the meter using MeterLink™ and contact your local area Emerson Flow service representative.													
45086 45087		Reserved Reserved		R				int								
45088		AO1IsFixed	Analog Output 1 (HART PV) is fixed Analog Output 1 current is in test mode and fixed. The current can be fixed by using the Outputs Test dialog of MeterLink™ by placing the output in test mode. Recommended Actions: 1. Once the Analog Output 1 is removed from test mode, this alarm will clear. See also IsAO1EnableTest data point.	R				int int	-	-	boolean	-	Current not fixed (FALSE) Current fixed (TRUE)			
45089	5088	AO1IsSaturated	Analog Output I (HART PV) is saturated Analog Output I is saturated (i.e. the loop current has reached its upper or lower endpoint and cannot increase or decrease any further). Recommended Actions: 1. The analog output may need to be rescaled to prevent it from saturating. Use the Field Setup Wizard in MeterLink™ to configure Analog Output 1.	R				int	-	-	boolean	-	Current not saturated (FALSE) Current saturated (TRUE)			
45090	5089	AO1ActionUponInvalidConte nt	Analog Output 1 current action upon invalid content Specifies the action for Analog Output 1 current when the content is invalid. No special action is taken when set to None.	RW	Y	Y	Y	int	-	-	uint8	-	High - 20 mA (0) Low - 4 mA (1) Hold last value (239) Very low - 3.5 mA (240) Very high - 20.5 mA (241) None (251) None (251)	240	0	251
45091	5090	AO2IsFixed	Analog Output 2 (HART SV) is fixed Analog Output 2 current is in test mode and fixed. The current can be fixed by using the Outputs Test dialog of MeterLink™ by placing the output in test mode. Recommended Actions: 1. Once the Analog Output 2 is removed from test mode, this alarm will clear. See also IsAO2EnableTest data point.	R				int	-	-	boolean	-	Current not fixed (FALSE) Current fixed (TRUE)			
45092	5091	AO2IsSaturated	Analog Output 2 (HART SV) is saturated Analog Output 2 is saturated (i.e. the loop current has reached its upper or lower endpoint and cannot increase or decrease any further). Recommended Actions: 1. The analog output may need to be rescaled to prevent it from saturating. Use the Field Setup Wizard in MeterLink [™] to configure Analog Output 2.	R				int	-	-	boolean	-	Current not saturated (FALSE) Current saturated (TRUE)			
45093	5092	AO2ActionUponInvalidConte nt	Analog Output 2 current action upon invalid content Specifies the action for Analog Output 2 current when the content is invalid. No special action is taken when set to None.	RW	Y	Y	Y	int	-	-	uint8	-	High - 20 mA (0) Low - 4 mA (1) Hold last value (239) Very low - 3.5 mA (240) Very high - 20.5 mA (241) None (251)	240	0	251
45094		ZeroFlowCalStatus	Zero-flow calibration status Current zero-flow calibration status indicator.	R				int	-	-	uint8	-	Inactive (0) In progress (1) Completed successfully (2) Failed - Chord failure (3) Failed - Too large offset (4) Failed - Too large estimated maximum deviation (5) Failed - Co alibration method change (6)			
45095	5094	ZeroFlowCalProgress	Zero-flow calibration progress (percent complete) Zero-flow calibration progress (percent complete).	R				int	%	%	uint8	%				

™ Liqui	d Ultrasonic Firmware: 1.61	Database: 2.29.017												
Reg Num	Label	Description	Acc	NV	Cnfg Pro	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
5095	AO1DataValidity	Analog Output 1 data invalid Analog Output 1 (AO1) is invalid. The analog output is considered invalid if the analog output is in test mode or the content the analog output is trying to drive is invalid or the loop current mode is disabled via HART. The content of AO1 is specified by AO1Content. Recommended Actions:	R			int	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
		 If an alarm exists for the content selected to be output on Analog Output 1 (AO1Content), resolving that issue should clear this alarm. If the content selected for Analog Output 1 is not in alarm, then verify that the output is not fixed or set in test mode or the loop current mode has been not been disabled via HART. If the issue is unresolved, collect a Maintenance Log using MeterLink[™] and contact your local area Emerson Flow service representative. 												
5096	AO2DataValidity	Analog Output 2 data invalid Analog Output 2 data invalid Analog Output 2 (Ao2) is invalid. The analog output is considered invalid if the analog output is in test mode or the content the analog output is trying to drive is invalid. The content of AO2 is specified by AO2Content. Recommended Actions: 1. If an alarm exists for the content selected to be output on Analog Output 2 (AO2Content), resolving that issue should clear this alarm. 2. If the content selected for Analog Output 2 is not in alarm, then verify that the output is not fixed or set in test mode. 3. If the issue is unresolved, collect a Maintenance Log using MeterLink [™] and contact your local area Emerson Flow service representative.	R			int	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
5097	Freq 1 Data Validity	Frequency Output 1 data invalid The parameter which the Frequency Output 1 is configured to represent is invalid or the output is currently in test mode. Recommended Actions: 1. You can determine whether the output is in test mode by using Meter Outputs in MeterLink™. 2. If the parameter for which Frequency Output 1 is configured is invalid, other alarms will be present that will help you resolve the issue. 3. If the issue is unresolved, collect a Maintenance Log and Archive Log from the meter using MeterLink™ and contact your local area Emerson Flow service representative.	R			int	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
5098	Freq2DataValidity	Frequency Output 2 data invalid The parameter which the Frequency Output 2 is configured to represent is invalid or the output is currently in test mode. Recommended Actions: 1. You can determine that the output is in test mode by using Meter Outputs in MeterLink ™. 2. If the parameter for which Frequency Output 2 is configured is invalid, other alarms will be present that will help you resolve the issue. 3. If the issue is unresolved, collect a Maintenance Log and Archive Log from the meter using MeterLink ™ and contact your local area Emerson Flow service representative.	R			int	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
5100	RTCSecondsSinceEpochRe ad	System time (read-only) This is used to read the system time in POSIX-compliant "time_t" format (seconds elapsed since midnight January 1, 1970 local time). Use the real-time clock set data point (RTCSecondsSinceEpochSet) to set the system time.	R	Y		long	sec	sec	int32	Epoch sec				
		Time of the last meter reset Time of the last meter reset in POSIX-compliant "time_1" format (seconds elapsed since midnight January 1, 1970) due to power failure (DidPowerFail), meter warm start (DidWarmStart) or software watchdog reset (WatchDogReset).	R	Y		long	sec	sec	int32	Epoch sec				
	-	Configuration checksum date. This is the date and time of the last configuration change in POSIX-compliant "time_t" format (seconds elapsed since midnight January 1, 1970).	R	Y		long	sec	sec	int32	Epoch sec				
5106	CnfgChksumValue	Configuration checksum value This is the checksum of the meter's configuration. All non-STRING write-protected data points are included in the checksum. The timestamp of the most recent change is in configuration checksum date (CnfgChksumDate).	R	Y		long	-	-	uint32	-				
		System temperature System temperature. The temperature is measured on the CPU Module and will read higher than the ambient due to internal heat rise. The alarm limits are system temperature low limit (SysTempLoLmt) and system temperature high limit (SysTempHILmt). The alarm is IsElecTempOutOrRange.	R			float	deg C	deg F	float32	deg C				
		Actual voltage of the system 2.5V supply. The alarm is IsElec/VoltOvtO/Range. The alarm limits are SysVoltage2V5LoLmt and SysVoltage2V5HiLmt.												
		Actual vollage of the system 3.3V supply. The alarm is IsElecVoltOutOlRange. The alarm limits are SysVoltage3V3LoLmt and SysVoltage3V3HiLmt.							108132	· ·				
	A 14 14 144	System 1.0V reading	R	+		float	v	v	float32	v]
5160	SysVoltage1V2	SysVoltage1VHiLmt. System 1.2V reading	R			float	v	v	float32	v				
5162	SysTempAcqModule	SysVoltage1V2HiLmt. System temperature - Acquisition Module	R	$\left \right $		float	deg C	deg F	float32	deg C				
		The temperature is measured in the Acquisition Module will read higher than the ambient due to internal heat rise. The alarm fimits are system temperature low limit (SysTempAcqModuleLoLmt) and system temperature high limit (SysTempAcqModuleHiLmt). The alarm is IsElecTempOutOfRange.												
	, , ,	Acquisition Module 1.2V reading Actual voltage of the system 1.2V supply in the Acquisition Module. The alarm is IsElecVoltOutOrRange. The alarm limits are SysVoltage1V2LoLmt and SysVoltage1V2HiLmt.	R			float	V	V	float32	v				
		Acquisition Module 2.5V reading Actual voltage of the system 2.5V supply in the Acquisition Module. The alarm is IsElecVoltOutOrRange. The alarm limits are SysVoltage2V5LoLmt and SysVoltage2V5HILmt.	R			float	V	V	float32	V				
5168	SysVoltageAcqModule3V3	Acquisition Module 3:30 reading Actual voltage of the system 3.3V supply in the Acquisition Module. The alarm is IsElecVoltOutOrRange. The alarm limits are SysVoltage3V3LoLmt and SysVoltage3V3HiLmt.	R			float	V	V	float32	V				
	status 5096 5096 5096 5096 5097 5098 5096 5097 5098 5096 5097 5098 5100 5102 5104 5105 5152 5154 5156 5152 5154 5160 5162 5164 5166	odus map is applicable for Roser Reg 5095 Label 5095 AO1DataValidity 5096 AO2DetaValidity 5097 Freq1DataValidity 5098 Freq2DataValidity	Bits a tap is applicable for Reservoir** Ligned 4-Path (DeviceMunder 214) and 2-Path (DeviceMunder 2142) maters Open procession DeviceSion Open procession DeviceSion DeviceSion Open procession DeviceSion DeviceSion DeviceSion Open procession DeviceSion DeviceSion DeviceSion DeviceSion DeviceSion DeviceSion DeviceSion DeviceSion DeviceSion DeviceSion DeviceSion DeviceSion DeviceSion <thdevicesion< th=""> DeviceSion DeviceSio</thdevicesion<>	Bits aug is applicable for Recommendant Liquid 4 Fabli (DeviceNumber 3112) match Acc 99 90 90 90 90 90 90 90 90 90 90 90 90 9	Bits augus applicable for Processors and a specific processors and applicable for Processors and applic	Bits map is applicable for Searchword Hoged 4-Full (DeviceMender 2404) and 2-Full (DeviceMender 2404) model and search of the search	Bits De la population de Construmentarie 4 begins de Pales (Seventaria De la population de Construmentaria de la de la population de la	allow a support of the Reserved V Lipsic 4 Area (by the Area (by the Reserved V Lipsic 4 Area (Books State S		Business approaches for semantic Vessel Ve	and and a set of the set of th	distance market market <td>Unit of the state of</td>	Unit of the state of

Rosemou	nt™ Liqu	id Ultrasonic Firmware: 1.6	1 Database: 2.29.017												
			mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding			Description						Modbus	No. 5	No. 5		Defer to the	Minimum	Maximum
Register Number	Reg Num	Label		Acc	NV (Cnfg Prot	Modbus Reg Type	Modbus Metric Unit	U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Value (native unit)	Value
45201	5200	LinearMtrFctr	Piecewise linearization meter factor	R			float	-	Unit -	float32	-			(namo ann)	(nativo anit)
			Piecewise linearization meter factor. This meter factor is applied to the flow velocity regardless of the selection of the calibration method (CalMethod) data point. It is computed from the piecewise velocities and the corresponding gains plus the offsets.												
45203		Reserved		R			float								
45205 45207	5204 5206	Reserved Reserved		R R			float float								
45209	5208	Reserved		R			float								
45211 45213	5210	Reserved Reserved		R R			float float								
45215	5212	Reserved		R			float								
45217	5216	Reserved		R			float								
45219 45221	5218 5220	Reserved Reserved		R R			float float								<u> </u>
45223	5222	Reserved		R			float								
45225		Reserved		R			float								
45227 45229	5226 5228	Reserved Reserved		R R			float float								<u> </u>
45231	5230	Reserved		R			float								
45233	5232	Reserved		R			float								
45235 45237		Reserved Reserved		R R			float float						+		<u> </u>
45239	5238	Reserved		R			float								
45241	5240	Reserved		R			float								
45243 45245	5242 5244	Reserved Reserved		R R			float float						+		<u> </u>
45247	5246	Reserved		R			float								
45249 45251	5248	Reserved		R			float								
45251	5250 5252	Reserved Reserved		R R			float float						+		<u> </u>
45255	5254	Reserved		R			float								
45257		Reserved		R			float								
45259 45261	5258 5260	Reserved Reserved		R R			float float								
45263	5262	Reserved		R			float								
45265 45267	5264 5266	Reserved Reserved		R R			float float								
45267	5266	Reserved		R			float								
45271	5270	Reserved		R			float								
45273 45275	5272 5274	Reserved Reserved		R R			float float								
45275	5274	Reserved		R			float								<u> </u>
45279	5278	Reserved		R			float								
45281 45283	5280 5282	Reserved Reserved		R R			float float								
45285	5284	Reserved		R			float								<u> </u>
45287	5286	Reserved		R			float								
45289 45291	5288 5290	Reserved Reserved		R R			float float								
45291	5290	Reserved		R			float								
45295	5294	Reserved		R			float								
45297 45299	5296 5298	Reserved Reserved		R R	-+		float float						+		───
45299	5300	Reserved		R	-+		float						+		
45303	5302	Reserved		R			float								
45305 45307	5304 5306	Reserved Reserved		R R	-+		float float						+		<u> </u>
45309		Reserved		R	-+		float						+		
45311		Reserved		R			float								
45313 45315		Reserved Reserved		R R	-+		float float						+		───
45315		Reserved		R			float						1		
45319		Reserved		R			float								
45321 45323		Reserved Reserved		R R	-+		float float						+		<u> </u>
45325		Reserved		R	-+		float						+		
45327		Reserved		R			float								
45329 45331		Reserved Reserved		R R	-+		float float						+		<u> </u>
45333		Reserved		R	-		float						+		<u> </u>
45335		Reserved		R			float								
45337 45339		Reserved Reserved		R R			float float								<u> </u>
45339 45341		Reserved		R			float						+		<u> </u>
<u> </u>															

Rosemou	nt™ Liqui	id Ultrasonic Firmware: 1.6	1 Database: 2.29.017													
			amount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
	moubuo		Description							Modbus	1					
Holding Register Number	Reg Num	Label		Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
45343		Reserved		R				float								
45345	5344			R				float								
45347 45349		Reserved Reserved		R				float								
45349		Reserved		R				float float								
45353		Reserved		R		-		float								
45355				R				float								
45357	5356	Reserved		R				float								
45361	5360	HighViscosityMethod	High viscosity calibration method selector Selects the calibration method used to determine the flow velocity measurement.	RW	Y	Y		float	-	-	uint8	-	Disabled (0) Enabled (1)	0	0	1
			If set to disabled, then the linear flow velocity (LinearCaIVeI) is a result of applying the factory calibration flow coefficients (A coefficients FwdA0, FwdA1, FwdA2, FwdA3, RevA0, RevA1, RevA2 and RevA3) and piecewise linearization meter factor (LinearMtrFctr) to the average weighted flow velocity (AvgWtdFlowVeI).													
			If set to enabled, then the linear flow velocity (LinearCalVeI) is a result of applying the zero calibration high viscosity flow offset (FwdA0HighViscosity or RevA0HighViscosity) and the high viscosity piecewise linearization meter factor (LinearMtrFctrHighViscosity) to the average weighted flow velocity (AvgWtdFlowVeI).													
45363	5362	FwdA0HighViscosity	Zero calibration high viscosity forward flow offset The forward flow offset used for high viscosity zero calibration. When the high viscosity method selector (High/ViscosityMethod) is set to enabled, then this offset is applied to the average weighted flow velocity (AvgWtdFlowVel) to calculate the factory calibrated flow velocity (DryCal/Vel).	RW	Y	Y	Y	float	m/s	ft/s	float32	m/s		0	-1	1
45365	5364	RevA0HighViscosity	Zero calibration high viscosity reverse flow offset The reverse flow offset used for high viscosity zero calibration. When the high viscosity method selector (High ViscosityMethod) is set to enabled, then this offset is applied to the average weighted flow velocity (AvgWtdFlowVel) to calculate the factory calibrated flow velocity (DypCaVe).	RW	Y	Y	Y	float	-	-	float32	m/s		0	-1	1
45367	5366	FwdProfileFactor1	Piecewise linearization forward profile factor 1 The first and highest forward profile factor used for high viscosity piecewise linearization. It is paired with high viscosity forward meter factor 1 (FwdNtFcrtHighVscosity) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFctrHighViscosity). If it is unused it should be set to zero. For profile factors above this point the high viscosity forward meter factor 1 (FwdNtrFctrHighViscosity) will be applied as the high viscosity linear meter factor (LinearMtrFctrHighVoscosity).	RW	Y	Y	Y	float	-	-	float32	-		0	0	2.5
45369	5368	FwdProfileFactor2	Piecewise linearization forward profile factor 2 The second forward profile factor used for high viscosity piecewise linearization. It is paired with high viscosity forward meter factor 2 (FwdNtrFcHrk]hylviscosity) 2 to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFctHighViscosity). If it is unused it should be set to zero.	RW	Y	Y	Y	float	-	-	float32	-		0	0	2.5
45371	5370	FwdProfileFactor3	Piecewise linearization forward profile factor 3 The third forward profile factor used for high viscosity piecewise linearization. It is paired with high viscosity forward meter factor 3 (FwdNtFrErthrigh/Viscosity) of form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFctrHigh/Viscosity). If it is unused it should be set to zero.	RW	Y	Y	Y	float	-	-	float32	-		0	0	2.5
45373	5372	FwdProfileFactor4	Piecewise linearization forward profile factor 4 The fourth forward profile factor used for high viscosity piecewise linearization. It is paired with high viscosity forward meter factor 4 (FwdNtFrErthrighViscosity4) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFctrHighViscosity). If it is unused it should be set to zero.	RW	Y	Y	Y	float	-	-	float32	-		0	0	2.5
45375	5374	FwdProfileFactor5	Piecewise linearization forward profile factor 5 The fifth forward profile factor used for high viscosity piecewise linearization. It is paired with high viscosity forward meter factor 5 (FwdNtFrErthigh/viscosity); Disrom an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFctrHigh/Viscosity). If it is unused it should be set to zero.	RW	Y	Y	Y	float	-	-	float32	-		0	0	2.5
45377	5376	FwdProfileFactor6	Piecewise linearization forward profile factor 6 The skth forward profile factor used for high viscosity piecewise linearization. It is paired with high viscosity forward meter factor 6 (FwdNtFrErthrigh/viscosity6) form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFctrHigh/Viscosity). If it is unused it should be set to zero.	RW	Y	Y	Y	float	-	-	float32	-		0	0	2.5
45379	5378	FwdProfileFactor7	Piecewise linearization forward profile factor 7 The seventh forward profile factor used for high viscosity piecewise linearization. It is paired with high viscosity forward meter factor 7 (fwdMtrFctrHighViscosity?) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFctrHighViscosity). If it is unused it should be set to zero.	RW	Y	Y	Y	float	-	-	float32	-		0	0	2.5
45381	5380	FwdProfileFactor8	Piecewise linearization forward profile factor 8 The eighth forward profile factor used for high viscosity piecewise linearization. It is paired with high viscosity forward meter factor 8 (fwdMtrFctrHghViscosity6) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFctrHighViscosity). If it is unused it should be set to zero.	RW	Y	Y	Y	float	-	-	float32	-		0	0	2.5
45383	5382	FwdProfileFactor9	Piecewies linearization forward profile factor 9 The ninth forward profile factor used for high viscosity piecewise linearization. It is paired with high viscosity forward meter factor 9 (FwdNtrFctHighViscosity)0 form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFctHighViscosity). If it is unused it should be set to zero.	RW	Y	Y	Y	float	-	-	float32	-		0	0	2.5
45385	5384	FwdProfileFactor10	Piecewise linearization forward profile factor 10 The tenth forward profile factor used for high viscosity piecewise linearization. It is paired with high viscosity forward meter factor 10 (FwdNtFrErthrigh/viscosity) for form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFctrHigh/Viscosity). If it is unused it should be set to zero.	RW	Y	Y	Y	float	-	-	float32	-		0	0	2.5
45387	5386	FwdProfileFactor11	Piecewise linearization forward profile factor 11 The eleventh forward profile factor used for high viscosity piecewise linearization. It is paired with high viscosity forward meter factor 11 (FwdNtFrEfrHighViscosity1) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFctrHighViscosity). If it is unused it should be set to zero.	RW	Y	Y	Y	float	-		float32	-		0	0	2.5

Rosemou	nt™ Liqu	uid Ultrasonic Firmware: 1.6	1 Database: 2.29.017													
The below	/ Modbus	s map is applicable for Rose	mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
45389	5388	3 FwdProfileFactor12	Piecewise linearization forward profile factor 12 The twelfth and lowest forward profile factor used for high viscosity piecewise linearization. It is paired with high viscosity forward meter factor 12 (PwdMrFcrHigh)Vesosity12 to form an endpoint of a line segment to the next highest endpoint. This line segment is used to interpolate the high viscosity forward meter factor (LinearMtrFcrHigh)Viscosity). If it is unused it should be set to zero. For profile factors below this point the high viscosity forward meter factor 12 (FwdMtrFcrHigh)Viscosity12 will be applied as the high viscosity linear meter factor (LinearMtrFcrHigh)Viscosity).	RW	Y	Y	Y	float	-	Unit -	float32	-		0	0	2.5
45391	5390	FwdMtrFctrHighViscosity1	Piecewise linearization forward high viscosity meter factor 1 The first forward meter factor used for high viscosity piecewise linearization. It is paired with forward profile factor 1 (FwdProfileFactor1) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LinearMtrFctrHighViscosity). If it is unused it should be set to one.	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
45393	5392	2 FwdMtrFctrHighViscosity2	Piecewise linearization forward high viscosity meter factor 2 The second forward meter factor used for high viscosity piecewise linearization. It is paired with forward profile factor 2 (FwdProfileFactor2) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LinearMtrFctrHighViscosity). If it is unused it should be set to one.	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
45395		FwdMtrFctrHighViscosity3	Piecewise linearization forward high viscosity meter factor 3 The third forward meter factor used for high viscosity piecewise linearization. It is paired with forward profile factor 3 (FwdProfileFactor3) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LinearMtrFctrHigh/Viscosity). If it is unused it should be set to one.	RW	Y	Y	Y	float	-	-	float32			1	0.9	1.1
45397		FwdMtrFctrHighViscosity4	Piecewise linearization forward high viscosity meter factor 4 The fourth forward meter factor used for high viscosity piecewise linearization. It is paired with forward profile factor 4 (FwdProfileFactor4) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LinearMtrFctrHigh/Viscosity). If it is unused it should be set to one.	RW r	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
45399		FwdMtrFctrHighViscosity5	Piecewise linearization forward high viscosity meter factor 5 The fifth forward meter factor used for high viscosity piecewise linearization. It is paired with forward profile factor 5 (FwdProfileFactor5) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LinearMtrFctrHighViscosity). If it is unused it should be set to one.	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
45401	5400	FwdMtrFctrHighViscosity6	Piecewise linearization forward high viscosity meter factor 6 The sixth forward meter factor used for high viscosity piecewise linearization. It is paired with forward profile factor 6 (FwdProfileFactor6) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LinearMtrFctrHigh Viscosity). If it is unused it should be set to one.	RW r	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
45403	5402	PwdMtrFctrHighViscosity7	Piecewise linearization forward high viscosity meter factor 7 The seventh forward meter factor used for high viscosity piecewise linearization. It is paired with forward profile factor 7 (FwdProfileFactor7) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (Linear/MtrFctrHigh/Viscosity). If it is unused it should be set to one.	RW	Y	Y	Y	float		-	float32	-		1	0.9	1.1
45405	5404	FwdMtrFctrHighViscosity8	Piecewise linearization forward high viscosity meter factor 8 The eighth forward meter factor used for high viscosity piecewise linearization. It is paired with forward profile factor 8 (FwdProfileFactor8) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LinearMtrFctrHigh/Viscosity). If it is unused it should be set to one.	RW	Y	Y	Y	float	-	-	float32			1	0.9	1.1
45407	5406	FwdMtrFctrHighViscosity9	Piecewise linearization forward high scosity meter factor 9 The ninth forward meter factor set for high viscosity piecewise linearization. It is paired with forward profile factor 9 (FwdProfileFactor9) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LinearMtrFctrHighViscosity). If it is unused it should be set to one.	RW r	Y	Y	Y	float	-	-	float32			1	0.9	1.1
45409	5408	3 FwdMtrFctrHighViscosity10	Piecewise linearization forward high viscosity meter factor 10 The tenth forward meter factor used for high viscosity piecewise linearization. It is paired with forward profile factor 10 (FwdProfileFactor10) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LinearMtrFctrHigh/viscosity). If it is unused it should be set to one.	RW	Y	Y	Y	float	-	-	float32			1	0.9	1.1
45411	5410	FwdMtrFctrHighViscosity11	Piecewise linearization forward high viscosity meter factor 11 The eleventh forward meter factor used for high viscosity piecewise linearization. It is paired with forward profile factor 11 (FwdProfileFactor 11) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LinearMtrFctrHigh/viscosity). If it is unused it should be set to one.	RW		Y	Y	float	-	-	float32	-		1	0.9	1.1
45413			Piecewise linearization forward high viscosity meter factor 12 The tweth forward meter factor used for high viscosity piecewise linearization. It is paired with forward profile factor 12 (FwdProfileFactor 12) to form an endpoint of a line segment to the next highest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LinearMtrFctrHigh/Viscosity). If it is unused it should be set to one.	RW		Y	Y	float	-	-	float32	-		1	0.9	1.1
45415		RevProfileFactor1	Piecewise linearization reverse profile factor 1 The first and highest reverse profile factor used for high viscosity piecewise linearization. It is paired with high viscosity reverse meter factor 1 (RevMtrFctrHigh/Viscosity) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFctrHigh/Viscosity). If it is unused it should be set to zero. For profile factors above this point the high viscosity reverse meter factor 1 (RevMtrFctrHigh/Viscosity) will be applied as the high viscosity linear meter factor (LinearMtrFctrHigh/Viscosity).	RW		Y			-	-	float32	-		0	0	2.5
45417		RevProfileFactor2	Piecewise linearization reverse profile factor 2 The second reverse profile factor used for high viscosity piecewise linearization. It is paired with high viscosity reverse meter factor 2 (RevMtFcrtHighViscosity2) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFcrtHighViscosity). If it is unused it should be set to zero.	RW		Ŷ	Y	float	-	-	float32			0	0	2.5
45419		3 RevProfileFactor3	Piecewise linearization reverse profile factor 3 The third reverse profile factor used for high viscosity piecewise linearization. It is paired with high viscosity reverse meter factor 3 (RevMtHFctrHighViscosity3) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFctrHighViscosity). If it is unused it should be set to zero.	RW	Y	Y	Y	float	-	-	float32			0	0	2.5
45421	5420	RevProfileFactor4	Preceverse linearization reverse profile factor 4 The fourth reverse profile factor used for high viscosity piecewise linearization. It is paired with high viscosity reverse meter factor 4 (RewMtrFctrHighViscosity4) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFctrHighViscosity). If it is unused it should be set to zero.	RW	Y	Y	Y	float	-	-	float32	-		0	0	2.5

The below Mode was is applicable for Rosemount ¹¹⁴ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters Holding Reg Holding Label Description Label Description Description Description Log Description Description Log Description Descri	Rosemou	nt™ Liaı	uid Ultrasonic Firmware: 1.6	1 Database: 2.29.017													1
No. N																	
No. No. <th>I</th> <th></th> <th></th> <th></th> <th></th> <th></th> <th></th> <th></th> <th></th> <th>1</th> <th></th> <th></th> <th></th> <th></th> <th></th> <th>Minimum</th> <th>Maximum</th>	I									1						Minimum	Maximum
Interfactor	Register Number	Num					Cnfg				Customary			Selections/Bitmap		Value (native unit)	Value (native unit)
1. End or equip will grant products with only drawn and will grant work with any drawn any drawn any drawn and will grant work with a	45423	-		The fifth reverse profile factor used for high viscosity piecewise linearization. It is paired with high viscosity reverse meter factor 5 (RevMtrFctrHighViscosity5) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFctrHighViscosity). If it is unused it should be set to zero.	RW	Y	Y	Y	float	-	-	float32	-		0	0	2.5
In words, words and is a start with three presents words in the local start with three presents with th	45425			The sixth reverse profile factor used for high viscosity piecewise linearization. It is paired with high viscosity reverse meter factor 6 (RevMtrFctrHighViscosity6) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the	RW	Y	Y	Y	float	-	-	float32			0	0	2.5
Image:	45427	5426	8 RevProfileFactor7	The seventh reverse profile factor used for high viscosity piecewise linearization. It is paired with high viscosity reverse meter factor 7 (RevMtrFctrHighViscosity7) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the	RW	Y	Y	Y	float	-	-	float32	-		0	0	2.5
Image: Control in the same problem is and the by more the same problem is any mo	45429	5428	3 RevProfileFactor8	The eighth reverse profile factor used for high viscosity piecewise linearization. It is paired with high viscosity reverse meter factor 8 (RevMtrFctrHighViscosity8) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the	RW	Y	Y	Y	float	-	-	float32	-		0	0	2.5
4 No. 1000 model biological biologica				The ninth reverse profile factor used for high viscosity piecewise linearization. It is paired with high viscosity reverse meter factor 9 (RevMtrFctHighViscosity9) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (LinearMtrFctrHighViscosity). If it is unused it should be set to zero.			Y	Y		-	-		-		0	0	2.5
1 1	45433			The tenth reverse profile factor used for high viscosity piecewise linearization. It is paired with high viscosity reverse meter factor 10 (RevMtrFctrHighViscosity10) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization meter factor (Linear/MtrFctrHighViscosity). If it is unused it should be set to zero.		Y	Y	Y	float	-	-	float32	-		0	0	2.5
444 5468 ReAMPECHAPPINGCOMPC / Security processing head with they is accord y means mean the and y accord y means means the accord y means means probe to y means means the accord y means means the accord y means means probe to y means means the accord y means means probe to y means means the accord y means means probe to y means means the accord y means means probe to y means means the accord y means me	45435	5434	4 RevProfileFactor11	The eleventh reverse profile factor used for high viscosity piecewise linearization. It is paired with high viscosity reverse meter factor 11 (RevMtrFctrHighViscosity11) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the		Y	Y	Y	float	-	-	float32	-		0	0	2.5
444 546 ReAMPEGHIGHUSSED Recent is marked and a sing the construction. It is paired with means profile factor (Suppose) is included in the physical sing the construction. It is paired with means profile factor (Suppose) is included in the physical sing the construction. It is paired with means profile factor (Suppose) is included in the physical sing the construction. It is paired with means profile factor (Suppose) is included in the physical sing the construction. It is paired with means profile factor (Suppose) is included in the physical sing the construction. It is paired with means profile factor (Suppose) is included in the physical sing the construction. It is paired with means profile factor (Suppose) is included in the physical sing the construction. It is paired with means profile factor (Suppose) is included in the physical sing the construction. It is paired with means profile factor (Suppose) is included in the physical sing the construction. It is paired with means profile factor (Suppose) is included in the physical sing the construction is included in the physical sing the construction. It is paired with means profile factor (Suppose) is included in the physical sing the construction. It is paired with means profile factor (Suppose) is included in the physical sing the construction. It is paired with means profile factor (Suppose) is included in the physical sing the construction. It is paired with means profile factor (Suppose) is included in the physical sing the construction is included in the physical sing thysical sing the construction is included in the physical sing thy	45437	5436	RevProfileFactor12	The twelfth and lowest reverse profile factor used for high viscosity piecewise linearization. It is paired with high viscosity reverse meter factor 12 (RevMtrFctrHigh/Viscosity/12) to form an endpoint of a line segment to the next highest endpoint. This line segment is used to interpolate the high viscosity inear meter factor (LinearMtrFctrHigh/Viscosity). If it is unused it should be set to zero. For profile factors below this point the high viscosity reverse meter factor 12 (RevMtrFctrHigh/Viscosity/12) will be applied as the high viscosity linear meter factor this point the high viscosity reverse meter factor 12 (RevMtrFctrHigh/Viscosity/12) will be applied as the high viscosity linear meter factor the point the high viscosity reverse meter factor 12 (RevMtrFctrHigh/Viscosity/12) will be applied as the high viscosity linear meter factor the point the high viscosity reverse meter factor (RevMtrFctrHigh/Viscosity/12) will be applied as the high viscosity linear meter factor the point of the high viscosity reverse meter factor (RevMtrFctrHigh/Viscosity/12) will be applied as the high viscosity linear meter factor the point of the high viscosity reverse meter factor to (RevMtrFctrHigh/Viscosity/12) will be applied as the high viscosity linear meter factor the point of the high viscosity reverse meter factor to (RevMtrFctrHigh/Viscosity/12) will be applied as the high viscosity linear meter factor the point of the high viscosity here the point of the poi		Y	Y	Y	float	-	-	float32	-		0	0	2.5
444 Rudhfrörthigh/rocady, if is unsacred in exerce profile factor 2 (RevPolisificator); in a single and the high vaccady poweries factor 2 (RevPolisificator); in a single and the high vaccady poweries factor 2 (RevPolisificator); in a single and the high vaccady poweries factor 2 (RevPolisificator); in a single and the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest based of the high vaccady poweries factor 2 (RevPolisificator); in a single and the rest b	45439	5438	3 RevMtrFctrHighViscosity1	The first reverse meter factor used for high viscosity piecewise linearization. It is paired with reverse profile factor 1 (RevProfileFactor1) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
4440 S448 RewMerCartigitVaccoally Rewmere meter factor (LineaMerCartigitVaccoally) Is unused it should be set to one. Rev Y Y Y Not Not Rev RevMerCartigitVaccoally RevMerCartigitVaccoally RevMerCartigitVaccoally RevMerCartigitVaccoally Rev Not Y Y Y Not Not RevMerCartigitVaccoally RevMerCa	45441	5440	RevMtrFctrHighViscosity2	The second reverse meter factor used for high viscosity piecewise linearization. It is paired with reverse profile factor 2 (RevProfileFactor2) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization.	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
Action The fourth waves matter factor used for high viscosity picewise lengration. It is paired with reverse profile factor 4 (RevProfileFactor4) to form an endpoint of a line segment to be next lowest endpoint. This line segment to be next lowest endp	45443	5442	2 RevMtrFctrHighViscosity3	The third reverse meter factor used for high viscosity piecewise linearization. It is paired with reverse profile factor 3 (RevProfileFactor3) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
45451 5450 RevMtrFctrHighViscoshy Piecewise Inearization reverse high viscosity meter factor 3 Its paired with reverse profile factor 6 RevProfileFactor(5) to meter factor (LnearMtfr=CtHighViscoshy) If is unused it should be set to one. Its paired with reverse profile factor 5 RevProfileFactor(5) to meter factor (LnearMtfr=CtHighViscoshy) If is unused it should be set to one. If with reverse profile factor 6 RevProfileFactor(5) to form an endpoint of a line segment to the next to west endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LnearMtfr=CtHighViscoshy) If is unused it should be set to one. If with reverse profile factor 6 RevProfileFactor(5) to form an endpoint of a line segment to the next to west endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LnearMtfr=CtHighViscoshy) If is unused it should be set to one. If with reverse profile factor 7 Rev V Y Y Y If ust If ust <t< td=""><td>45445</td><td>5444</td><td>4 RevMtrFctrHighViscosity4</td><td>The fourth reverse meter factor used for high viscosity piecewise linearization. It is paired with reverse profile factor 4 (RevProfileFactor4) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization.</td><td></td><td>Y</td><td>Y</td><td>Y</td><td>float</td><td>-</td><td>-</td><td>float32</td><td>-</td><td></td><td>1</td><td>0.9</td><td>1.1</td></t<>	45445	5444	4 RevMtrFctrHighViscosity4	The fourth reverse meter factor used for high viscosity piecewise linearization. It is paired with reverse profile factor 4 (RevProfileFactor4) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization.		Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
Image: Substrate The sixth reverse meter factor used for high viscosity piecewise linearization. It is paired with reverse profile factor 6 (RevProfileFactor6) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization. It is paired with reverse profile factor 7 The seventh reverse meter factor used for high viscosity piecewise linearization. This is neigherent to the next lowest endpoint. This line segment to use and to interpolate the high viscosity piecewise linearization. This is neigherent to used to interpolate the high viscosity piecewise linearization. This preferent is used to interpolate the high viscosity piecewise linearization. This preferent is used to interpolate the high viscosity piecewise linearization. This is neigherent to used to next lowest endpoint. This line segment to the next lowest endpoint. This line segment to the next lowest endpoint. This is neigherent to used to next lowest endpoint. This line segment to the next lowest en	45447	5446	RevMtrFctrHighViscosity5	The fifth reverse meter factor used for high viscosity piecewise linearization. It is paired with reverse profile factor 5 (RevProfileFactor5) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
Image: The seventh reverse meter factor used for high viscosity piecewise linearization. It is paired with reverse profile factor 7 (RevProfileFactor) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization. It is paired with reverse profile factor 8 (RevProfileFactor) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linearization. It is paired with reverse profile factor 9 (RevProfileFactor) to form an endpoint of a line segment to used to next. Rev Y Y Y Y float - - float32 - 45453 5454 RevMtrFctrHighViscosity Piecewise linearization reverse high viscosity meter factor used for high viscosity piecewise linearization. It is paired with reverse profile factor 9 (RevProfileFactor) to form an endpoint of a line segment to used to next. Rev Y Y Y float32 - - float32 - 45455 5454 RevMtrFctrHighViscosity Piecewise linearization. It is paired with reverse profile factor 9 (RevProfileFactor) to form an endpoint of a line segment to used to ninterpolate the high viscosity piecewise linearization. Rev Y Y Y Y float32 - - 1 45455 5454 RevMtrFctrHighViscosity Piecewise linearization. It is paired with reverse profile factor 9 (RevProfileFactor) to form an endpoint of a line segment to the next lowest endpoint. T	45449	5448	3 RevMtrFctrHighViscosity6	The sixth reverse meter factor used for high viscosity piecewise linearization. It is paired with reverse profile factor 6 (RevProfileFactor6) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
The eighth reverse meter factor used for high viscosity picewise linearization. It is pared with reverse profile factor 8 (RevProfileFactor8) to form an endpoint of a line segment to the next based is should be set to one. RevProfileFactor9 (RevProfileFactor9) to form an endpoint of a line segment to the next based is nearbould be set to one. RevProfileFactor9 (RevProfileFactor9) to form an endpoint of a line segment to the next based is nearbould be set to one. RevProfileFactor9 (RevProfileFactor9) to form an endpoint of a line segment to the next based is nearbould be set to one. RevProfileFactor9 (RevProfileFactor9) to form an endpoint of a line segment to the next based in therepolate the high viscosity picewise linear				The seventh reverse meter factor used for high viscosity piecewise linearization. It is paired with reverse profile factor 7 (RevProfileFactor7) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LinearMtrFctrHigh/Viscosity). If it is unused it should be set to one.			Y	Y		-	-		-		1	0.9	1.1
The ninth reverse meter factor used for high viscosity piecewise linearization. It is paired with reverse profile Factor 9 (RevProfileFactor9) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear				The eighth reverse meter factor used for high viscosity piecewise linearization. It is paired with reverse profile factor 8 (RevProfileFactor8) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LinearMtrFctrHigh Viscosity). If it is unused it should be set to one.		Y	Y	Y		-	-		-		1	0.9	1.1
	45455	5454	4 RevMtrFctrHighViscosity9	The ninth reverse meter factor used for high viscosity piecewise linearization. It is paired with reverse profile factor 9 (RevProfileFactor9) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1

Rosemou	nt™liqu	id Ultrasonic Firmware: 1.61	Database 2 29 017													
			mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding			Description							Modbus					Minimum	Maximum
Register Number	Reg Num	Label		Acc		Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Value (native unit)	Value (native unit)
45457	5456	RevMtrFctrHighViscosity10	Piecewise linearization reverse high viscosity meter factor 10 The tenth reverses meter factor used for high viscosity piecewise linearization. It is paired with reverse profile factor 10 (RevProfileFactor10) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LinearMtrFctrHighViscosity). If it is unused it should be set to one.	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
45459	5458	RevMtrFctrHighViscosity11	Piecewise linearization reverse high viscosity meter factor 11 The eleventh reverse meter factor used for high viscosity piecewise linearization. It is paired with reverse profile factor 11 (RevProfile=factor 11) to form an endpoint of a line segment to the next lowest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LinearMttFctrHighViscosity). If it is unused it should be set to one.	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
45461	5460	RevMtrFctrHighViscosity12	Piecewise linearization reverse high viscosity meter factor 12 The twelfith reverse meter factor used for high viscosity piecewise linearization. It is paired with reverse profile factor 12 (RevProfileFactor12) to form an endpoint of a line segment to the next highest endpoint. This line segment is used to interpolate the high viscosity piecewise linear meter factor (LinearMttFctrHighViscosity). If it is unused it should be set to one.	RW	Y	Y	Y	float	-	-	float32	-		1	0.9	1.1
45463	5462	LinearMtrFctrHighViscosity	High viscosity piecewise linearization meter factor This meter factor is applied to the factory calbrated flow velocity (DryCalVel) when the high viscosity calibration method (High/VscosityMethod) is enabled. It is computed from the high viscosity piecewise linearization profile factors (FwdProfileFactor1.FwdProfileFactor12 or RevProfileFactor1.RevProfileFactor12) and the corresponding piecewise linearization high viscosity meter factors (FwdMtrFctrHighViscosity1.FwdMtrFctrHighViscosity12 or RevMtrFctrHighViscosity1.RevMtrFctrHighViscosity12).	R	Y			float	-	-	float32	-				
45465	5464	CalProfileFactor	Calibration average profile factor This is the average profile factor (ProfileFactor) while the timed calibration flag (CalFlag) is set to TRUE (1) or while the DI1 gates the calibration when DI1 is configured to synchronize calibration (IsD)1UsedForCal).	R				float	-	-	float32	-				
45467	5466	Freq1FullScaleProfileFactor	Frequency Output 1 pair profile factor corresponding to the maximum frequency Specifies the Frequency Output 1 pair profile factor corresponding to the maximum frequency selected (Freq1MaxFrequency) when the Frequency Output 1 pair cortext (Freq1Content) is set to profile factor (ProfileFactor).	RW	Y	Y	Y	float	-	-	float32	-		2.5	0	5
45469	5468	Freq2FullScaleProfileFactor	Frequency Output 2 pair profile factor corresponding to the maximum frequency Specifies the Frequency Output 2 pair profile factor corresponding to the maximum frequency selected (Freq2MaxFrequency) when the Frequency Output 2 pair content (Freq2Content) is set to profile factor (ProfileFactor).	RW	Y	Y	Y	float	-	-	float32	-		2.5	0	5
45471	5470	Al1Input	Analog input 1 (temperature) current value Analog input 1 (temperature) current value, represents live flow-condition temperature (LiveFlowTemperature).	R				float	ma	ma	float32	ma				
45473	5472	Al2Input	Analog input 2 (pressure) current value Analog input 2 (pressure) current value, represents live flow-condition pressure (LiveFlowPressure).	R				float	ma	ma	float32	ma				
45475	5474	Al3Input	Analog input 3 current value	R				float	ma	ma	float32	ma				
48099	8098	OptlOModule2Type	Analog input 3 current value, available when Expansion I/O Module is connected. Stot 2 Optional I/O Module type Optional I/O Module type present in slot 2 of the electronics backplane. If meter does not have a second slot then module type is Slot not present (255).	R				long	-	-	uint8	-	None (0) RS-232 (1) RS-485 (2) Expansion I/O (3)			
48999	8998	CPUBdSerialNumber	CPU Module serial number	R				long	-	-	uint32	-	Slot not present (255)			
49001	9000	DeviceNumber	The CPU Module serial number is on a label on the CPU Module. Its minimum expected value is 0018000. Meter device number Changing this value requires warm-starting the meter. This value should only be changed at the factory or when replacing a CPU Module	R	Y	Y	Y	long	-	-	uint16	-	3814 - Four-path (3814) 3812 - Dual-path (3812)	3814	3812	3814
49003	9002	CPUBdSerialNumber	in the field. CPU Module serial number	R				long	-	-	uint32	-				
49005	9004	CPUBdRevNum	The CPU Module serial number is on a label on the CPU Module. Its minimum expected value is 0018000. CPU Module revision number The CPU Module hardware revision. The CPU Module and the I/O board (IOBdType) make up the CPU Module.	R				long	-	-	uint16	-				
49007	9006	CPUBdSwIntVer	CPU Module firmware version number as integer CPU Module firmware version number (CPUBdSwVer) (read as an integer for Modbus compatibility).	R				long	-	-	uint32	-				
49009	9008	CPUBdFPGAVer	CPC Module immate version number (CPCBGSWVer) (read as an integer for modulus compatibility). CPU Module FPGA version The CPU Module FPGA (field-programmable gate array) version that correlates to the firmware version number (CPUBdSwVer).	R				long	-	-	uint16	-				
49011	9010	DSPBdRevNum	DSP Board revision number The revision number of the DSP board. Along with the transducer interface board (XdcrIntBdRevNum), the DSP board is one of the two boards in the Acquisition Module.	R	Y			long		-	uint16	-				
49013	9012	AcquisitionBdFPGAVer	Acquisition Module FPGA version The Acquisition Module FPGA (field-programmable gate array) version that correlates to the firmware version number (CPUBdSwVer).	R				long	-	-	uint16	-				
49015	9014	IOBdType	I/O board type number Type number of the I/O board. The I/O board and the CPU (CPUBdRevNum) make up the CPU Module.	R	Y			long	-	-	uint16	-				
49017	9016	XdcrIntBdRevNum	Transducer interface board revision number The revision number of the transducer interface board. Along with the DSP board (DSPBdRevNum), the transducer interface board is one of the two boards in the Acquisition Module.	R				long	-	-	uint16	-				
49019	9018	DatabaseConfigVersion	Database configuration version Sequentially numbered major changes to the database. Normally incremented only when structural changes are performed such as adding or removal of fields. Minor changes such as adding records (database points) are indicated by the build number (DatabaseBuildNumber). When taken together the version and the build number (DatabaseBuildNumber) nunque) describe a particular version of the database. This is often described using a decimal point to separate the major and minor numbers as XXX.YYY where XXX is the version and YYY is the build number (DatabaseBuildNumber). When the version is changed the meter will cold start.	R				long	-	-	uint16	-				
49021		DatabaseBuildNumber	Database configuration build number Sequentially numbered revisions between major changes to the database (DatabaseConfigVersion).	R				long	-	-	uint8	-				
49023	9022	AcqBdSwIntVer	Acquisition Module firmware version number as integer Acquisition Module firmware version number (read as an integer for Modbus compatibility).	R				long	-	-	uint32	-				
49025	9024	OptlOModule1Type	Slot 1 Optional I/O Module type Optional I/O Module type present in slot 1 of the electronics backplane.	R				long	-	-	uint8	-	None (0) RS-232 (1) RS-485 (2) Expansion I/O (3)			
49027	9026	ElectronicsPlatform	Electronics platform on which the meter is running Electronics platform on which the meter is running.	R				long	-	-	uint8	-	3804 (0) 3810 Series (1)			
			•	•	• •				•		•		•	•	•	

Rosemour	nt™liqui	d Ultrasonic Firmware: 1.61	Database: 2.29.017													
			nount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
	moubus		Description	1						Modbus	1					
Holding Register Number	Reg Num	Label	Descriptor	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)		Maximum Value (native unit)
49029	9028	ChordalConfig	Chordal configuration The arrangement of the chords on meters with four or more sets of transducers. The chord arrangement is determined by the X dimensions (XA, XB, XC and XD). Meter with fewer than four sets of transducers, as defined by the device number (DeviceNumber), are set to a chordal configuration of NA (0).	R	Y			long	-	Unit -	uint8	-	N/A (0) BG (2)			
49031	9030	HARTManufacturerIDCode	HART manufacturer ID code HART manufacturer ID code. HART slave devices are identified by their manufacturer ID, device type (HARTDeviceType) and device revision (HARTDeviceRevisionLevel).	R				long	-	-	uint8	-	Rosemount (38)			
49033		HARTDeviceType	HART device type HART device type. HART slave devices are identified by their manufacturer ID (HARTManufacturerIDCode), device type and device revision (HARTDeviceRevisionLevel).	R				long	-	-	uint8	-	154 - Liquid 3810 Series meter (154)			
49035		HARTMinNumPreambles	HART (via AO1) minimum number of Master command preamble bytes HART, via AO1, minimum number of Master command preamble bytes.	R	Y	Y	Y	long	-	-	uint8	-		5	5	20
49037		n	HART universal command major revision number HART universal command major revision number.	R	Y			long	-	-	uint8	-				
49039		HARTDeviceRevisionLevel	HART device revision level HART device revision level. HART slave devices are identified by their manufacturer ID (HARTManufacturerIDCode), device type (HARTDeviceType) and device revision level.	R				long	-	-	uint8	-				
49041	9040	HARTSoftwareRevisionLevel	HART device software revision level HART device software revision level.	R				long	-	-	uint8	-				
49043		HARTHardwareRevisionLev el	HART device hardware revision level HART device hardware revision level. For the ultrasonic meter, this is the CPU Module's I/O board type (IOBdType).	R				long	-	-	uint8	-				
49045		e	HART physical signaling code HART physical signaling code.	R	Y			long	-	-	uint8	-	Bell 202 current (0)			
49047		HARTFlagAssignments	HART flag assignments HART flag assignments.	R	Y			long	-	-	uint8	-	Multi-sensor field device (1)			
49049	9048	HARTDeviceID	Unique HART device ID Unique HART device ID. This number is different for every device manufactured by Rosemount with this device type. It is identical to CPUBdSerialNumber	R	Y			long	-	-	uint32	-				
49051		ProgramChksum	Program checksum value This is the checksum of the meter's programs. All NOR flash program partitions are included in the checksum.	R	Y			long	-	-	uint32	-				
49061		Reserved		R				long								
49063 49065		Reserved Reserved		R				long long								
49067		Reserved		R				long								
49069		Reserved		R				long								
49071		Reserved		R				long								
49073		Reserved		R				long								
49075 49077		Reserved Reserved		R				long								
49077		Reserved		R				long long								
49091		Reserved		R				long								
49093	9092	Reserved		R				long								
49095		Reserved		R				long								
49097 49099		Reserved Reserved		R				long long								
49101		Reserved		R				long								
49103	9102	Reserved		R				long								
49105		Reserved		R				long								
49107 49109		Reserved Reserved		R				long								
49109		AO2Content	Analog Output 2 content (and HART secondary variable) Selects the data to be represented by Analog Output 2.1s used for HART communication as the Secondary Variable content.	RW	Y	Y	Y	long long	-	-	int32	-	Uncorrected volume flow rate (0) Average flow velocity (2) Average speed of sound (3)	0	0	3
49113	9112	AO2Dir	Selects the flow direction represented by the Analog Output 2 Selects the flow direction represented by Analog Output 2. When set to "Reverse" or "Forward", the analog output represents the specified content when the flow is in selected direction. When set to "Absolute", the analog output represents the specified content regardless of the flow direction.	RW	Y	Y	Y	long	-	-	int32	-	Reverse (0) Forward (1) Absolute (2)	2	0	2
49115		Reserved		R	μŢ	ШĪ		long								L]
49117 49151		Reserved Reserved		R	┝─┤	┝─┤		long float								───
49151		Reserved		R				float							1	┼──┤
49155		Reserved		R				float							1	
49157		Reserved		R				float								
49159		Reserved		R				float						_		└───┤
49161 49163		Reserved Reserved		R	┝─┤	╞─┤		float float							+	├
49165		Reserved		R				float							1	
49167		Reserved		R				float								
49169		Reserved		R	μŢ	ШĪ		float								1
49171 49173		Reserved Reserved		R				float float						_		—┩
49173		Reserved		R		\vdash		float								┝──┤
49177		Reserved		R				float							1	
49179		Reserved		R				float								
49181		Reserved		R	μŢ	ШĪ		float								1
49183 49185		Reserved Reserved		R R	┝─┤	┝─┤		float float								───┦
49185		Reserved		R		⊢┤		float								┥──┤
	- 100	= =		1											1	

Rosemour	nt™ Liqui	d Ultrasonic Firmware: 1.61	Database: 2.29.017												
			mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters												
Holding Register Number	Reg Num	Label	Description	Acc	NV C	infg Pr	ot Reg Typ		Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
49189		Reserved	Flow temperature one minute average	R R			float	den C		fleet22	K				
49191		e	A running average of flow-condition temperature (FlowTemperature) over one minute when the running averages are valid (IsRunningAvgValid).				float	deg C	deg F	float32	к				
49193			Flow pressure one minute average A running average of flow-condition pressure (FlowPressure) over one minute when the running averages are valid (IsRunningAvgValid).	R			float	MPa	psi	float32	MPa				
49195	9194	RunningAvgTurbulenceA	Chord A turbulence one minute average A running average of chord A turbulence over one minute when the running averages are valid (IsRunningAvgValid).	R			float	%	%	float32	%				
49197	9196	RunningAvgTurbulenceB	Chord B turbulence one minute average A running average of chord B turbulence over one minute when the running averages are valid (IsRunningAvgValid).	R			float	%	%	float32	%				
49199	9198	RunningAvgTurbulenceC	Chord C turbulence one minute average A running average of chord C turbulence over one minute when the running averages are valid (IsRunningAvgValid).	R			float	%	%	float32	%				
49201		RunningAvgTurbulenceD	Chord D turbulence one minute average A running average of chord D turbulence over one minute when the running averages are valid (IsRunningAvgValid).	R			float	%	%	float32	%				
49203	9202	RunningAvgAvgFlow	Avg flow averaged for one minute A running average of average flow velocity (AvgFlow) over one minute when the running averages are valid (IsRunningAvgValid).	R			float	m/s	ft/s	float32	m/s				
49205	9204	RunningAvgCrossFlow	Cross-flow one minute average A running average of cross-flow (CrossFlow) over one minute when the running averages are valid (IsRunningAvgValid).	R			float	-	-	float32	-				
49207	9206	RunningAvgProfileFactor	Profile factor one minute average A running average of profile factor (ProfileFactor) over one minute when the running averages are valid (IsRunningAvgValid).	R			float	-		float32	-				
49209	9208	RunningAvgSymmetry	Symmetry one minute average A running average of symmetry (Symmetry) over one minute when the running averages are valid (IsRunningAvgValid).	R			float	-	-	float32	-				
49211	9210	RunningSDevCrossFlow	Running standard deviation of cross-flow over a minute A running average of standard deviation of cross-flow (SDevCrossFlow) over a minute when the running averages are valid (IsRunning/AvgVald).	R			float	-	-	float32	-				
49213	9212	RunningSDevProfileFactor	Running standard deviation of the profile factor over a minute A running average of standard deviation of the profile factor (SDevProfileFactor) over a minute when the running averages are valid (IsRunningAvgVald).	R			float	-	-	float32	-				
49215	9214	RunningSDevSymmetry	Running standard deviation of symmetry over a minute A running average of standard deviation of symmetry (SDevSymmetry) over a minute when the running averages are valid (IsRunningAvgVald).	R			float	-	-	float32	-				
49217	9216	ReverseFlowVol	Accumulated volume for reverse flow alarm Volume flowed from continuous flow in reverse direction. This volume is compared to the reverse flow limit (ReverseFlowVolLmt) to determine the reverse flow alarm (ISReverseFlowDetected). It is only accumulated when the flow velocity (AvgWtdFlowVel) is below the reverse flow velocity threshold (ReverseFlowDetectionZeroCut).	R			float	volume	volume	float32	m3				
49219	9218	SignalAmplitudeA1	Batch average signal amplitude on path A1 Batch average of the signal amplitude when transducer A1 receives a signal.	R			float	mV	mV	float32	mV				
49221	9220	SignalAmplitudeA2	Batch average signal amplitude on path A2 Batch average of the signal amplitude when transducer A2 receives a signal.	R			float	mV	mV	float32	mV				
49223		SignalAmplitudeB1	Batch average signal amplitude on path B1 Batch average of the signal amplitude when transducer B1 receives a signal.	R			float	mV	mV	float32	mV				
49225		SignalAmplitudeB2	Batch average signal amplitude on path B2 Batch average of the signal amplitude when transducer B2 receives a signal.	R			float	mV	mV	float32	mV				
49227		SignalAmplitudeC1	Batch average signal amplitude on path C1 Batch average of the signal amplitude when transducer C1 receives a signal.	R			float	mV	mV	float32	mV				
49229		SignalAmplitudeC2	Batch average signal amplitude on path C2 Batch average of the signal amplitude when transducer C2 receives a signal.	R			float	mV	mV	float32	mV				
49231	9230	SignalAmplitudeD1	Batch average signal amplitude on path D1 Batch average of the signal amplitude when transducer D1 receives a signal.	R			float	mV	mV	float32	mV				
49233		SignalAmplitudeD2	Batch average signal amplitude on path D2 Batch average of the signal amplitude when transducer D2 receives a signal.	R			float	mV	mV	float32	mV				
49235	9234	NoiseAmplitudeA1	Batch average noise amplitude on path A1 Batch average of the noise amplitude when transducer A1 receives a signal.	R			float	mV	mV	float32	mV				
49237	9236	NoiseAmplitudeA2	Batch average noise amplitude on path A2 Batch average of the noise amplitude when transducer A2 receives a signal.	R			float	mV	mV	float32	mV				
49239	9238	NoiseAmplitudeB1	Batch average noise amplitude on path B1 Batch average of the noise amplitude when transducer B1 receives a signal.	R			float	mV	mV	float32	mV				
49241	9240	NoiseAmplitudeB2	Batch average noise amplitude on path B2 Batch average of the noise amplitude when transducer B2 receives a signal.	R			float	mV	mV	float32	mV				
49243	9242	NoiseAmplitudeC1	Batch average noise amplitude on path C1 Batch average of the noise amplitude when transducer C1 receives a signal.	R			float	mV	mV	float32	mV				
49245		NoiseAmplitudeC2	Batch average noise amplitude on path C2 Batch average of the noise amplitude when transducer C2 receives a signal.	R			float	mV	mV	float32	mV				
49247		NoiseAmplitudeD1	Batch average noise amplitude on path D1 Batch average of the noise amplitude when transducer D1 receives a signal.	R			float	mV	mV	float32	mV				
49249		NoiseAmplitudeD2	Batch average noise amplitude on path D2 Batch average of the noise amplitude when transducer D2 receives a signal.	R			float	mV	mV	float32	mV				
49251		FlowAnalysisHighFlowLmt	Upper flow velocity limit for performing flow analysis diagnostics The upper flow velocity limit for performing Dual-Configuration meter diagnostics (IsColocMeterQFlowRangeErr and IsColocMeterSndSpdRangeErr) and gating "flow analysis gated" values in daily and hourly logs.	RW	Y	ΥY		m/s	ft/s	float32	m/s		14.63	1	50
49253		FlowAnalysisLowFlowLmt	Lower flow velocity limit for performing flow analysis diagnostics The lower flow velocity limit for performing Dual-Configuration meter diagnostics (IsColocMeterQFlowRangeErr and IsColocMeterGndSpdRangeErr) and gating "flow analysis gated" values in daily and hourly logs. This value may not be less than the lower velocity threshold (ZeroCut).		Y	Y Y		m/s	ft/s	float32	m/s		0.61	-3.40E+38	3.40E+38
49255		ReverseFlowVolLmt	Reverse flow alarm limit This is the limit for the reverse flow alarm (IsReverseFlowDetected). If the volume for reverse flow (ReverseFlowVol) exceeds this value with continuous reverse flow, the reverse flow alarm will be set.		Y	ΥY		volume	volume	float32	m3		0	0	3.40E+38
49257	9256	ReverseFlowDetectionZeroC ut	Velocity threshold below which reverse flow volume accumulates Velocity threshold below which the flow velocity is considered reversed (and thus the reverse flow volume (ReverseFlowVol) is accumulated).	RW	Y	ΥY	' float	m/s	ft/s	float32	m/s		0.1	0	3.40E+38

Rosemour	nt™liqui	d Ultrasonic Firmware: 1.61	Database: 2 29 017													
			mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
			Description				1			Modbus				I	A finite second	Marchan
Holding Register Number	Reg Num	Label		Acc	NV	Cnfg P	rot Reg	ibus Type I	Modbus Metric Unit	U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
49259		SDevCrossFlow	Standard deviation of cross-flow Standard deviation of cross-flow calculated using measurement sequences received in a batch. This is used to calculate one minute running average of standard deviation of cross-flow (RunningSDevCrossFlow).	R			flc	at	-	-	float32	-				
49261	9260	SDevProfileFactor	Standard deviation of profile factor Standard deviation of profile factor calculated using measurement sequences received in a batch. This is used to calculate one minute running average of standard deviation of profile factor (RunningSDevProfileFactor).	R			flo	at	-	-	float32	-				
49263	9262	SDevSymmetry	Standard deviation of symmetry Standard deviation of symmetry calculated using measurement sequences received in a batch. This is used to calculate one minute running average of standard deviation of symmetry (RunningSDevSymmetry).	R			flc	at	-	-	float32	-				
49276	9275	AreSwComponentsCompati ble	Kernel, File System and Firmware are compatible versions When TRUE (1), the versions of the kernel (OSVer), file system (FileSysVer) and firmware (CPUBdSwVer), are compatible with each other. When FALSE (0), the appropriate software component(s) need to be updated.	R	\square		ir	nt	-	-	boolean	-				
49277		ible	Kernel, File System and Firmware are not compatible versions The inversion of the software compatibility Boolean (AreSwComponentsCompatible) for the Modbus system status bit field (SystemStatus). When FALSE (0), the versions of the kernel, file system and firmware are compatible with each other. When TRUE (1), the appropriate software component(s) need to be updated.	R			ir		-	-	boolean	-				
49278		Reserved		R	\square		ir									
49279 49280		Reserved IsRunningAvgValid	One minute average validity	R	+		ir	nt nt			boolean	-	Invalid (FALSE)			
43200	3213	isi tuming Avg valid	Are the values in the one minute averages valid for use with the baseline	i.					-	-	boolean		Valid (TRUE)			
49281	9280	RunningAvgSwirlAngle	Swirl angle one minute average A running average of swirl angle (SwirlAngle) over one minute when the running averages are valid (IsRunningAvgValid).	R			ir	nt	deg	deg	int8	deg				
49282	9281	IsReverseFlowDetected	Reverse flow detected The meter has accurulated a reverse flow volume greater than a user configurable limit. Limits are specified by the reverse flow volume limit (ReverseFlowVolLmt) and by the reverse flow detection zero flow cutoff (ReverseFlowDetectionZeroCut), This alarm may be enabled or disabled (IsReverseFlowDetectionEnabled). This alarm is latched (IsReverseFlowDetectedLatched). Recommended Actions:	R			ir	nt	-	-	boolean	-				
			 Check the valves for leaks. If the metering run is known to have some volume of reverse flow when the flow is stopped, reconfigure the reverse flow volume limit (ReverseFlowVolLmt) to allow a greater volume. If the meter regularly flows in the reverse direction, this alarm should be disabled. It is only intended to be used for unidirectional applications. If the issue is unresolved, collect an Archive Log using MeterLink™ and contact your local area Emerson Flow service representative. 													
49283		IsAnyBaselineAvail	Baselines supported for this meter type This indicates whether or not the baselines are supported. The value is FALSE (0) for liquid meters.	R	Y		ir	nt	-	-	boolean	-	Not Available (FALSE) Available (TRUE)			
49284	9283	SwirlAngleHighLmt	Swirl angle high limit The flow swirl angle limit above the baseline beyond which there is increased uncertainty in flow measurement. It is set internally when the swirl angle limit (SwirlAngleLmt) is set.	R	Y		ir	nt	deg	deg	int8	deg				
49285		SwirlAngleLowLmt	Swirt angle low limit The flow swirt angle limit below the baseline beyond which there is increased uncertainty in flow measurement. It is set internally when the swirt angle limit (SwirtAngleLmt) is set.	R			ir		deg	deg	int8	deg				
49286		SwirlAngleLmt	Swirl angle limit The flow swirl angle limit around the baseline (SwirlAngleLowLmt, SwirlAngleHighLmt) beyond which there is increased uncertainty in flow measurement.	RW		Y	Y ir		deg	deg	uint8	deg		5	0	90
49301	9300	PressureInvalidLatched	Flow pressure invalid, latched until acknowledged The alarm value for flow-condition pressure (PressureInvalid) that remains set until manually cleared.	RW	Y		ir	nt	-	-	boolean	-		FALSE (0)	FALSE (0)	TRUE (1)
49302	9301	TemperatureInvalidLatched	Flow temperature invalid, latched until acknowledged The alarm value for flow-condition temperature (TemperatureInvalid) that remains set until manually cleared.	RW	Y		ir	nt	-	-	boolean	-		FALSE (0)	FALSE (0)	TRUE (1)
49303	9302	IsAcqModuleErrorLatched	Acquisition Module error, latched until acknowledged The alarm value for Acquisition Module errors (IsAcqModuleError) that remains set until manually cleared.	RW	Y		ir	nt	-	-	boolean	-		FALSE (0)	FALSE (0)	TRUE (1)
49304	9303	IsMeterVelAboveMaxLmtLat	Meter velocity above max limit, latched until acknowledged The alarm value for the maximum velocity (IsMeter/velAboveMaxLmt) that remains set until manually cleared.	RW	Y		ir	nt	-	-	boolean	-		FALSE (0)	FALSE (0)	TRUE (1)
49305	9304		The alarm value for the maximum velocity (servere vero/overnaciting that remains see unin manualy ceared. Average speed of sound out of limits, latched unit acknowledged The latch for the average speed of sound out of limits alarm (IsAvgSoundVelRangeErr) that remains set until manually cleared	RW	Y		ir	nt	-	-	boolean	-		FALSE (0)	FALSE (0)	TRUE (1)
49306	9305	IsAcqModeLatched	Acquisition mode, latched until acknowledged The latched alarm for acquisition mode (IsAcqMode) that remains set until manually cleared.	RW	Y		ir	nt	-	-	boolean	-		FALSE (0)	FALSE (0)	TRUE (1)
49307	9306	IsTooFewOperChordsLatch	Too few operating chords, latched until acknowledged The alarm value for too few chords (IsTooFewOperChords) that remains set until manually cleared.	RW	Y		ir	nt	-	-	boolean	-		FALSE (0)	FALSE (0)	TRUE (1)
49308	9307		Reverse flow detected, latched until acknowledged	RW	Y		ir	nt	-	-	boolean	-		FALSE (0)	FALSE (0)	TRUE (1)
49309	9308	hed IsReverseFlowDetectionEna bled	The latch for the reverse flow alarm (IsReverseFlowDetected) that remains set until manually cleared. Enables or disables reverse flow detection Disables reverse flow detection (IsReverseFlowDetected) when set FALSE (0). Setting this to TRUE (1) will enable reverse flow detection.	RW	Y	Y	ir	nt	-	-	boolean	-	Disabled (FALSE) Enabled (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
49310	9309	Reserved		R			ir	nt						1		
49311		Reserved		R			ir									
49312 49313		Reserved Reserved		R			ir ir									
49313		Reserved		R			ir							+		├───┨
49315		Reserved		R	_		ir									
49316		Reserved		R			ir									
49317		Reserved		R	_		ir									\square
49318 49319		Reserved Reserved		R			ir ir									┥──┤
49320		Reserved		R	++		ir									
49321		Reserved		R			ir									
49322		Reserved Reserved		R			ir									
49323	9322	IVE361 AGR	1	R	┹┻┻		ir	п				1	l			L

Rosemoun	t™ Liau	id Ultrasonic Firmware: 1.6	1 Database: 2.29.017													—
			mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
			Description							Modbus					Malan	Marchan
Holding Register Number	Reg Num	Label		Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
49324		Reserved		R				int								
49325		Reserved		R				int								└─── ┃
49326 49327		Reserved Reserved		R				int int								┝───┦
49327		Reserved		R				int								
49329		Reserved		R				int								
49330	9329	Reserved		R				int								
49331		Reserved		R				int								
49332	9331			R				int								
49333 49334		Reserved Reserved		R R				int int								┝───┦
49335		Reserved		R				int								
49336	9335			R				int								
49337	9336	Reserved		R				int								
49338	9337	SetXdcrType	Set transducer type Sets the type of transducer installed. Changing this data point will overwrite transducer configuration parameters (XdcrFreq, XdcrNumDrwcQcles, DliChkSI, NegSpanSI, PkPIsVI/dthSI, PosSpanSI, SampPerCycle, SampInterval, TmDevLow1, Tspf, TspfLo, TspfHi, Tspe and Tamp) with default values. Once these transducer configuration values are written, the value of this data point is saved in the transducer type data point (XdcrType), and then set transducer type is set to zero.	RW	Y		Y	int	-	-	uint8	-	Automatically reset by the meter (0) LT-01/LT-03/LT-06/LT-07/LT-08/LT-09/LT-14/LT-15 (1) LT-04 (2) LT-05 (3) LT-10/LT-11/LT-16/LT-17 (4)	0	0	4
49339	9338	XdcrNumDriveCycles	Number of cycles for transducer Number of cycles for transducer. Will be overwritten when transducer type (SetXdcrType) changes.	RW	Y	Y	Y	int	-	-	uint8	-		1	1	2
49340	9339	SampPerCycle	Samples per cycle The number of times the waveform is sampled between two zero crossings with the same slope (one cycle). Usually adjusted by setting the transducer type (SetXdcrType). This value should only be changed at the factory or under the direction of Emerson Flow Support.	RW	Y	Y	Y	int	-	-	uint8	-	8 (8) 10 (10) 12 (12)	10	8	12
49341	9340	ColocMeterMode	Dual-Configuration meter mode Configures the meter to operate as a single head meter ("Disabled", 0), a Dual-Configuration meter's head 1 ("Transmitter Head 1", 1) or a Dual-Configuration meter's head 2 ("Transmitter Head 2", 2). The meters that measure the same flow may share a meter body or be installed in series with each other with only data sharing enabled. The Dual-Configuration meter's mode can be set to "Transmitter Head 1" or "Transmitter Head 2" only if the device number (DeviceNumber) is 3814. When meter is configured as a Dual-Configuration meter, it can be configured to synchronize transducer firing (XdorFiringSync) and also to enable data sharing and clock synchronization with Dual-Configuration meter (ColocMeterIPAddress).	RW	Y	Y	Y	int	-	-	uint8	-	Disabled (0) Transmitter Head 1 (1) Transmitter Head 2 (2)	0	0	2
49342	9341	XdcrFiringSync	Transducer firing synchronization control Configure transducer firing synchronization to be enabled ("Enabled", 1) or disabled ("Disabled", 0) between Dual-Configuration meters (IsXderFiringSyncActive). Transducer firing synchronization can only be enabled ("Enabled", 1) if Dual-Configuration meter mode (ColcoMeterMode) is not disabled ("Disabled", 0).	RW	Y	Y	Y	int	-	-	boolean	-	Disabled (FALSE) Enabled (TRUE)	FALSE (0)	FALSE (0)	TRUE (1)
49343	9342	IsXdcrFiringSyncActive	Transducer firing synchronization active in batch This indicates that all waveforms in a batch have Transducer Firing Synchronization (XdcrFiringSync) active.	R				int	-	-	boolean	-	Disabled (FALSE) Enabled (TRUE)			
49348		lsXdcrFiringSyncError	Transducer firing synchronization error: A problem with transducer firing synchronization in a batch (IsXdcrFiringSyncActive) when the transducer firing synchronization (XdcrFiringSync) is enabled and the Dual-Configuration meters' Acquisition Modules are not able to synchronize for multiple consecutive batches (AlarmDef). Possible causes include incorrect configuration, transducer synchronization cable is disconnected or damaged, and one of the two heads is not powered up or power cycling. Recommended Actions: 1. Verify that the transducer synchronization cable is connected between the two Acquisition Modules located in the base enclosures. 2. Verify that the transducer firing synchronization (XdcrFiringSync) is enabled on both heads. 4. Verify that the Dual-Configuration meter mode (ColocMeterMode) is set to "Transmitter Head 1" on one head and "Transmitter Head 2" on the other head. 5. For model number 3818, both heads must have the same configuration for stack size (StackSize), desired stacking transducer emission rate (StackFirateDesired) and desired transducer emission rate (EmRateDesired). 6. If the issue is unresolved, collect a Maintenance Log using MeterLink [™] and contact your local area Emerson Flow service representative.	R				int	-	-	boolean	-				
49349		IsColocMeterCommErr	Dual-Configuration meter communication error The Dual-Configuration meters are not communicating, either due to incorrect configuration or the other head is not reachable. It could also indicate that the Dual-Configuration meter clock is out of sync. Check the Dual-Configuration meter communication error reasons (ColocMeterCommErrReasons) for details. Recommended action: 1. Check the Ethernet connection between the Dual-Configuration meters. 2. Make sure that the Dual-Configuration meter IP address (ColocMeterIPAddress) on the head 1 is the same as the Ethernet IP address (Eth IPAddr) on the head 2 and vice versa. 3. If the clock synchronization (IsColocMeterClockSyncEnabled) is enabled, make sure that the PTP domain number (PTPDomainNumber) is the same on both meter heads. 4. Colect the Archive Logs (Daily, Hourly, Audit, Alarm, and System) using MeterLink™ and contact your local area Emerson Flow service representative.	R				int	-	-	boolean					
49350		ed	Dual-Configuration meter communication error, latched until acknowledged Latched alarm for Dual-Configuration meter communication error (IsColocMeterCommErr) that remains set until manually cleared.	RW		v		int	-		boolean		Disabled (FALSE)		FALSE (0)	TRUE (1)
49351		CheckEnabled	Enables or disables Dual-Configuration meter speed of sound range check error Enables Dual-Configuration meter speed of sound check feature (IsColocMeterSndSpdRangeCheckFeatureActive) when set TRUE (1). Setting this to FALSE (0) will disable Dual-Configuration meter speed of sound check feature.	RW	Ŷ	Ŷ		int	-	-	boolean	-	Enabled (TRUE)	TRUE (1)	FALSE (0)	TRUE (1)
49352	9351	IsColocMeterSndSpdRange CheckFeatureActive	Dual-Configuration meter speed of sound range check feature is active This is TRUE (1), when the Dual-Configuration meter speed of sound range check (IsColocMeter&ndSpdRangeCheckEnabled) is TRUE (1), Dual-Configuration meter IP address (ColocMeterIPAddress) is configured with an IP address other than the loopback address or meter's Ethernet IP address (Eth1IPAddr) and Dual-Configuration meter mode (ColocMeterMode) is set to "Transmitter Head 1" or "Transmitter Head 2".	R				int	-	-	boolean	-	Disabled (FALSE) Enabled (TRUE)			

Rosemou	nt™ Liqu	id Ultrasonic Firmware: 1.61	Database: 2.29.017													
			mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
49353	9352	IsColocMeterSndSpdRange Err	Dual-Configuration meter speed of sound range check error A Dual-Configuration meter speed of sound range error is detected. This could indicate a problem with the meter or the Dual- Configuration meter which could affect meter measurement. This alarn indicates that the one-hour running average of average speed of sound (ColoCMeterRunningAvgAvgSndVel) of the Dual-Configuration meters differ by more than the specified speed of sound range check error limit (ColoCMeterRunningAvgAvgSndVel) of the Dual-Configuration meters differ by more than the specified speed of sound range check fits alarn is so to TRUE (1), when the condition stated above is met and when the Dual-Configuration meter speed of sound range check feature (IsColoCMeterGndSpdRangcCheckFeatureActive) is TRUE (1) and the average speed of sound one-hour running average (IsColoCMeterGndSpdRangcCheckFeatureActive) is TRUE (1) and the average flow when the average flow velocity (AvgFlow) is less than the diagnostic analysis low flow limit (FlowAnalysisLowFlowLmt) or is greater than the diagnostic analysis high flow limit (FlowAnalysisHighFlowLmt). Recommended Actions: 1. Check there are no active alarm conditions which could be affecting speed of sound measurement. 2. Collect the Active Lags (Daly, Hourly, Audit, Alarm, and System), Maintenance Log and Waveform stream file using MeterLink [™] while	R				int	-	Unit -	boolean					
49354	0252	InColorMotorSpdSpdPappa	the meter is experiencing the issue and contact your local area Emerson Flow service representative. <td>RW</td> <td>Y</td> <td></td> <td></td> <td>int</td> <td></td> <td></td> <td>boolean</td> <td></td> <td></td> <td>FALSE (0)</td> <td>FALSE (0)</td> <td>TRUE (1)</td>	RW	Y			int			boolean			FALSE (0)	FALSE (0)	TRUE (1)
		ErrLatched	Latched alarm for Dual-Configuration meter speed of sound range check error (IsColocMeterSndSpdRangeErr) that remains set until manually cleared.						-			-				
49355	9354	IsColocMeterQFlowRangeC heckEnabled	Enables or disables Dual-Configuration meter uncorrected flow rate range check error Enables Dual-Configuration meter flow-condition volumetric flow rate range check feature (IsColocMeterQFlowRangeCheckFeatureActive) when set to TRUE (1). Setting this to FALSE (0) will disable Dual-Configuration meter flow- condition volumetric flow rate range check feature.	RW	Y	Y		int	-	-	boolean	-	Disabled (FALSE) Enabled (TRUE)	TRUE (1)	FALSE (0)	TRUE (1)
49356	9355	IsColocMeterQFlowRangeC heckFeatureActive	Dual-Configuration meter uncorrected flow rate range check feature is active This is TRUE (1), when the Dual-Configuration meter flow-condition volumetric flow rate range check (IsColocMeterQFlowRangeCheckEnabled) is TRUE (1), Dual-Configuration meter IP address (ColocMeterIPAddress) is configured with an IP address other than the loopback address or meter's Ethernet IP address (Eth'IIPAddr) and Dual-Configuration meter mode (ColocMeterMode) is set to Transmitter Head 1* or "Transmitter Head 2*.	R				int	-	-	boolean	-	Disabled (FALSE) Enabled (TRUE)			
49357	9356	IsColocMeterQFlowRangeEr r	Dual-Configuration meter uncorrected flow rate range check error A Dual-Configuration meter flow-condition volumetric flow rate range error is detected. This alarm could indicate a problem with the meter or the Dual-Configuration meter flow-condition volumetric flow rate range error is detected. This alarm indicates that the flow-condition volumetric flow rate one-hour running average (ColcoMeterRunningAvgOFlow) of the Dual-Configuration meters differ by more than the specified flow- condition volumetric flow rate range check error imit (ColcoMeterQFlowErtImit). This alarm is TRUE (1), when the condition stated above is met and when the Dual-Configuration meter flow-condition volumetric flow rate range check feature ((ScOlcoMeterRunningAvgOFlow/Valid) is TRUE (1) on the flow-condition volumetric flow rate en-hour running average (IsCotcoMeterRunningAvgOFlowValid) is TRUE (1) on to the hou-condition volumetric flow rate one-hour running average (IsCotcoMeterRunningAvgOFlowValid) is TRUE (1) on to the hou-condition volumetric flow rate one-hour running average (IsCotcoMeterRunningAvgOFlowValid) is TRUE (1) on to the hou-condition volumetric flow rate and whet mit (FlowAna)sisHighFlowLm). Recommended Actions: 1. The alarm could be an indication of possible buildup of material on the meter bore. The meter run should be checked and cleaned if necessary. 2. On meter head 1, check the meter diagnostics Symmetry, SwitAngle, ProfileFactor and CrossFlow and compare them against their baseline values. 3. Collect the Archive Logs (Daily, Hourly, Audit, Alarm, and System), Maintenance Log and Waveform stream file using MeterLink [™] while the meter is experiencing the issue and contact your local area Emerson Flow service representative.	R				int	-	-	boolean	-				
49358	9357	IsColocMeterQFlowRangeEr rLatched	Dual-Configuration meter uncorrected flow rate range check error, latched until acknowledged Latched alarm for Dual-Configuration meter flow-condition volumetric flow rate range check error (IsColocMeterQFlowRangeErr) that	RW	Y			int		-	boolean	-		FALSE (0)	FALSE (0)	TRUE (1)
49359	9358	lsColocMeterRunningAvgAv gSndVelValid	remains set until manually cleared. Average speed of sound running average for Dual-Configuration meter diagnostic error validity The validity of average speed of sound one hour running average (ColocMeterRunningAvgAvgSndVel). This is used for Dual- Configuration meter speed of sound range check error (IsColocMeterSndSpdRangeErr).	R				int	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
49360	9359	IsColocMeterRunningAvgQF lowValid	Uncorrected flow rate running average for Dual-Configuration meter diagnostic error validity The validity of Dual-Configuration meter flow-condition volumetric flow rate one hour running average (ColocMeterRunningAvgQFlow). This is used for Dual-Configuration meter flow-condition volumetric flow rate range check error (IsColocMeterQFlowRangeErr).	R				int	-	-	boolean	-	Invalid (FALSE) Valid (TRUE)			
49361	9360	IsColocMeterClockSyncEna bled	Enables or disables clock synchronization with Dual-Configuration meter Enables clock synchronization for a data sharing Dual-Configuration meter when set to TRUE (1) in both transmitter heads.	RW	Y	Y		int	-	-	boolean	-	Disabled (FALSE) Enabled (TRUE)	TRUE (1)	FALSE (0)	TRUE (1)
49362	9361	PTPDomainNumber	PTP domain number Configures the PTP (Precision Time Protocol) domain number. This allows the Dual-Configuration meter's head 2 clock to synchronize to the Dual-Configuration meter's head 1 clock. The Dual-Configuration meter clock synchronization (IsColocMeterClockSyncEnabled) must be enabled on both Dual-Configuration meters to synchronize clock. When set to 128, meaning auto-configure PTP domain, then on the Dual-Configuration meter head 1, the low order octet of Ethernet IP address (Eth IIPAddr) is used as PTP domain number. While on the Dual-Configuration meter head 2, the low order octet of Dual- Configuration meter IP address (ColocMeterIPAddress) is used as the PTP domain number.	RW	Y	Y		int	-	-	uint8	-		128	0	255
49363	9362	ColocMeterCommErrReaso ns	Dual-Configuration meter communication error reason The reasons for Dual-Configuration meter communication error (IsColoc/MeterCommErr). 0 – No error 1 – Dual-Configuration meter IP address could not be reached 2 – Previously established connection with Dual-Configuration meter has gone down. This could be due to reasons that can cause the connection to go down, including the remote meter rebooting, network connectivity issues, or problems with the internal system error on the Dual-Configuration meter 3 – Internal error or system call failure 4 – Dual-Configuration meter clock out of sync	R				int	-	-	uint8	-	No error (0) Dual-Configuration meter IP address unreachable (1) Waining for Dual-Configuration meter response (2) System internal error (3) Dual-Configuration meter clock out of sync (4)			
49364	9363	XdcrType	Transducer type The set of transducers with the same tracking parameters of which the installed transducers are a member. The value is typically set by the set transducer type (SetXdcrType). However, this value may be manually entered or overwritten.	RW	Y	Y	Y	int	-	-	uint8	-	Not set (0) LT-01/LT-03/LT-06/LT-07/LT-08/LT-09/LT-14/LT-15 (1) LT-04 (2) LT-05 (3) LT-10/LT-11/LT-16/LT-17 (4)	0	0	4
49371	9370	ColocMeterSndSpdErrLimit	Error limit for Dual-Configuration meter speed of sound range check error Limit on the difference between average speed of sound one hour average (ColocMeterRunningAvgAvgSndVel) of the Dual- Configuration meters. This is used to generate Dual-Configuration meter speed of sound range check alarm (IsColocMeterSndSpdRangeErr).	RW	Y	Y	Y	float	%	%	float32	%		0.5	0	10

Rosemou	nt™ Liqu	id Ultrasonic Firmware: 1.6	1 Database: 2.29.017		—											
The below	/ Modbus	map is applicable for Rose	mount [™] Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg I	Prot	Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
49373	9372	ColocMeterQFlowErrLimit	Error limit for Dual-Configuration meter uncorrected flow rate range check error Limit on the difference between flow-condition volumetric flow rate one hour average (ColocMeterRunningAvgQFlow) of the Dual- Configuration meters. This is used to generate Dual-Configuration meter flow-condition volumetric flow rate range check alarm (IsColocMeterCHowRangeErr).	RW	Y	Y	Y	float	%	Unit %	float32	%		1	0	10
49375	9374	ColocMeterRunningAvgAvg SndVel	Average speed of sound running average for Dual-Configuration meter diagnostic error One hour running average of average speed of sound (AvgSndVei). The running average is updated once in a minute using average speed of sound samples per batch. It is used to indicate Dual-Configuration meter speed of sound range check alarm (IsColocMeterSndSpdRangeErr).	R				float	m/s	ft/s	float32	m/s				
49377	9376	ColocMeterRunningAvgQFlo w	Uncorrected flow rate running average for Dual-Configuration meter diagnostic error One hour running average of Dual-Configuration meter flow-condition volumetric flow rate (QFlow). The running average is updated once in a minute using flow-condition volumetric flow rate samples per batch. It is used to indicate Dual-Configuration meter flow-condition volumetric flow rate range check alarm (IsColocMeterQFlowRangeErr).	R				float	volume/time	volume/time	float32	m3/hr				
49401	9400	BatchSeqNum	Batch sequence number The batch sequence number which is zero on a warm start and then incremented each batch period (BatchUpdatePeriod).	R				long	-	-	uint32	-				
49411	9410	XdcrHousingLengthA1	Transducer assembly A1 housing length The length of the transducer assembly A1 housing. The length is engraved on the housing body and is also included in the Zero Flow Calibration report.	RW	Y	Y	Y	float	m	ft	float32	m		0	0	0.508
49413		XdcrHousingLengthA2	Transducer assembly A2 housing length The length of the transducer assembly A2 housing. The length is engraved on the housing body and is also included in the Zero Flow Calibration report.	RW	Y	Y	Y	float	m	ft	float32	m		0	0	0.508
49415		MeterHousingLengthA	Chord A meter housing length The meter housing length for chord A. The length is located on the tag attached to the ultrasonic meter body and is also included in the Zero Flow Calibration report provided with the meter.	RW	Y	Y	Y	float	m	ft	float32	m		0	0	5
49417	9416		Chord A length ("L" dimension) The distance between the transducer faces on chord A. The factory setting should only be changed when changing a transducer or after a meter cold start.	RW	Y	Y	Y	float	m	ft	float32	m		0.3175	0	5
49419		DitDiyA	Chord A difference in upstream and downstream delay times The adjustment to the chord A delta times (the individual times used for DItTmA (DItTmA)) to ensure calibration at zero flow. Chord A general delta times Chord A difference in upstream Chord A difference Chord A difference in upstream Chord A difference	RW	Y	Y	Y	float	us	us	float32	us		0	-1	1
49421 49425		AvgDlyA XdcrHousingLengthB1	Chord A average delay time The chord-specific delay for chord A primarily due to the signal processing algorithm and acoustic propagation time within the transducer including the matching layer. It is used in conjunction with the overall system delay (SystemDelay). Transducer assembly B1 housing length	RW	Y	Y	Y	float	us	us 4	float32 float32	us		0	0	50 0.508
			The length of the transducer assembly B1 housing. The length is engraved on the housing body and is also included in the Zero Flow Calibration report.		Y	Y	Y		m	π 6		m		0	0	
49427		XdcrHousingLengthB2	Transducer assembly B2 housing length The length of the transducer assembly B2 housing. The length is engraved on the housing body and is also included in the Zero Flow Calibration report.	RW	Y	Ŷ	Y	float	m	ft	float32	m		0	0	0.508
49429		MeterHousingLengthB	Chord B meter housing length The meter housing length for chord B. The length is located on the tag attached to the ultrasonic meter body and is also included in the Zero Flow Calibration report provided with the meter.	RW	Y	Ŷ	Y	float	m	ft	float32	m		0	0	5
49431	9430		Chord B length ("L" dimension) The distance between the transducer faces on chord B. The factory setting should only be changed when changing a transducer or after a meter cold start.	RW	Y	Y	Y	float	m	π	float32	m		0.4445	U	5
49433		DitDiyB	Chord B difference in upstream and downstream delay times The adjustment to the chord B delta times (the individual times used for DItTmB (DItTmB)) to ensure calibration at zero flow.	RW	Y	Y	Y	float	us	us	float32	us		0	-1	1
49435		AvgDlyB	Chord B average delay time The chord-specific delay for chord B primarily due to the signal processing algorithm and acoustic propagation time within the transducer including the matching layer. It is used in conjunction with the overall system delay (SystemDelay).	RW	Y	Y	Y	float	us	us	float32	us		0	0	50
49439		XdcrHousingLengthC1	Transducer assembly C1 housing length The length of the transducer assembly C1 housing. The length is engraved on the housing body and is also included in the Zero Flow Calibration report.	RW	Y	Y	Y	float	m	ft	float32	m		0	0	0.508
49441		XdcrHousingLengthC2	Transducer assembly C2 housing length The length of the transducer assembly C2 housing. The length is engraved on the housing body and is also included in the Zero Flow Calibration report.	RW	Y	Y	Y	float	m	ft	float32	m		0	0	0.508
49443		MeterHousingLengthC	Chord C meter housing length The meter housing length for chord C. The length is located on the tag attached to the ultrasonic meter body and is also included in the Zero Flow Calibration report provided with the meter.	RW	Y	Y	Y	float	m	ft	float32	m		0	0	5
49445	9444		Chord C length ('L' dimension) The distance between the transducer faces on chord C. The factory setting should only be changed when changing a transducer or after a meter cold start.	RW	Y	Y	Y	float	m	ft	float32	m		0.4445	0	5
49447	9446	DitDlyC	Chord C difference in upstream and downstream delay times The adjustment to the chord C delta times (the individual times used for DltTmC (DltTmC)) to ensure calibration at zero flow.	RW	Y	Y	Y	float	us	us	float32	us		0	-1	1
49449		AvgDlyC	Chord C average delay time The chord-specific delay for chord C primarily due to the signal processing algorithm and acoustic propagation time within the transducer including the matching layer. It is used in conjunction with the overall system delay (SystemDelay).	RW	Y	Y	Y	float	us	us	float32	us		0	0	50
49453		XdcrHousingLengthD1	Transducer assembly D1 housing length The length of the transducer assembly D1 housing. The length is engraved on the housing body and is also included in the Zero Flow Calibration report.	RW	Y	Y	Y	float	m	ft	float32	m		0	0	0.508
49455		XdcrHousingLengthD2	Transducer assembly D2 housing length The length of the transducer assembly D2 housing. The length is engraved on the housing body and is also included in the Zero Flow Calibration report.	RW	Y	Y	Y	float	m	ft	float32	m		0	0	0.508
49457		MeterHousingLengthD	Chord D meter housing length The meter housing length for chord D. The length is located on the tag attached to the ultrasonic meter body and is also included in the Zero Flow Calibration report provided with the meter.	RW	Y	Y	Y	float	m	ft	float32	m		0	0	5
49459	9458		Chord D length ("L" dimension) The distance between the transducer faces on chord D. The factory setting should only be changed when changing a transducer or after a meter cold start.	RW	Y	Y	Y	float	m	ft	float32	m		0.3175	0	5
49461	9460	DltDlyD	Chord D difference in upstream and downstream delay times The adjustment to the chord D delta times (the individual times used for DtTmD (DtTmD)) to ensure calibration at zero flow.	RW	Y	Y	Y	float	us	us	float32	us		0	-1	1
		•			<u>ب</u>		_				•				•	

Rosemou	nt™ Liqui	d Ultrasonic Firmware: 1.61	Database: 2.29.017													
			mount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg I		Modbus Reg Type	Modbus Metric Unit	Modbus U.S. Customary	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
49463	9462	AvgDlyD	Chord D average delay time The chord-specific delay for chord D primarily due to the signal processing algorithm and acoustic propagation time within the transducer including the matching layer. It is used in conjunction with the overall system delay (SystemDelay).	RW	Y	Y	Y	float	us	Unit us	float32	us		0	0	50
49473	9472	IsChordLengthMismatchedA	In-use length is not equal to the calculated length for chord A The in-use chord length (L) does not match the calculated chord length. The meter calculates chord length as, calculated_length = meter_housing_length (MeterHousingLengthA) - transducer1_housing_length (XdcrHousingLengthA1) - transducer2_housing_length (XdcrHousingLengthA2).	R				int	-	-	boolean	-				
			This alarm is disabled when all the chord component lengths (MeterHousingLengthA, XdcrHousingLengthA1, XdcrHousingLengthA2) are set to zero. When the component lengths are updated, the meter doesn't update the in-use chord length (LA). The in-use chord length shall be updated when updating the chord component lengths when replacing the transducer. Recommended Actions:													
			 Open the Transducer Swap-Out wizard in MeterLink[™] and verify the component lengths for chord A are correct. Compare them against a Zero Flow Calibration report if you have one or read the values off the individual components. This report can be requested from your Emerson Flow service representative. The wizard will calculate the new chord length (LA) which can be written to the meter if different from the value in Use to clear this atarm. If the issue is unresolved, collect Meter Archive Logs (Daily, Hourly, Audit, Alarm and System) with MeterLink[™] and contact your local area Emerson Flow service representative. 													
49474	9473	IsChordLengthMismatchedB	In-use length is not equal to the calculated length for chord B The in-use chord length (LB) does not match the calculated chord length. The meter calculates chord length as, calculated length = meter_housing_length (MeterHousingLengthB) - transducer1_housing_length (XdcrHousingLengthB1) - transducer2_housing_length (XdcrHousingLengthB2).	R				int	-	-	boolean	-				
			This alarm is disabled when all the chord component lengths (MeterHousingLengthB, XdcrHousingLengthB1, XdcrHousingLengthB2) are set to zero. When the component lengths are updated, the meter doesn't update the in-use chord length (LB). The in-use chord length shall be updated when updating the chord component lengths when replacing the transducer.													
			Recommended Actions: 1. Open the Transducer Swap-Out wizard in MeterLink [™] and verify the component lengths for chord B are correct. Compare them against a Zero Flow Calibration report if you have one or read the values off the individual components. This report can be requested from your Emerson Flow service representative. The wizard will calculate the new chord length (LB) which can be written to the meter if different from the value In Use to clear this alarm. 2. If the issue is unresolved, collect Meter Archive Logs (Daily, Hourly, Audit, Alarm and System) with MeterLink [™] and contact your local area Emerson Flow service representative.													
49475	9474	IsChordLengthMismatchedC	In-use length is not equal to the calculated length for chord C The in-use chord length (LC) does not match the calculated chord length. The meter calculates chord length as, calculated_length = meter_housing_length (MeterHousingLengthC) - transducer1_housing_length (XdcrHousingLengthC1) - transducer2_housing_length (XdcrHousingLengthC2).	R				int		-	boolean	-				
			This alarm is disabled when all chord component lengths (MeterHousingLengthC, XdcrHousingLengthC1, XdcrHousingLengthC2) are set to zero. When the component lengths are updated, the meter doesn't update the in-use chord length (LC). The in-use chord length shall be updated when updating the chord component lengths when replacing the transducer. Recommended Actions:													
			 Open the Transducer Swap-Out wizard in MeterLink™ and verify the component lengths for chord C are correct. Compare them against a Zero Flow Calibration report if you have one or read the values off the individual components. This report can be requested from your Emerson Flow service representative. The wizard will calculate the new chord length (LC) which can be written to the meter if different from the value Ib set to clear this alarm. If the issue is unresolved, collect Meter Archive Logs (Daily, Hourly, Audit, Alarm and System) with MeterLink™ and contact your local area Emerson Flow service representative. 													
49476	9475	IsChordLengthMismatchedD	In-use length is not equal to the calculated length for chord D The in-use chord length (LD) does not match the calculated chord length. The meter calculates chord length as, calculated length =	R				int	-	-	boolean	-				
			meter_housing_length (MeterHousingLengthD) - transducer1_housing_length (XdcrHousingLengthD1) - transducer2_housing_length (XdcrHousingLengthD2). This alarm is disabled when all chord component lengths (MeterHousingLengthD, XdcrHousingLengthD1, XdcrHousingLengthD2) are set													
			to zero. When the component lengths are updated, the meter doesn't update the in-use chord length (LD). The in-use chord length shall be updated when updating the chord component lengths when replacing the transducer. Recommended Actions:													
			1. Open the Transducer Swap-Out wizard in MeterLink™ and verify the component lengths for chord D are correct. Compare them against a Zero Flow Calibration report if you have one or read the values off the individual components. This report can be requested from your Emerson Flow service representative. The wizard will calculate the new chord length (LD) which can be written to the meet if different from the value in Use to clear this alarm. 2. If the issue is unresolved, oldect Meter Archive Logs (Daily, Hourly, Audit, Alarm and System) with MeterLink™ and contact your local area Emerson Flow service representative.													
49481	9480	IsChordLengthMismatched	In-use chord length does not match calculated chord length The in-use chord length does not match for one or more chords. See chord alarms for more details (IsChordLengthMismatchedA, IsChordLengthMismatchedB, IsChordLengthMismatchedC, IsChordLengthMismatchedD).	R				int	-	-	boolean	-				
			Recommended Actions: 1. Open the Transducer Swap-Out wizard in MeterLink [™] and verify the component lengths for chord (for four-path meters LA, LB, LC and LD, for dual-path meters LA and LB and for single-path meters LA) are correct. Compare them against a Zero Flow Calibration report if you have one or read the values off the individual components. This report can be requested from your Emerson Flow service representative. The wizard will calculate the new chord lengths which can be written to the meter if different from the value in Use to clear this alarm. 2. If the issue is unresolved, collect Meter Archive Logs (Dally, Hourly, Audit, Alarm and System) with MeterLink [™] and contact your local area Emerson Flow service representative.													
	65533	Reserved		R	\vdash		+	float				<u></u>				
	65534	Reserved		R				long	l					1	page 69	

Rosemou	nt™ Liquio	d Ultrasonic Firmware: 1.61	Database: 2.29.017													
The below	Modbus	map is applicable for Roser	nount™ Liquid 4-Path (DeviceNumber 3814) and 2-Path (DeviceNumber 3812) meters													
Holding Register Number	Reg Num	Label	Description	Acc	NV	Cnfg P	rot	lodbus eg Type	Modbus Metric Unit	Modbus U.S. Customary Unit	Native Data Type	Native Data Unit	Selections/Bitmap	Default Value (native unit)	Minimum Value (native unit)	Maximum Value (native unit)
	65535	Reserved		R				int								í l
																i l

		mware: 1.61 Database: 2.29.017			
e below Modbus m	nap is applicable	for Rosemount™ Liquid 4-Path (DeviceNumber	- 3814) and 2	-Path (DeviceNumber 3812) meters	
lolding Register Number	Туре	Register Label	Bit In Register	Status/Alarm/Alert Label	Status-Leve
502	INT	IsWarmStartReq	NA	IsWarmStartReq	Red
1300	INT	DidColdStart	NA	DidColdStart	Red
1302	INT	DidCnfgChksumChg	NA	DidCnfgChksumChg	Yellow
1305	INT	WatchDogReset	NA	WatchDogReset	Red
			0	IsHardFailedA	Yellow
			1	IsHardFailedB	Yellow
			2	IsHardFailedC	Yellow
2300	LONG	DataQlty	3	IsHardFailedD	Yellow
			8	Reserved	NA
			16	IsTooFewOperChords	Red
			17	IsMeterVelAboveMaxLmt	Yellow
			0	DidExceedMaxNoiseA	Yellow
			1	IsSNRTooLowA	Yellow
			2	DidTmDevChkFailA	Yellow
			4	DidDltTmChkFailA	Yellow
			5	IsXdcrMaintenanceRequiredA	Yellow
			6	IsStackingIncompleteA	Yellow
			7	IsChordLengthMismatchedA	Red
2458	INT	StatusA	8	IsSigClippedA	Yellow
2100			9	IsSigQltyBadA	Yellow
			9 10	IsSigDistortedA	Yellow
			10	IsPeakSwitchDetectedA	Yellow
					Yellow
			12	IsMeasSndSpdRangeA	
			13		Yellow
			14	IsFailedForBatchA	Yellow
			15		Red
			0		Yellow
			1	ISSNRTooLowB	Yellow
			2	DidTmDevChkFailB	Yellow
			4	DidDltTmChkFailB	Yellow
			5	IsXdcrMaintenanceRequiredB	Yellow
			6	IsStackingIncompleteB	Yellow
			7	IsChordLengthMismatchedB	Red
2459	INT	StatusB	8	IsSigClippedB	Yellow
			9	IsSigQltyBadB	Yellow
			10	IsSigDistortedB	Yellow
			11	IsPeakSwitchDetectedB	Yellow
			12	IsMeasSndSpdRangeB	Yellow
			13	IsBatchInactiveB	Yellow
			14	IsFailedForBatchB	Yellow
			15	IsAcqMode	Red
Т			0	DidExceedMaxNoiseC	Yellow
			1	IsSNRTooLowC	Yellow
			2	DidTmDevChkFailC	Yellow
			4	DidDltTmChkFailC	Yellow
			5	IsXdcrMaintenanceRequiredC	Yellow
			6	IsStackingIncompleteC	Yellow
			7	IsChordLengthMismatchedC	Red
2460	INT	StatusC	8	IsSigClippedC	Yellow
			9	IsSigQltyBadC	Yellow
			10	IsSigDistortedC	Yellow
			11	IsPeakSwitchDetectedC	Yellow
			12	IsMeasSndSpdRangeC	Yellow
			12	IsBatchInactiveC	Yellow
			13	IsFailedForBatchC	Yellow
			14	IsAcqMode	Red

below Modbus r	nap is applicable	e for Rosemount™ Liquid 4-Path (DeviceNumber	3814) and 2-	-Path (DeviceNumber 3812) meters	
olding Register Number	Туре	Register Label	Bit In Register	Status/Alarm/Alert Label	Status-Leve
			0	DidExceedMaxNoiseD	Yellow
			1	IsSNRTooLowD	Yellow
			2	DidTmDevChkFailD	Yellow
			4	DidDltTmChkFailD	Yellow
			5	IsXdcrMaintenanceRequiredD	Yellow
			6	IsStackingIncompleteD	Yellow
			7	IsChordLengthMismatchedD	Red
2461	INT	StatusD	8	IsSigClippedD	Yellow
			9	IsSigQltyBadD	Yellow
			10	IsSigDistortedD	Yellow
			11	IsPeakSwitchDetectedD	Yellow
			12	IsMeasSndSpdRangeD	Yellow
			13	IsBatchInactiveD	Yellow
			14	IsFailedForBatchD	Yellow
			15	IsAcqMode	Red
			0	Reserved	NA
			1	AreSwComponentsIncompatible	NA
			2	DidPowerFail	Red
			3	IsAcqModuleIncompatible	Red
			4	IsXdcrFiringSyncError	Yellow
			5	IsEstimatedFlowVelocityInUse	Yellow
2462	INT	SystemStatus	6	DidWarmStart	Yellow
			7	IsColocMeterQFlowRangeErr	Yellow
			8	IsTooFewOperChords	Red
			9	IsMeterVelAboveMaxLmt	Yellow
			9 14	IsReverseFlowDetected	Yellow
2464	INT	QMeterValidity	15	WatchDogReset QMeterValidity	Red
2464		QFlowValidity	NA	QFlowValidity	Red
2465	INT		NA	-	Red
2470	INT	PressureValidity TemperatureValidity	NA	PressureValidity	Yellow
2471	INT	ExpCorrPressValidity	NA	TemperatureValidity ExpCorrPressValidity	Yellow
2474	INT	ExpCorrTempValidity	NA	,	Red
2475	INT		NA	ExpCorrTempValidity IsAvqSoundVelRangeErr	Red
2478	INT	IsAvgSoundVelRangeErr	NA	° °	Yellow
			7	IsColocMeterQFlowRangeErrLatched	Yellow
2492	INT	SystemStatusLatched	8	IsTooFewOperChordsLatched	Red
			9	IsMeterVelAboveMaxLmtLatched	Yellow
			14	IsReverseFlowDetectedLatched	Yellow
a. 16-			0	IsColocMeterCommErrLatched	Yellow
2493	INT	FieldIOStatusLatched	1	PressureInvalidLatched	Yellow
			2	TemperatureInvalidLatched	Yellow
2496	INT	SOSCompareStatus	3	IsColocMeterSndSpdRangeErr	Yellow
2497	INT	SOSCompareStatusLatched	3	IsColocMeterSndSpdRangeErrLatched	Yellow
			0	IsColocMeterCommErr	Yellow
			1	PressureInvalid	Yellow
4264	LONG	FieldIOStatus	2	TemperatureInvalid	Yellow
			8	DidResetUsers	Yellow
			18	IsCorePresent	Red
5003	INT	IsClkInvalid	NA	IsClkInvalid	Yellow
5004	INT	IsAcqModuleError	NA	IsAcqModuleError	Red
5005	INT	IsAlarmLogFull	NA	IsAlarmLogFull	Yellow
5006	INT	IsAuditLogFull	NA	IsAuditLogFull	Yellow
5007	INT	IsDailyLogFull	NA	IsDailyLogFull	Yellow
5008	INT	IsHourlyLogFull	NA	IsHourlyLogFull	Yellow
5009	INT	IsSystemLogFull	NA	IsSystemLogFull	Yellow
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ne below Modbus ma	ip is applicable	e for Rosemount™ Liquid 4-Path (DeviceNu	mber 3814) and 2	-Path (DeviceNumber 3812) meters	
Holding Register Number	Туре	Register Label	Bit In Register	Status/Alarm/Alert Label	Status-Leve
5011	INT	IsElecVoltOutOfRange	NA	IsElecVoltOutOfRange	Yellow
5075	INT	HARTTVValidity	NA	HARTTVValidity	Red
5076	INT	HARTQVValidity	NA	HARTQVValidity	Red
5077	INT	HARTSlot0Validity	NA	HARTSlot0Validity	Red
5078	INT	HARTSlot1Validity	NA	HARTSlot1Validity	Red
5079	INT	HARTSlot2Validity	NA	HARTSlot2Validity	Red
5080	INT	HARTSlot3Validity	NA	HARTSlot3Validity	Red
5095	INT	AO1DataValidity	NA	AO1DataValidity	Red
5096	INT	AO2DataValidity	NA	AO2DataValidity	Red
5097	INT	Freq1DataValidity	NA	Freq1DataValidity	Red
5098	INT	Freq2DataValidity	NA	Freq2DataValidity	Red
9302	INT	IsAcqModuleErrorLatched	NA	IsAcqModuleErrorLatched	Red
9304	INT	IsAvgSoundVelRangeErrLatched	NA	IsAvgSoundVelRangeErrLatched	Yellow
9305	INT	IsAcqModeLatched	NA	IsAcqModeLatched	Red
10515	INT	IsQFlowInvalid	NA	IsQFlowInvalid	NA

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Modbus no		
1.	The units are as show	n below (in alphabetical order):
	Unit	Description
	-	dimensionless or not applicable
	%	percent
	μs	microseconds
	1/degC	inverse degree-Celsius
	1/degF	inverse degree-Fahrenheit
	1/K	inverse Kelvin
	1/MPa	inverse megapascal
	1/psi	inverse pounds-per-square-inch
	bbl	US petroleum barrel
	bits/sec	bits per second
	cPoise	centipoise
	deg	degrees (angular measure)
	deg C	degrees Celsius
	deg F	degrees Fahrenheit
	energy	energy unit
	Epoch sec	time in seconds since Epoch (midnight Jan. 1, 1970)
	ft	feet
	ft/s	feet per second
	gain (dB)	gain in decibels
	gal	US liquid gallon
	hr	hour
	Hz	Hertz
	in K	inches Kelvin
	ĸ KHz	kiloHertz
	kg/m3 L	kilogram per cubic meter Liter
	L Ibm/ft3	pounds mas per cubic foot.
	m	meters
	ma	milliamperes
	m/s	meters per second
	min	minutes
	MPa	MegaPascals
	ms	milliseconds
	ns	nanoseconds
	Pa.s	Pascal seconds
	psi	pounds-per-square inch
	pulses/volume	pulses per volume where the volume unit is determined by the
	•	UnitsSystem, VolUnitUS, and VolUnitMetric data points
	s/m	
	s/m s2/m2	seconds per meter square seconds per square meter
	sample intervals	sample intervals
	sec	seconds per meter
	sec/ft	seconds per foot
	sec2/ft2	square seconds per square foot
	Time pulses	Time pulses (0.001000 sec per time pulse)
	V	Volts
	v	VOIG

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volume	volume where the volume unit is determined by the UnitsSystem, VolUnitUS, and VolUnitMetric data points
volume lower	lower volume portion (i.e., amount below overflow of 10 ⁹ volume units) where the volume unit is determined by the UnitsSystem, VolUnitUS, and VolUnitMetric data points
volume overflow	overflow volume portion (i.e., multiples of 10 ⁹ volume units) where the volume unit is determined by the UnitsSystem, VolUnitUS, and VolUnitMetric data points
volume/pulse	volume per frequency pulse where the volume unit is determined by the UnitsSystem, VolUnitUS, and VolUnitMetric data points
volume/time	volume per time unit where the volume unit is determined by the UnitsSystem, VolUnitUS, and VolUnitMetric data points and the time unit is determined by the VolFlowRateTimeUnit data point

- 2. When no units are listed then the value is dimensionless or not applicable.
- The native data types are as follows: int8, int16, int32, and int64 are 8-, 16-, 32-, and 64-bit integers uint8, uint16, uint32, and uint64 are 8-, 16-, 32-, and 64-bit unsigned integers float32 is 32-bit floating point float64 is 64-bit floating point boolean is a Boolean value (i.e., has FALSE or TRUE value where FALSE=0, TRUE=1) bitfield is a bitmapped collection of Boolean database points
- 4. The "Selections/Bitmap" column is used to indicate selection values and bitfield bit mapping. For selection values, the selection option is followed by the corresponding data point value in parentheses. For bitfields, the bit number is followed by the boolean data point label. Following the data point label, in parentheses, is the data point characteristics: NV if non-volatile, Config if a configuration point, and Prot if write-protected. Bit 0 is the least significant bit.
- 5. Following list contains the Modbus extensions (features not defined in standard Modbus) that are implemented in Rosemount[™] ultrasonic flow meters.

a.	32-bit values like floats and longs occupy two consecutive Modbus 16-bit registers. Modbus implemented in Rosemount [™] ultrasonic flow meters is big endian. So the first (lowest number) register contains the most significant word with the most significant byte first, and the second the least significant byte last (high byte first and high word first). 32-bit floating point values are stored in IEEE 754 Floating-Point format.
b.	Some other Modbus devices use a pre-defined type based on the register number. Rosemount [™] ultrasonic flow meters uses types (int, long, float) without regard to register number.
С.	In Rosemount [™] liquid meters, registers are dual mapped to accommodate different flow computers So all liquid registers, starting at 1 have a duplicate at the register +40001.
d.	All liquid registers may be read in either metric or U.S. Customary units.

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e.	When a Modbus register is undefined in the meter a value of zero is returned. There are 3 dummy registers at the end of the Modbus map (65533-65535) that are reserved for internal use to facilitate this.
f.	If an odd number of registers are polled for 32-bit values, the meter returns one extra register so that a complete set of 32-bit values are polled. It is recommended to use transactions with registers of the same Modbus type.

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